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# Homework #11

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Due: (in class quiz)

## Problem 1: Negative Capacities and Minimum Cuts

In a standard minimum s-t cut problem, we assume that all capacities are nonnegative; allowing an arbitrary set of positive and negative capacities results in a problem that is computationally much more difficult. However, as we'll see here, it is possible to relax the non negativity requirement a little and still have a problem that can be solved in polynomial time.

Let G = (V, E) be a directed graph, with source  $s \in V$ , sink  $t \in V$ , and edge capacities  $\{c_e\}$ . Suppose that for every edge e that has neither s nor t as an endpoint, we have  $c_e \geq 0$ . Thus  $c_e$  can be negative for edges e that have at least one end equal to either s or t. Give a polynomial time algorithm to find an s-t cut of minimum value in such a graph. (Despite the new non negativity requirements, we still define the value of an s-t cut (A, B) to be the sum of the capacities of all edges e for which the tail of e is in A and the head of e is in B.)

#### Solution

We transform an instance with this kind of negativity to an equivalent one where all capacities are non-negative. Consider any node v and suppose there are edges (s, v), (v, t). In fact, if one of these edges does not exist, we can simply add it with capacity 0; this makes for an equivalent problem. (One could do without this, but it makes the following description easier.)

If both capacities on these edges are non-negative, we leave them as is. Otherwise, we add  $d_v = \max(|c_{sv}|, |c_{vt}|)$  to both capacities. Now all capacities are non-negative, and we compute a minimum cut (A, B) as usual (e.g., by computing the max flow using the Ford-Fulkerson algorithm and then putting all of the nodes reachable from s in A). We claim that (A, B) is a minimum cut in the original network as well. Consider the difference between the capacity of (A, B) in the original network (which we'll denote as  $\operatorname{cap}(A, B)$ ) and the capacity in the new network (which we'll denote as  $\operatorname{cap}'(A, B)$ ). For each node v for which the capacities of incident edges were modified, the capacity of the cut (A, B) has been changed by exactly  $d_v$ , regardless of which side of the cut v is on. Thus, letting  $D = \sum_v d_v$ , we have  $\operatorname{cap}'(A, B) = \operatorname{cap}(A, B) + D$ . Since D is independent of the choice of (A, B), then finding a cut minimizing  $\operatorname{cap}(A, B)$  is the same as finding one minimizing  $\operatorname{cap}'(A, B)$ .

#### Problem 2: Flow Networks

An ad hoc sensor network network is made up of low-cost, low-power devices that are distributed in some physical space. One example of these networks in the literature involves tossing a bunch of these sensors out of an airplane over a forest. The sensors are then randomly distributed and expected to monitor for conditions that are indicative of a forest fire.

The sensor nodes, however, are prone to failure for a variety of reasons. A given sensor s can detect that it is about to fail (in practice, this may not be possible, but let's assume it's true). When s determines it is failing, it needs to send a representation of its current state to some other nearby sensor that can take over for it. Each device has a limited transmission range, d; i.e., a node can communicate with exactly the set of nodes within d meters. (Notice that this relationship is symmetric: if sensor  $s_1$  can communicate with  $s_2$ , the reverse is also true.) Because some set of the sensor's neighbors may have already failed, we actually want to make sure that we send the backup copy to some live node; therefore when a sensor s is failing, it should send its state to s other sensors. These s sensors constitute the s sensor s

You're given a set of n sensors with known positions represented by an (x, y) coordinate for each sensor. You must design an algorithm that determines whether it is possible to choose a back up set for each of the n devices (i.e., for each device, find k other sensors with d meters), with the added constraint that a single sensor can serve as a back up for at most b other sensors. You must also output the back up sets for each sensor, given that a solution exists.

To be completely clear, ensure you complete the following steps:

- Formulate the problem as a network flow problem. This means define the vertices, edges, and capacities of the network flow graph and relate your rationale for the structure of the network flow graph to the original problem.
- Be sure to represent k and b in your network flow graph.
- Given a max-flow or a min-cut on your network flow graph, describe how you can determine whether it is possible to choose a back up set for each sensor.
- Given a max-flow or a min-cut on your network flow graph, describe how to state the back up sets, given that a feasible solution exists.

#### Solution

For the flow network G, there is a single source vertex s and a single sink vertex t. For each device i, we have two nodes  $u_i$  and  $v_i$ . There is an edge  $(s, u_i)$  from the source to every u vertex with capacity k and an edge  $(v_i, t)$  from every v vertex to the sink with capacity b. If devices i and j ( $i \neq j$ ) are within d meters of each other, we have two edges  $(u_i, v_j)$  and  $(u_j, v_i)$ , all of capacity 1. These edges connecting a vertex to s signify the backup requirement of each node, and the edges connecting a vertex to t significy the backup capability of each node. The pair of edges connecting the u and v vertices for i and j represent each's ability to back up the other. That is, for each sensor i, it has two roles: a sensor that needs back up support (signified by  $u_i$ ) and a sensor that can provide back up support (signified by  $v_i$ ). The capacity of  $(v_i, t)$  gives the maximum ability of sensor i to provide back up support.

We compute the max flow f of G. If all of the edges leaving the source are saturated (i.e., they all have k capacity), then it is possible to make the back up system. In such a max flow, if  $f_{u_i,v_j} = 1$  then device j is one of the backup sensors for device i.

## Problem 3: Zero-Weight Cycle

You are give a directed graph G = (V, E) with weights  $w_e$  on its edges  $e \in E$ . The weights can be negative or positive. The Zero-Weight Cycle Problem is to decide if there is a simple cycle in G so that that sum of the edge weights on this cycle is exactly 0. Prove that Zero-Weight Cycle is NP-Complete by reducing from the subset sum problem.

The Subset Sum Problem. Given natural numbers  $w_1, w_2, ..., w_n$  and a target number W, is there a subset of  $\{w_1, w_2, ..., w_n\}$  that adds up to precisely W?

#### Solution

Zero-Weight-Cycle is in NP because we can exhibit a cycle in G and it can be checked that the sum of the edge weights on this cycle are equal to 0.

We now show that  $Subset-Sum \leq_p Zero-Weight-Cycle$ . We are given numbers  $w_1, \ldots, w_n$  and we want to know if there is a subset that adds up to exactly W. We construct an instance of Zero-Weight-Cycle in which the graph has nodes  $0,1,2,\ldots,n$  and an edge (i,j) for all pairs i < j. The weight of an edge (i,j) is equal to  $w_j$ . Finally, there is an edge (n,0) of weight -W.

We claim that there is a subset that adds up to exactly W if and only iff G has a zero-weight-cycle. If there is such a subset S, then we define a cycle that starts at 0, goes through the nodes whose indices are in S, and then returns to ) on the edge (n,0). The weight of -W on the edge (n,0) precisely cancels the sum of the other edge weights. Conversely, all cycles in G must use the edge (n,0), and so if there is a zero-weight-cycle, then the other edges must exactly cancel -W—in other words, their indices must give a set

## Problem 4: Efficient Recruiting

Suppose you're helping to organize a summer sports camp, and the following problem comes up. The camp is supposed to have at least one counselor who is skilled at each of the n sports covered by the camp (baseball, volleyball, etc.). They have received job applications from m potential counselors. For each of the n sports, there is some subset of the m applicants qualified in that sport. The question is: For a given number k < m, is it possible to hire at most k of the counselors and have at least one counselor qualified in each of the n sports? We'll call this the *Efficient Recruiting* Problem. Show that *Efficient Recruiting* is NP-Complete.

The Vertex Cover Problem. Given a graph G and a number k, does G contain a vertex cover of size at most k? (Recall that a vertex cover  $V' \subseteq V$  is a set of vertices such that every edge  $e \in E$  has at least one of its endpoints in V'.)

### Solution

Efficient Recruiting is in NP, since given a set of k counselors, we can check that they cover all of the sports.

Suppose we had an algorithm A that solves *Efficient Recruiting*; here is how we would solve an instance of *Vertex Cover*. Given a graph G = (V, E) and an integer k, we would define a sport  $S_e$  for each edge e and a counselor  $C_v$  for each vertex v.  $C_v$  is qualified in sport  $S_e$  if and only if e has an endpoint equal to v.

Now if there are k counselors that, together, are qualified in all sports, the corresponding vertices in G have the property that each edge has an end in at least one of them; so they define a vertex cover of size k. Conversely, if there is a vertex cover of size k, then this set of counselors has the property that each sport is contained in the list of qualifications of at least one of them.

Thus, G has a vertex cover of size at most k if and only if the instance of Efficient Recruiting that we create can be solved with at most k counselors. Moreover, the instance of Efficient Recruiting has size polynomial in the size of G. Thus if we could determine the answer to the Efficient Recruiting instance in polynomial time, we could also solve the instance of Vertex Cover in polynomial time.