

**Dhruv Sandesara- djs3967**

3/10/17

## **Homework 6. Loops and Arrays in C**

Due: **Wednesday 3/8 / Thursday 3/9** in Class **Problem6.2**: Write a function (most\_freq), that takes an array of numbers and finds out the

most frequently occurring value in the array.

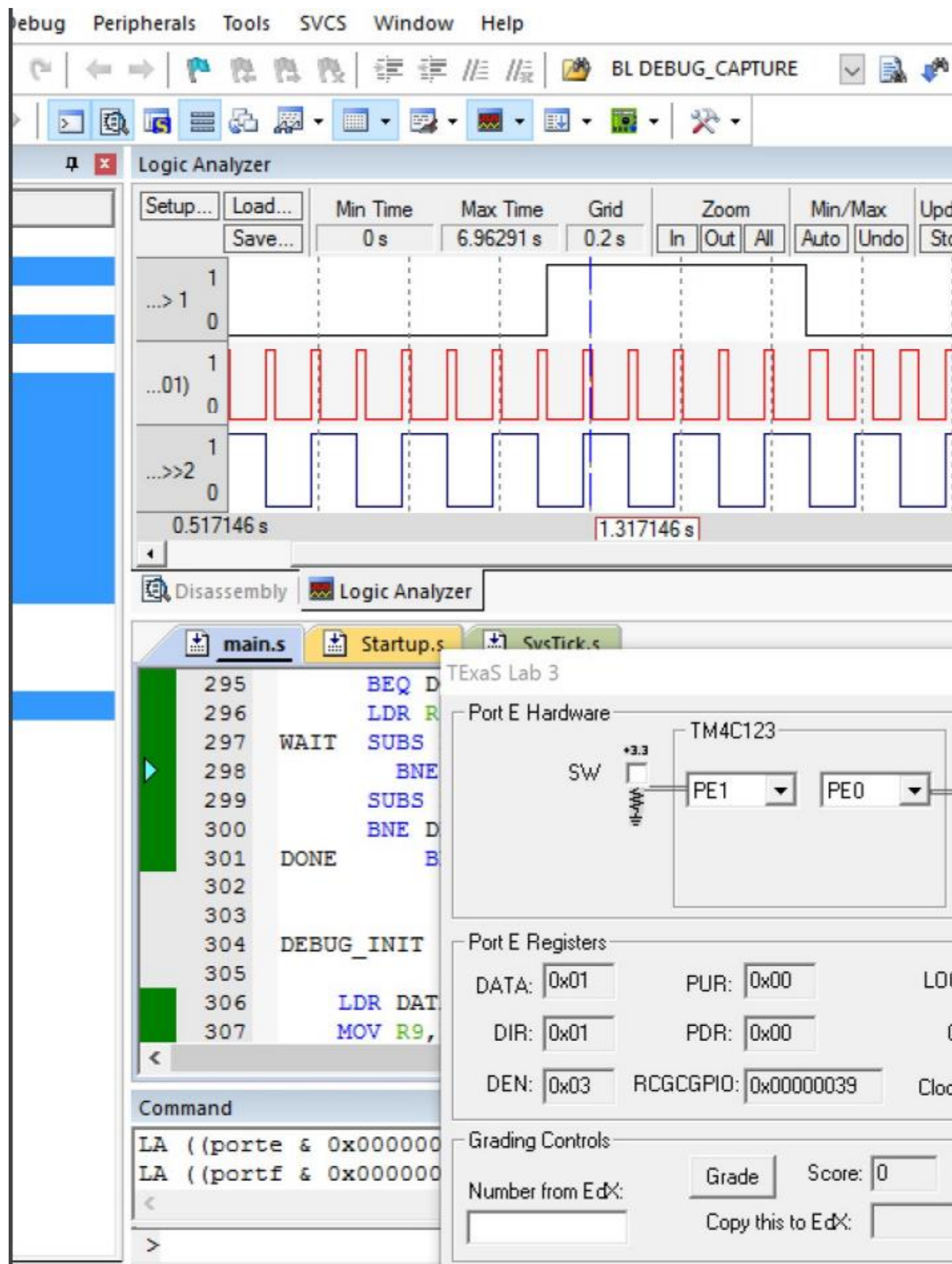
```
int most_freq (int* input, int size);
void main() { int array[10] = {1,2,2,3,3,3,7,8,9,3}; int
freq = most_freq(array, 10);

print(freq); // assume this prints to an LED screen or an
output port }

int most_freq (int* input, int size)
{
int count=1, tempCount;
int popular = input[0];
int temp = 0;
for (int i=0; i<size; i++)
{
if(temp== input[j])
{tempCount++;
}

if(tempCount > count)
{
popular= temp;
count=tempCount;
}
}
return popular;
} }
```

---



Copy this

```
/* main.c for Homework 6  
Dhruv Sandesara djs3967
```

```
;  
;  
;  
;  
;  
;  
;  
;  
;  
;  
;  
;  
;  
;  
;  
;
```

```
; 32-bit entry in the Time Buffer
```

Brief description of the program The LED toggles at 8 Hz and a varying duty-cycle Repeat the functionality from Lab2-3 but now we want you to insert debugging instruments which gather data (state and timing) to verify that the system is functioning as expected.

Hardware connections (External: One button and one LED) PE1 is Button input (1 means pressed, 0 means not pressed) PE0 is LED output (1 activates external LED on protoboard) PF2 is Blue LED on Launchpad used as a heartbeat

Instrumentation data to be gathered is as follows: After Button(PE1) press collect one state and time entry. After Button(PE1) release, collect 7 state and time entries on each change in state of the LED(PE0): An entry is one 8-bit entry in the Data Buffer and one

The Data Buffer entry (byte) content has: Lower nibble is state of LED (PE0) Higher nibble is state

of Button (PE1)

```
;
;
;
; The Time Buffer entry (32-bit) has:
; ; ; ; ; ; */
```

24-bit value of the SysTick's Current register (NVIC\_ST\_CURRENT\_R) Note: The size of both buffers is 50 entries. Once you fill these

entries you should stop collecting data The heartbeat is an indicator of the running of the program. On each iteration of the main loop of your program toggle the LED to indicate that your code(system) is live (not stuck or dead).

```
// ***** 1. Pre-processor Directives Section *****
#include <stdint.h> #include "tm4c123gh6pm.h"

// ***** 2. Global Declarations Section *****

// FUNCTION PROTOTYPES: Each subroutine defined void
DisableInterrupts(void); // Disable interrupts void
EnableInterrupts(void); // Enable interrupts void
TEaS_Init(void); // ***** 3. Subroutines Section
***** void Ports_Init(void) {

volatile unsigned long delay; SYSCTL_RCGC2_R =
0x30; delay = SYSCTL_RCGC2_R;

//Init PortE GPIO_PORTE_DIR_R &= 0xFD;
GPIO_PORTE_DIR_R |=0x1; GPIO_PORTE_AFSEL_R &= 0xFC;
GPIO_PORTE_DEN_R |= 0x3;

//Init PortF GPIO_PORTF_DIR_R &= 0xFD;
GPIO_PORTF_DIR_R |=0x4; GPIO_PORTF_AFSEL_R &= 0xFB;
GPIO_PORTF_DEN_R |= 0x4; GPIO_PORTF_PUR_R &= 0xFB;
```

```

}

// Initialize SysTick with busy wait running at bus
clock. void SysTick_Init(void)

{
    NVIC_ST_CTRL_R = 0;
    NVIC_ST_RELOAD_R = 0x00FFFFFF; NVIC_ST_CURRENT_R = 0;
    NVIC_ST_CTRL_R = 0x00000005;

}
uint32_t Delaytime = 116548;
// Delay for the count units (ms)
void Delay(uint8_t count)
{
    uint8_t i;
    for(i = count; i > 0; i--)
    {
        Delaytime = 116548;
        while (Delaytime > 0)
        {
            Delaytime--;
        }
    }
}

// -UUU- Declare your debug dump arrays and indexes
into the // arrays here uint8_t
DataBuffer[50]; uint32_t TimeBuffer[50];

void DebugInit(void)
{ uint32_t p;

for (p = 0; p < 50; p++)

{ TimeBuffer[p] = 0xFFFFFFFF;

    DataBuffer[p] = 0xFF;

}
}

```

```

void ToggleLEDOOn(void)
{
    GPIO_PORTF_DATA_R |= 0x4;
    GPIO_PORTE_DATA_R |= 0x1;
}
void ToggleLEDOff(void)
{ GPIO_PORTF_DATA_R &= ~(0x4);

GPIO_PORTE_DATA_R &= ~(0x1); }

uint32_t intree = 0;
void Debug_Capture(void)
{
    if(intree == 50)
{ return;

} else {

DataBuffer[intree] = ((GPIO_PORTE_DATA_R & 0x1)) |
((GPIO_PORTE_DATA_R & 0x2)<<3);

intree++; }

}

uint8_t onTrack = 1;
uint8_t Pushtrack = 0;
uint8_t offTrack = 4;
uint8_t onCapture = 0;
uint8_t offCapture = 0;
uint8_t onAllow = 1;
int main(void)
{ TExaS_Init(); Ports_Init(); // initialize ports
SysTick_Init(); // initialize SysTick
EnableInterrupts(); //Enable interrupts

    DebugInit();
while(1)

{ if ((GPIO_PORTE_DATA_R & 0x2)==2)

```

```

        {
            Pushtrack = 1;
            if (onAllow == 1)
            {
                onCapture = 1;
                onAllow--;
            }
        }

        else if(Pushtrack == 1)
        { onAllow++;

            onTrack++;
            offTrack--;
            offCapture = 7;
            Pushtrack = 0;
            if (onTrack == 6)
TimeBuffer[intree] = NVIC_ST_CURRENT_R;
        }

        { onTrack = 0;

            offTrack = 5;
        }

        if(onTrack > 0)
        {
            ToggleLEDon();
        }
        if(onCapture == 1)
        {
            onCapture = 0;
            Debug_Capture();
        }
        if (offCapture > 0)
        {
            Debug_Capture();
            offCapture--;
        }
        Delay(onTrack);

```



```
    if (offTrack > 0)
    {
        ToggleLEDOff();
    }
    if (offCapture > 0)
    {
        Debug_Capture();
        offCapture--;
    }

    Delay(offTrack);
}
```