

Mobility Data Representations

for Spatiotemporal Tasks



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INTRODUCTION

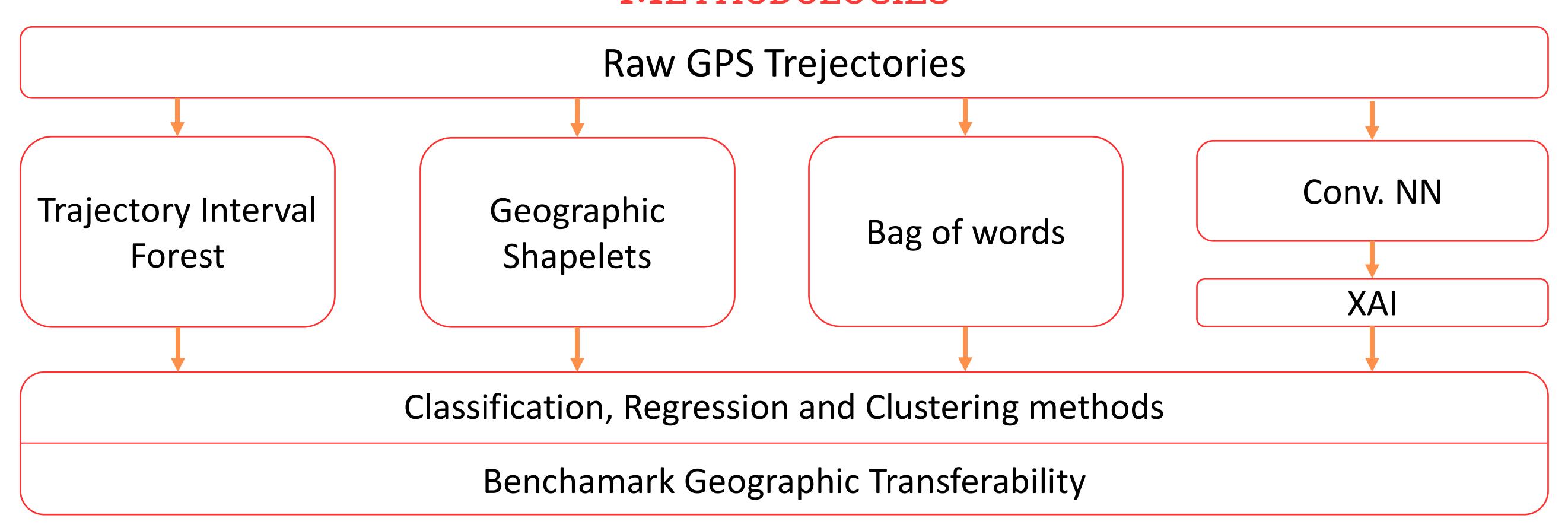
Mobility data (MD) are everywhere. Smartphones and connected cars, as well as tracking devices with GPS capabilities, produce enormous amounts of spatiotemporal data. The most similar field in the literature is time series (TS), which involves streams of observations over a finite period. TS research is more extensively explored, particularly in classification tasks, where a wide variety of methods exist [1].

Comparing TS with mobility literature, we can observe that the former tends to focus more on report-style publications, emphasizing the results of the analysis rather than the methodologies employed.

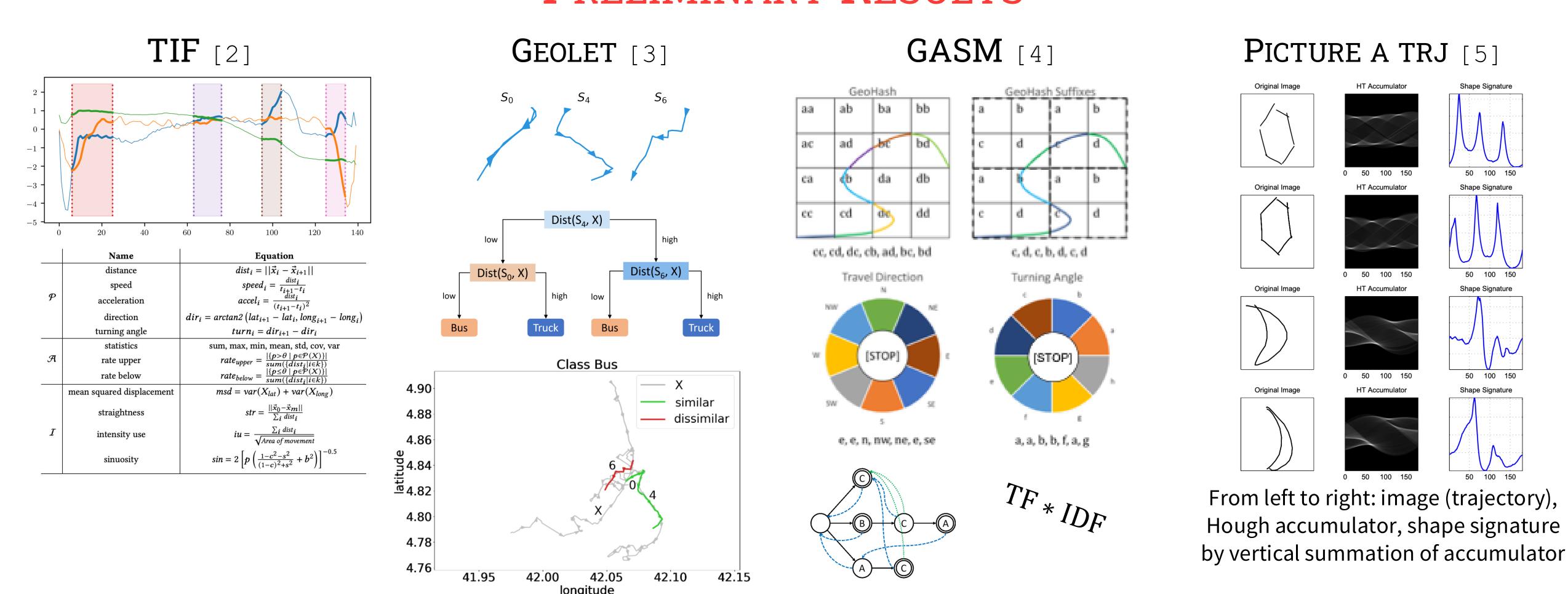
Another key challenge in MD analysis is achieving geographic transferability of models. A model trained on data from one region may perform poorly when applied to another due to differences in the road network patterns or population behavior.

During my PhD, I'm focusing on developing fast, reusable, and effective trajectory representations suitable for multiple machine learning tasks, with an emphasis on geographic transferability and interpretability.

METHODOLOGIES



PRELIMINARY RESULTS



ON GEOGRAPHIC TRANSFERABILITY

Transfer a Local Models Framework:

- 1. Source domain identification
- 2. Source-target domain linking
- 3. Target Domain refining



Ensemble of Local Models

Ensemble of Local models:

- 1. Most similar city transfer,
- 2. Weighted model ensemble
- 3. Weighted data sampling

Takeaway messages:

- 1. The transfer is better between similar cities
- 2. Accuracy(A \rightarrow B) != Accuracy(B \rightarrow A)

	Destination Dataset (predict)													
			Rome			New York			Athens			All cities		
Source Dataset (fit)			No-train	Train D	Train OD	No-train	Train D	Train OD	No-train	Train D	Train OD	No-train	Train D	Train OD
	Rome	KNN	0.900	-	-	-0.033	0	-0.041	-0.058	-0.075	-0.075	-0.159	0.017	0.034
		DT	0.967	-	-	-0.484	0.025	-0.530	-0.564	-0.008	-0.481	-0.042	-0.009	-0.468
		RF	0.975	-	-	0.025	0	0	-0.017	-0.017	-0.008	0.008	0	0.017
	NY	KNN	0.025	0.033	0.033	0.942	-	-	-0.025	-0.033	-0.017	0.017	0.008	0.008
		DT	-0.041	0.008	0.016	0.950	-	-	-0.033	-0.017	-0.025	-0.017	-0.025	0
		RF	0	0.008	0	0.958	-	-	-0.017	-0.033	-0.025	0	0.017	0.025
	Athens	KNN	0.025	0.033	0.033	0.025	0.008	0.025	0.975	-	_	0.067	0.025	0.059
		DT	-0.041	0.008	0.016	0.033	-0.016	0.042	1.000	-	-	-0.034	-0.017	0.008
		RF	0	0.008	0	0.034	0.017	0.025	1.000	-	-	0.017	0.025	0.025
	All	KNN	0	0.008	-0.025	-0.024	-0.024	-0.008	-0.066	-0.041	-0.057	0.933		
		DT	0.025	0.016	0.025	0.042	0.050	0.050	-0.025	-0.017	-0.008	0.992		
		RF	0.008	0.008	0.017	0.017	0.034	0.025	-0.017	-0.025	-0.017	0.975		

Table 1: F1-score deltas of geographically transferred models. Negative values indicate that the model trained and tested on the destination city performs better.

CONCLUSIONS

To sum up, we proposed TIF based on a survey of MD analysis, which served as one of the baselines for my work. Then, we introduced Geolet, the first shapelet-based method for raw Trajectories, and began investigating its capabilities and limitations.

We plan to integrate the developed trajectory transformations with other methods we are collaborating on [6], creating interpretable pipelines for Mobility Data Analytics.

Additionally, we plan to integrate deep learning techniques, for example generative models, to produce the discriminative sub-trajectories used by Geolet in the transformation.

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