

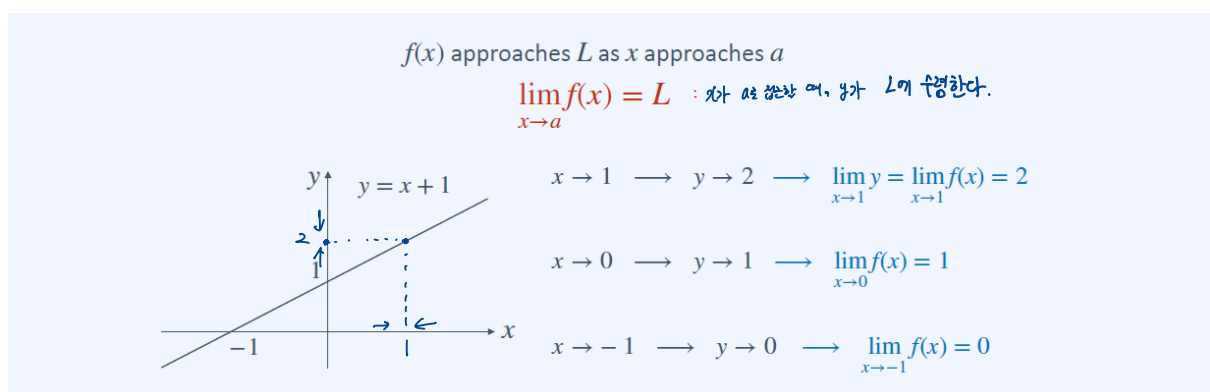
Part 1_Ch 02_미적분학

📅 date	@2023/04/19
🕒 time	19:00
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Chapter 02. 미적분학

2.1. Limits

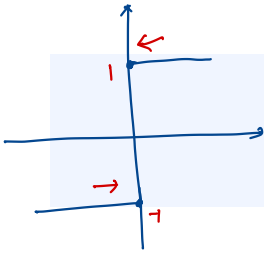
Limits : 극한



Left / Right-hand Limits : 좌극한, 우극한

: 극한값의 경향을 나타내!

$$y = \begin{cases} 1, & x \geq 0 \\ -1, & x < 0 \end{cases}$$

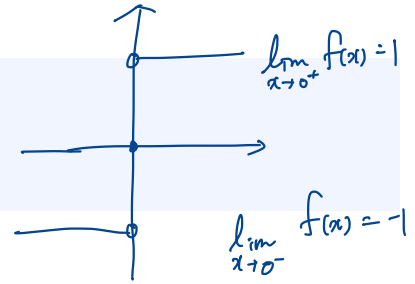


좌극한: left-hand limits

$$\lim_{x \rightarrow a^-} f(x)$$

우극한: right-hand limits

$$\lim_{x \rightarrow a^+} f(x)$$



Existence of Limits : 극한값의 존재 조건

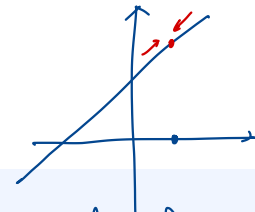
$$\lim_{x \rightarrow a^-} f(x) = \lim_{x \rightarrow a^+} f(x)$$

Continuity

연속성이기 위한 조건
① 극한값 = 함수값

$f(x)$ is continuous at $x = a$, if $\lim_{x \rightarrow a} f(x) = f(a)$

→ 극한값과 함수값이 같을 때,
연속적이다



$$\lim_{x \rightarrow 1^+} f(x) = \lim_{x \rightarrow 1^-} f(x)$$

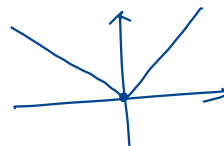
$$x_1 \leq x \leq x_2$$

Continuity on Intervals

$\forall a \in [x_1, x_2], \lim_{x \rightarrow a} f(x) = f(a) \rightarrow f(x)$ is continuous on $[x_1, x_2]$

$\forall a \in D, \lim_{x \rightarrow a} f(x) = f(a) \rightarrow f(x)$ is continuous
연속함수

$$y = |x| = \begin{cases} x, & x \geq 0 \\ -x, & x < 0 \end{cases}$$



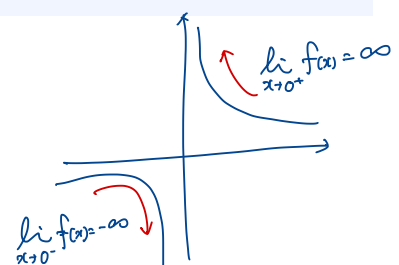
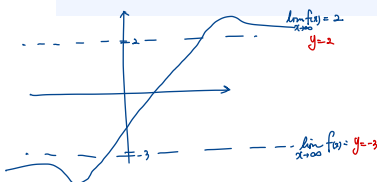
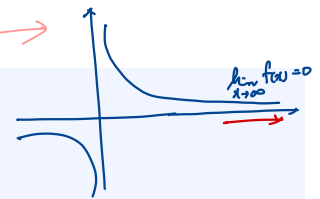
Limits and Asymptotes : 점근선을 다룰 때, 수평선과 방한선을 알아볼 수 있다.

horizontal asymptotes

$$\lim_{x \rightarrow \pm \infty} f(x) = L$$

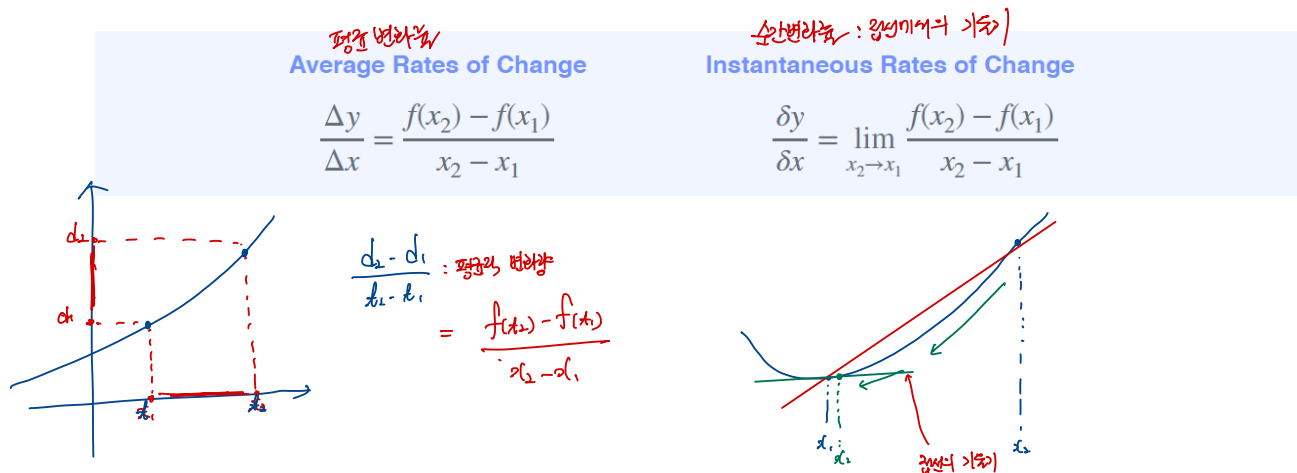
vertical asymptotes

$$\lim_{x \rightarrow a} f(x) = \pm \infty$$

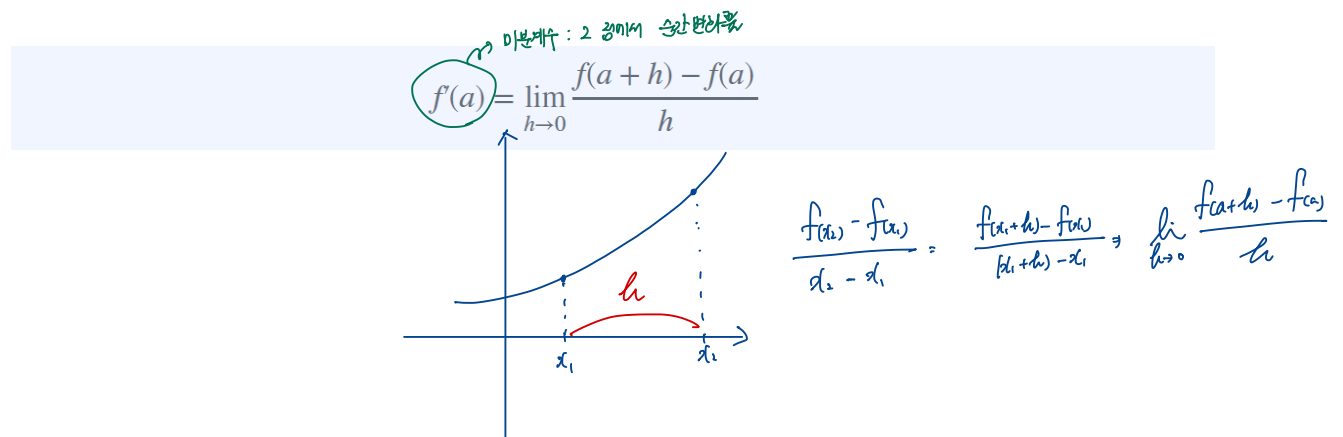


2.2. Differentiation and Derivatives

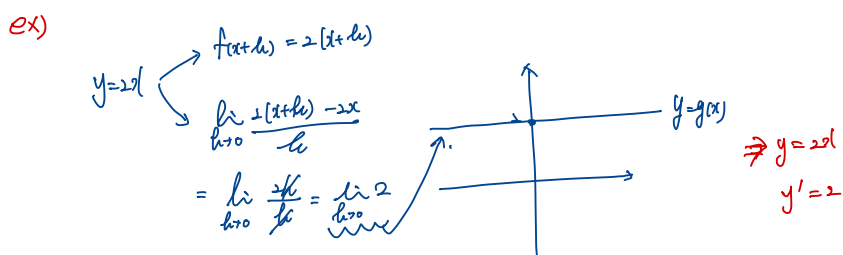
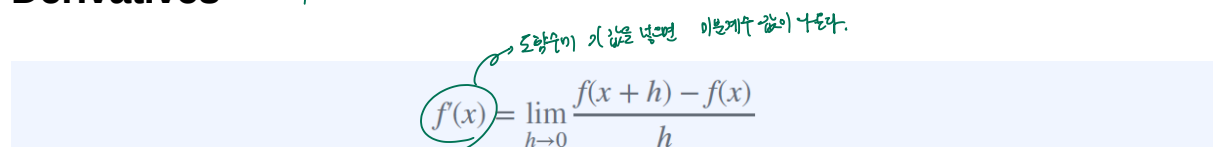
Rates of Change



Differential Coefficients



Derivatives : 도함수



Notations

$$f'(x) / y'$$

$$\frac{df(x)}{dx} / \frac{dy}{dx} / \frac{d}{dx}[f(x)]$$

Derivative Formulas

$$f(x) = c \rightarrow f'(x) = 0$$

$$f(x) = x^n \rightarrow f'(x) = nx^{n-1}$$

$$f(x) = a^x \rightarrow f'(x) = a^x \cdot \ln(a)$$

$$f(x) = \log_a x \rightarrow f'(x) = \frac{1}{x \cdot \ln(a)}$$

$$f(x) = \sin(x) \rightarrow f'(x) = \cos(x)$$

$$f(x) = \cos(x) \rightarrow f'(x) = -\sin(x)$$

$$f(x) = \tan(x) \rightarrow f'(x) = \sec^2(x) = \frac{1}{\cos^2 x}$$

자연상수는 simple한 것만 만들 수 있지!

$$\begin{aligned} f(x) = e^x &\rightarrow f'(x) = e^x \cdot \ln(e) \\ &= e^x \\ g(x) = \ln(x) &\rightarrow g'(x) = \frac{1}{x \cdot \ln(e)} = \frac{1}{x} \end{aligned}$$

Differentiation Rules

$$\frac{d}{dx}[c \cdot f(x)] = c \cdot \frac{d}{dx}[f(x)] : \text{상수배가 곱하면 상수배}$$

$$\frac{d}{dx}[f(x) \pm g(x)] = \frac{d}{dx}[f(x)] \pm \frac{d}{dx}[g(x)]$$

$$\frac{d}{dx}[f(x) \cdot g(x)] = f'(x) \cdot g(x) + f(x) \cdot g'(x)$$

$$\frac{d}{dx} \left[\frac{f(x)}{g(x)} \right] = \frac{f'(x)g(x) - f(x)g'(x)}{\{g(x)\}^2}$$

Note! linearity of differentiation

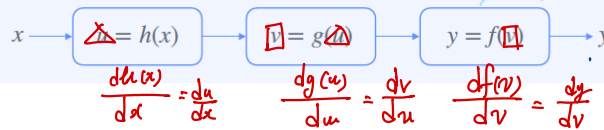
Chain Rule

함성값을 따르는 부분

$$\frac{d}{dx} [f(g(x))] = f'(g(x)) \cdot g'(x)$$

$f(g(x))$: 함수값을 따르는 $x \rightarrow \boxed{g} \rightarrow \boxed{f} \rightarrow y$

$$y = f(g(h(x))) \Rightarrow \frac{dy}{dx} = \frac{dy}{dv} \cdot \frac{dv}{du} \cdot \frac{du}{dx}$$



ex) $\frac{f(g(x))}{g(x)} = f(g(x)) \rightarrow f'(g(x)) \cdot g'(x)$

$$e^x + x^2 = g(x) \rightarrow u = e^x + x^2 \rightarrow \frac{du}{dx} = e^x + 2x$$

$$u^3 = f(u) \rightarrow y = u^3 \rightarrow \frac{dy}{du} = 3u^2 = 3(e^x + x^2)$$

$$\frac{dy}{dx} = \frac{dy}{du} \times \frac{du}{dx} = 3(e^x + x^2) \cdot (e^x + 2x)$$

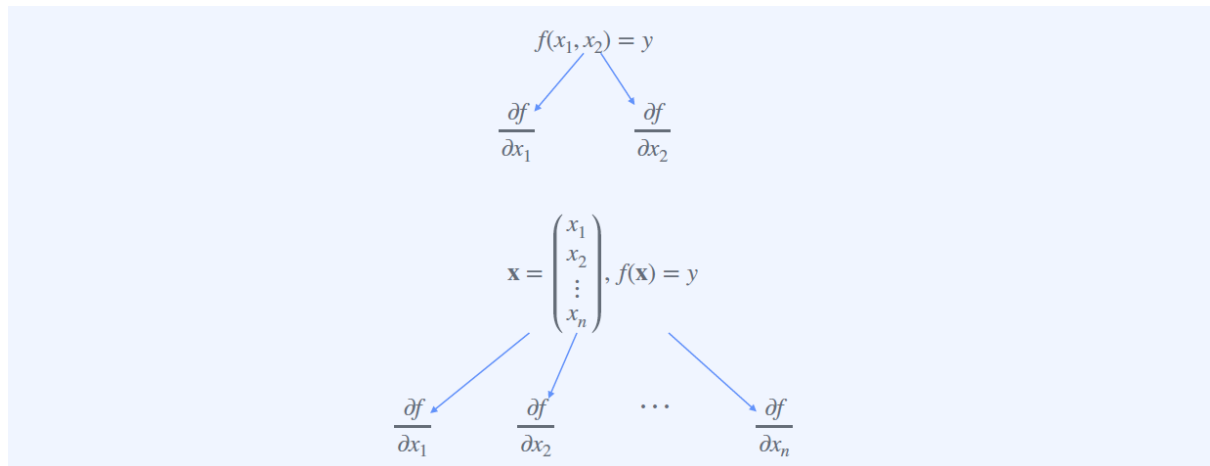
2.3. Gradient-based Optimization

Case Study: Quadratic Functions

$$x := x - \alpha \frac{dy}{dx}$$

2.4. Matrix Calculus

Multivariate Functions



Gradients

$$f(x_1, x_2) = y \quad \longrightarrow \quad \nabla_{(x_1, x_2)} f = \left(\frac{\partial f}{\partial x_1} \quad \frac{\partial f}{\partial x_2} \right)$$
$$f(\mathbf{x}) = y \quad \longrightarrow \quad \nabla_{\mathbf{x}} f(\mathbf{x}) = \left(\frac{\partial f(\mathbf{x})}{\partial x_1} \quad \frac{\partial f(\mathbf{x})}{\partial x_2} \quad \dots \quad \frac{\partial f(\mathbf{x})}{\partial x_n} \right)$$
$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \frac{\partial f}{\partial \mathbf{x}}$$

Gradient-based Optimization

$$\mathbf{x} := \mathbf{x} - \alpha \nabla_{\mathbf{x}} f(\mathbf{x})$$

Optimizations of Artificial Neurons

$$\begin{aligned}
 z = f(\mathbf{x}; \theta) &= \theta_n x_n + \theta_{n-1} x_{n-1} + \dots + \theta_1 x_1 + \theta_0 \\
 a = g(z) &= \frac{1}{1 + e^{-z}} \quad \longrightarrow \quad \nu(\mathbf{x}; \theta) = g(f(\mathbf{x}; \theta)) \\
 \theta &:= \theta - \alpha \frac{\partial \nu(\mathbf{x}; \theta)}{\partial \theta}
 \end{aligned}$$

Vector Functions

$$\begin{aligned}
 f_1(x) &= y_1 \\
 f_2(x) &= y_2 \\
 &\vdots \\
 f_m(x) &= y_m
 \end{aligned}
 \quad \longrightarrow \quad
 \mathbf{f}(x) = \begin{pmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_m(x) \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$

Vector Functions and Gradients

$$\mathbf{f}(x) = \begin{pmatrix} f_1(x) \\ f_2(x) \\ \vdots \\ f_m(x) \end{pmatrix} \quad \longrightarrow \quad \frac{\partial \mathbf{f}}{\partial x} = \begin{pmatrix} \frac{\partial f_1}{\partial x} \\ \frac{\partial f_2}{\partial x} \\ \vdots \\ \frac{\partial f_m}{\partial x} \end{pmatrix}$$

Multivariate and Vector Functions

$$\mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}, \begin{matrix} f_1(\mathbf{x}) = y_1 \\ f_2(\mathbf{x}) = y_2 \\ \vdots \\ f_m(\mathbf{x}) = y_m \end{matrix} \longrightarrow \mathbf{f}(\mathbf{x}) = \begin{pmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_m(\mathbf{x}) \end{pmatrix} = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_m \end{pmatrix}$$

General Jacobians

$$\mathbf{f}(\mathbf{x}) = \begin{pmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_m(\mathbf{x}) \end{pmatrix} \longrightarrow \frac{\partial \mathbf{f}}{\partial \mathbf{x}} = \begin{pmatrix} \frac{\partial f_1}{\partial \mathbf{x}} \\ \frac{\partial f_2}{\partial \mathbf{x}} \\ \vdots \\ \frac{\partial f_m}{\partial \mathbf{x}} \end{pmatrix} = \begin{pmatrix} \nabla_{\mathbf{x}} f_1 \\ \nabla_{\mathbf{x}} f_2 \\ \vdots \\ \nabla_{\mathbf{x}} f_m \end{pmatrix} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \frac{\partial f_1}{\partial x_2} & \cdots & \frac{\partial f_1}{\partial x_n} \\ \frac{\partial f_2}{\partial x_1} & \frac{\partial f_2}{\partial x_2} & \cdots & \frac{\partial f_2}{\partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1} & \frac{\partial f_m}{\partial x_2} & \cdots & \frac{\partial f_m}{\partial x_n} \end{pmatrix}$$

$$\mathbf{f} \in \mathbb{R}^m, \mathbf{x} \in \mathbb{R}^n \longrightarrow \frac{\partial \mathbf{f}}{\partial \mathbf{x}} \in \mathbb{R}^{m \times n}$$

Matrix Calculus

$$\begin{array}{ccccccc}
 \mathbf{x} \in \mathbb{R}^\alpha & \longrightarrow & \mathbf{f}(\mathbf{x}) = \mathbf{u} \in \mathbb{R}^\beta & \longrightarrow & \mathbf{g}(\mathbf{u}) = \mathbf{v} \in \mathbb{R}^\gamma & \longrightarrow & h(\mathbf{v}) = y \in \mathbb{R} \\
 \mathbf{x} = \begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_\alpha \end{pmatrix} & & \mathbf{f}(\mathbf{x}) = \begin{pmatrix} f_1(\mathbf{x}) \\ f_2(\mathbf{x}) \\ \vdots \\ f_\beta(\mathbf{x}) \end{pmatrix} & & \mathbf{g}(\mathbf{u}) = \begin{pmatrix} g_1(\mathbf{u}) \\ g_2(\mathbf{u}) \\ \vdots \\ g_\gamma(\mathbf{u}) \end{pmatrix} & & \\
 \frac{\partial \mathbf{u}}{\partial \mathbf{x}} \in \mathbb{R}^{\beta \times \alpha} & & \frac{\partial \mathbf{v}}{\partial \mathbf{u}} \in \mathbb{R}^{\gamma \times \beta} & & \frac{\partial y}{\partial \mathbf{v}} \in \mathbb{R}^{1 \times \gamma} & & \\
 & & \frac{\partial y}{\partial \mathbf{x}} = \frac{\partial y}{\partial \mathbf{v}} \cdot \frac{\partial \mathbf{v}}{\partial \mathbf{u}} \cdot \frac{\partial \mathbf{u}}{\partial \mathbf{x}} & & & &
 \end{array}$$

2.5. Integration

Equally Spaced Intervals

$$\Delta x = \frac{b - a}{n}$$

Mensuration by Parts

$$S' = \sum_{k=0}^{n-1} f(a + \Delta x \cdot k) \cdot \Delta x$$

Definite Integrals

$$[n \rightarrow \infty] \rightarrow \left[\sum_{k=0}^{n-1} f(a + \Delta x \cdot k) \cdot \Delta x \rightarrow S \right]$$

$$S = \lim_{n \rightarrow \infty} \sum_{k=0}^{n-1} f\left(a + \frac{b-a}{n} \cdot k\right) \cdot \frac{b-a}{n}$$

$$\lim_{n \rightarrow \infty} \sum_{k=0}^{n-1} f\left(a + \frac{b-a}{n} \cdot k\right) \cdot \frac{b-a}{n} = \int_a^b f(x) dx$$

note! definite integrals are not areas

Indefinite Integrals

$$\int f(x) dx = F(x) + C$$

Integral Formulas

$$\int f(x) dx = F(x) + C$$

$$f(x) = a \rightarrow \int f(x) dx = ax + C$$

$$f(x) = \sin(x) \rightarrow \int f(x) dx = -\cos(x) + C$$

$$f(x) = x^n \rightarrow \int f(x) dx = \frac{1}{n+1} x^{n+1} + C$$

$$f(x) = \cos(x) \rightarrow \int f(x) dx = \sin(x) + C$$

$$f(x) = a^x \rightarrow \int f(x) dx = \frac{a^x}{\ln(a)} + C$$

$$f(x) = \frac{1}{x} \rightarrow \int f(x) dx = \ln|x| + C$$

Integration Rules

$$\int [k \cdot f(x)] dx = k \cdot \int f(x) dx$$
$$\int [f(x) \pm g(x)] dx = \int f(x) dx \pm \int g(x) dx$$

Fundamental Theorem of Calculus

$$\text{Part.2} \quad \int f(x) dx = F(x) + C \longrightarrow \int_a^b f(x) dx = F(b) - F(a)$$