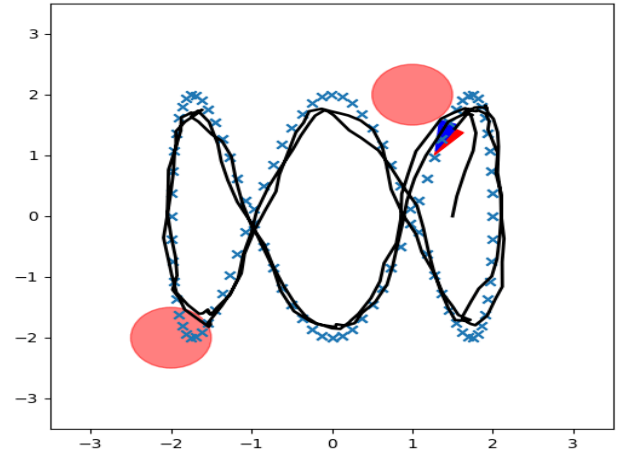
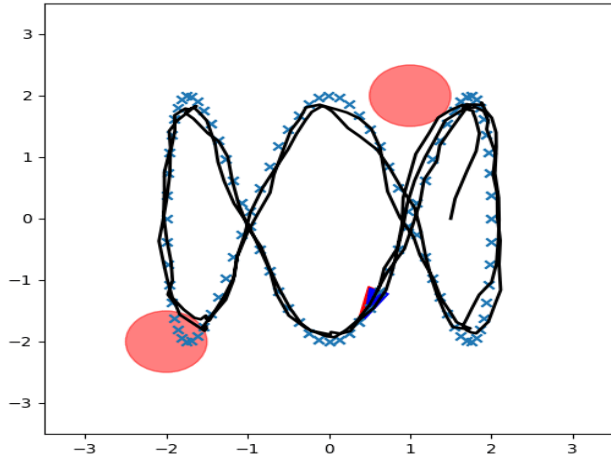


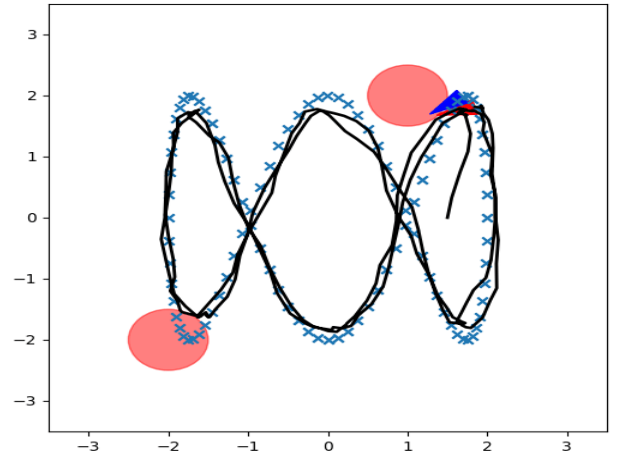
(a)  $Q = 10, q = 10, R = 5, T = 10$



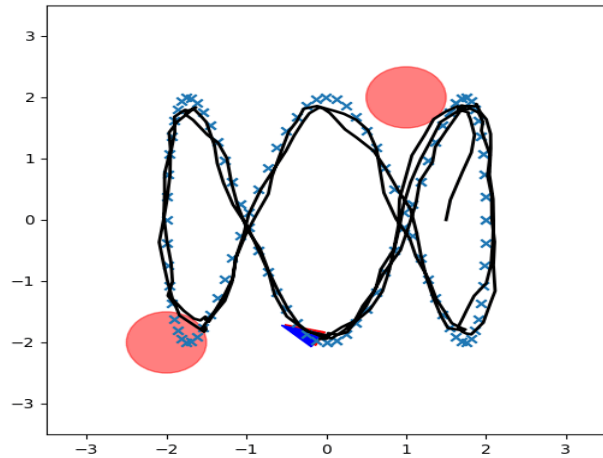
(b)  $Q = 10, q = 10, R = 5, T = 10$



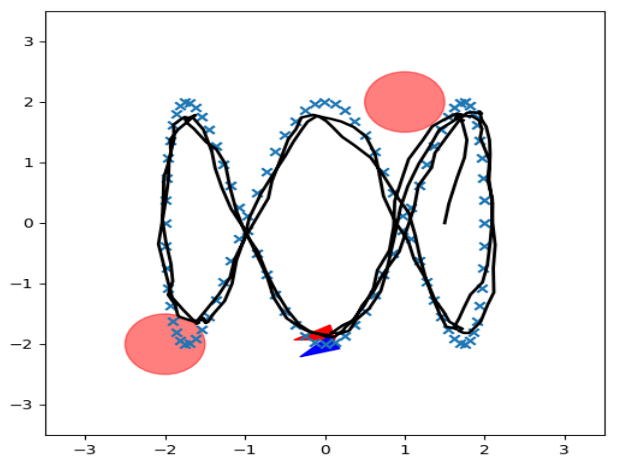
(c)  $Q = 20, q = 10, R = 5, T = 10$



(d)  $Q = 10, q = 30, R = 5, T = 10$

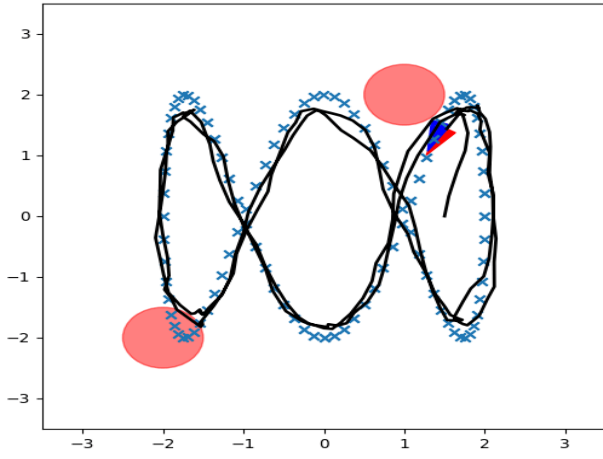


(e)  $Q = 21, q = 10, R = 5, T = 10$

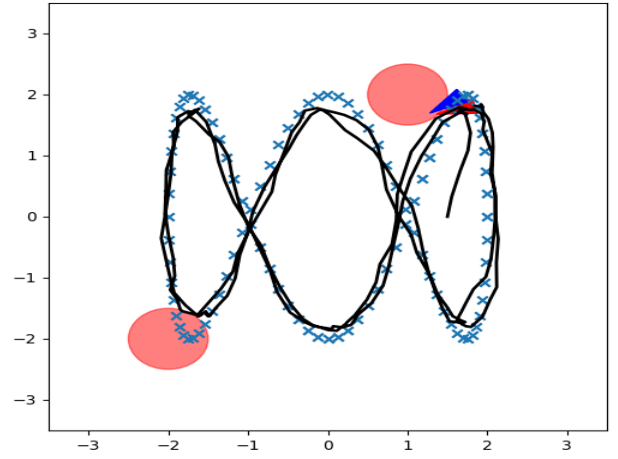


(f)  $Q = 10, q = 80, R = 5, T = 10$

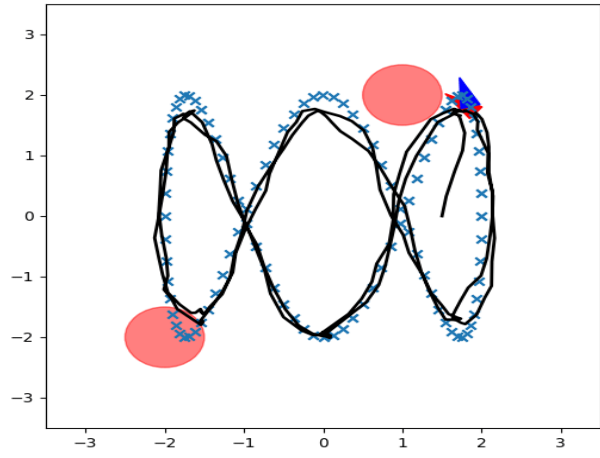
Figure 1: CEC controller: Effects of  $Q$  and  $q$  respectively



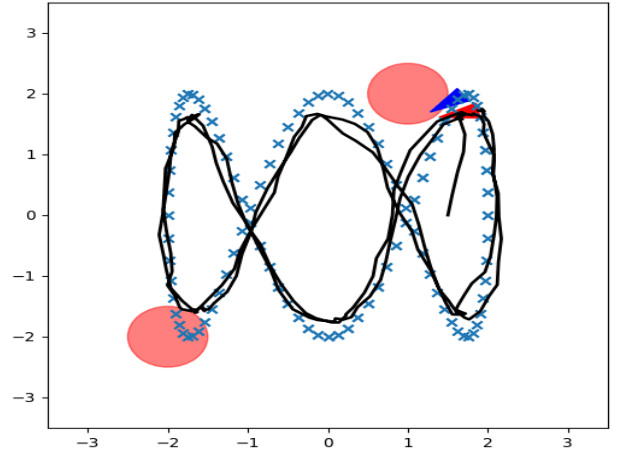
(a)  $Q = 10, q = 10, R = 5, T = 10$



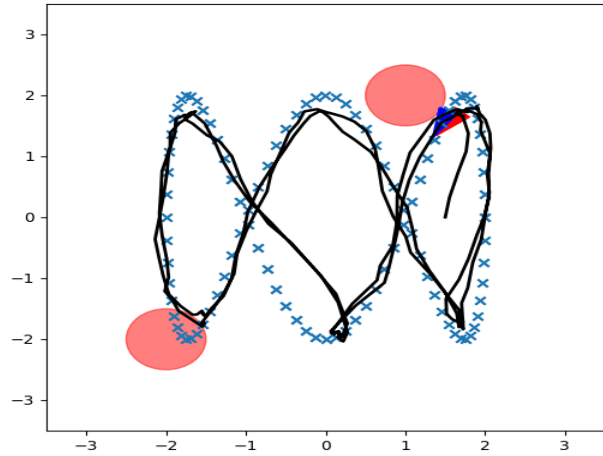
(b)  $Q = 10, q = 30, R = 5, T = 10$



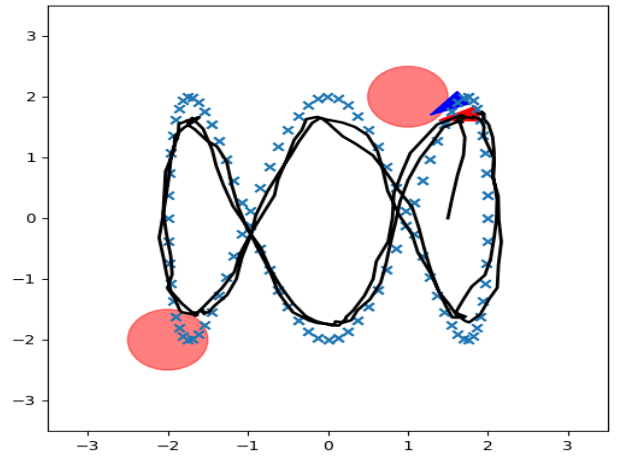
(c)  $Q = 10, q = 10, R = 5, T = 15$



(d)  $Q = 10, q = 30, R = 10, T = 10$

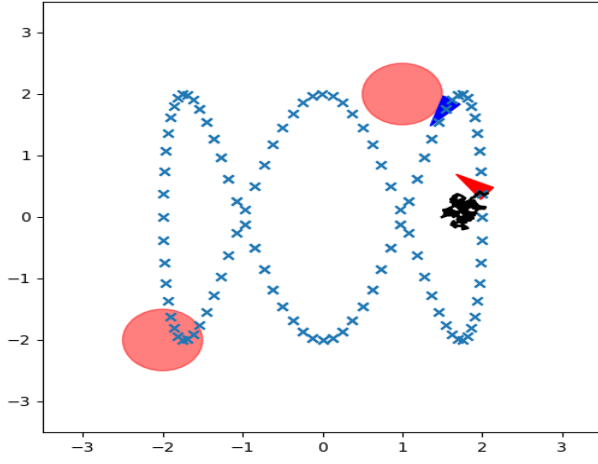


(e)  $Q = 10, q = 10, R = 5, T = 25$

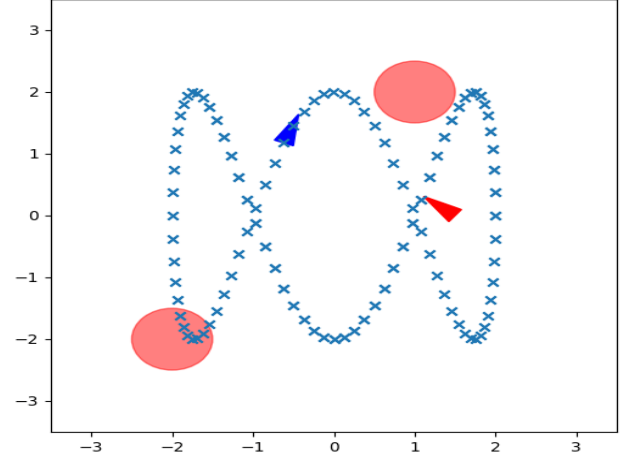


(f)  $Q = 10, q = 30, R = 15, T = 10$

Figure 2: CEC controller: Effects of  $T$  and  $R$  respectively



(a)  $Q = 10$ ,  $q = 10$ ,  $R = 2$



(b)  $Q = 10$ ,  $q = 30$ ,  $R = 5$

Figure 3: GPI controller