

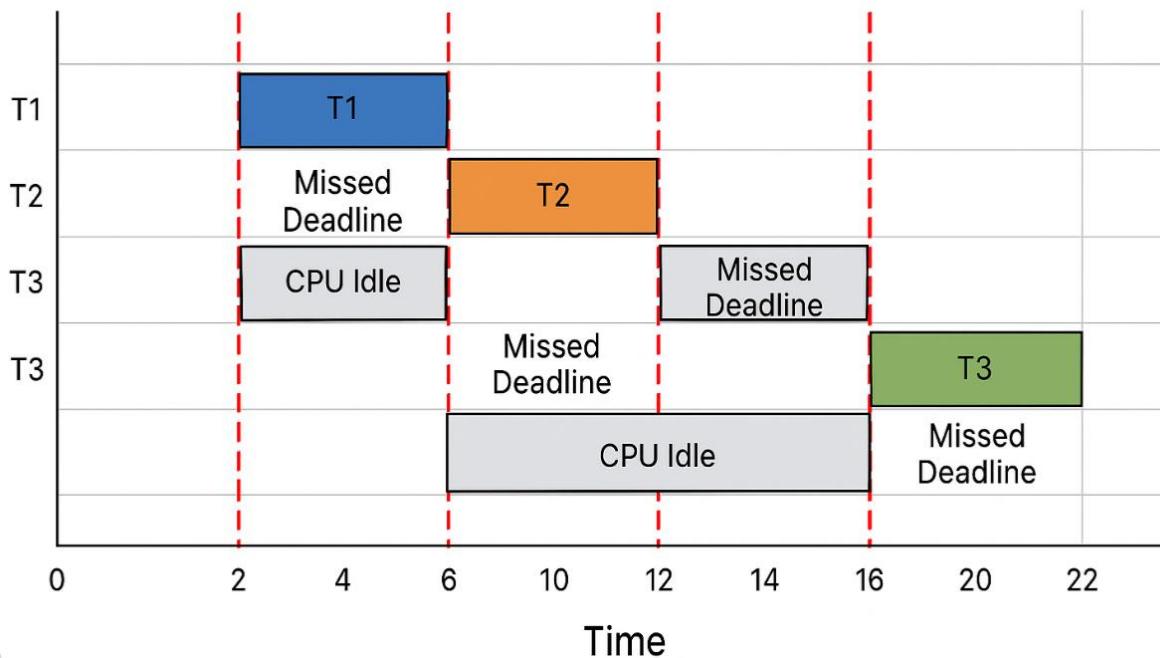
# Project Proposal: Real-Time Task Timing Visualizer (Simulator)

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## 1. Goal

Build a simulator that models real-time task scheduling on a CPU. The simulator will run task traces (periodic, aperiodic, interrupts) and dynamically visualize scheduling decisions, deadlines, and missed deadlines. It will support multiple real-time scheduling algorithms, allow dynamic task arrivals, and provide interactive visualization.

# REAL-TIME TASK SCHEDULING VISUALIZER



## 2. Features

- **Dynamic Task Arrivals**
  - Tasks can arrive at runtime (random arrivals, scripted from JSON/CSV, or user-added via GUI).
- **Scheduling Algorithms**
  - Real-time: Rate Monotonic (RM), Earliest Deadline First (EDF), Deadline Monotonic (DM), Least Laxity First (LLF).
  - OS-style: FCFS, Shortest Job First (SJF/SRTF), Round Robin (RR), Fixed Priority.
- **Visualization**
  - Gantt-chart style timeline of task execution.
  - Deadline markers, with missed deadlines highlighted.

- CPU idle periods shown distinctly.
  - **Metrics**
    - CPU utilization, response times, missed deadlines count.
    - Export results to CSV.
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### 3. Extensions

1. **Energy-aware scheduling**
    - Simulate CPU energy states (active vs idle).
    - Show estimated energy consumption under different schedulers.
  2. **Multiprocessor Scheduling**
    - Simulate dual-core or multi-core scheduling (Global EDF, Partitioned RM).
  3. **Task Dependencies**
    - Support Directed Acyclic Graphs (DAGs) to model precedence constraints.
  4. **Priority Inversion Simulation**
    - Model resource locking and priority inversion.
    - Compare with Priority Inheritance protocol.
  5. **Jitter Modeling**
    - Introduce variability in task release times and visualize its impact.
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### 4. Tools & Implementation Plan

- **Language:** Python (preferred for fast prototyping and visualization).
- **Visualization:**
  - Matplotlib (Python desktop app).
  - Optional: D3.js (web-based interactive version).
- **Trace Input:**
  - Generated synthetic tasks.
  - User interactive input (add task at runtime).
  - Optional: load from CSV/JSON traces.
- **System Requirements:**
  - Runs on a general-purpose laptop (Windows/Linux/Mac).
  - No special hardware required.

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## 5. Project Phases

### 1. Task Model & Simulator Core

- Implement task objects (arrival, exec, deadline, priority).
- Discrete time loop to simulate execution.

### 2. Scheduler Implementations

- RM, EDF, DM, LLF → baseline.
- Add OS schedulers for comparison (FCFS, RR, SJF).

### 3. Visualization Layer

- Gantt chart with deadlines, idle times, and missed deadlines.

### 4. Metrics & Reporting

- CPU utilization, response times, deadline misses → CSV export.

### 5. Extensions

- Energy-aware, multiprocessor, priority inversion, jitter, DAG dependencies.

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## 6. Deliverables

- **Simulator Software** (Python app).
- **Visualization Tool** (timeline plots, interactive GUI).
- **Documentation** (design decisions, how to run, sample traces).
- **Demo** showing multiple scheduling algorithms on the same workload.