

Model Comparison

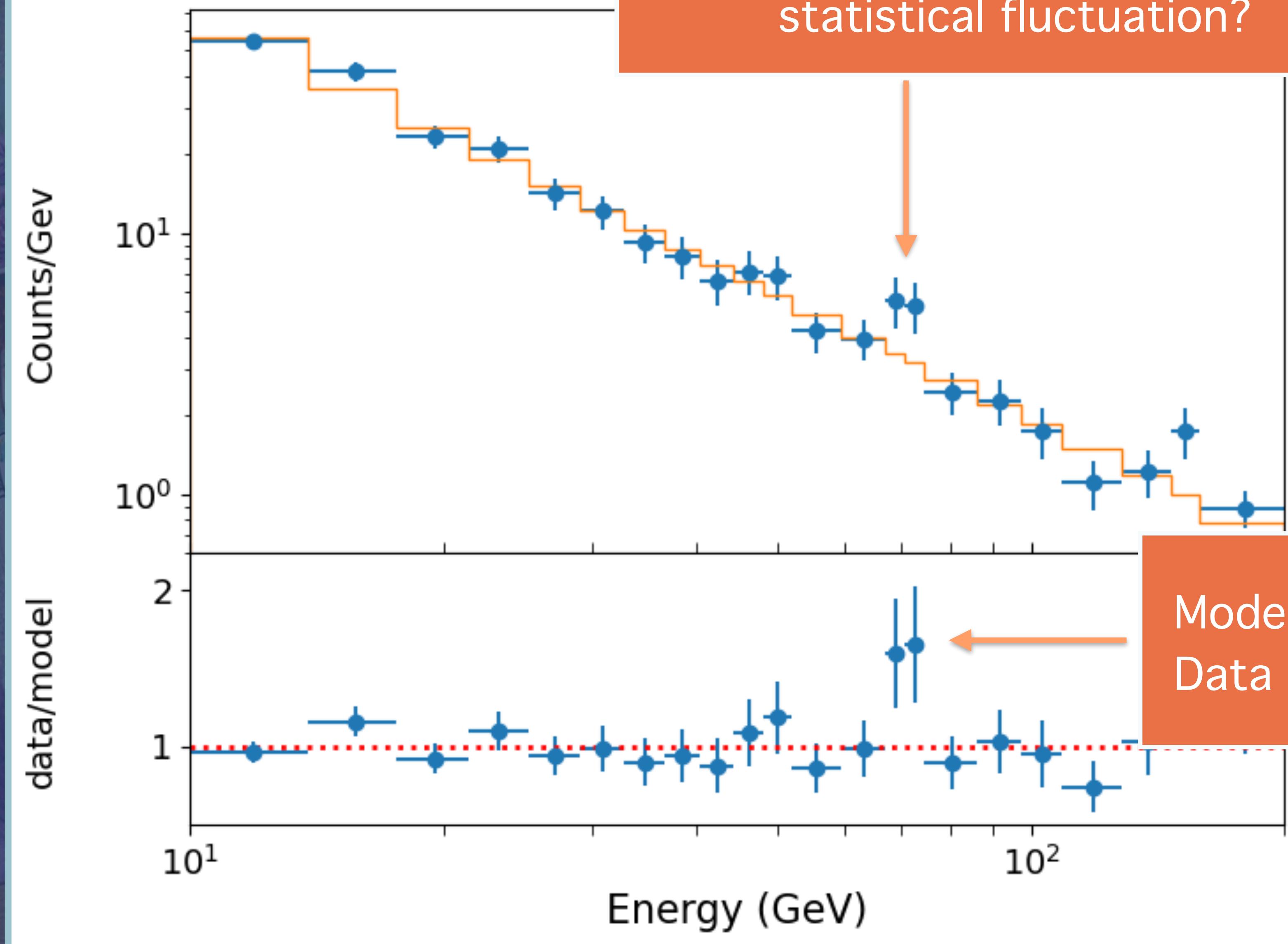
DANIELA HUPPENKOTHEN



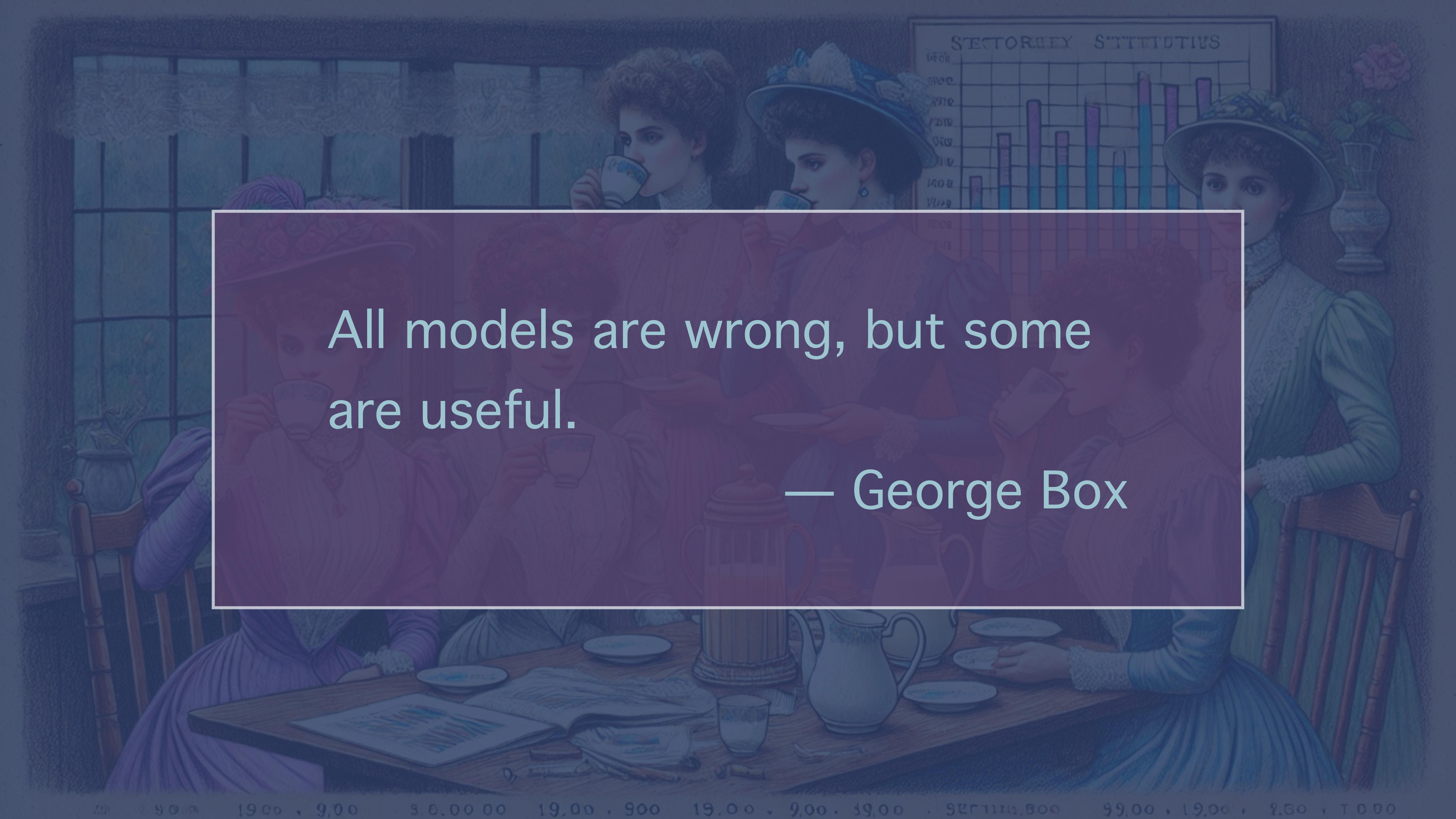
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Is there an emission line? Or is it a statistical fluctuation?



Model misspecification?
Data issues?



All models are wrong, but some
are useful.

— George Box

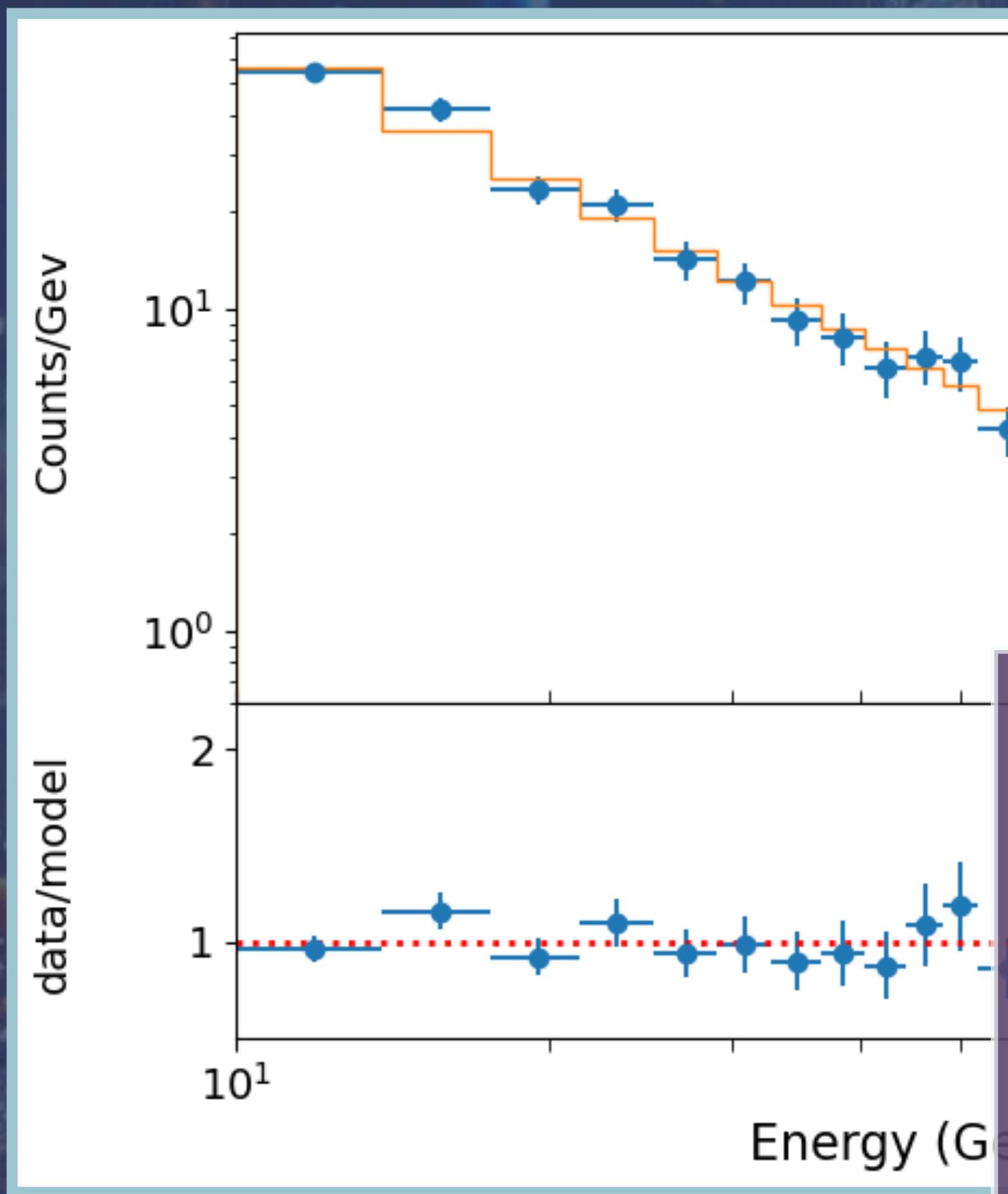
Model comparison: which of models A or B was more probable to have generated the data?

Selected Model Comparison Methods

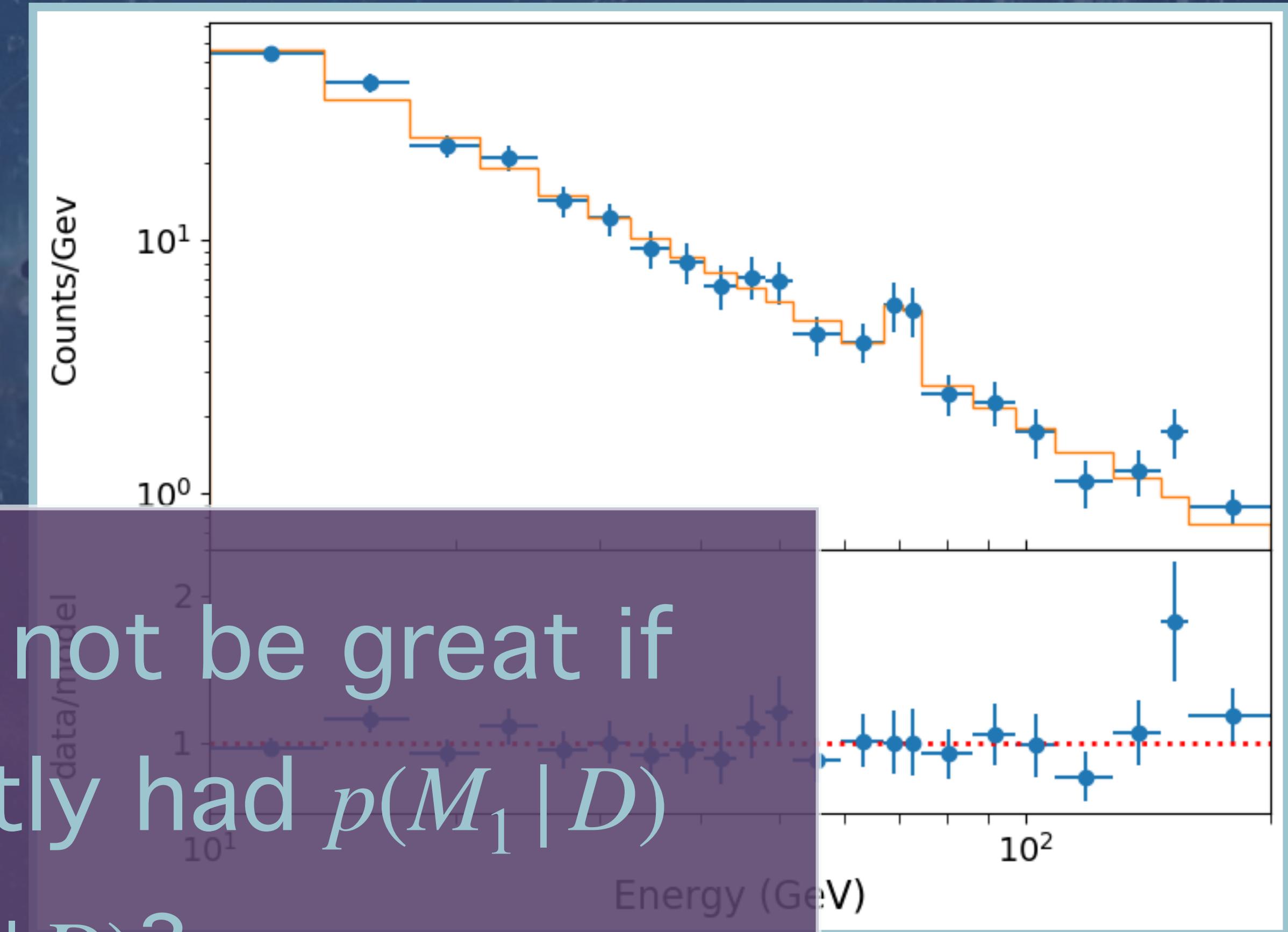
- Hypothesis testing
- Information Criteria
- Posterior Odds (today)

👻 Model comparison is really hard! 🕸️
(If you can reframe your problem as a parameter estimation problem, you should!)

Which is better?



Would it not be great if
we directly had $p(M_1 | D)$
and $p(M_2 | D)$?



$$P(\theta | D) = \frac{P(D | \theta)P(\theta)}{P(D)}$$

Bayes rule

We kind of cheated here!

θ = parameters

D = data

$$P(\theta | D, I) = \frac{P(D | \theta, I)P(\theta | I)}{P(D | I)}$$

θ = parameters

D = data

I = other assumptions

$$P(\theta | D, M, I_{\text{rest}}) = \frac{P(D | \theta, M, I_{\text{rest}})P(\theta | M, I_{\text{rest}})}{P(D | M, I_{\text{rest}})}$$

θ = parameters

D = data

$I = (M, I_{\text{rest}})$ other assumptions

$$P(\theta | D, M) = \frac{P(D | \theta, M)P(\theta | M)}{P(D | M)}$$

θ = parameters

D = data

M = model choice

Likelihood of the
model, integrated
over all parameters!

$$P(M | D, I) = \frac{P(D | M, I)P(M | I)}{P(D | I)}$$

D = data

M = model choice

$$\frac{p(M_1 | D, I)}{p(M_0 | D, I)} = \frac{p(D | M_1, I)p(M_1 | I)}{p(D | M_0, I)p(M_0 | I)}$$

Posterior odds

Bayes factor

D = data

M_1, M_0 = The models to be compared

Bayesian Model Comparison

... allows you to directly compare the relative odds of two hypotheses

... also enables you to put sensible priors on both models

But: Bayes factors are very sensitive to the parameter priors of each model

Bayes factors involve intractable integrals in high dimensions and are thus very challenging to compute!



$$p(D|M) = \int_{-\infty}^{\infty} p(D|\theta, M)p(\theta|M)d\theta$$

θ = parameters

D = data

M = model choice

We've been ignoring this
during MCMC! 😬

Nested Sampling

Further reading:

- <https://arxiv.org/abs/2101.09675>
- <https://www.nature.com/articles/s43586-022-00121-x>

Sampling method to compute integral $p(D|M)$:

- 1) Draw points from prior
- 2) Pick point(s) with lowest likelihood
- 3) Draw contours at that likelihood surface
- 4) Sample new point(s) from within those contours
- 5) Repeat from step 2

<https://chi-feng.github.io/mcmc-demo/app.html>