# GraspTracker: tracking user grab posture with built-in sensors on mobile devices

## Team GraspTrackers

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#### I. RESEARCH PROBLEM & LITERATURE REVIEW

Mobile devices are used in countless user contexts, which constantly change over time. To provide the best user experience in mobile device use, the interaction method should be aware of the users context and adapt to it in real-time. Thus, it is important for mobile devices to grasp the user context. Especially, the hand posture of the user should be considered as a critical factor, since touching is the most dominant interaction method. Prior works [7, 8] revealed that there is a difference in manipulating mobile devices depending on the hand postures. However, our mobile devices yet do not provide the user's hand posture context, thus cannot be adapted accordingly.

To address this problem, several works have been proposed. Lung-Pan Cheung et al. [3], Kim et al. [4], and Harrison et al. [5] used additional capacitive touch sensors to sense how the users grab mobile devices. However, they leveraged additional sensing devices that are not usually equipped with commodity mobile devices, incurring additional costs and inconveniences to users.

To overcome prior works' limitation, Mayank Goel et al. [2] detected hand posture on mobile phones by combining the three features: touch size, the shape of the swipe arc, rotation of the device, which can be measured using built-in sensors. Nonetheless, it senses the hand posture based on the user's already-taken action including swipe and touch. There would be some time gap between the user's actual hand posture change and the prediction by the application, which can possibly degrade the user's QoE.

In this study, we aim to solve the stated problem from the following perspectives: tracking user grab posture transition (i) only using built-in sensors, and (ii) in real-time without time lag.

### II. PLAN & DELIVERABLES

Until the end of this semester, we will build an android application that tracks the user's real-time grab posture. Grasp-Tracker will be evaluated using predefined grasp postures which are widely used by users as ground truth [6].

We will decide whether we have succeeded or not by the following criteria. (i) The hand posture classification accuracy is above 85%, and (ii) whether the user is satisfied with the delay between posture change and GraspTracker detection. The criteria performance was chosen based on state-of-the-art using built-in sensors [2].

Our plan for this semester is as follows:

$10/1 \sim 10/15$	Study android programming Reproduce GripSense [2]
10/16 ~ 10/26	Gather sensor data &
	determine what sensor to use
10/27 ~ 11/27	Implement classifier &
	In-lab experiment
$11/28 \sim 12/5$	Evaluation & user test
$12/6 \sim 12/9$	Project demo preparation

#### III. ROLE OF EACH MEMBER

For a literature search, demo and presentation, we will have same weight on preparation. For the other research processes, we distributed as follows.

Seungjoo Lee	Android app building Sensor data acquiring & processing
HyungJun Yoon	Machine learning classifier Evaluation & user test

IV. REFERENCES

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