

# Code Generation (Part -2)

Course : 2CS701/IT794 – Compiler  
Construction

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Ref : Ch.9 Compilers Principles, Techniques, and Tools by Alfred Aho, Ravi Sethi, and Jeffrey Ullman



# Glimpse

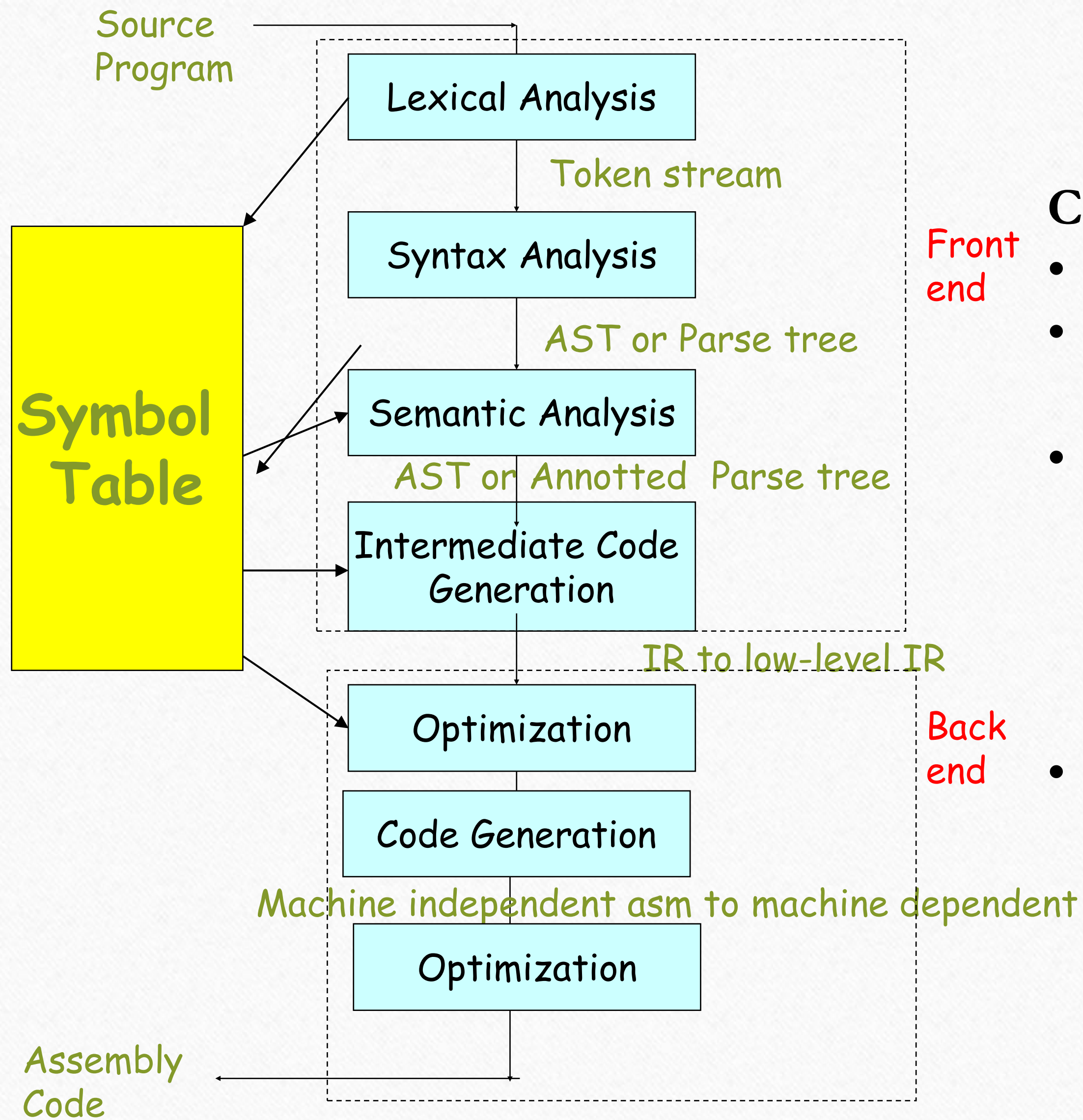
## Part-1

- Introduction
- Code Generation Issues

## Part-2

- **Basic Code Generation Case Study**
- **Introduction to Basic Block, and Control Flow Diagram**





## Code Generation

- Final Phase of Compilation
- Produces a semantically equivalent target program
- Main Functionalities :
  - Instruction selection
  - Register allocation and assignment
  - Instruction ordering
- **Functionalities for QoS**
  - Produce Correct code (semantic preserving)
  - Efficiency
    - Effective use of resources
    - User Heuristics to generate good, but suboptimal code



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

- Expression statement with symbols
- Array reference
- Structure Field reference
- Pointer reference
- If statement
- While statement
- Function call



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### Expression statement

Expression statement :  $(x = x + 3) + 4$

Assembly Code :

```
mov ax, word ptr [bp-2]
add ax, 3
mov word ptr [bp-2], ax
add ax, 4
```

Notes

- The *bp* is used as the frame pointer.
- The **static simulation method** is used to convert the intermediate code into the target code.



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### Array Reference

Array reference Example :

$(a[i + 1] = 2) + a[j]$

Where, i and j are declared as

```
int i, j;
```

```
int a[10];
```

```
( 1 ) mov bx,word ptr [bp-2]
```

```
( 2 ) shl bx , 1
```

```
( 3 ) lea ax, word ptr [bp-22]
```

```
( 4 ) add bx , ax
```

```
( 5 ) mov ax , 2
```

```
( 6 ) mov word ptr [bx],ax
```

```
( 7 ) mov bx,word ptr [bp-4]
```

```
( 8 ) shl bx , 1
```

```
( 9 ) lea dx,word ptr [bp-24]
```

```
( 10 ) add bx , dx
```

```
( 11 ) add ax,word ptr [bx]
```



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### Structure Field Reference

#### Structure Example

```
typedef struct rec
{ int i;
  char c;
  int j;
} Rec;
Rec x;
x.j = x.i;
```



```
mov ax, word ptr [bp-6]
mov word ptr [bp-3],ax
```

#### Note:

Integer variable has size 2 bytes;  
Character variable has size 1 bytes;  
Local variables are allocated **only on even-byte** boundaries;  
The offset computation for **j** ( $-6 + 3 = -3$ ) is performed statically by the **compiler**.



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### Pointer Field Reference

```
typedef struct treeNode
{ int val;
  struct treeNode * lchild,
    * rchild;
} TreeNode;

...
Rec x;
TreeNode *p;
```



The code generated for the statement  
`p->lchild = p;`  
is  
`mov word ptr [si+2], si`

And the statement  
`p = p->rchild;`  
is  
`mov si, word ptr [si+4]`

Note:

Assume pointer has size 2



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### IF Statement

```
if (x>y)
y++;
else x--;
```



```
mov bx, word ptr [bp-2] //x
mov dx, word ptr [bp -4] //y
cmp bx , dx
jle short @1@86
inc dx
jmp short @1@114
@1@86 :
    dec bx
@1@114 :
```



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### While Statement

```
while (x<y)  
y -= x;
```



```
jmp short @1@170  
@1@142 :  
    sub dx , bx  
@1@170 :  
    cmp bx , dx  
    jl short @1@142
```



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### Function Call

- function definition:

```
int f( int x, int y)
{
    return x+y+1 ;
}
```

- And a corresponding call  
`f (2+3, 4)`



```
mov ax,4
push ax
mov ax,5
push ax
call near ptr _f
pop cx
pop cx
```

#### Notes:

- The arguments are pushed on the stack **in reverse order**;
- The caller is responsible for **removing the arguments from the stack after the call**.
- The call instruction on the 80x86 **automatically pushes the return address** onto the stack.



# Case Study of Basic Code Generation

## The Borland 3.0 C Compiler for the 80X86

### Function Definition

```
_f  proc near  
    push bp  
    mov bp , sp  
    mov ax, word ptr [bp+4]  
    add ax, word ptr [bp+6]  
    inc ax  
    jmp short @1@58  
@1@58 :  
    pop bp  
    ret  
_f  endp
```



# Basic Blocks and Flow of Control

- Partition the intermediate code into basic blocks
  - The flow of control can only enter the basic block through the first instruction in the block. That is, there are no jumps into the middle of the block.
  - Control will leave the block without halting or branching, except possibly at the last instruction in the block.
- The basic blocks become the nodes of a flow graph
- Use : Code Optimization, Register Allocation

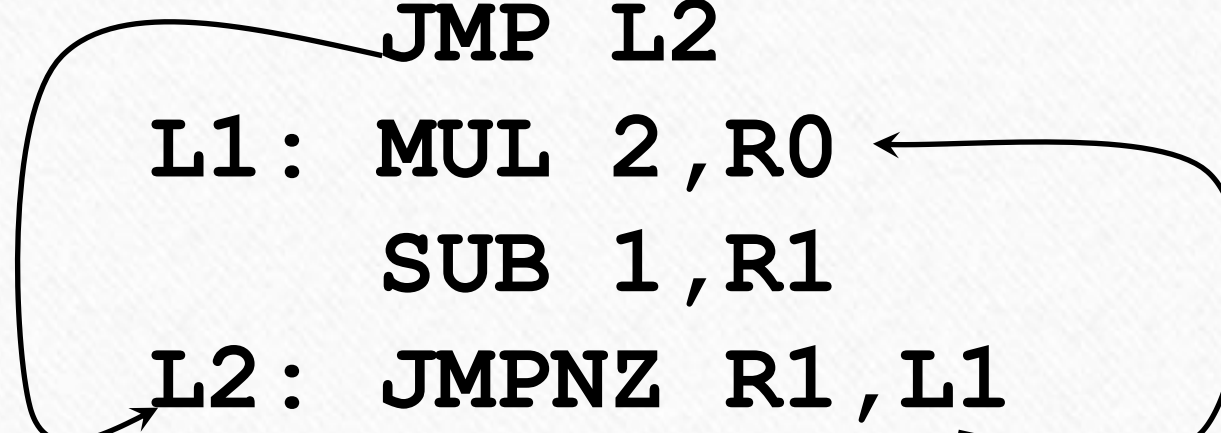


# Flow Graphs

- A *flow graph* is a graphical depiction of a sequence of instructions with control flow edges
- A flow graph can be defined at the intermediate code level or target code level

```
      MOV 1,R0
      MOV n,R1
      JMP L2
L1:   MUL 2,R0
      SUB 1,R1
L2:   JMPNZ R1,L1
```

```
      MOV 0,R0
      MOV n,R1
      JMP L2
L1:   MUL 2,R0
      SUB 1,R1
L2:   JMPNZ R1,L1
```

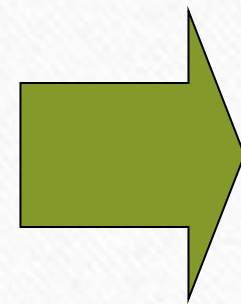




# Basic Blocks

- A *basic block* is a sequence of consecutive instructions with exactly one entry point and one exit point (with natural flow or a branch instruction)

```
MOV 1,R0
MOV n,R1
JMP L2
L1: MUL 2,R0
    SUB 1,R1
L2: JMPNZ R1,L1
```



```
MOV 1,R0
MOV n,R1
JMP L2
```

```
L1: MUL 2,R0
    SUB 1,R1
```

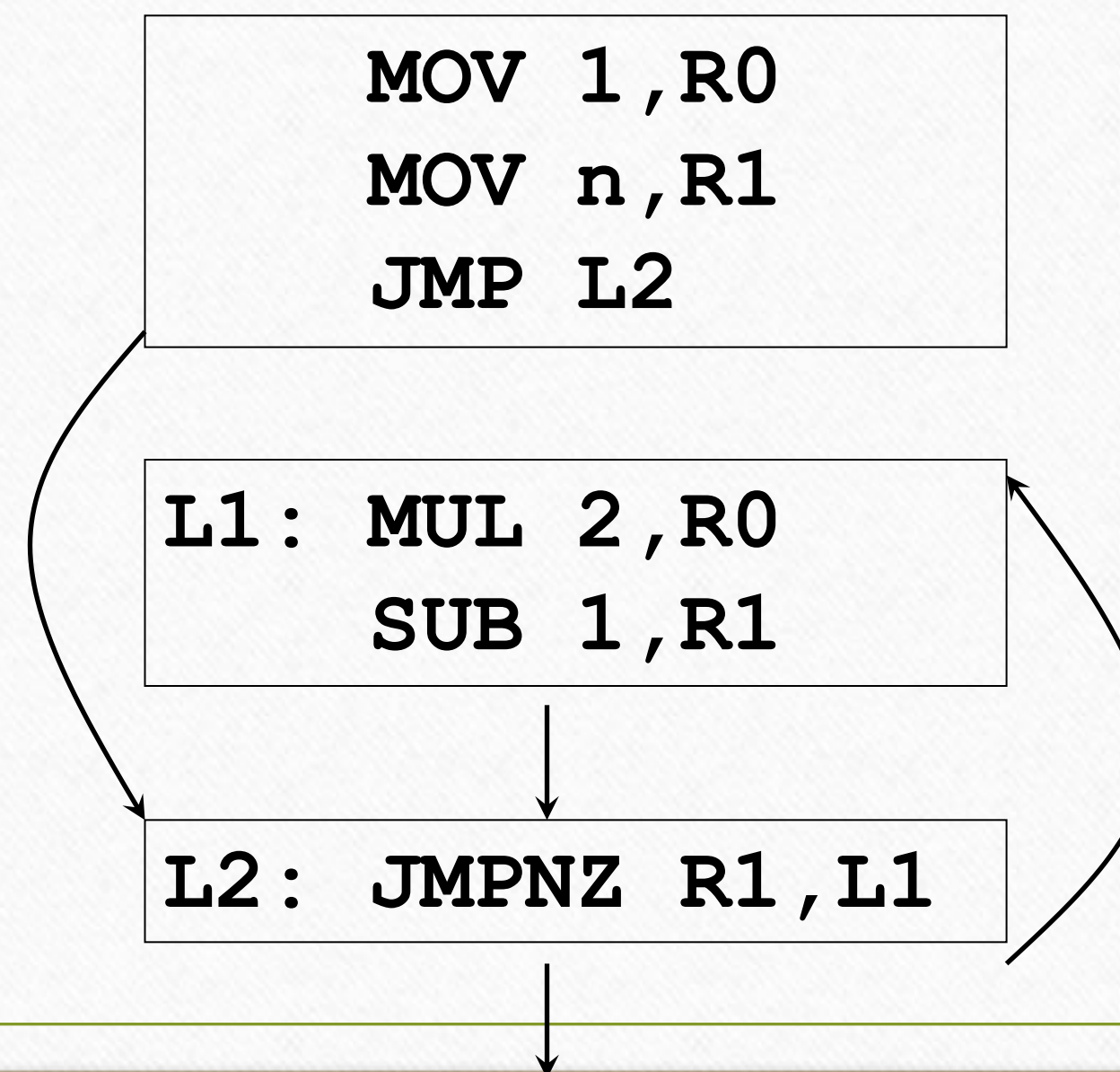
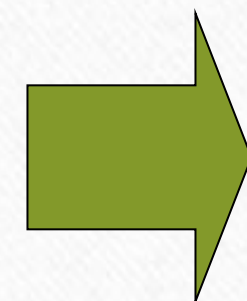
```
L2: JMPNZ R1,L1
```



# Basic Blocks and Control Flow Graphs

- A *control flow graph* (CFG) is a directed graph with basic blocks  $B_i$  as vertices and with edges  $B_i \rightarrow B_j$  iff  $B_j$  can be executed immediately after  $B_i$

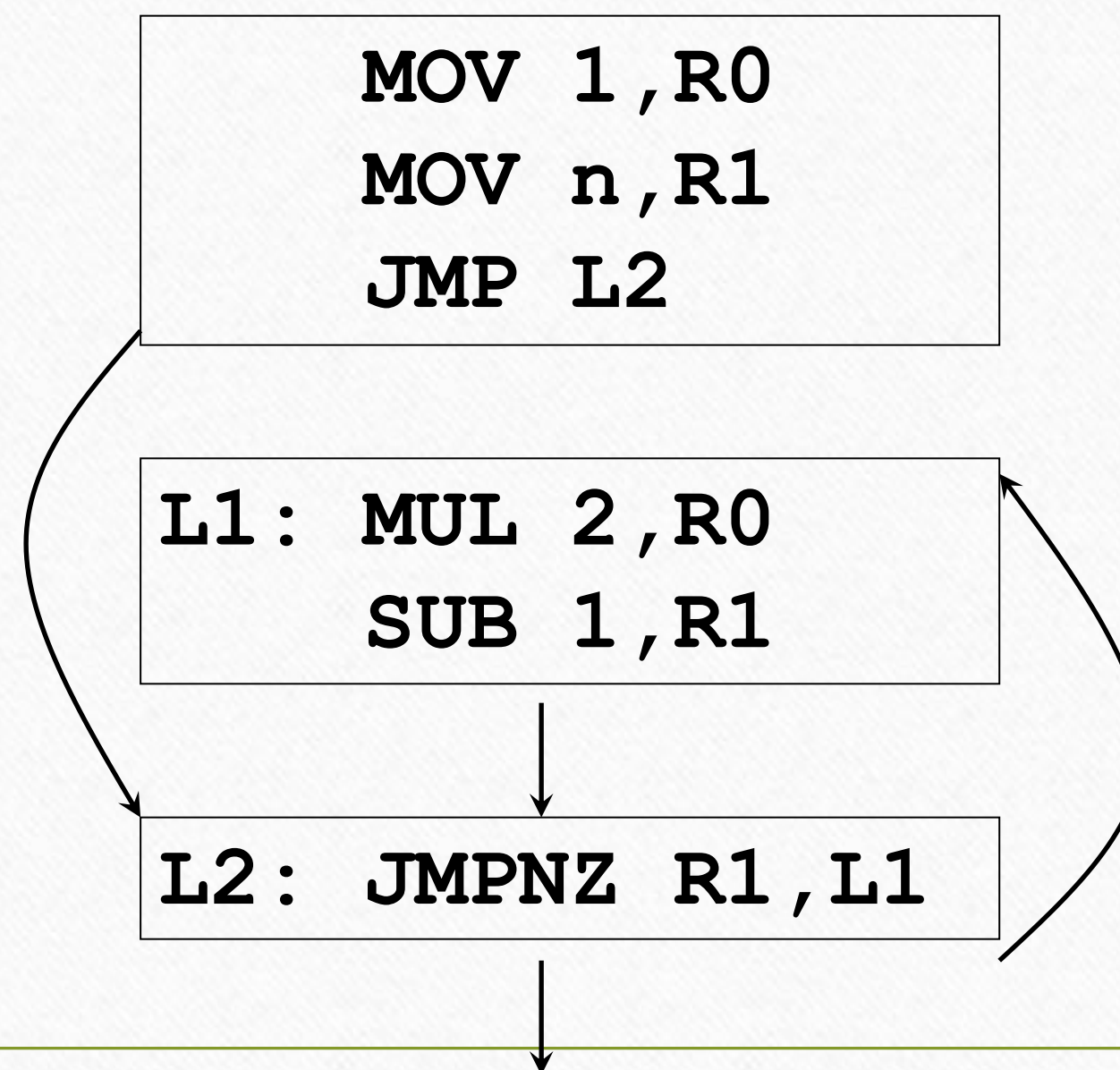
```
MOV 1, R0
MOV n, R1
JMP L2
L1: MUL 2, R0
    SUB 1, R1
L2: JMPNZ R1, L1
```





# Successor and Predecessor Blocks

- Suppose the CFG has an edge  $B_1 \rightarrow B_2$ 
  - Basic block  $B_1$  is a *predecessor* of  $B_2$
  - Basic block  $B_2$  is a *successor* of  $B_1$





# Partition Algorithm for Basic Blocks

*Input:* A sequence of three-address statements

*Output:* A list of basic blocks with each three-address statement in exactly one block

1. Determine the set of *leaders*, the first statements of basic blocks
  - a) The first statement is the leader
  - b) Any statement that is the target of a goto is a leader
  - c) Any statement that immediately follows a goto is a leader
2. For each leader, its basic block consists of the leader and all statements up to but not including the next leader or the end of the program

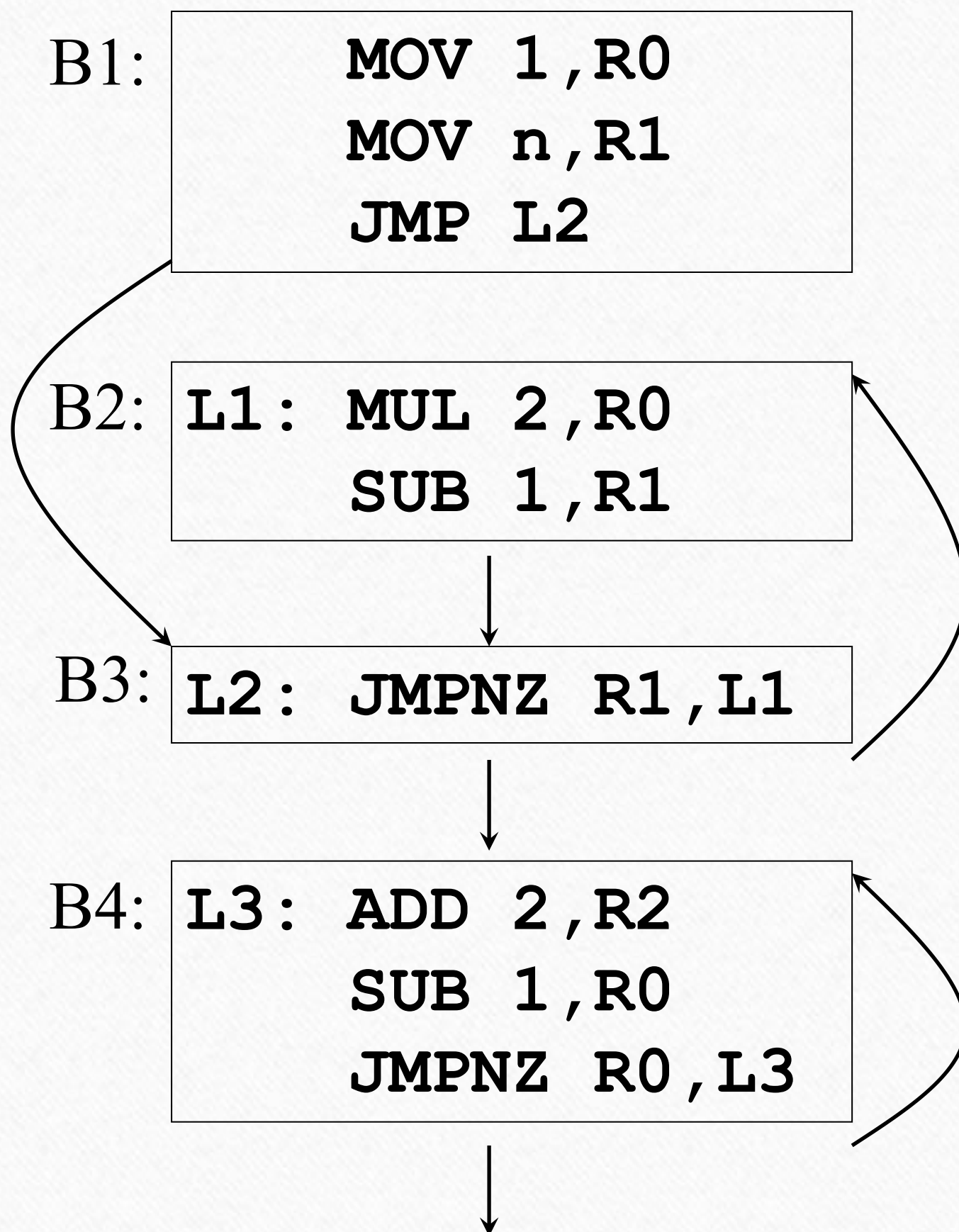


# Loops

- A *loop* is a collection of basic blocks, such that
  - All blocks in the collection are *strongly connected*
  - The collection has a unique *entry*, and the only way to reach a block in the loop is through the entry



# Loops (Example)



Strongly connected components:

$SCC = \{ \{B2, B3\}, \{B4\} \}$

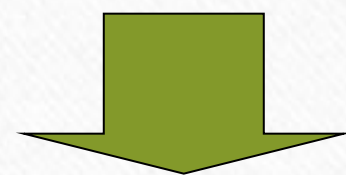
Entries:  
B3, B4



# Equivalence of Basic Blocks

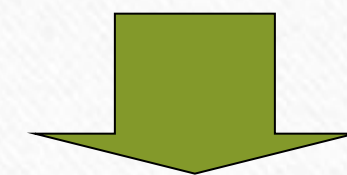
- Two basic blocks are (semantically) *equivalent* if they compute the same set of expressions

```
b := 0
t1 := a + b
t2 := c * t1
a := t2
```



```
a := c*a
b := 0
```

```
a := c * a
b := 0
```



```
a := c*a
b := 0
```

Blocks are equivalent, assuming **t1** and **t2** are *dead*: no longer used (no longer *live*)



# Transformations on Basic Blocks

- A *code-improving transformation* is a code optimization to improve speed or reduce code size
- *Global transformations* are performed across basic blocks
- *Local transformations* are only performed on single basic blocks
- Transformations must be safe and preserve the meaning of the code
  - A local transformation is safe if the transformed basic block is guaranteed to be equivalent to its original form