

Ch 3 - Intensity Transformations

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Overview

- Goal is to modify pixel intensity to improve the visibility of objects of interest in an image
- General form of operation:

```
For (int y = 0; y < Ydim, y++)  
    For (int x = 0; x < Xdim; x++)  
        Output[y][x] = Map( Input[y][x] )
```
- Different Map functions give different effects
- Slope of curve determines enhancement effect

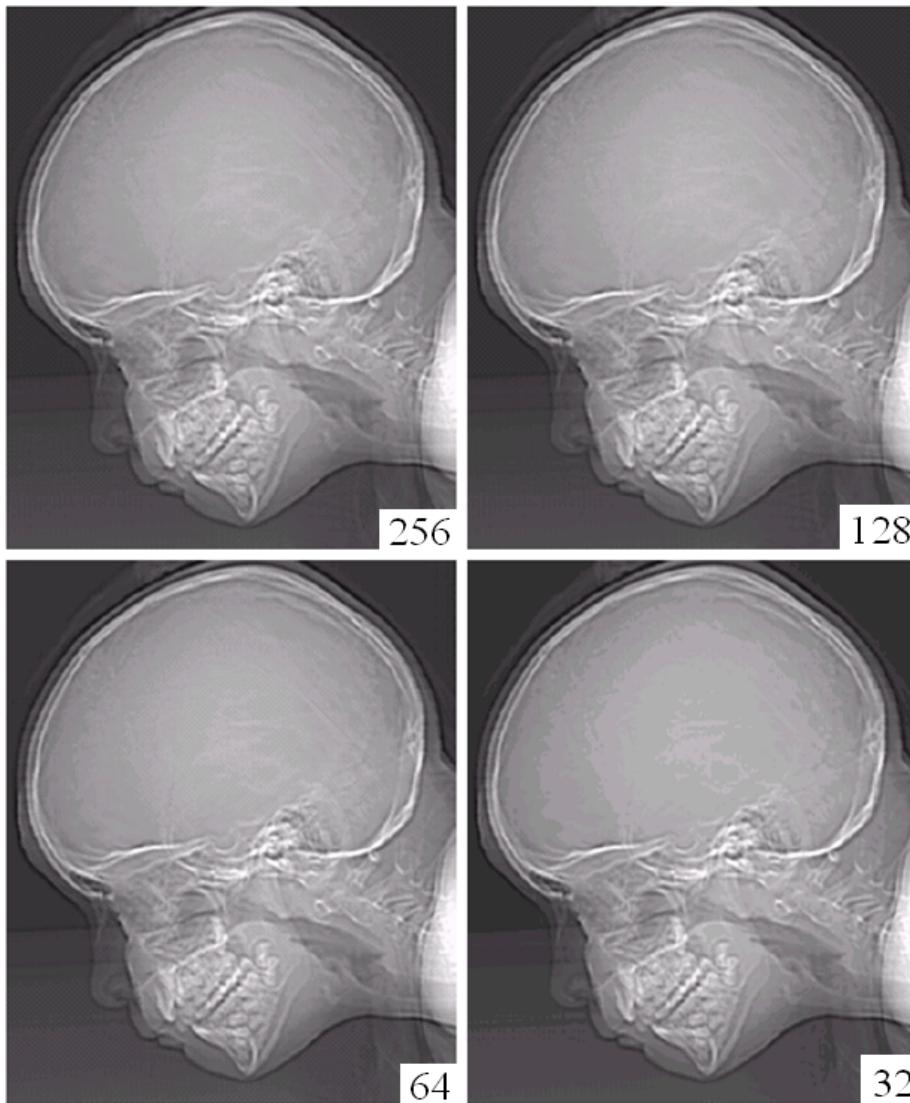
Linear Map

- A linear map function is used to compress or stretch the intensity range of pixels in an image
- Typically used prior to data storage or display
- $\text{Map}(i) = A * i + B$
- Example:
 - Input range = $[I_{\min}..I_{\max}]$
 - Output range = $[O_{\min}..O_{\max}]$
 - $\text{Map}(i) = (O_{\max} - O_{\min}) * (i - I_{\min}) / (I_{\max} - I_{\min}) + O_{\min}$

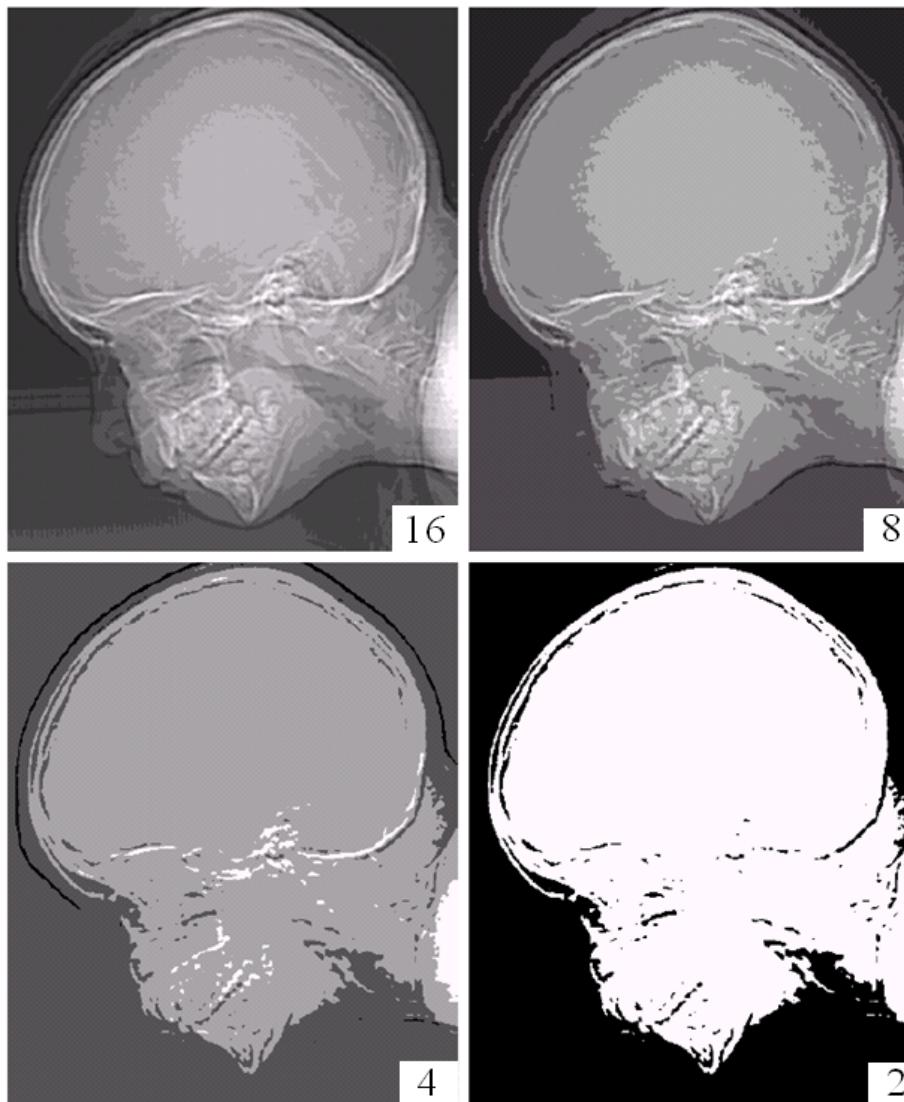
Linear Map

- When the linear map function has $A < 1$ the output range is smaller input range
- When pixels are stored in integers this results in quantization and loss of information
- Example:
 - Input range [0..255]
 - $\text{Map}(i) = i / 2$ yields 128 intensity levels
 - $\text{Map}(i) = i / 4$ yields 64 intensity levels
 - $\text{Map}(i) = i / 8$ yields 32 intensity levels

Linear Map

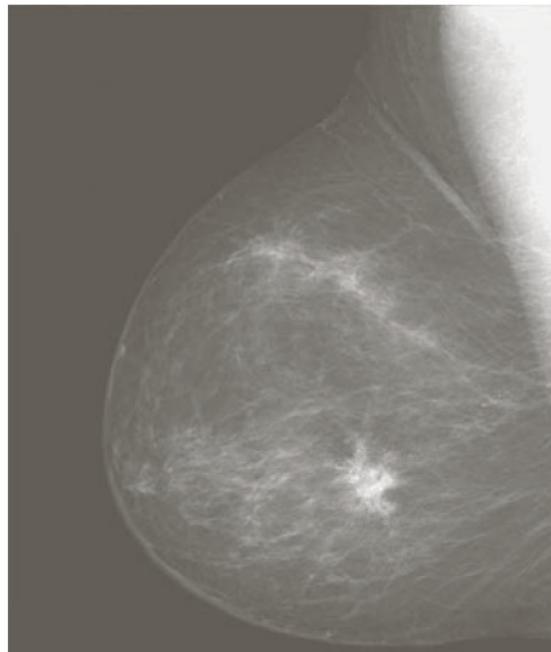


Linear Map



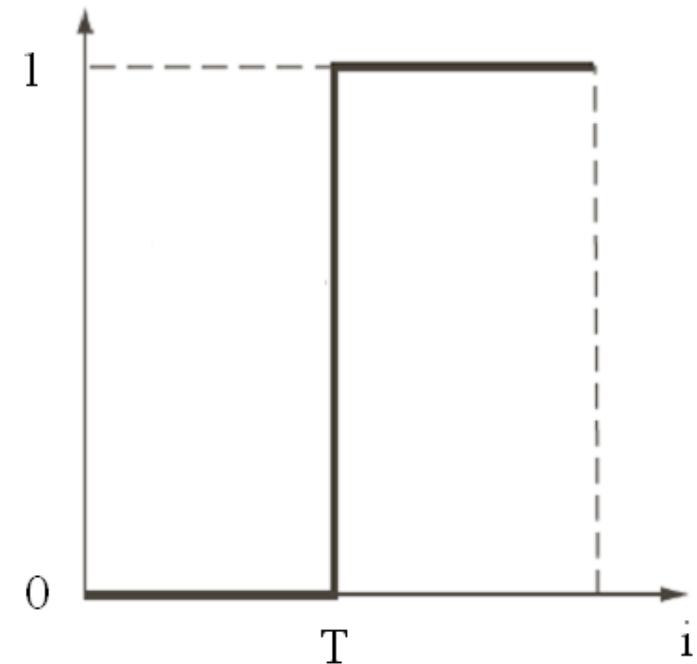
Inverse Map

- An inverse linear map will convert a negative image into a positive image (and vice versa)
- $\text{Map}(i) = 255 - i$



Thresholding

- An intensity transformation which produces a black and white output image
- $\text{Map}(i) = \begin{cases} 0 & \text{if } i < T \\ 1 & \text{if } i \geq T \end{cases}$



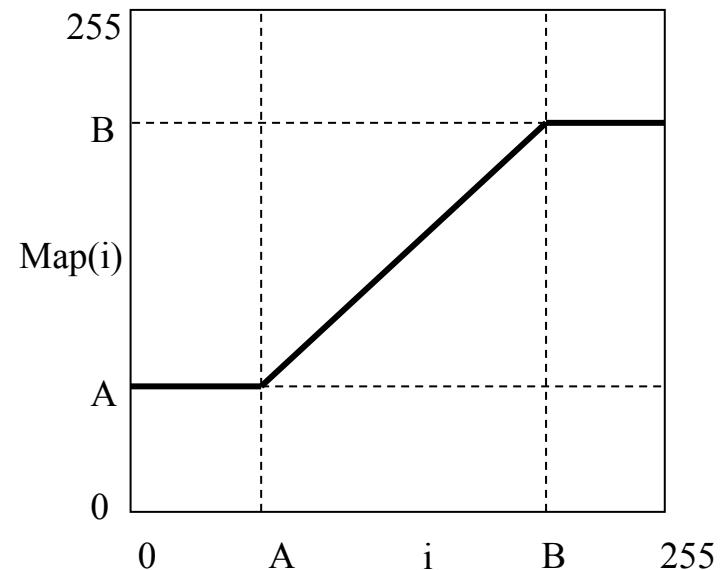
Thresholding

- By selecting the threshold T we can separate objects of interest from the background



Windowing

- When objects of interest have intensity values in the range $[A..B]$ we can exclude all pixels outside this range to enhance object visibility
- $\text{Map}(i) = \begin{cases} A & \text{if } (i < A) \\ B & \text{if } (i > B) \\ i & \text{otherwise} \end{cases}$



Windowing



50..200

Windowing

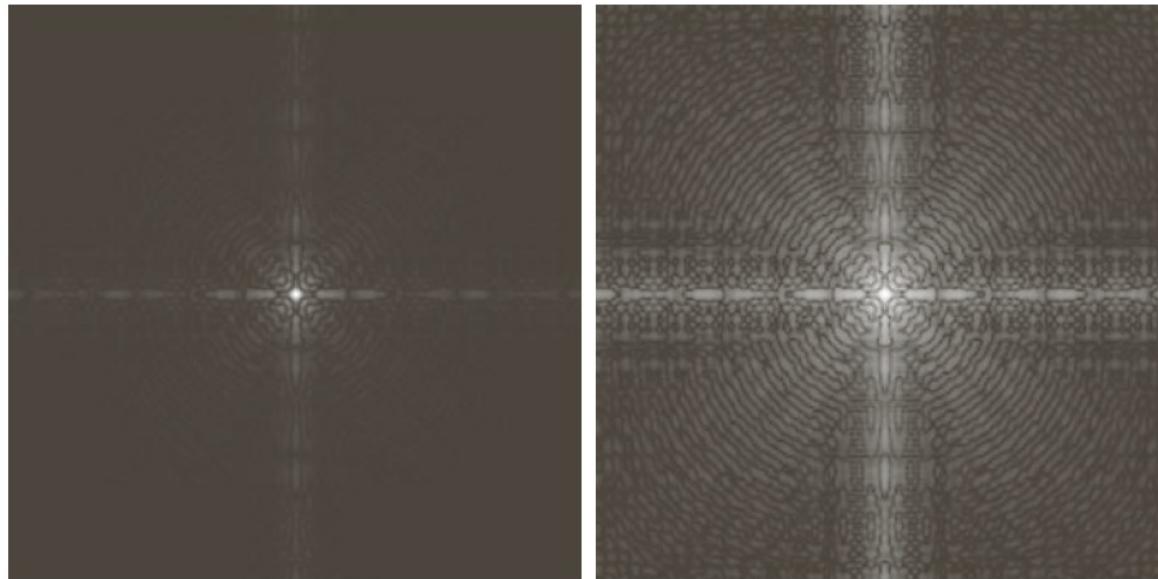


Log Transformation

- The log function can be used to reduce the intensity range in an image
- The inverse log function can be used to expand the intensity range in an image
- $\text{Map}(i) = c * \log(1 + i)$
- Example:
 - Input range [a..b]
 - Output range [0..255]
 - $\text{Map}(i) = 255 * \log(1 + i - a) / \log(1 + b - a)$

Log Transformation

- Log transformations often used to display the Fourier transform of an image

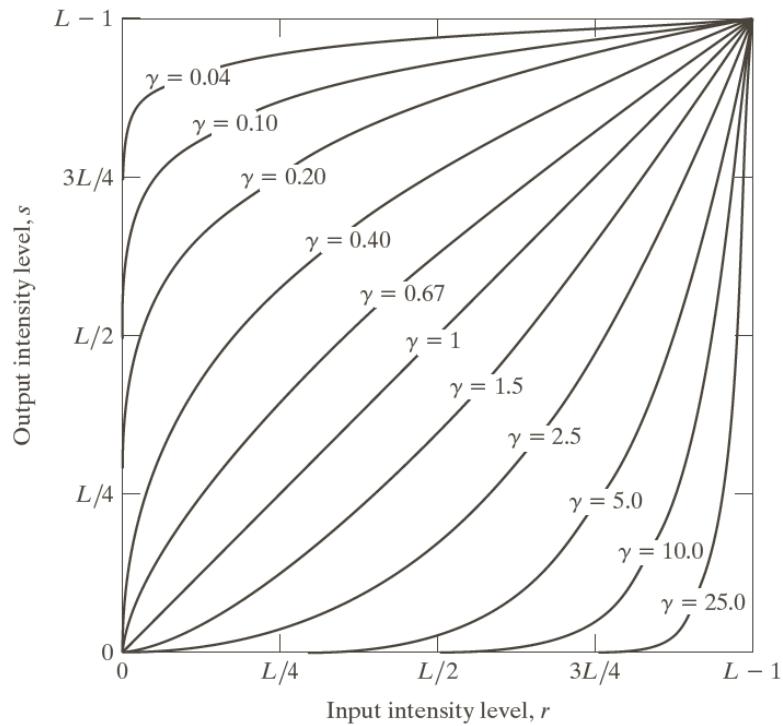


Power Law Transformation

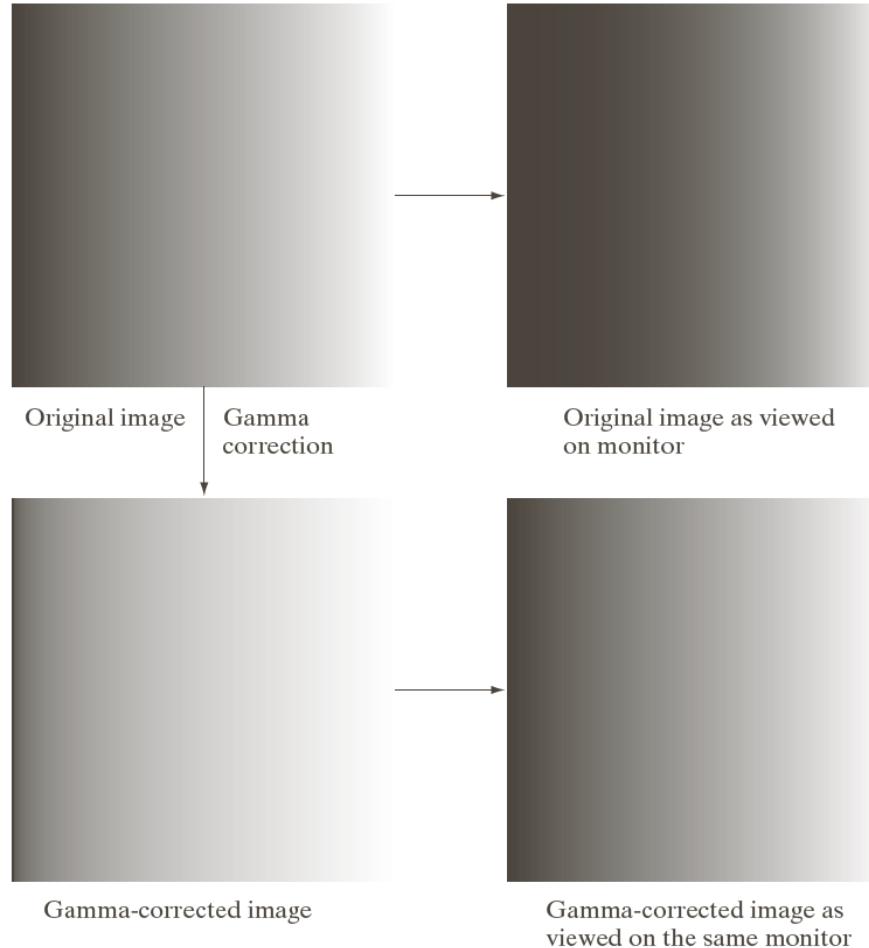
- A power law function (gamma function) stretches and compresses intensities to improve object visibility in an image
- $\text{Map}(i) = c * i^\gamma$
- Example:
 - Input range [a..b]
 - Output range [0..255]
 - $\text{Map}(i) = 255 * (i-a)^\gamma / (b-a)^\gamma$

Power Law Transformation

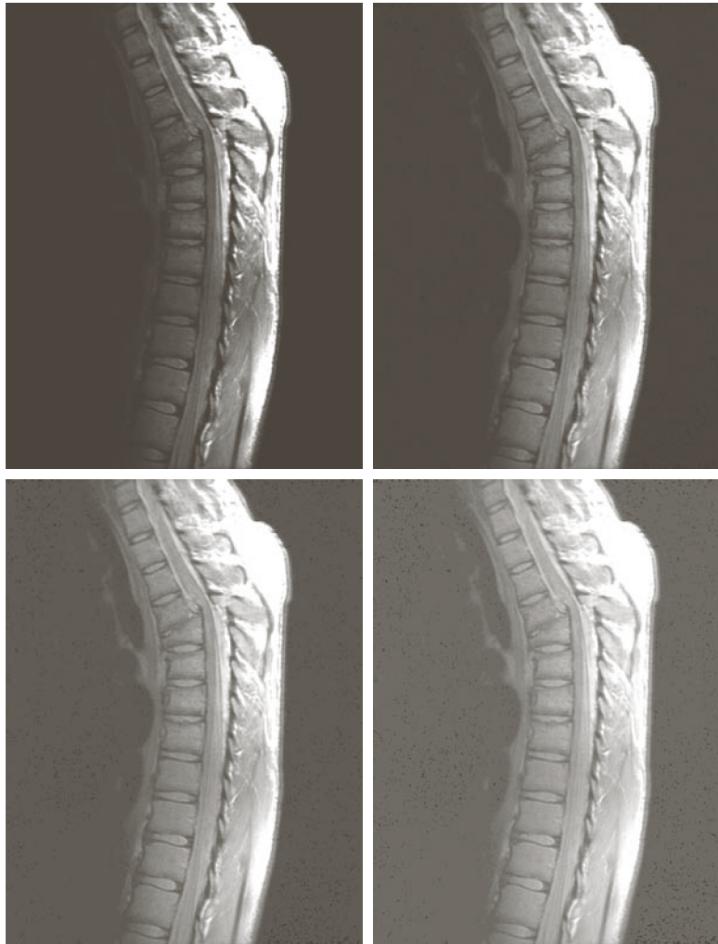
- We get different effects by changing power γ
- Slope > 1 enhanced, slope < 1 de-enhanced



Power Law Transformation



Power Law Transformation



Power Law Transformation

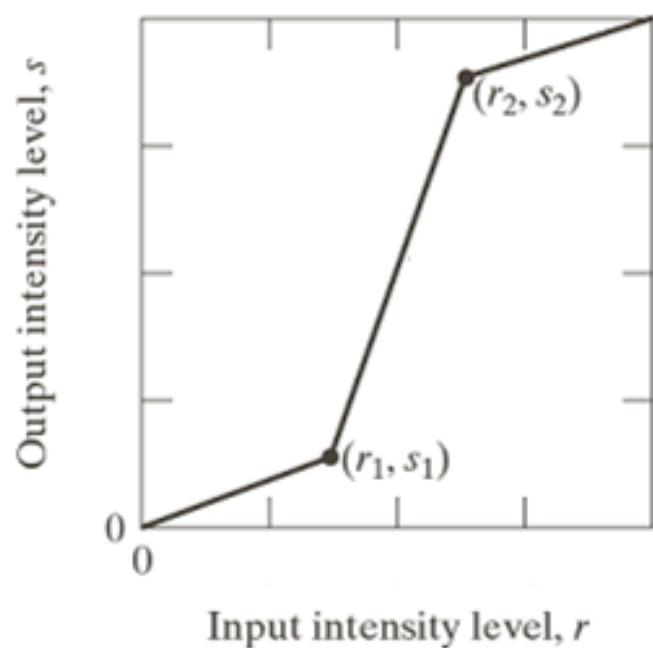


Contrast Stretching

- Sometimes we know the intensity range of objects of interest, and we want to enhance this range without losing all information about intensities outside this range
- Contrast stretching uses a piecewise linear $\text{Map}(i)$ function to accomplish this goal

Contrast Stretching

- User specifies points (r_1, s_1) and (r_2, s_2)
 - Input $[0..r_1]$ is mapped to output $[0..s_1]$
 - Input $[r_1..r_2]$ is mapped to output $[s_1..s_2]$
 - Input $[r_2..255]$ is mapped to output $[s_2..255]$

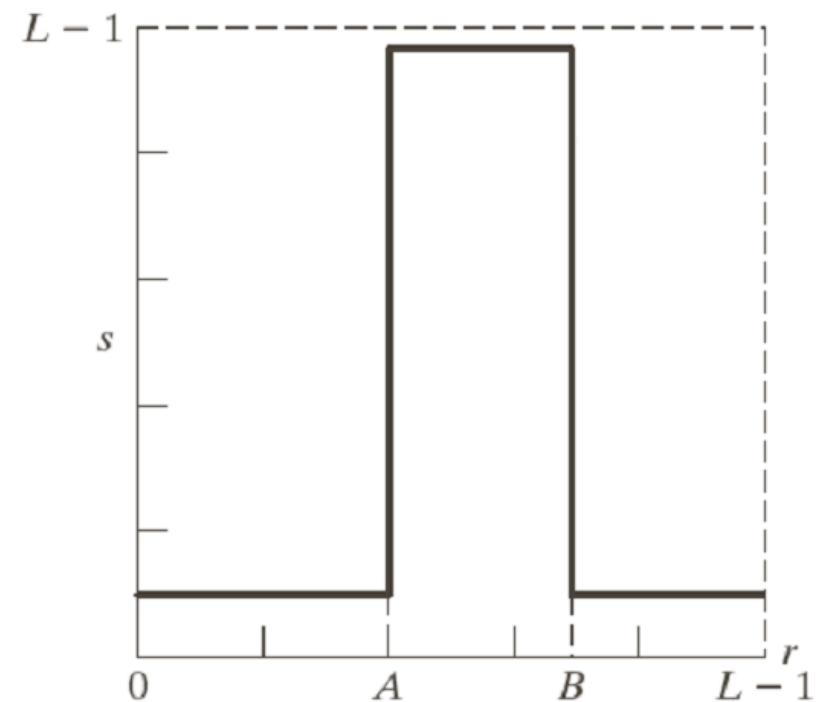


Contrast Stretching



Intensity Slicing

- One way to emphasize pixels with intensity values $[A..B]$ is to make these pixels white, and map intensities outside this range to black
- This is very similar to intensity thresholding

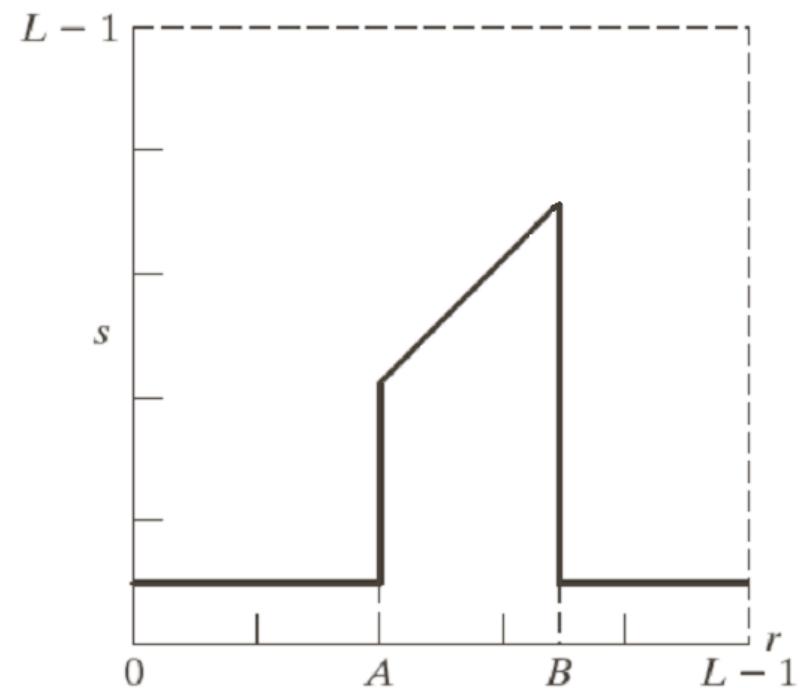


Intensity Slicing



Intensity Slicing

- Another option is to leave intensities $[A..B]$ unchanged and map intensities outside this range to black
- This reduces the amount of ‘background clutter’ in the image

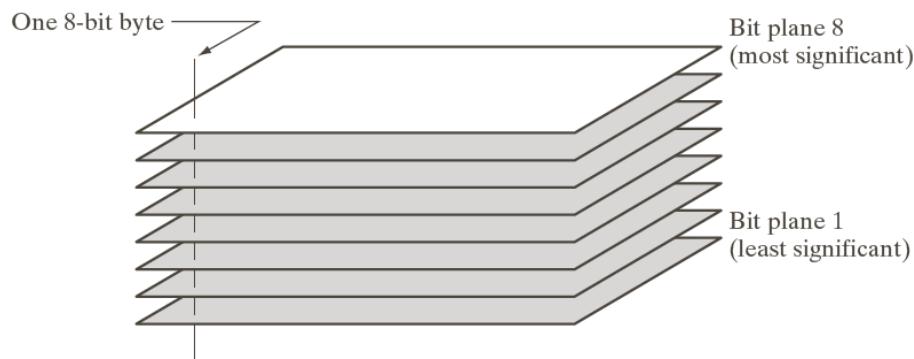


Intensity Slicing

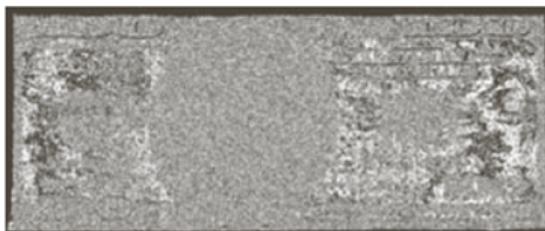
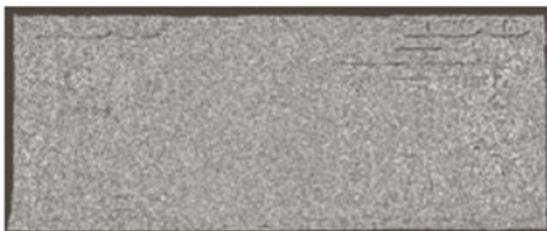
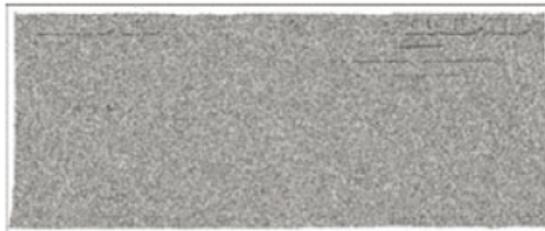
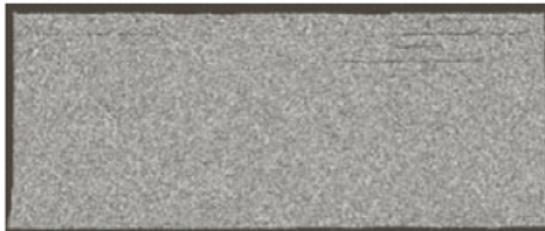


Bit Plane Images

- Some image features can be visualized by looking at the bit plane images
- The most important details should be in the most significant bit plane, the least significant bit plane looks like noise



Bit Plane Images



Bit Plane Images

- Here we have images reconstructed using only the most significant bit planes



bits 7-8



bits 6-8



bits 5-8

Conclusion

- Intensity transformations can produce a wide variety of image enhancement effects
- The key to selecting a technique is understanding how each method modifies the intensity distribution in an image