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## PSet 6 – Synchronization

## <u>Problem 1 – Spin Lock</u>

```
spinlock.h:
#include <stdlib.h>
#include <stdio.h>
#include <string.h>
#include <unistd.h>
#include <fcntl.h>
#include <errno.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/mman.h>
#include <sys/stat.h>
#include <sys/wait.h>
typedef struct spinlock{
 volatile char primlock;
}spinlock;
int tas(volatile char *lock);
void spin lock(struct spinlock *1);
void spin unlock(struct spinlock *1);
spinlock.c:
#include "spinlock.h"
void spin lock(struct spinlock *1) {
  while (tas(&(1->primlock)) != 0)
    ;
  }
}
void spin unlock(struct spinlock *1) {
  1->primlock = 0;
}
```

## <u>Problem 2 – Test the test-and</u>-set

```
spintest.c:
#include "spinlock.h"
int main(int argc, char **argv) {
  long long unsigned int nchild, niter;
 pid t pid;
  if(argc != 3) {
    fprintf(stderr, "Error: Please input 3 arguments\n");
    exit(255);
  }
  nchild = atoll(argv[1]);
  niter = atoll(argv[2]);
  int *map = mmap(NULL, 4096, PROT READ|PROT WRITE,
MAP ANONYMOUS | MAP SHARED, 0, 0);
  if(map < 0){
    fprintf(stderr, "Error: failed to mmap() anonymous page
- %s\n", strerror(errno));
   exit(255);
  }
  map[0] = 0;
  spinlock *lock;
  lock = (spinlock *) (map + sizeof(spinlock));
  lock -> primlock = map[1];
  for (int i = 0; i < nchild; i++) {
    switch(pid = fork()){
      case -1:
        fprintf(stderr, "Error: failed to fork() #%dth time
- %s\n", i, strerror(errno));
        break;
      case 0:
        spin lock(lock);
        for(int j = 0; j < niter; j++){
          map[0]++;
        spin unlock(lock);
        exit(0);
        break;
    }
```

```
for(int i = 0; i < nchild; i++) {
    wait(0);
}

printf("value of map[0] = %d\n", map[0]);
return 0;
}</pre>
```

Output of without and then with spin lock protection:

```
dhpark@HAL-9001:/mnt/d/Dropbox/School/Copper Onion/3.Junear/Operating Systems/Homework/Assignment 6 Synchronization/src $ ./a.out 4 100000
value of map[0] = 320877
dhpark@HAL-9001:/mnt/d/Dropbox/School/Copper Onion/3.Junear/Operating Systems/Homework/Assignment 6 Synchronization/src $ gcc spinlock.c spintest.c tas64.S
dhpark@HAL-9001:/mnt/d/Dropbox/School/Copper Onion/3.Junear/Operating Systems/Homework/Assignment 6 Synchronization/src $ ./a.out 4 100000
value of map[0] = 400000
dhpark@HAL-9001:/mnt/d/Dropbox/School/Copper Onion/3.Junear/Operating Systems/Homework/Assignment 6 Synchronization/src $ ./a.out 4 100000
value of map[0] = 400000
dhpark@HAL-9001:/mnt/d/Dropbox/School/Copper Onion/3.Junear/Operating Systems/Homework/Assignment 6 Synchronization/src $ ./a.out 4 100000
```

## <u>Problem 3 – Implement Condition Variables</u>

cv.h:

```
#include "spinlock.h"

typedef struct cv{
   int i;
   spinlock lock;
   pid_t pid[64];
   sigset_t sigMask;
}cv;

void cv_init(struct cv *cv);
void cv_wait(struct cv *cv, struct spinlock *mutex);
int cv_broadcast(struct cv *cv);
int cv_signal(struct cv *cv);

cv.c:
#include "cv.h"
```

```
void sigHandle(int signum) {
   ;
}

void cv_init(struct cv *cv) {
   spinlock *lock;

   int *map = mmap(NULL, 4096, PROT_READ|PROT_WRITE,
MAP_ANONYMOUS|MAP_SHARED, 0, 0);
```

```
if(map < 0){
    fprintf(stderr, "Error: failed to mmap() anonymous page
- %s\n", strerror(errno));
    exit(255);
  lock = (spinlock *) (map + sizeof(spinlock));
  cv->lock = *lock;
  for (int i = 0; i < 64; i++) {
    cv->pid[i] = 0;
  cv->i = 0;
  signal(SIGUSR1, sigHandle);
  sigfillset(&cv->sigMask);
  sigdelset(&cv->sigMask, SIGUSR1);
}
void cv wait(struct cv *cv, struct spinlock *mutex) {
  if(cv->i>=64){
     fprintf(stderr, "Error: too many processes\n");
     exit(255);
  spin lock(&cv->lock);
  cv->pid[cv->i] = getpid();
  cv->i++;
  spin unlock(&cv->lock);
  spin unlock(mutex);
  sigprocmask(SIG BLOCK, &cv->sigMask, NULL);
  sigsuspend(&cv->sigMask);
  if(cv->i>0){
     spin lock(&cv->lock);
     cv - pid[cv - i - 1] = 0;
     cv->i--;
     spin unlock(&cv->lock);
     spin lock(mutex);
  return;
  }
  sigprocmask(SIG UNBLOCK, &cv->sigMask, NULL);
  spin lock(mutex);
}
```

```
int cv broadcast(struct cv *cv) {
  int wakeNum = 0;
  spin lock(&cv->lock);
  if(cv->i == 0){
    spin unlock(&cv->lock);
    return 0;
  for (int j = 0; j < 64; j++) {
    if(cv->pid[j] > 0){
      kill(cv->pid[j], SIGUSR1);
      wakeNum++;
    }
  }
  spin unlock(&cv->lock);
  return wakeNum;
}
int cv signal(struct cv *cv) {
  int wakeNum = 0;
  spin lock(&cv->lock);
  if(cv->i == 0){
    spin unlock(&cv->lock);
    return 0;
  kill(cv->pid[cv->i - 1], SIGUSR1);
  wakeNum++;
  spin unlock(&cv->lock);
  return wakeNum;
}
Problem 4 – A FIFO using condition variables
fifo.h:
#include "cv.h"
#define MYFIFO BUFSIZ 1024
typedef struct fifo{
  int state, readNext, writeNext;
  unsigned long buf[MYFIFO BUFSIZ];
  spinlock lock;
```

```
cv w, r;
}fifo;
void fifo init(struct fifo *f);
void fifo wr(struct fifo *f, unsigned long d);
unsigned long fifo rd(struct fifo *f);
fifo.c:
#include "fifo.h"
void fifo init(struct fifo *f){
  cv *readMap = NULL, *writeMap = NULL;
  readMap = (cv *)mmap(NULL, sizeof(cv), PROT READ|PROT WRITE,
MAP SHARED | MAP ANONYMOUS, -1, 0);
  writeMap = (cv *)mmap(NULL, sizeof(cv), PROT READ|PROT WRITE,
MAP SHARED | MAP ANONYMOUS, -1, 0);
  if(readMap < 0){
       fprintf(stderr, "Error: failed to mmap() anonymous file
for read %s\n", strerror(errno));
       exit(255);
  if(writeMap < 0){</pre>
    fprintf(stderr, "Error: failed to mmap() anonymous file for
write %s\n", strerror(errno));
    exit(255);
  }
  fifo->r = *readMap;
  fifo->readNext = 0;
  cv init(&fifo->r);
  fifo->w = *writeMap;
  fifo->writeNext = 0;
  cv init(&fifo->w);
  fifo->state = 0;
  fifo->lock.primlock = 0;
}
void fifo wr(struct fifo *f, unsigned long d) {
  spin lock(&fifo->lock);
  while(fifo->state >= MYFIFO BUFSIZ) {
       cv wait(&fifo->w, &fifo->lock);
  }
```

```
fifo->buf[fifo->writeNext++] = x;
  fifo->writeNext %= MYFIFO BUFSIZ;
  fifo->state++;
  cv signal(&fifo->r);
  spin unlock(&fifo->lock);
}
unsigned long fifo rd(struct fifo *f) {
  unsigned long fifoRead;
  spin lock(&fifo->lock);
  while(fifo->state <= 0){</pre>
       printf("Fifo read is %d complete\n", ++z);
       cv wait(&fifo->r, &fifo->lock);
  }
  fifoRead = fifo->buf[fifo->readNext++];
  fifo->readNext %= MYFIFO BUFSIZ;
  fifo->state--;
  cv signal(&fifo->w);
  spin unlock(&fifo->lock);
  return fifoRead;
}
<u>Problem 5 – Test your FIFO</u>
ftest.c:
#include "fifo.h"
int main(int argc, char **argv) {
  int writers, items;
  fifo *fifo1;
  pid t pid1, pid2;
  if(argc < 3){
    printf("Error: please input 3 arguments\n");
    exit(255);
  writers = atoi(argv[1]+2);
  items = atoi(argv[2]+2);
  printf("Beginning test with %d writers, %d items each\n",
```

writers, items);

```
fifo1 = (fifo *)mmap(NULL, sizeof(fifo), PROT READ|PROT WRITE,
MAP SHARED | MAP ANONYMOUS, -1, 0);
  if(fifo1 < 0){
    fprintf(stderr, "Error: failed to mmap() anonymous page for
fifo - %s\n", strerror(errno));
    exit(255);
  }
  fifo init(fifo1);
  for (int i = 0; i < writers; i++) {
    switch(pid1 = fork()){
      case -1:
        fprintf(stderr, "Error: failed to fork() #%dth time
- %s\n", i, strerror(errno));
        break;
      case 0:;
        unsigned long writeBuf[items];
        for (int j = 0; j < items; j++) {
          writeBuf[j] = getpid()*10000 + j;
          fifo wr(fifo1, writeBuf[j]);
        }
        printf ("Write %d completed\n", i);
        exit(0);
        break;
    }
  switch(pid2 = fork()){
    case -1:
      fprintf(stderr, "Error: failed to fork() - %s\n",
strerror(errno));
     break;
    case 0:;
      unsigned long readBuf[writers * items];
      for (int i = 0; i < (writers * items); i++) {
        readBuf[i] = fifo rd(fifo1);
      }
      printf("All streams done\n");
      break;
  }
  printf("Waiting for writer children to die\n");
```

```
for(int i = 0; i < writers + 1; i++) {
    wait(0);
}
return 0;
}</pre>
```

Output of testing the FIFO: