## Artificial Intelligence -Assignment 2 REPORT

jump\_1.cpp implements A\* Algorithm , jump\_2.cpp implements IDA\* Algorithm

**State Representation**: A matrix (NxN) with the same format as the input file: one entry for every space on the board, with zeros for empty spaces and a different number for each color.

**Heuristic** (h) used for Search (both A\* and **IDA**\*):

- Given a state,  $\mathbf{h}(state) = (\#distinct\ colours\ in\ the\ grid\ corresponding\ to\ state) 1$
- It is obvious that at-least  $\mathbf{h}$ (state) number of moves are required to finally leave 1 color on the grid. Hence an underestimate of the actual  $\mathbf{h}$ \*(state)

Memory bounded  $A^*$  algorithm used: Iterative Deepening  $A^*$  (IDA\*)

**IDA\_star** function iteratively calls the search function with increasing *bound* values until a goal state is found, or no such state can be found.

**Search** function implements a depth-first search algorithm until the **f** value of a node/state does not exceed the value of *bound*, in which case the function stops expanding that node and returns back to the remaining nodes ( if any, else it exits like DFS )

```
node
                  current node
                  the cost to reach current node
g
                 estimated cost of the cheapest path (root..node..goal)
h(node)
                 estimated cost of the cheapest path (node..goal)
cost(node, succ) path cost function
is_goal(node)
                 goal test
successors(node) node expanding function
procedure ida_star(root)
  bound := h(root)
    t := search(root, 0, bound)
    if t = FOUND then return FOUND
    if t = \infty then return NOT_FOUND
    bound := t
  end loop
end procedure
function search(node, g, bound)
  f := g + h(node)
  if f > bound then return f
  if is_goal(node) then return FOUND
  min := ∞
  for succ in successors(node) do
    t := search(succ, g + cost(node, succ), bound)
    if t = FOUND then return FOUND
    if t < min then min := t</pre>
  end for
  return min
end function
```

## Results

Input	A* algorithm	IDA* algorithm
	#nodes expanded	
4 3 1221 2132 3132 0230	Nodes expanded 468 (1,4)>(4,4) (1,1)>(1,4) (4,2)>(1,2) (2,1)>(4,1) (4,4)>(4,2) (4,1)>(4,3) (4,3)>(1,3) (1,4)>(1,1)	Nodes expanded 12211 (2,1)>(4,1) (1,4)>(4,4) (1,1)>(1,4) (4,2)>(1,2) (4,4)>(4,2) (4,1)>(4,3) (4,3)>(1,3) (1,4)>(1,1)
4 3 3321 3132 3202 1031	Nodes expanded 864 (4,4)>(4,2) (1,3)>(3,3) (2,1)>(2,3) (1,4)>(4,4) (4,1)>(2,1) (1,1)>(3,1) (3,1)>(3,4) (4,4)>(2,4) (2,4)>(2,2) (1,2)>(3,2) (4,2)>(2,2)	Nodes expanded 65476  (1,3)>(3,3) (2,1)>(2,3) (4,1)>(2,1) (1,1)>(3,1) (4,4)>(4,2) (1,4)>(4,4) (3,1)>(3,4) (4,4)>(2,4) (2,4)>(2,2) (1,2)>(3,2) (4,2)>(2,2)