```
┌─────────────────────────────────────┐
│         view_frames Result          │
│                                     │
│   Recorded at time: 1576093447.131  │
└─────────────────────────────────────┘

              ( base )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
            ( shoulder )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
         ( shoulder_to_arm )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
           ( upper_arm )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
            ( forearm )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
             ( wrist )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
          ( wrist_hand )
                 │
                 │  Broadcaster: /robot_state_publisher
                 │  Average rate: 10.204 Hz
                 │  Most recent transform: 1576093447.129 ( 0.003 sec old)
                 │  Buffer length: 4.900 sec
                 ▼
           ( hand_ball )
```