

Experiment # 7, 8

To study performance analysis of coherent and non-coherent BPSK demodulation in the presence of noise.

i) PC with MATLAB and VSA software

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```
h_pn=commsrc.pn('GenPoly',[7 6 0],'InitialStates',[0 0 0 0 0 0
1],'NumBitsOut',N);
synchronization_bits=generate(h_pn);
%~~~~~ [sync bits, data bits]~~~~~
tx_text=[synchronization_bits;txt_to_bin]
% ~~~~~BIT Sequence to Signal (Upsampling)~~~~~%
bits_I=2*(tx_text-0.5);
sig ipt_I=upsample(bits_I,8
%~~~~~Rectangular filter~~~~~%
ract_fil=ones(8,1);
sig_ract=conv(ract_fil, sig ipt_I);%
sig_ract_I=sig_ract/sqrt(var(sig_ract));

csvwrite('Coh_Rect_text_ref.csv',tx_text);
csvwrite('Coh_Rect_text_data.csv',sig_ract_I);
```

Receiver Code:

```
clc;
clear all;
close all;
spsym=8; % samples per symbol
%~~~~~ Acquireing the data ~~~~~%
RX_ss_tmp = csvread ('acquired_coherent_7_22.csv',0,0);
figure;
plot(RX_ss_tmp(1:2000,:));
RX_ss=complex(RX_ss_tmp(:,1),RX_ss_tmp(:,2));
Ract_filt=ones(spsym,1); %Filter Length = spsym
XX_signal = conv(Ract_filt,RX_ss); % Ractangular pulse shaped signal
RX_signal =XX_signal/max([real(XX_signal);imag(XX_signal)]); %normalizing
the convolved signal
%~~~~~ EYE Diagram ~~~~~%
eye_len=spsym;
eye_frame_len=floor(length(RX_signal)/eye_len);
I_eye=zeros(eye_len,eye_frame_len);
Q_eye=zeros(eye_len,eye_frame_len);
for i=1:eye_frame_len
    I_eye(:,i)= real(RX_signal((i-1)*eye_len+1:i*eye_len,1));
    Q_eye(:,i)=imag(RX_signal((i-1)*eye_len+1:i*eye_len,1));
end
figure;
plot(I_eye(:,1:100));
%~~~~~Sampling Instant Identification ~~~~~%
eye_var=zeros(eye_len,1);
for i=1:eye_frame_len
    for j=1:eye_len
        eye_var(j,1)=eye_var(j,1)+I_eye(j,i)^2;
    end
end
eye_var=eye_var/eye_frame_len;
[~,eye_offset]=max(eye_var(1:spsym));

%~~~~~ Sample the symbols by downsampling ~~~~~%
Symbols=zeros(floor(length(RX_signal)/spsym),1);
for i=1:length(Symbols)-1
    Symbols(i,1)=RX_signal((i-1)*spsym+eye_offset,1);
end
figure
plot(Symbols(1:100))
```

```

figure
plot(atan(imag(Symbols(1:1000))./real(Symbols(1:1000))));
%~~implementation of phase and frequency correction(PLL/Costas
loop)~~~~~%
K1_PLL =0.0313;
K2_PLL =2.49e-4;
unwrap_phi_array = zeros(size(Symbols));
phi_array = zeros(size(Symbols));
freq_array = zeros(size(Symbols));
filt_phi_array = zeros(size(Symbols));
filt_freq_array = zeros(size(Symbols));
phi_array(1:2)=atan(imag(Symbols(1:2))./real(Symbols(1:2)));
unwrap_phi_array(1:2)=phi_array(1:2);
for i=3:length(Symbols)
    phi=atan(imag(Symbols(i))/real(Symbols(i)));
    phi1(i)=phi;
    old_phi=phi_array(i-1);
    if (phi-old_phi < -pi/2)
        freq = pi+phi-old_phi;
    elseif (phi-old_phi > pi/2)
        freq = -pi+phi-old_phi;
    else
        freq = phi-old_phi;
    end
    freq_array(i)=freq;
    unwrap_phi_array(i)=unwrap_phi_array(i-1)+freq;
    phi_array(i)=phi;
    % filter coefficient and equation is given in page 411 and 412 of given
    % google drive link
    %
https://drive.google.com/file/d/1FpZeWW0sb8Ve\_C0QDALye7r1kmmb3nmd/view?usp=sharing

    filt_phi_array(i) = (2-K1_PLL-K2_PLL)*filt_phi_array(i-1) ...
                        -(1-K1_PLL)*filt_phi_array(i-2) ...
                        +(K1_PLL+K2_PLL)*unwrap_phi_array(i-1) ...
                        -(K1_PLL)*unwrap_phi_array(i-2);
    Symbols(i) = Symbols(i)*complex(cos(filt_phi_array(i)), -
sin(filt_phi_array(i)));

end

figure
plot(Symbols(1:100));
%~~~~~Loading transmitted data for BER
Calculation~~~~~%
tx_bits = csvread('Coh_Rect_text_ref.csv',1);
tx_bits_bipolar=2*tx_bits-1;
%~~~~~Finding the starting bit and detect the bits (Works in good
SNR)~~~~~%
bits_rec_bipolar=sign(real(Symbols));
corval=zeros(length(tx_bits_bipolar),1);
%~~~~~ Using synchronization bit finding stating start of the data
packet~~~~~%
for i=1:length(tx_bits)*2
    corval(i,1)=sum(tx_bits_bipolar(1:128).*bits_rec_bipolar(i:i+127));
end
figure;
plot(corval)

```

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```
[peak,start_bit_ind]=max(abs(corval)); %searching maximum correlation value
and its index number
start_bit_ind
peak
ss=sign(corval(start_bit_ind)); % required to correct the polarity of
PLL output
bits_rec=(ss*bits_rec_bipolar+1)/2; %converting 1--->1 and -1---->0
detected_bits=bits_rec(start_bit_ind:start_bit_ind+length(tx_bits)-1);
%chooping out of one packet data
%~~~~~%

Nof_err_bits=sum(abs(tx_bits-detected_bits)); %finding number of bits get
flipeid
BER=Nof_err_bits/length(tx_bits); % Bit error rate
Nof_err_bits
BER

%~~~~~binary to text conversion
%~~~~~%
bin_to_text=[0;detected_bits];
bin_to_text=bin_to_text(129:end);
btxt = reshape(bin_to_text,[8, length(bin_to_text)/8]);
if length(class(btxt))== 6
    text = char(bin2dec(char(btxt+48)));
else
    text = char(bin2dec(btxt));
end
text
```

Experiment # 8

Purpose: Analysis of the performance of the non-coherent demodulation in the presence of noise.

Equipment and materials:

Equipment Required

i) PC with MATLAB and VSA software

Procedure:

- 1) Add a MATLAB code for differential encoding and decoding in MATLAB function written in
The code for differential encoding and decoding is given as follows:

```
% ~~~~~Differential Encoding ~~~~~%
diff_bits=zeros(length(tx_text),1);
diff_bits(1)=xor(0,tx_text(1));
for i=2:length(diff_bits)
    diff_bits(i)=xor(diff_bits(i-1),tx_text(i)); % XOR ing privious bit to
current bit
end

%~~~~~Diferential Decoding~~~~~%
angle_array=[0;atan2(imag(Symbols),real(Symbols))];
angle_diff=abs(angle_array(2:end)-angle_array(1:end-1));
for i=1:length(angle_diff)
    if angle_diff(i)>3*pi/2
        angle_diff(i)=0;
    end
end
bits_rec_bipolar=sign(angle_diff-pi/2);
```