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Program : **B.Tech**

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Subject Code: **BT-102**

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Module 5: Matrices**Contents**

Rank of a Matrix, Solution of Simultaneous Linear Equations by Elementary Transformation, Consistency of Equation, Eigen Values and Eigen Vectors, Diagonalization of Matrices, Cayley-Hamilton theorem and its applications to find inverse

Matrix : It is a rectangular arrangement of elements.

It is denoted by capital letter, while their elements by small letter.

i.e. $A = [a_{ij}]_{m \times n}$, Where $m = \text{No. of rows}$, $n = \text{No. of columns}$.

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

i.e. A matrix is simply a rectangular (or square) array of numbers arranged in rows and columns. In fact, the term “array” is used pretty much interchangeably with matrix. Programmers tend to use “array”, while mathematicians and biologists tend to use “matrix”. The entries in a matrix are termed *elements* of the matrix.

Useful types of Matrix:-

[1] **Rectangular Matrix:** If $m \neq n$ then the Matrix $A = [a_{ij}]_{m \times n}$ is called a **rectangular** Matrix.

For example $\begin{bmatrix} 6 & -3 & 1 \\ 2 & 0 & 9 \end{bmatrix}$

[2] **Square Matrix:** If $m = n$ then the Matrix $A = [a_{ij}]_{m \times n}$ is called a **Square** Matrix.

For example $\begin{bmatrix} 1 & -3 \\ 2 & 7.2 \end{bmatrix}$

[3] **Sub-matrix of a Matrix :-** A matrix, which is obtained from a given matrix by deleting any number of rows and number of columns is called a Sub-matrix of a Matrix.

Each matrix has two sub matrix like matrix itself and zero matrix.

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For example: For the matrix $A = \begin{bmatrix} 6 & -3 & 1 \\ 2 & 0 & 9 \end{bmatrix}$

The sub matrices are

$$A, 0, A_1 = \begin{bmatrix} 6 \\ 2 \end{bmatrix}, A_2 = \begin{bmatrix} -3 \\ 0 \end{bmatrix}, A_3 = \begin{bmatrix} 1 \\ 9 \end{bmatrix}, A_4 = \begin{bmatrix} 6 & -3 \\ 2 & 0 \end{bmatrix}, A_5 = \begin{bmatrix} -3 & 1 \\ 0 & 9 \end{bmatrix}, A_6 = \begin{bmatrix} 6 & 1 \\ 2 & 9 \end{bmatrix}$$

$$A_7 = \begin{bmatrix} 6 & -3 \end{bmatrix}, A_8 = \begin{bmatrix} -3 & 1 \end{bmatrix}, A_9 = \begin{bmatrix} 2 & 0 \end{bmatrix}, A_{10} = \begin{bmatrix} 0 & 9 \end{bmatrix}, A_{11} = \begin{bmatrix} 6 & 1 \end{bmatrix}, A_{12} = \begin{bmatrix} 2 & 9 \end{bmatrix}$$

$$A_{13} = \begin{bmatrix} 6 \end{bmatrix}, A_{14} = \begin{bmatrix} -3 \end{bmatrix}, A_{15} = \begin{bmatrix} 1 \end{bmatrix}, A_{16} = \begin{bmatrix} 2 \end{bmatrix}, A_{17} = \begin{bmatrix} 0 \end{bmatrix}, A_{18} = \begin{bmatrix} 9 \end{bmatrix}$$

Rank of a Matrix: The order of max. order non-singular sub-matrix is called the rank of the matrix and it is denoted by $\rho(A)$ for example If $A = \begin{bmatrix} 6 & -3 & 1 \\ 2 & 0 & 9 \end{bmatrix}$ then it's rank i.e. $\rho(A) = 2$

If A is a square matrix of order n then it's nullity exists and it is $N(A) = n - \rho(A)$.

Some important conclusions:-

- Since the non-singular matrix is a square matrix, therefore the rank of a non-singular matrix of order n is n and it's nullity is zero.
- Rank of a Unit matrix of order n is n and it's nullity is zero.
- If A is matrix of order $m \times n$, then it's rank is $\leq m$ or $\leq n$.
- The rank of a zero matrix is taken as **zero**.
- The rank is always a non-negative whole number.

Practice problems: Find the rank of following matrices

$$A = \begin{bmatrix} 2 & 1 & -1 \\ 0 & 3 & -2 \\ 2 & 4 & -3 \end{bmatrix}, B = \begin{bmatrix} 1 & 3 & 4 & 3 \\ 3 & 9 & 12 & 3 \\ 1 & 3 & 4 & 1 \end{bmatrix}$$

Answers : $\rho(A) = 2$ because

$$|A| = \begin{vmatrix} 2 & 1 & -1 \\ 0 & 3 & -2 \\ 2 & 4 & -3 \end{vmatrix} = 0$$

Therefore $\rho(A) \neq 3$, Now we take a non-singular sub-matrix $A_1 = \begin{bmatrix} 2 & 1 \\ 0 & 3 \end{bmatrix}$ of A such

$$\text{that } |A_1| = \begin{vmatrix} 2 & 1 \\ 0 & 3 \end{vmatrix} = 6 \neq 0, \text{ hence } \rho(A) = 2 \text{ and } N(A) = n - \rho(A) = 3 - 2 = 1$$

Similarly $\rho(B) = 2$.

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Elementary transformations or operations on a matrix :- Any one of the following transformation on a matrix is called an elementary transformation :

[1] Interchange of any two rows or columns

i.e. we symbolized as say $R_i \leftrightarrow R_j$ or $C_i \leftrightarrow C_j$

[2] Multiplication of a row or a column by a non-zero scalar.

i.e. We symbolized as say $\rightarrow kR_i$ or $\rightarrow kC_i$ where $k \neq 0$

[3] Addition of k times the elements of a row (or a column) to the corresponding elements of another row (or a column).

i.e. We symbolized as say

$\rightarrow R_i + kR_j$ or $\rightarrow C_i + kC_j$ where $k \neq 0$

Normal Form of a Matrix:

By means of elementary transformations every matrix A of order $m \times n$ can be reduced to one of

the following forms: $\begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}$, $\begin{bmatrix} I_r \\ 0 \end{bmatrix}$, $[I_r \ 0]$, $[I_r]$

and these are called its normal forms and r is the rank of A .

Example-1: Reduce the following matrix to normal form $A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix}$

And hence find its rank.

Solution: Given that $A = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 1 & 2 & 3 & 4 \\ 3 & 4 & 5 & 2 \end{bmatrix}$

$\rightarrow R_2 - R_1$ and $\rightarrow R_3 - 3R_1$

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$$\sim \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix}$$

$$\rightarrow C_2 - C_1, \rightarrow C_3 - C_1 \text{ and } \rightarrow C_4 + C_1$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 5 \\ 0 & 1 & 2 & 5 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 2 & 5 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\rightarrow C_3 - 2C_2 \text{ and } \rightarrow C_4 - 5C_2$$

$$\sim \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} I_2 & 0 \\ 0 & 0 \end{bmatrix} \sim \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix}$$

Hence the $\rho(A) = 2$.

Computation of two non-singular matrices by the normal form : It is well explained by the following example.

Example-2 : Find the non-singular matrices P and Q such that PAQ is in normal form of A

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \\ 1 & 3 & 2 \\ 2 & 1 & 3 \end{bmatrix}$$

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Solution: Here the order of given matrix A is 4×3 , Therefore, the matrices P and Q must be of order 4 and 3 respectively.

Thus to find the non-singular matrices P and Q , we write

$$A = I_4 A I_3$$

Now, reduce the matrix A on the L.H.S. to its normal form by the application of elementary transformations.

Each elementary row transformation is effected by performing the same on the prefactor unit matrix I_4 of A and each elementary column transformation is effected by performing the same on the post factor unit matrix I_3 of A . i.e.

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 2 & 1 \\ 1 & 3 & 2 \\ 2 & 1 & 3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow R_2 - 3R_1, \rightarrow R_3 - R_1 \text{ and } \rightarrow R_4 - 2R_1$$

$$\sim \begin{bmatrix} 1 & 2 & 3 \\ 0 & -4 & -8 \\ 0 & 1 & -1 \\ 0 & -3 & -3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -3 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -2 & 0 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow C_2 - 2C_1, \text{ and } \rightarrow C_3 - 3C_1$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & -4 & -8 \\ 0 & 1 & -1 \\ 0 & -3 & -3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -3 & 1 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -2 & 0 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$R_2 \leftrightarrow R_3$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & -4 & -8 \\ 0 & -3 & -3 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -3 & 1 & 0 & 0 \\ -2 & 0 & 0 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

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$$\rightarrow R_3 + 4R_2 \text{ and } \rightarrow R_4 + 3R_2$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & -12 \\ 0 & 0 & -6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7 & 1 & 4 & 0 \\ -5 & 0 & 3 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -3 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow C_3 + C_2$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & -12 \\ 0 & 0 & -6 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7 & 1 & 4 & 0 \\ -5 & 0 & 3 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -5 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\rightarrow \frac{1}{6} C_3$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \\ 0 & 0 & -2 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7 & 1 & 4 & 0 \\ -5 & 0 & 3 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -5/6 \\ 0 & 1 & 1/6 \\ 0 & 0 & 1/6 \end{bmatrix}$$

$$\rightarrow -1/2 R_3$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7/2 & -1/2 & -2 & 0 \\ -5 & 0 & 3 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -5/6 \\ 0 & 1 & 1/6 \\ 0 & 0 & 1/6 \end{bmatrix}$$

$$\rightarrow R_4 + R_3$$

$$\sim \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7/2 & -1/2 & -2 & 0 \\ -3/2 & -1/2 & 1 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -5/6 \\ 0 & 1 & 1/6 \\ 0 & 0 & 1/6 \end{bmatrix}$$

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$$\sim \begin{bmatrix} I_3 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7/2 & -1/2 & -2 & 0 \\ -3/2 & -1/2 & 1 & 1 \end{bmatrix} A \begin{bmatrix} 1 & -2 & -5/6 \\ 0 & 1 & 1/6 \\ 0 & 0 & 1/6 \end{bmatrix} = PAQ$$

$$\therefore P = \begin{bmatrix} 1 & 0 & 0 & 0 \\ -1 & 0 & 1 & 0 \\ -7/2 & -1/2 & -2 & 0 \\ -3/2 & -1/2 & 1 & 1 \end{bmatrix} \text{ and } Q = \begin{bmatrix} 1 & -2 & -5/6 \\ 0 & 1 & 1/6 \\ 0 & 0 & 1/6 \end{bmatrix}$$

Echelon Form of Matrix: The matrix obtained by applying a series of elementary row transformations such that

[1] All the rows with zero elements will be below the non-zero rows .i.e. All zero rows below the non-zero rows.

[2] The number of zeros before the first non-zero element in a row is less than the number of such zeros in the next row.

For example: $A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 2 & 1 \\ 0 & 0 & 2 \\ 0 & 0 & 0 \end{bmatrix}$ $B = \begin{bmatrix} 1 & 1 & 1 & -1 \\ 0 & 2 & 3 & 4 \\ 0 & 0 & 5 & 2 \end{bmatrix}$

Note:- 1. Rank = No. of non-zero rows in the Echelon form: $\rho(A)=3$ and $\rho(B)=3$.

2. Condition [1] is not compulsory.

Example -1: Reduce the following matrix to Echelon form $A = \begin{bmatrix} 1 & 2 & 3 & -1 \\ -2 & -1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$

Solution: Given matrix is $A = \begin{bmatrix} 1 & 2 & 3 & -1 \\ -2 & -1 & -3 & -1 \\ 1 & 0 & 1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$

$$\rightarrow R_2 + 2R_1, \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 3 & 3 & -3 \\ 0 & -2 & -2 & 2 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

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$$\rightarrow 1/3 R_2 \text{ and } \rightarrow 1/2 R_3$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 1 & 1 & -1 \\ 0 & -1 & -1 & 1 \\ 0 & 1 & 1 & -1 \end{bmatrix}$$

$$\rightarrow R_3 + R_2, \rightarrow R_4 - R_2$$

$$\sim \begin{bmatrix} 1 & 2 & 3 & -1 \\ 0 & 1 & 1 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

It is in Echelon form

Therefore $\rho(A) = \text{No. of non-zero rows} = 2$

Solution of system of Non-homogeneous linear algebraic equations:-Let us consider a system of m equations and n in unknowns

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = b_2$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = b_m$$

The Augmented matrix is

$$[A : B] = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \cdots & \cdots & \cdots & \cdots & \cdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{bmatrix}$$

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Now by applying a series of elementary row transformations, we reduce the above matrix to **Echelon form and we will find say $[A_1 : B_1]$ of $[A : B]$**

$$\rho[A : B] = \text{No. of non-zero rows in the echelon form of } [A : B] = r \text{ and}$$

Now the $\rho[A] = \text{No. of non-zero rows in the echelon form of } [A] = s \text{ and } n$

Conclusions:

[1] Consistent: If $\rho[A : B] = \rho[A]$ then system is consistent.

[i] If $\rho[A : B] = \rho[A] = n$, then system has a unique solution or a trivial solution.

[ii] If $\rho[A : B] = \rho[A] < n$, then system has a many solutions or a non-trivial solution.

[2] In-Consistent: If $\rho[A : B] \neq \rho[A]$ then system is in-consistent.

Example -1: Examine whether the following system of equations are consistent or not and if it is consistent then solve it.

$$\begin{aligned} \text{[i] } x + y - 2z &= 5 \\ x - 2y + z &= -2 \\ -2x + y + z &= 4 \end{aligned}$$

Solution: The Augmented matrix is

$$[A : B] = \begin{bmatrix} 1 & 1 & -2 & 5 \\ 1 & -2 & 1 & -2 \\ -2 & 1 & 1 & 4 \end{bmatrix}$$

$$\rightarrow R_2 - R_1, \rightarrow R_3 + 2R_1$$

$$\sim \begin{bmatrix} 1 & 1 & -2 & 5 \\ 0 & -3 & 3 & -7 \\ 0 & 3 & -3 & 14 \end{bmatrix}$$

$$\rightarrow R_3 + R_2$$

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$$\sim \begin{bmatrix} 1 & 1 & -2 & 5 \\ 0 & -3 & 3 & -7 \\ 0 & 0 & 0 & 7 \end{bmatrix}$$

$$\rightarrow 1/-3 R_2 \text{ and } \rightarrow 1/7 R_3$$

$$\sim \begin{bmatrix} 1 & 1 & -2 & 5 \\ 0 & 1 & -1 & 7/3 \\ 0 & 0 & 0 & 1 \end{bmatrix} \sim [A_1 : B_1]$$

It is in Echelon form

Therefore $\rho[A:B]=3$ and $\rho(A)=2$, Hence $\rho[A:B] \neq \rho[A]$ i.e. system is in-consistent.

$$\begin{aligned} \text{[ii] } \quad x + 2y - z &= 1 \\ x + y + 2z &= 9 \\ 2x + y - z &= 2 \end{aligned}$$



Solution: The Augmented matrix is

$$[A : B] = \begin{bmatrix} 1 & 2 & -1 & 1 \\ 1 & 1 & 2 & 9 \\ 2 & 1 & -1 & 2 \end{bmatrix}$$

$$\rightarrow R_2 - R_1, \rightarrow R_3 - 2R_1$$

$$\sim \begin{bmatrix} 1 & 2 & -1 & 1 \\ 0 & -1 & 3 & 8 \\ 0 & -3 & 1 & 0 \end{bmatrix}$$

$$\rightarrow (-1)R_2$$

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$$\sim \begin{bmatrix} 1 & 2 & -1 & 1 \\ 0 & 1 & -3 & -8 \\ 0 & -3 & 1 & 0 \end{bmatrix}$$

$$\rightarrow R_3 + 3R_2$$

$$\sim \begin{bmatrix} 1 & 2 & -1 & 1 \\ 0 & 1 & -3 & -8 \\ 0 & 0 & -8 & -24 \end{bmatrix}$$

$$\rightarrow (-1/8)R_3$$

$$\sim \begin{bmatrix} 1 & 2 & -1 & 1 \\ 0 & 1 & -3 & -8 \\ 0 & 0 & 1 & 3 \end{bmatrix} \sim [A_1 : B_1]$$

It is in Echelon form

Therefore $\rho[A:B]=3$ and $\rho(A)=3$, Hence

$$\rho[A:B]=\rho[A] \text{ and } n=3$$

Hence $\rho[A:B]=\rho[A]=n=3$ i.e. System is consistent and has a unique or a trivial solution.

It is find as follows

$$A_1 X = B_1$$

$$\sim \begin{bmatrix} 1 & 2 & -1 \\ 0 & 1 & -3 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ -8 \\ 3 \end{bmatrix}$$

$$\sim \begin{bmatrix} x+2y-z \\ y-3z \\ z \end{bmatrix} = \begin{bmatrix} 1 \\ -8 \\ 3 \end{bmatrix}$$

Therefore,

$$x+2y-z=1 \dots(i)$$

$$y-3z=-8 \dots(ii)$$

$$z=3, \text{Hence from above } y=1 \text{ and } x=2$$



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$$\begin{aligned}
 \text{[iii] } & x - y + 2z = 4 \\
 & 3x + y + 4z = 6 \\
 & x + y + z = 1
 \end{aligned}$$

Solution: The Augmented matrix is

$$[A : B] = \begin{bmatrix} 1 & -1 & 2 & 4 \\ 3 & 1 & 4 & 6 \\ 1 & 1 & 1 & 1 \end{bmatrix}$$

$$\rightarrow R_2 - 3R_1, \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 1 & -1 & 2 & 4 \\ 0 & 4 & -2 & -6 \\ 0 & 2 & -1 & -3 \end{bmatrix}$$

$$\rightarrow (1/2)R_2$$

$$\sim \begin{bmatrix} 1 & -1 & 2 & 4 \\ 0 & 2 & -1 & -3 \\ 0 & 2 & -1 & -3 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & -1 & 2 & 4 \\ 0 & 2 & -1 & -3 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim [A_1 : B_1]$$

It is in Echelon form



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Therefore $\rho[A:B]=2$ and $\rho(A)=2$, Hence

$$\rho[A:B]=\rho[A] \text{ and } n=3$$

$$\text{Hence } \rho[A:B]=\rho[A]=2 < n=3$$

i.e. System is consistent and has many solution or a Non-trivial solution.

It is find as follows

$$A_1 X = B_1$$

$$\sim \begin{bmatrix} 1 & -1 & 2 \\ 0 & 2 & -1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 4 \\ -3 \\ 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} x-y+2z \\ 2y-z \\ 0 \end{bmatrix} = \begin{bmatrix} 4 \\ -3 \\ 0 \end{bmatrix}$$

Therefore,

$$x-y+2z=4 \dots(i)$$

$$2y-z=-3 \dots(ii)$$

$\therefore 3-2=1$ i.e. we have one independent variable.

let $z=k$, where $k \in R$, Hence from above $y = \frac{k-3}{2}$ and by equation (i) $x = \frac{5-3k}{2}$

Example -2: By the method of elementary transformation of matrices investigate the value of λ and μ for which the system of equations

$$x + y + z = 6$$

$$x + 2y + 3z = 10$$

$$x + 2y + \lambda z = \mu$$

have (i) no solution (ii) a unique solution (iii) an infinite number of solution.

Solution: The Augmented matrix is

$$[A : B] = \begin{bmatrix} 1 & 1 & 1 & 6 \\ 1 & 2 & 3 & 10 \\ 1 & 2 & \lambda & \mu \end{bmatrix}$$

$$\rightarrow R_2 - R_1, \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 1 & \lambda-1 & \mu-6 \end{bmatrix}$$

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$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & 1 & 1 & 6 \\ 0 & 1 & 2 & 4 \\ 0 & 0 & \lambda - 3 & \mu - 10 \end{bmatrix} \sim [A_1 : B_1]$$

It is in Echelon form and their rank depends upon the values of λ and μ .

Hence, we have

- (i) **No solution** : We know that for this case $\rho[A:B] \neq \rho[A]$ i.e. system is inconsistent. therefore $\lambda = 3$ and $\mu \neq 10$ i.e. $\mu \in R$ excluding $\mu = 10$.
- (ii) **A unique solution** : We know that for this case $\rho[A:B] = \rho[A]$ and $n = 3$
i.e. $\rho[A:B] = \rho[A] = n = 3$ i.e. System is consistent and has a unique or a trivial solution.
Hence, we have $\lambda \neq 3$ and $\mu \in R$.
- (iii) **An infinite number of solution** : We know that for this case
 $\rho[A:B] = \rho[A]$ and $n = 3$
Hence $\rho[A:B] = \rho[A] = 2 < n = 3$ i.e.
System is consistent and has many solution or a Non-trivial solution.
Hence, $\lambda = 3$ and $\mu = 10$

Solution of system of Homogeneous linear algebraic equations:-

Let us consider a system of m equations and n in unknowns

$$a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n = 0$$

$$a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n = 0$$

$$\vdots$$

$$a_{m1}x_1 + a_{m2}x_2 + \cdots + a_{mn}x_n = 0$$

The Augmented matrix is

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$$[A : B] = \begin{bmatrix} a_{11} & a_{12} & \dots & a_{1n} & 0 \\ a_{21} & a_{22} & \dots & a_{2n} & 0 \\ \dots & \dots & \dots & \dots & \dots \\ a_{m1} & a_{m2} & \dots & a_{mn} & 0 \end{bmatrix}$$

Now by applying a series of elementary row transformations, we reduce the above matrix to **Echelon form** and we will find say $[A_1 : B_1]$ of $[A : B]$

$$\rho[A : B] = \text{No. of non-zero rows in the echelon form of } [A : B] = r \text{ and}$$

Now the $\rho[A] = \text{No. of non-zero rows in the echelon form of } [A] = s$
and n is the number of unknowns.

Conclusions:

If $\rho[A : B] = \rho[A]$ then system is consistent.

[i] If $\rho[A : B] = \rho[A] = n$, then system has a unique solution or a trivial solution and it is $x_1 = x_2 = \dots = x_n = 0$

[ii] If $\rho[A : B] = \rho[A] < n$, then system has a many solutions or a non-trivial solutions.

Note :- [1] The **system of Homogeneous linear algebraic equations are always** consistent.

[2] If $|A| \neq 0$, then, we have unique solution, $x_1 = x_2 = \dots = x_n = 0$.

[3] If $|A| = 0$, then, we have many solution or Non-trivial solutions.

Example -1: Examine whether the following system of equations are consistent or not and if it is consistent then solve it.

$$\begin{aligned} \text{[i] } \quad & x + 3y - 2z = 0 \\ & 2x - y + 4z = 0 \\ & x - 11y + 14z = 0 \end{aligned}$$

Solution: The Augmented matrix is

$$[A : B] = \begin{bmatrix} 1 & 3 & -2 & 0 \\ 2 & -1 & 4 & 0 \\ 1 & -11 & 14 & 0 \end{bmatrix}$$

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$$\rightarrow R_2 - 2R_1, \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 1 & 3 & -2 & 0 \\ 0 & -7 & 8 & 0 \\ 0 & -14 & 16 & 0 \end{bmatrix}$$

$$\rightarrow R_3 - 2R_2$$

$$\sim \begin{bmatrix} 1 & 3 & -2 & 0 \\ 0 & -7 & 8 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \sim [A_1 : B_1]$$

It is in Echelon form

Therefore $\rho[A:B] = 2$ and $\rho(A) = 2$, Hence

$$\rho[A:B] = \rho[A] \text{ and } n = 3$$

$$\text{Hence } \rho[A:B] = \rho[A] = 2 < n = 3$$

i.e. System is consistent and has many solution or a Non-trivial solution.

It is find as follows

$$A_1 X = B_1$$

$$\sim \begin{bmatrix} 1 & 3 & -2 \\ 0 & -7 & 8 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} x+3y-2z \\ -7y+8z \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Therefore,

$$x+3y-2z=0 \dots(i)$$

$$-7y+8z=0 \dots(ii)$$

$\therefore 3-2=1$ i.e. we have one independent variable.

let $z = k$, where $k \in R$, Hence from above $y = \frac{8k}{7}$ and by equation (i) $x = \frac{-10k}{7}$

Example -2 Determine 'b' for which the system of equations

$$2x + y + 2z = 0$$

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$$x + y + 3z = 0$$

$$4x + 3y + bz = 0$$

have (i) a unique solution i.e. trivial solution (iii) an infinite number of solution i.e. a non-trivial solutions. Find the non-trivial solutions.

Solution: The Augmented matrix is

$$[A : B] = \begin{bmatrix} 2 & 1 & 2 & 0 \\ 1 & 1 & 3 & 0 \\ 4 & 3 & b & 0 \end{bmatrix}$$

$$R_1 \leftrightarrow R_2$$

$$\sim \begin{bmatrix} 1 & 1 & 3 & 0 \\ 2 & 1 & 2 & 0 \\ 4 & 3 & b & 0 \end{bmatrix}$$

$$\rightarrow R_2 - 2R_1, \rightarrow R_3 - 4R_1$$

$$\sim \begin{bmatrix} 1 & 1 & 3 & 0 \\ 0 & -1 & -4 & 0 \\ 4 & -1 & b-12 & 0 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & 1 & 3 & 0 \\ 0 & -1 & -4 & 0 \\ 0 & 0 & b-8 & 0 \end{bmatrix} \sim [A_1 : B_1]$$

It is in Echelon form and their rank depends upon the values of b .

Hence, we have

- (i) **A unique solution or a trivial solution :** We know that for this case
 $\rho[A : B] = \rho[A]$ and $n = 3$
i.e. $\rho[A : B] = \rho[A] = n = 3$ i.e. System is consistent and has a unique or a trivial solution.
Hence, we have $b - 8 \neq 0 \Rightarrow b \neq 8$.
- (ii) **An infinite number of solution or a non-trivial solution :** We know that for this case

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$$\rho[A:B] = \rho[A] \text{ and } n = 3$$

$$\text{Hence } \rho[A:B] = \rho[A] = 2 < n = 3 \text{ i.e.}$$

System is consistent and has many solution or a Non-trivial solution.

$$\text{Hence, } b - 8 = 0 \Rightarrow b = 8.$$

It is find as follows

$$A_1 X = B_1$$

$$\sim \begin{bmatrix} 1 & 1 & 3 \\ 0 & -1 & -4 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\sim \begin{bmatrix} x + y + 3z \\ -y - 4z \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Therefore,

$$x + y + 3z = 0 \dots (i)$$

$$-y - 4z = 0 \dots (ii)$$

$\therefore 3 - 2 = 1$ i.e. we have one independent variable.

let $z = k$, where $k \in \mathbb{R}$, Hence from above $y = -4k$ and by equation (i) $x = k$

Characteristic Equation: If A is a square matrix of order n , Then the equation $|A - \lambda I| = 0$ is called a **Characteristic Equation** of A . Since it is a polynomial of degree n , therefore, it has n roots say $\lambda_1, \lambda_2, \lambda_3 \dots \dots \dots \lambda_n$ are called **Characteristic roots or latent roots or eigen values**.

Characteristic Value Problem: If

A is a square matrix of order n , determine the scalars λ and then non-zero vectors X , which simultaneously satisfy the equation

$$AX = \lambda X \text{ or } [A - \lambda I]X = 0.$$

This is known as **Characteristic value problem**. X are called **Characteristic vectors or latent vectors or eigenvectors**.

Note: If $\lambda_1, \lambda_2, \lambda_3 \dots \dots \dots \lambda_n$ be the **eigen values of A** , then A^n has the **eigen values** $\lambda_1^n, \lambda_2^n, \dots \dots \dots \lambda_n^n$.

Example -1: Find the Eigen values of A^4 , where $A = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$

Solution: We know that for Eigen value of A , $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 1 \\ 1 & 1-\lambda \end{vmatrix} = 0 \Rightarrow (1-\lambda)^2 - 1 = 0 \Rightarrow \lambda = 0, 2$$

Hence the **Eigen values of A^4** are **$0^4, 2^4$ i.e. 0, 16**

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Example -2: Find the Eigen values of $4A^{-1} + 3A + 2I$, where $A = \begin{bmatrix} 1 & 0 \\ 2 & 4 \end{bmatrix}$

Solution: We know that for Eigen value of A , $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 0 \\ 2 & 4-\lambda \end{vmatrix} = 0 \Rightarrow (1-\lambda)(4-\lambda) - 0 = 0 \Rightarrow \lambda = 1, 4$$

Now, the Eigen values of A^{-1} are $1^{-1}, 4^{-1}$ i.e. $1, \frac{1}{4}$ and those of $4A^{-1}$ are $4 \cdot 1, 4 \cdot \frac{1}{4} \Rightarrow 4, 1$. The Eigen values of $3A$, are $3 \cdot 1, 3 \cdot 4$, i.e. $3, 12$.

Hence, the eigen values of

$4A^{-1} + 3A$ are $4 + 3, 1 + 12$ i.e. $7, 13$.

Since the eigen values of unit matrix I of 2×2 order are $1, 1$, therefore the eigen values of $2I$ are $2, 2$.

Thus, the Eigen values of $4A^{-1} + 3A + 2I$ are $7 + 2 = 9$ and $13 + 2 = 15$.

Example -3: Find the Eigen values and Eigen vectors of

$$A = \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix}$$

Solution: We know that for Eigen value of A , $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 8-\lambda & -6 & 2 \\ -6 & 7-\lambda & -4 \\ 2 & -4 & 3-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (8-\lambda)[(7-\lambda)(3-\lambda) - 16] - (-6)[-6(3-\lambda) + 8] + 2[24 - 2(7-\lambda)] = 0$$

$$\Rightarrow -\lambda^3 + 18\lambda^2 - 45\lambda = 0$$

$$\Rightarrow (-\lambda)(\lambda - 3)(\lambda - 15) = 0 \Rightarrow \lambda = 0, 3, 15$$

Now, we will find the corresponding Eigen vectors.

For this, we have the characteristic value problem

$$[A - \lambda I]X = 0$$

$$\sim \begin{bmatrix} 8-\lambda & -6 & 2 \\ -6 & 7-\lambda & -4 \\ 2 & -4 & 3-\lambda \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \text{-----[1]}$$

First put $\lambda = 0$, in equation [1]

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$$\sim \begin{bmatrix} 8 & -6 & 2 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{2}R_1$$

$$\sim \begin{bmatrix} 4 & -3 & 1 \\ -6 & 7 & -4 \\ 2 & -4 & 3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$R_1 \leftrightarrow R_3$$

$$\sim \begin{bmatrix} 2 & -4 & 3 \\ -6 & 7 & -4 \\ 4 & -3 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_3 + 3R_1, \rightarrow R_3 - 2R_1$$

$$\sim \begin{bmatrix} 2 & -4 & 3 \\ 0 & -5 & 5 \\ 0 & 5 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 2 & -4 & 3 \\ 0 & -5 & 5 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{5}R_2$$

$$\sim \begin{bmatrix} 2 & -4 & 3 \\ 0 & -1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

It is in Echelon form ,

Therefore $\rho[A - \lambda I] = 2$ for $\lambda = 0$ and $n = 3$, Hence

Hence , No. of Linearly Independent Eigen vector $= 3 - 2 = 1$

i.e. $2x - 4y + 3z = 0 \dots\dots[i]$

$$-y + z = 0$$

$$\Rightarrow y = z = k_1 \text{ where } k_1 \in R, \text{ Hence by (i), } x = \frac{k_1}{2}$$

$$\text{Thus the Eigen vector } X = X_1 = X_{\lambda=0} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \frac{k_1}{2} \\ k_1 \\ k_1 \end{bmatrix}$$

Now , put $\lambda = 3$, in equation [1]



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$$\sim \begin{bmatrix} 5 & -6 & 2 \\ -6 & 4 & -4 \\ 2 & -4 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_1 + R_2$$

$$\sim \begin{bmatrix} -1 & -2 & -2 \\ -6 & 4 & -4 \\ 2 & -4 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{2}R_2, \rightarrow \frac{1}{2}R_3$$

$$\sim \begin{bmatrix} -1 & -2 & -2 \\ -3 & 2 & -2 \\ 1 & -2 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_2 - 3R_1, \rightarrow R_3 + R_1$$

$$\sim \begin{bmatrix} -1 & -2 & -2 \\ 0 & 8 & 4 \\ 0 & -4 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{4}R_2, \rightarrow \frac{1}{2}R_3$$

$$\sim \begin{bmatrix} -1 & -2 & -2 \\ 0 & 2 & 1 \\ 0 & -2 & -1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_3 + R_2$$

$$\sim \begin{bmatrix} -1 & -2 & -2 \\ 0 & 2 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

It is in Echelon form,



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Therefore $\rho[A - \lambda I] = 2$ for $\lambda = 3$ and $n = 3$, Hence
Hence, No. of Linearly Independent Eigen vector $= 3 - 2 = 1$

$$\text{i.e. } -x - 2y - 2z = 0 \dots\dots [i]$$

$$2y + z = 0$$

$$\Rightarrow 2y = -z \text{ Let } z = k_2 \text{ where } k_2 \in R,$$

$$\therefore y = -\frac{k_2}{2} \text{ Hence by (i), } x = -k_2$$

$$\text{Thus the Eigen vector } X = X_2 = X_{\lambda=3} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} -k_2 \\ -\frac{k_2}{2} \\ k_2 \end{bmatrix}$$

Now, put $\lambda = 15$, in equation [1]

$$\sim \begin{bmatrix} -7 & -6 & 2 \\ -6 & -8 & -4 \\ 2 & -4 & -12 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{2} R_2, \rightarrow \frac{1}{2} R_3$$

$$\sim \begin{bmatrix} -7 & -6 & 2 \\ -3 & -4 & -2 \\ 1 & -2 & -6 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$R_1 \leftrightarrow R_3$$

$$\sim \begin{bmatrix} 1 & -2 & -6 \\ -3 & -4 & -2 \\ -7 & -6 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_2 + 3R_1, \rightarrow R_3 + 7R_1$$

$$\sim \begin{bmatrix} 1 & -2 & -6 \\ 0 & -10 & -20 \\ -7 & -6 & -40 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{10} R_2, \rightarrow \frac{1}{20} R_3$$

$$\sim \begin{bmatrix} 1 & -2 & -6 \\ 0 & -1 & -2 \\ 0 & -1 & -2 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} 1 & -2 & -6 \\ 0 & -1 & -2 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

It is in Echelon form,



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Therefore $\rho[A - \lambda I] = 2$ for $\lambda = 3$ and $n = 3$, Hence
Hence, No. of Linearly Independent Eigen vector $= 3 - 2 = 1$

$$\text{i.e. } x - 2y - 6z = 0 \dots\dots[i]$$

$$-y - 2z = 0$$

$$\Rightarrow -y = 2z \text{ Let } z = k_3 \text{ where } k_3 \in R,$$

$$\therefore y = -2k_3 \text{ Hence by (i), } x = 2k_3$$

$$\text{Thus the Eigen vector } X = X_3 = X_{\lambda=3} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2k_3 \\ -2k_3 \\ k_3 \end{bmatrix}$$

Example -4: Find the Eigen values and Eigen vectors of

$$A = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$$

Solution: We know that for Eigen value of **A**, $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 6-\lambda & -2 & 2 \\ -2 & 3-\lambda & -1 \\ 2 & -1 & 3-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (6 - \lambda)[(3 - \lambda)^2 - 1] - (-2)[-2(3 - \lambda) + 2] + 2[2 - 2(3 - \lambda)] = 0$$

$$\Rightarrow \lambda^3 - 12\lambda^2 + 36\lambda - 32 = 0$$

Since $\lambda = 2$ satisfies the above equation, $(\lambda - 2)$ is one factor of it.

$$\lambda^2(\lambda - 2) - 10\lambda(\lambda - 2) + 16(\lambda - 2) = 0$$

$$\Rightarrow (\lambda - 2)(\lambda^2 - 10\lambda + 16) = 0$$

$$\Rightarrow (\lambda - 2)(\lambda - 2)(\lambda - 8) = 0 \Rightarrow \lambda = 2, 2, 8$$

Now, we will find the corresponding Eigen vectors.

For this, we have the characteristic value problem

$$[A - \lambda I]X = 0$$

$$\sim \begin{bmatrix} 6-\lambda & -2 & 2 \\ -2 & 3-\lambda & -1 \\ 2 & -1 & 3-\lambda \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \dots\dots\dots[1]$$

$$\sim \begin{bmatrix} 4 & -2 & 2 \\ -2 & 1 & -1 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad \text{Now, put } \lambda = 2, \text{ in equation [1]}$$

$$\rightarrow \frac{1}{2} R_1$$

$$\sim \begin{bmatrix} 2 & -1 & 1 \\ -2 & 1 & -1 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_2 + R_1, \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 2 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

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It is in Echelon form,

Therefore $\rho[A - \lambda I] = 1$ for $\lambda = 2$ and $n = 3$, Hence

Hence, No. of Linearly Independent Eigen vector $= 3 - 1 = 2$

i.e. $2x - y + z = 0 \dots\dots[i]$

Let $y = k_1$ $z = k_2$ where $k_1, k_2 \in R$,

\therefore Hence by (i), $x = \frac{k_1 - k_2}{2}$

$$\text{Thus the Eigen vector } X = X_{\lambda=2} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \frac{k_1 - k_2}{2} \\ k_1 \\ k_2 \end{bmatrix} = \begin{bmatrix} \frac{k_1}{2} \\ k_1 \\ 0 \end{bmatrix} + \begin{bmatrix} \frac{-k_2}{2} \\ 0 \\ k_2 \end{bmatrix} = X_1 + X_2$$

Now, put $\lambda = 8$, in equation [1]

$$\sim \begin{bmatrix} -2 & -2 & 2 \\ -2 & -5 & -1 \\ 2 & -1 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_2 - R_1, \rightarrow R_3 + R_1$$

$$\sim \begin{bmatrix} -2 & -2 & 2 \\ 0 & -3 & -3 \\ 0 & -3 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} -2 & -2 & 2 \\ 0 & -3 & -3 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

It is in Echelon form,

Therefore $\rho[A - \lambda I] = 2$ for $\lambda = 8$ and $n = 3$, Hence

Hence, No. of Linearly Independent Eigen vector $= 3 - 2 = 1$

i.e. $-2x - 2y + 2z = 0 \dots\dots[i]$

$$-3y - 3z = 0$$

$\Rightarrow y + z = 0 \Rightarrow y = -z$ Let $z = k_3$ where $k_3 \in R$,

$\therefore y = -k_3$ Hence by (i), $x = 2k_3$

$$\text{Thus the Eigen vector } X = X_3 = X_{\lambda=8} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2k_3 \\ -k_3 \\ k_3 \end{bmatrix}$$

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Diagonalization of Matrices:-

If A is a square matrix of order n has n linearly independent Eigen –vectors, $X_1, X_2, X_3, \dots, X_n$, then a matrix B can be found such that $B^{-1}AB$ is a diagonal matrix. Where B is called the Modal Matrix and $B = [X_1 X_2 \dots X_n]$.

Example: Verify the Diagonalization of Matrix

$$A = \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix}$$

Solution: We know that for Eigen value of A , $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 6-\lambda & -2 & 2 \\ -2 & 3-\lambda & -1 \\ 2 & -1 & 3-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (6-\lambda)[(3-\lambda)^2 - 1] - (-2)[-2(3-\lambda) + 2] + 2[2 - 2(3-\lambda)] = 0$$

$$\Rightarrow \lambda^3 - 12\lambda^2 + 36\lambda - 32 = 0$$

Since $\lambda = 2$ satisfies the above equation, $(\lambda - 2)$ is one factor of it.

$$\lambda^2(\lambda - 2) - 10\lambda(\lambda - 2) + 16(\lambda - 2) = 0$$

$$\Rightarrow (\lambda - 2)(\lambda^2 - 10\lambda + 16) = 0$$

$$\Rightarrow (\lambda - 2)(\lambda - 2)(\lambda - 8) = 0 \Rightarrow \lambda = 2, 2, 8$$

Now, we will find the corresponding Eigen vectors.

For this, we have the characteristic value problem

$$[A - \lambda I]X = 0$$

$$\sim \begin{bmatrix} 6-\lambda & -2 & 2 \\ -2 & 3-\lambda & -1 \\ 2 & -1 & 3-\lambda \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \text{-----[1]}$$

Now, put $\lambda = 2$, in equation [1]

$$\sim \begin{bmatrix} 4 & -2 & 2 \\ -2 & 1 & -1 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow \frac{1}{2} R_1$$

$$\sim \begin{bmatrix} 2 & -1 & 1 \\ -2 & 1 & -1 \\ 2 & -1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_2 + R_1, \rightarrow R_3 - R_1$$

$$\sim \begin{bmatrix} 2 & -1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

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It is in Echelon form,

Therefore $\rho[A - \lambda I] = 1$ for $\lambda = 2$ and $n = 3$, Hence

Hence, No. of Linearly Independent Eigen vector $= 3 - 1 = 2$

i.e. $2x - y + z = 0 \dots\dots[i]$

Let $y = k_1$ $z = k_2$ where $k_1, k_2 \in R$,

\therefore Hence by (i), $x = \frac{k_1 - k_2}{2}$

$$\text{Thus the Eigen vector } X = X_{\lambda=2} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} \frac{k_1 - k_2}{2} \\ k_1 \\ k_2 \end{bmatrix} = \begin{bmatrix} \frac{k_1}{2} \\ k_1 \\ 0 \end{bmatrix} + \begin{bmatrix} \frac{-k_2}{2} \\ 0 \\ k_2 \end{bmatrix} = X_1 + X_2$$

Now, put $\lambda = 8$, in equation [1]

$$\sim \begin{bmatrix} -2 & -2 & 2 \\ -2 & -5 & -1 \\ 2 & -1 & -5 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_2 - R_1, \rightarrow R_3 + R_1$$

$$\sim \begin{bmatrix} -2 & -2 & 2 \\ 0 & -3 & -3 \\ 0 & -3 & -3 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

$$\rightarrow R_3 - R_2$$

$$\sim \begin{bmatrix} -2 & -2 & 2 \\ 0 & -3 & -3 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

It is in Echelon form,

Therefore $\rho[A - \lambda I] = 2$ for $\lambda = 8$ and $n = 3$, Hence

Hence, No. of Linearly Independent Eigen vector $= 3 - 2 = 1$

i.e. $-2x - 2y + 2z = 0 \dots\dots[i]$

$$-3y - 3z = 0$$

$\Rightarrow y + z = 0 \Rightarrow y = -z$ Let $z = k_3$ where $k_3 \in R$,

$\therefore y = -k_3$ Hence by (i), $x = 2k_3$

$$\text{Thus the Eigen vector } X = X_3 = X_{\lambda=8} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} = \begin{bmatrix} 2k_3 \\ -k_3 \\ k_3 \end{bmatrix}$$



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Now, the Modal Matrix $B = [X_1 X_2 \dots \dots X_n]$ Therefore, $B = [X_1 X_2 X_3]$

Hence

$$B = \begin{bmatrix} 1/2 & -1/2 & 2 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} =$$

 \therefore Now for $\text{Adj } B$

$$\begin{aligned} C_{11} &= (-1)^{1+1}[1] = 1, C_{12} = (-1)^{1+2}[1] = -1, C_{13} = (-1)^{1+3}[1] = 1 \\ C_{21} &= (-1)^{2+1}[-5/2] = 5/2, C_{22} = (-1)^{2+2}[1/2] = 1/2, C_{23} = (-1)^{2+3}[1/2] = -1/2 \\ C_{31} &= (-1)^{3+1}[1/2] = 1/2, C_{32} = (-1)^{3+2}[-5/2] = 5/2, C_{33} = (-1)^{3+3}[1/2] = 1/2 \end{aligned}$$

Hence,

$$\text{adj } B = \begin{bmatrix} 1 & 5/2 & 1/2 \\ -1 & 1/2 & 5/2 \\ 1 & -1/2 & 1/2 \end{bmatrix} \quad \text{and } |B| = 3$$

$$\text{Therefore, } B^{-1} = \frac{\text{adj } B}{|B|} = \begin{bmatrix} 1/3 & 5/6 & 1/6 \\ -1/3 & 1/6 & 5/6 \\ 1/3 & -1/6 & 1/6 \end{bmatrix}$$

$$B^{-1}AB = \begin{bmatrix} 1/3 & 5/6 & 1/6 \\ -1/3 & 1/6 & 5/6 \\ 1/3 & -1/6 & 1/6 \end{bmatrix} \begin{bmatrix} 6 & -2 & 2 \\ -2 & 3 & -1 \\ 2 & -1 & 3 \end{bmatrix} \begin{bmatrix} 1/2 & -1/2 & 2 \\ 1 & 0 & -1 \\ 0 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 2 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 8 \end{bmatrix} = \text{diag}(2, 2, 8)$$

Hence the given matrix is diagonalizable.

Cayley Hamilton Theorem : Every square matrix satisfies its own characteristic equation.**Verification** : We know thatIf A is a square matrix of order n , Then the characteristic equation $|A - \lambda I| = 0$. it is a polynomial of degree n .i.e. $(-1)^n [a_0 \lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_{n-1} \lambda + a_n] = 0$ -----[1]Then to prove the above theorem, if λ is replaced by A , then above equation is satisfied i.e.

$$(-1)^n [a_0 A^n + a_1 A^{n-1} + a_2 A^{n-2} + \dots + a_{n-1} A + a_n I] = 0$$

For this, let $B = \text{adj}(A - \lambda I)$ -----[2]

$$\Rightarrow B = B_0 \lambda^{n-1} + B_1 \lambda^{n-2} + B_2 \lambda^{n-3} + \dots + B_{n-2} \lambda + B_{n-1}$$

Now by equation [2], $(A - \lambda I)B = (A - \lambda I)\text{adj}(A - \lambda I)$

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$$\Rightarrow (A - \lambda I)B = |A - \lambda I| I \quad \text{Since } A \text{ adj } A = |A|I$$

$$\Rightarrow (A - \lambda I)[B_0 \lambda^{n-1} + B_1 \lambda^{n-2} + B_2 \lambda^{n-3} + \dots + B_{n-2} \lambda + B_{n-1}]$$

$$= (-1)^n [a_0 \lambda^n + a_1 \lambda^{n-1} + a_2 \lambda^{n-2} + \dots + a_{n-1} \lambda + a_n] I$$

Now equating the coefficients of like powers of λ on the both sides, we get

$$\begin{aligned} -B_0 I &= (-1)^n a_0 I \\ AB_0 - B_1 I &= (-1)^n a_1 I \\ AB_1 - B_2 I &= (-1)^n a_2 I \\ &\dots \dots \dots \\ AB_{n-2} - B_{n-1} I &= (-1)^n a_{n-1} I \\ AB_{n-1} &= (-1)^n a_n I \end{aligned}$$

Now, premultiplying these equations by $A^n, A^{n-1}, A^{n-2}, \dots, A, I$ and then adding, we get

$$(-1)^n [a_0 A^n + a_1 A^{n-1} + a_2 A^{n-2} + \dots + a_{n-1} A + a_n I] = 0 \dots \dots [3]$$

This shows the Cayley Hamilton theorem.

If A is a non-singular matrix, then multiply [3] by A^{-1} , we get

$$A^{-1} = -\frac{1}{a_n} [a_0 A^{n-1} + a_1 A^{n-2} + \dots + a_{n-1} I]$$

Example-1: Verify Cayley Hamilton theorem to find A^{-1} and A^8 if $A = \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix}$

Solution: We know that for Eigen value of A , $|A - \lambda I| = 0$

$$\Rightarrow \begin{vmatrix} 1-\lambda & 2 \\ 2 & -1-\lambda \end{vmatrix} = 0 \Rightarrow -(1-\lambda)^2 - 4 = 0 \Rightarrow \lambda^2 - 5 = 0$$

Now to prove Cayley Hamilton theorem, we will prove that, if λ is replaced by A , then above equation is satisfied i.e. $A^2 - 5I = 0 \dots \dots [1]$

$$\text{For this, } A^2 = AA = \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 1+4 & 2-2 \\ 2-2 & 4+1 \end{bmatrix} = \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix}$$

$$\therefore \text{L.H.S. of (1) is } A^2 - 5I = \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix} - 5 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} = 0 = \text{R.H.S. of (1)}$$

Hence the Cayley Hamilton theorem is verified.

Now to find A^{-1} , Multiply equation (1) by A^{-1} on the both sides

$$\text{We get } A^{-1} = \frac{1}{5} A = \frac{1}{5} \begin{bmatrix} 1 & 2 \\ 2 & -1 \end{bmatrix}$$

Now to find A^8 , for this by Equation (1) $A^2 = 5I$

$$\therefore A^4 = A^2 A^2 = 25I$$

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$$\text{Hence, } A^8 = A^4 A^4 = 625I = 625 \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 625 & 0 \\ 0 & 625 \end{bmatrix}$$

Example -2: Verify Cayley Hamilton theorem and hence find the matrix represented by $A^5 - 4A^4 -$

$$7A^3 + 11A^2 - A - 10I. A = \begin{bmatrix} 1 & 4 \\ 2 & 3 \end{bmatrix}$$

$$\text{Solution: } |A - \lambda I| = 0 \text{ implies } \begin{vmatrix} 1 - \lambda & 4 \\ 2 & 3 - \lambda \end{vmatrix} = 0$$

$$\Rightarrow \lambda^2 - 4\lambda - 5 = 0.$$

For CHT, we have to prove $A^2 - 4A - 5I = 0$.

$$\begin{bmatrix} 9 & 16 \\ 8 & 17 \end{bmatrix} - \begin{bmatrix} 4 & 16 \\ 8 & 12 \end{bmatrix} - \begin{bmatrix} 5 & 0 \\ 0 & 5 \end{bmatrix} = \begin{bmatrix} 9 - 4 - 5 & 16 - 16 \\ 8 - 8 & 17 - 12 - 5 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\text{Now } A^5 - 4A^4 - 7A^3 + 11A^2 - A - 10I = (A^3 - 2A + 3I)(A^2 - 4A - 5I) + A + 5I$$

$$\text{By CHY } A^5 - 4A^4 - 7A^3 + 11A^2 - A - 10I = A + 5I$$





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