OS LAB ASSIGNMENT - 3

Done By	Roll Number
N Sree Dhyuti	CED19I027

Preemptive Priority Scheduling:

```
CODE:
// N Sree Dhyuti
// CED19I027
// Lab 3 : Q1
// Inclusion of required libraries
#include <stdio.h>
// Function to sort the elements in 5 arrays consecutively : Bubble Sort
// Here arr1 is the array with respect to which the sorting is happening
// Eg : sort (AT, BT, PID, P, BT1, 1, num -1) means we are sorting the 5 arrays wrt Arrival time
and in the array range 1 to num-1
void sort(float* arr1, float* arr2, float* arr3, float* arr4, float* arr5, int start, int end)
{
       int a, b;
       for(a = start; a < end - 1; a++)
       {
               for(b = a; b < end; b++)
                      if(arr1[a] > arr1[b])
                              float temp;
                              // Swap
                              temp = arr1[b]; arr1[b] = arr1[a]; arr1[a] = temp;
                              temp = arr2[b]; arr2[b] = arr2[a]; arr2[a] = temp;
                              temp = arr3[b]; arr3[b] = arr3[a]; arr3[a] = temp;
                              temp = arr4[b]; arr4[b] = arr4[a]; arr4[a] = temp;
                              temp = arr5[b]; arr5[b] = arr5[a]; arr5[a] = temp;
                      }
               }
       }
}
```

```
// Function to check if an array has all values as zero or not
int check_array(float* arr, int num)
{
       for(int i = 0; i < num; i++)
       {
              if(arr[i] != 0)
                      return 1;
       }
       return 0;
}
// Main
int main()
{
       // Define required variables
       int num, j;
       float current_time=0,avg_wt = 0, avg_tat = 0;
       printf("Number of Processes : ");
       scanf("%d", &num);
       // Incase the user types a negative value for num
       if(num < 0)
       {
              printf("Invalid Number of processes. Try again\n");
              main();
       }
       // Create arrays for storing Process ID, Arrival time and Burst time
       // CT (Completion time, WT (Waiting time), TAT (Turn Around time), P (Priority Value)
       float PID[num], AT[num], BT[num], P[num], CT[num], WT[num], TAT[num];
       // Check Array : To update the times left for each processes to reach completion
       float BT1[num];
       // Take all necessary inputs from user
       for(int i = 0; i < num; i++)
       {
              printf("Enter PID :");
              scanf("%f", &PID[i]);
              printf("Enter Arrival time of Process %f :", PID[i]);
              scanf("%f", &AT[i]);
```

```
scanf("%f", &BT[i]);
              BT1[i] = BT[i];
              printf("Enter Priority Value of Process %f :", PID[i]);
              scanf("%f", &P[i]);
       }
       printf("OUTPUTS : \n\n");
       // While we have atleast one process which is not completed...
       while (check_array(BT1, num))
       {
              // Sort the data based on Arrival time
              sort(AT,BT,PID,P,BT1,0,num);
              // Find all the processes whose arrival time < current time
              int j = 0;
              for(j = 0; j < num; j++)
              {
                      if(AT[j] > current_time)
                             break;
              }
              //Sort those processes being considered according to their Priority Value
              // Highest priority element will be in the j-1 th position
              sort(P, AT, BT, PID, BT1, 0, j);
              j = j - 1;
              // Find the process which has the highest priority among incomplete processes
              while (BT1[j] == 0)
              {
                      j = j - 1;
              }
              // Check if two or more processes have the same priority values
              // Incase they do, choose the process with Least Arrival time to reduce the
Overall Average Waiting time
              int k = j;
              int min_at = k;
              while (P[k] == P[k - 1])
              {
                      if(AT[k] <= AT[min_at] && BT1[k] != 0)
                             min_at = k;
```

printf("Enter Burst time of Process %f:", PID[i]);

```
}
                   k--;
            if(AT[k] <= AT[min_at] && BT1[k] != 0)
            {
                   min_at = k;
            }
            BT1[min_at] = BT1[min_at] - 1;
            current_time = current_time + 1;
            printf("From time = %f to time = %f, \n Undergoing Process %f....\n",
current_time - 1, current_time, PID[min_at]);
        printf("-----\n \n");
            if (BT1[min_at] == 0)
                   // Other Calculations
                   CT[min_at] = current_time;
                   TAT[min_at] = CT[min_at] - AT[min_at];
                   WT[min_at] = TAT[min_at] - BT[min_at];
                   avg_wt = avg_wt + WT[min_at]/num;
                   avg_tat = avg_tat + TAT[min_at]/num;
            }
      }
      // Print all details
      printf("PID
                      ΑT
                               BT
                                        CT
                                                 TAT
                                                           WT\n");
      for (int i = 0; i < num; i++)
                              %f %f %f %f\n",PID[i], AT[i], BT[i], CT[i], TAT[i],
            printf("%f
                        %f
WT[i]);
      printf("-----\n \n");
      printf("Average Waiting time : %f\n", avg_wt);
      printf("Average Turn Around time : %f\n", avg_tat);
      return 0;
}
```

(1) Preemptive Priority Scheduling Algorithm

Code Explanation:

Step1: Take all inputs from user (No of processes, Arrival Time, PID, Busst Time,

Step 2: Create an additional check array BTI [] to keep a check of the o time left by each processto pinish.

SKP3: Sort the array w.r.t Arrival Time. Find all processes that are already

Step4: Of those, choose the process with highest priority value. Incase of multiple processes with same periority value, choose the one with least Arrival Time (To reduce any waiting time). If they have same arrival time too, choose the perocess with least essentime Perocess it for Isecond.

Steps: update the BTI check array with remaining times.

Step 6: Continue step 4 95 unill & all the processes are completed.

Reg. Calculations:

CT = CT = Cassed time when process finishes TAT = CT - AT WT = CT-BT ang. TAT = ETAT/n ang. WT = INT/n

Example: Schedule the following processes using preemptine priority scheduling.

PID	AT	ВТ	Priority
1	0	4	4
2	0	5	5
3	0	1	7
4	0	2	2
5	0	3	1
6	D	6	6

A So, we simply of keep choosing procedure with highest to least priorities

At time t=0, Processes: P1, P2, P3) P4, P5, P6 gantt chart:

At t=1

levocesses: P1, P2, P4, P5 (P6)

Gantt. P3 P6

At t=7,

Processes: P1, P2) P4, P5

Gantt Chart:

P3 P6 P2

Perocesses: P. P4, P5

Gantt : P2 P6 P2 P1
0 1 7 12 16

At t = 16, Perocesses: (Py) Ps

Gantt Chart:

P3 P6 P2 P1 P4 0 1 7 12 16 18

At t= 18, perocesses: Ps

Final Gantt Chart:

P3	P6	P2	P,	Py	P5
0 1	7	7	12 1	6 18	3 21

PIP	AT	BT	Priorty	CT	TAT	WAT
1	D	4	4	16	16	12
2	D	5	5	12	12	7
3	0	1	7	1		0
4	0	2	2	18	18	16
5	0	3)	21	21	18
6	0	6	6	7	7	1
			_		1	

AV9 TAT =
$$\sum TAT = 16 + 12 + 1 + 18 + 21 + 7 = 100 +$$

CODE OUTPUT FOR THE SAME EXAMPLE:

D:\SEM 5\OS\LAB\LAB3\CED19I027_Lab3_Q1.exe

```
From time = 15.000000 to time = 16.000000,
Undergoing Process 1.000000....
From time = 16.000000 to time = 17.000000,
Undergoing Process 4.000000....
From time = 17.000000 to time = 18.000000,
Undergoing Process 4.000000....
From time = 18.000000 to time = 19.000000,
Undergoing Process 5.000000....
From time = 19.000000 to time = 20.000000,
Undergoing Process 5.000000....
From time = 20.000000 to time = 21.000000,
Undergoing Process 5.000000....
PID
              AT
                             BT
                                            CT
                                                                           WT
            0.000000 3.000000 21.000000 21.000000 18.000000
0.000000 2.000000 18.000000 18.000000 16.000000
0.000000 4.000000 16.000000 16.0000000 12.0000000
5.000000
4.000000
1.000000
                                                        12.000000
2.000000
            0.000000
                           5.000000 12.000000
                                                                       7.000000
6.000000 0.000000 6.000000 7.000000 7.000000 1.000000 3.000000 0.000000 1.000000 1.000000 0.000000
Average Waiting time : 9.000000
Average Turn Around time : 12.500000
Process exited after 20.2 seconds with return value 0
Press any key to continue . . .
```

Example! Schedule the following processes using priority scheduling (preemptive)

PID	AT	BT	Periority
1	0	4	4
2	١	5	5
3	2	1	7
ч	3	2	2
5	4	3	1110
6	5	6	6

Sol At time t = 0,

Processes : (P) Gantt Chart: [P]

1 3 3 3 3 3 3

tional front chart:

At time t= 1,

Perocess: P. (P2)

Gantt chart:

P₁ P₂

	Pi	P2	B	Py	PS	P6
BT	3	4	1	2	3	6

Att=2,

Perocesses: P1, P2, (3)

gantt chart:

Pi	P2	P3	1
0	1 2		3

At t=3)

perocesses: P. P. Py

Gantter P1 P2 P3 P2

[Pi	P2	Py	Py	Ps	PL
BT	3	2	6	2	3	6

At t= 5, Revocesses: P1, P2, P4, P5, P6

PI	P2 P3	P2	PL
0	1 2 3	5	11

	PI	P2	B	P4	Ps	P6/
BT	3	2	p	2	3	0

BTUH 3 0 0 2 3 \$

Br 6 6 6 2 3 6

At t=11)

perocesses: Pi (P2) Pu, Ps Gantt chart:

2 P3 P2 P6 P2	Pal	Pal	Pal	Pa	P.
---------------	-----	-----	-----	----	----

At t = 13)

Perocesses: P. Py, Ps Gantt Chart:

0	P	0	D	0	0	D
TI	12	13	12	16	P2	1.1

At time t= 16, perocesses: (Ry)Ps

PI	P2	P3	PZ	P6	Pz	Pi	P4
0	1	2 =	3 5	5 1	1 13	3 1	6 1

| P2 P1 P4 | BT 000 0 3 0

At time t = 18,
Perocesses: (Ps)

FINAL GANTT CHART

T	0 1	P.	P.	Pa	PIL	Py	Ps
P1 P2	13	12	16	1	13 16	5 1	8 21

				-		
PID	AT	BT	PR	CT	TAT	WAT
1	0	4	4	16	16	12
2	1	5	5	13	12	7
3	2	1	7	3	1	0
4	3	2	2	18	15	13
5	4	3	1	21	17	14
6	5	6	6	11	6	0

$$\frac{6}{5} = \frac{6}{6} = \frac{6}{11} = \frac{67}{6} = \frac{67}{6} = \frac{11.166666}{6}$$

$$\frac{5}{6} = \frac{57}{6} = \frac{16+12+1+15+17+6}{6} = \frac{67}{6} = \frac{11.166666}{6}$$

$$\frac{5}{6} = \frac{57}{6} = \frac{11.166666}{6}$$

ang
$$NT = \frac{2m}{n} = \frac{6}{6}$$

ang $NT = \frac{2NT}{n} = \frac{12+7+0+13+14+0}{6} = \frac{46}{6} = \frac{7.6666}{6}$
ang $NT = \frac{2NT}{n} = \frac{12+7+0+13+14+0}{6} = \frac{46}{6} = \frac{7.6666}{6}$

CODE OUTPUT FOR SAME EXAMPLE:

```
From time = 18.000000 to time = 19.000000,
Undergoing Process 5.000000...

From time = 19.000000 to time = 20.000000,
Undergoing Process 5.000000...

From time = 20.000000 to time = 21.0000000,
Undergoing Process 5.000000...

PID AT BT CT TAT WT
5.000000 4.000000 3.000000 21.000000 17.000000 14.000000
4.000000 3.000000 2.000000 18.000000 15.000000 13.000000
1.000000 0.000000 4.000000 16.000000 16.000000 12.000000
2.000000 1.000000 5.000000 13.000000 12.000000 7.000000
6.000000 5.000000 6.000000 11.000000 6.000000 0.000000
3.000000 2.000000 1.000000 0.000000 0.000000 0.000000

Average Waiting time : 7.666666
Average Turn Around time : 11.166666

Process exited after 19.88 seconds with return value 0
Press any key to continue . . .
```

Preemptive Round Robin Scheduling:

```
CODE:
// N Sree Dhyuti
// CED19I027
// Lab 3 : Q2
// Inclusion of required libraries
#include <stdio.h>
//global variables for ready queue
int front = -1;
int rear = -1;
// Queue Structure definition
struct q
```

```
{
  //Function Prototypes
       void (*enqueue) (int* readyq, int x, struct q*, int n);
  int (*dequeue) (int* readyq, struct q*, int n);
  int (*isfilled) (int* readyq, struct q*, int n);
  int (*search) (int* readyq, struct q*, int n, int a);
};
//structure variables
void enqueue1(int* readyq, int x, struct q*, int n);
int dequeue1(int* readyq, struct q*, int n);
int isfilled1(int* readyq, struct q*, int n);
int search1(int* readyq, struct q*, int n, int a);
// Function to sort the elements in 4 arrays consecutively : Bubble Sort
// Here arr1 is the array with respect to which the sorting is happening
// Eg : sort (AT, BT, PID, BT1, 1, num -1) means we are sorting the 4 arrays wrt Arrival Time and
in the array range 1 to num-1
void sort(float* arr1, float* arr2, float* arr3, int* arr4, int start, int end)
{
       int a, b;
       for(a = start; a < end - 1; a++)
       {
               for(b = a; b < end; b++)
                       if(arr1[a] > arr1[b])
                              float temp;
                              // Swap
                              temp = arr1[b]; arr1[b] = arr1[a]; arr1[a] = temp;
                              temp = arr2[b]; arr2[b] = arr2[a]; arr2[a] = temp;
                              temp = arr3[b]; arr3[b] = arr3[a]; arr3[a] = temp;
                              temp = arr4[b]; arr4[b] = arr4[a]; arr4[a] = temp;
                       }
               }
       }
}
// Function to check if an array has all values as zero or not
int check_array(float* arr, int num)
{
       for(int i = 0; i < num; i++)
       {
               if(arr[i] != 0)
               {
```

```
return 1;
              }
       }
       return 0;
}
// Main
int main()
{
  struct q q1;
  // STRUCTURE ENCAPSULATION
  // Assigning Functions to the queue structure
  q1.enqueue = enqueue1;
  q1.dequeue = dequeue1;
  q1.isfilled = isfilled1;
  q1.search = search1;
       // Define required variables
       int num, time_quantum, p_flag = 0;
       float current_time = 0, avg_wt = 0, avg_tat = 0;
       printf("Number of Processes : ");
       scanf("%d", &num);
       // Incase the user types a negative value for num
       if(num < 0)
       {
              printf("Invalid Number of processes. Try again\n");
              main();
      }
       // Create arrays for storing Process ID, Arrival Time and Burst Time
       // CT (Completion Time, WT (Waiting Time), TAT (Turn Around Time)
       int PID[num];
       float AT[num], BT[num], CT[num], WT[num], TAT[num];
       // Check Array : To update the Times left for each processes to reach completion
       float BT1[num];
       // Ready Queue - the queue which holds the names of all processes that are to be
readily processed
       int readyq[num];
       // Take all necessary inputs from user
```

```
for(int i = 0; i < num; i++)
       {
              printf("Enter PID :");
              scanf("%d", &PID[i]);
              printf("Enter Arrival Time of Process %d :", PID[i]);
              scanf("%f", &AT[i]);
              printf("Enter Burst Time of Process %d :", PID[i]);
              scanf("%f", &BT[i]);
              BT1[i] = BT[i];
       }
       printf("Value of Time Quantum: ");
       scanf("%d",&time_quantum);
       // Sort all processes w.r.t Arrival Time
       sort(AT, BT, BT1, PID, 0, num);
       while(check_array(BT1, num))
       {
              // Find all the processes whose arrival time < current time and enqueue them in
ready queue
              int j = 0;
              for(j = 0; j < num; j++)
                     if(AT[j] > current_time)
                     {
                             break;
                     // If PID is not present in the queue, then enqueue
                     if((!(q1.search(readyq, &q1, num, PID[j]))) && BT1[j] != 0 && PID[j] !=
p_flag)
                     {
                             q1.enqueue(readyq, PID[j], &q1, num);
                     }
              // Incase the previously processed process is still incomplete, enque it
              if(p_flag != 0)
              {
                     if(!(q1.search(readyq, &q1,num, p_flag)))
                     {
                             q1.enqueue(readyq, p_flag, &q1, num);
```

```
}
              }
              int a;
              // While the ready queue is filled with atleast one process...
              if(q1.isfilled(readyq, &q1, num))
              {
                     // Dequeue a process from ready queue
                     a = q1.dequeue(readyq, &q1, num);
                     // Search for that process in the processes arrays using PID
                     int i = 0;
                     for (i = 0; i < num; i++)
                     {
                             if (PID[i] == a)
                                    break;
                     }
                     // Update current time, Time remaining for that process to complete
accordingly
                     if(BT1[i] > time_quantum)
                             current_time = current_time + time_quantum;
                             BT1[i] = BT1[i] - time_quantum;
                             p_flag = PID[i];
                     }
                     else
                     {
                             current_time = current_time + BT1[i];
                             BT1[i] = 0;
                             p_flag = 0;
                            // When a process is completed, do all calculations
                             CT[i] = current_time;
                             TAT[i] = CT[i] - AT[i];
                             WT[i] = TAT[i] - BT[i];
                             avg_wt = avg_wt + (WT[i] / num);
                             avg_tat = avg_tat + (TAT[i] / num);
                     }
              }
              else
              {
                     current_time = current_time + 1;
              }
```

```
}
      // Print all details
                                           CT
      printf("PID
                       AT
                                 BT
                                                    TAT
                                                               WT\n");
      for (int i = 0; i < num; i++)
                                %f %f %f %f\n",PID[i], AT[i], BT[i], CT[i], TAT[i],
             printf("%d
                           %f
WT[i]);
      printf("-----\n \n");
      printf("Average Waiting Time : %f\n", avg_wt);
       printf("Average Turn Around Time: %f\n", avg_tat);
      return 0;
}
// Structure Encapsulated function to enqueue an element into a queue
void enqueue1(int* readyq, int x, struct q* stk, int n)
{
  // When queue is empty
      if(front == -1 && rear == -1)
  {
    front = 0;
    rear = 0;
    readyq[rear] = x;
  }
  // When queue is full
  else if((rear + 1) % n == front)
  {
    printf("Given circular queue is full.\n");
  }
  else
    rear = (rear + 1) % n;
    readyq[rear] = x;
  }
}
// Structure Encapsulated function to dequeue an element from a queue
int dequeue1(int* readyq, struct q* stk, int n)
{
```

```
//When queue is empty
       if(front == -1 && rear == -1)
  {
     printf("No data has been inputted by user.\n");
     return -1;
  }
  // When only one element is left in queue
  else if(front == rear)
  {
     int e = front;
     front = -1;
     rear = -1;
     return readyq[e];
  }
  else
     int e = front;
     front = (front + 1) % n;
     return readyq[e];
  }
}
// Structure Encapsulated function to check if a queue is filled or empty
int isfilled1(int* readyq, struct q* stk, int n)
{
  //When queue is empty
       if(front == -1 && rear == -1)
     return 0;
  else
     return 1;
}
// Structure Encapsulated function to search for a particular element in the queue
int search1(int* readyq, struct q* stk, int n, int a)
{
       if(front == -1 && rear == -1)
               return 0;
       else
       {
               for(int i = front; i <= n; i++)
               {
                      if(readyq[i%n] == a)
                              return 1;
                      i = i \% n;
```

}

}

```
N. See Dhyat
                                      CED19 I 027
(2) Preemptive Round Robin Scheduling Algorithm
 Code explanation:
Step1: Take all inputs from the uses.
    (No of processes, Arrival Time, Burst time, Time grantin)
Step2: Create an additional Check array BTIET
     to keep a check of the time left by the
     each process to finish.
Step3: Sort the arrays w.r.t arrival Time
       Find all the processes that are already
Step4: Enqueue othose professes (if not enqueed) in the Ready Queue.
       Dequeue one process & complete the process by the value of time quantum.
Step 6: If the perocess is to be still & completed,
         ens check for all processes that are
        arrived at this newtime & then enque
        this process too if required.
        Update BTI array to keep a check of
         times remaining for each process.
        Repeat steps 3,4,5,6,7 untill all
        the processes are completed.
      CT= time at which a process is completed
Rig. Calculations:
    TAT= CT-AT
     WT= TAT- BT
     ETAT = ETAT
          ang NT = ZNT
```

Example: Schedule the following processes using preemptive round robin scheduling.

PID	AT	ВТ
13	FO	845
2	0	5
3	0	1
4	0	2.
5	D	3
6	0	6
6		0

Time Quantom = 2

At time t=0

perocesses: (Pi)P2, P3, P4, P5, P6

Gantt Chart:

Employe fully 93

BT P2 P3 P4 P5 P6

Left 2 5 1 2 3 6

At time t=2

Ready Queare: P2 P3 P4 P5 P6 P1

Gantt Chart:

	PI	P2	P3	Py	P5	PL
BT	2	3	1	2	3	6
les	_				0	-

At t=4,

Ready Que ne: Pz Py Ps P6 P1 P2

	Pi	PZ	Pf	Py	PS	R
BTest	2	3	Ø	2	4	6

At t=5, Ready Queue: Py Ps P6 P1 P2

Gantt Chart:

Pi	1	02	P3	PY	T
0	2	4	5		7

Ready Queue: Ps P6 P1 P2 Gantt Chart: P1 P2 P3 P4 P5 At t= 9, Ready Queue: P6 P1 P2 P5 Gantt Chart: P1 P2 P3 P4 P5 P6 P1 P2 P3 P4 P5

2 4 5 7 9 11 uft 2.3 0 9 2 At t=11, Ready Queue: P, P2 P5 P6 Gant Chart P1 P2 P3 P4 P5 P6 P1 BT O 3 Ready Quene: P2 P5 P6 Gantt chart: P1 P2 P3 P4 P5 P6 P1 P2
D 2 4 5 7 9 11 13 15 BT D1 D D 2 4 At t=15, Ready Quene: P5 P6 P2 P1 P2 P3 P4 P5 P6 P1 P2 P5 BT D 10 B B At .t= 16, Ready Queue: P6 P2 P1 P2 P3 P4 P5 P6 P1 P2 P5 P6 0 2 4 5 7 9 11 13 15 16 18

At t=18, Ready Queve: P2 P6

	PI	1 1/2	P3/	PA	Pt	P-6	1
BITH	B	10	6	10	10	2	7

At t= 19, Ready Queue: Po

& FINAL GANTT CHART:

P ₁ P ₂	1 - 1	5	p_	0.	p.	P2	Pel	P6	P2	P6_
P1 P2	P3	Pu	15	16	11		13	18	1	9

1	PID	AT	BT	CT	TAT	WT
Ì	1	0	4	13	13	9
1	2	0	5	19	19	14
	3	0)	5	5	4
	4	0	2	7	7	5
	5	0	3	16	16	13
	6	0	6	21	21	15

$$Avg \cdot TAT = 13+19+5+7+16+21 = 13.500001$$

Avg.
$$WT = \frac{2WT}{n} = \frac{9+14+4+5+13+15}{6} = 10$$

CODE OUTPUT FOR THE SAME EXAMPLE:

D:\SEM 5\OS\LAB\LAB3\CED19I027_Lab3_Q2.exe

```
Enter Burst Time of Process 2 :5
Enter PID :3
Enter Arrival Time of Process 3 :0
Enter Burst Time of Process 3 :1
Enter PID :4
Enter Arrival Time of Process 4:0
Enter Burst Time of Process 4 :2
Enter PID :5
Enter Arrival Time of Process 5 :0
Enter Burst Time of Process 5 :3
Enter PID :6
Enter Arrival Time of Process 6:0
Enter Burst Time of Process 6 :6
Value of Time Quantum : 2
                       ВТ
PID
         AT
                                    CT
                                                   TAT
                                                                          WT

      0.000000
      4.000000
      13.000000
      13.000000
      9.000000

      0.000000
      5.000000
      19.000000
      19.000000
      14.000000

      0.000000
     0.000000
                    1.000000
                                 5.000000
                                               5.000000 4.000000
                                               7.000000
                                                             5.000000
                    2.000000
     0.000000
                                 7.000000
                                              16.000000
                    3.000000
                                  16.000000
                                                             13.000000
      0.000000
      0.000000
                                   21.000000
                                                21.000000
                    6.000000
                                                               15.000000
Average Waiting Time : 10.000000
Average Turn Around Time : 13.500001
Process exited after 33.64 seconds with return value 0
Press any key to continue . . .
```

Example: Schedule the following process using premptive Round Robin Scheduling

PID	AT	BT
١	0	4
2		5
3	2	1
4	3	2
5	4111	311
6	5	6

Time Quantum=2

So) At time t=0
Ready Queue: Pi

Gantt PI

P/	Pi-	Pz	P3	P4	P5	Pa
Teff	2	5	1	2	3	6

1 3 4 3 9 9

At t=2, Ready Queue: P2P3P1

Gantt Chast:

PI-	PZ
0 7	

BT

PI	P2	P3	Py	B	P6
2	3	1	2	3	6

At t=4, Ready Queue: @P3P1P4P5P2

Gantt Chart:

PI	Pr	Pz
11	12	13

	PI	PL	P3	Py	P5	P6
ST	2	3	9	2	3	6

At t=5, Ready Queue: P1 P4 P5 P2 P6

Gantt Chart:

-	PI	P2	P3	Pi
0	2		4 5	

	PI	1/2	P2	194	B	P6
BT	Ø		_	2	3	6

GEN 1105
At t = 7
Ready queve: Py P5 Poz P6
Gantt Chast: BT 6 3 6 9 3 6
P ₁ P ₂ P ₃ P ₁ P ₄ 0 2 4 5 7 9
At $t=9$, 3 3 3 3 3 3 3 3 3 3 3
Ready Queue: P5 P2 P6
Gantt Chart:
P1 P2 B P1 P4 P5 0 2 4 5 7 9 11 BT 0 3 0 0 1 6
At $t=11$,
Ready Queue: P2 P6 P5
Gantt chart:
P1 P2 P3 P1 P4 P5 P2 BT P2 P3 P4 P5 P4
P1 P2 P3 P1 P4 P5 P2 Left 0 1 6 1 6
At t=13,
Ready Queve: P6 P5 P2
Gantt Chart:
P. P2 P3 P, P4 P5 P2 P6 BT 6 1 9 9 1 4
Gantt Chast: P1 P2 P3 P1 P4 P5 P2 P6 0 2 4 5 7 9 11 13 15 BT 0 1 0 0 1 4
21 2 15
Ready Queve: Ps P2 P6
Gantt Chart: P1 P2 P3 P1 P4 P5 P2 P6 P5 D 2 4 5 7 9 11 13 15 16 BT D 1 0 0 9 4
At t=16, Ready Queue: P2 P6
Ready Gulul: 1216
(-1220000 P P-P) 25 0 DO 25 P6
P1 P2 P3 P1 P4 P5 P2 P6 P5 P2 P6 P5 P2 P6 P6 P6 P6 P7 P2 P6 P5 P6

At t=17, Ready Quelle: PG FINAL GANTT CHART

1,1001

P	1	P2	P3	PI	Py	P5	P2	P6	P5	PZ	P6
0	2	L	1 5	-	7 0	7	11 11	3	15 1	6 1	7 2

AT	BT	CT	TAT	WT
0	4	7	7	3
1	5	17	16	s II a
2	1	5	3	2
3	2	9	6	4
4	3	16	12	9
5	6	21	16	10
		0 4 1 5 2 1 3 2 4 3	0 4 7 1 5 17 2 1 5 3 2 9 4 3 16	0 4 7 7 1 5 17 16 2 1 5 3 3 2 9 6 4 3 16 12

Avg. TAT =
$$\frac{2TAT}{n}$$

= $\frac{7+16+3+6+12+16}{6}$
= 10

Avg :
$$WT = \frac{2WT}{N}$$

= $\frac{3+11+2+4+9+10}{6}$
= $\frac{6}{5}$

CODE OUTPUT FOR THE SAME EXAMPLE:

D:\SEM 5\OS\LAB\LAB3\CED19I027_Lab3_Q2.exe

```
Enter PID :3
Enter Arrival Time of Process 3 :2
Enter Burst Time of Process 3 :1
Enter PID :4
Enter Arrival Time of Process 4:3
Enter Burst Time of Process 4 :2
Enter PID :5
Enter Arrival Time of Process 5 :4
Enter Burst Time of Process 5 :3
Enter PID :6
Enter Arrival Time of Process 6 :5
Enter Burst Time of Process 6 :6
Value of Time Quantum : 2
                                          7.000000 TAT
PID
           AT
                       BT
                                      CT
                                                                  WΤ
                   4.000000 7.000000
      0.000000
                                                     3.000000
      1.000000
                  5.000000
                              17.000000
                                           16.000000
                                                        11.000000
     2.000000
                  1.000000
                              5.000000
                                          3.000000
                                                      2.000000
                              9.000000
     3.000000
                  2.000000
                                          6.000000
                                                      4.000000
                               16.000000
                   3.000000
                                           12.000000
                                                        9.000000
      4.000000
      5.000000
                   6.000000
                               21.000000
                                            16.000000
                                                         10.000000
Average Waiting Time : 6.500000
Average Turn Around Time : 10.000000
Process exited after 19.21 seconds with return value 0
Press any key to continue . . .
```

THE END