Mathematician spotlight: Sarah Koch, Associate Professor, University of Michigan

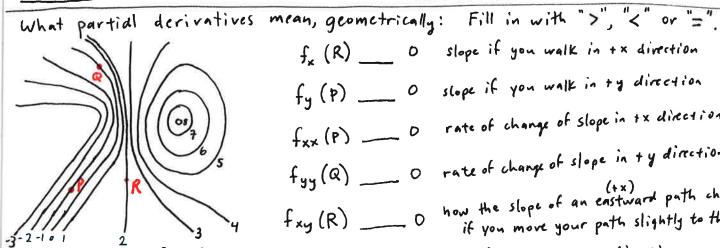
- Complex dynamics, complex analysis

- comes with beautiful pictures - search for "Julia set" online

Last time: O linear approximation of a function f: Rm > 1Rn

2) second partial derivatives fxx, fxy, fyy (etc. for more variables).

This time: Explore those more, plus the Chain Rule.



fx (R) \_\_\_ O slope if you walk in +x direction

fy (P) \_\_\_ O slope if you walk in ty direction

fxx (P) \_\_ O rate of change of slope in +x direction

fyy (Q) \_\_\_ O rate of change of slope in ty direction

fxy (R) \_\_\_\_ 0 how the slope of an eastward path changes,

fxy (R) \_\_\_\_ 0 if you move your path slightly to the north

(ty).

fy (R) \_\_\_ o slope if you walk in ty direction

Level curves of f(xiy) Example of linear approximation: Find the (xiy) woordinates of the following points:

 $(r,\theta)=(2.1,\frac{\pi}{3}-0.1)\Rightarrow (x_1y)=\frac{r}{2}$ Homom, need a calculator or linear approximation.

Then  $Df = \begin{bmatrix} 2x/2r & 2x/20 \\ 2y/2r & 2y/20 \end{bmatrix} = \begin{bmatrix} ---- \\ ---- \end{bmatrix}$ . Let f: R<sup>2</sup> → R<sup>2</sup> be defined by  $f(r,\theta) = \begin{bmatrix} r \cdot \cos \theta \\ r \cdot \sin \theta \end{bmatrix} = \begin{bmatrix} x \cdot (r,\theta) \\ y \cdot (r,\theta) \end{bmatrix}$ 

We want the linear approximation at \$\vec{a} = (2, \vec{z}). So let's plug in:

 $\Rightarrow L(2.1, \frac{\pi}{3}-0.1) = \begin{bmatrix} 1\\ \sqrt{3} \end{bmatrix} + \begin{bmatrix} \frac{1}{2} & -\sqrt{3}\\ \frac{5}{2} & 1 \end{bmatrix} \begin{bmatrix} 0.1\\ -0.1 \end{bmatrix} \approx \begin{bmatrix} 1.223\\ 1.719 \end{bmatrix}$ L(r,0)= f(な) + Df(な)(ナーな)  $\begin{bmatrix} 1 \\ \sqrt{3} \end{bmatrix} + \begin{bmatrix} \frac{1}{2} & -\sqrt{3} \\ \sqrt{3}/2 & 1 \end{bmatrix} \begin{bmatrix} r-2 \\ \theta - \frac{\pi}{3} \end{bmatrix}$ 

actual value is [1.226] wow, so close! [1.705]

It seems like we can differentiate anything! How about functions of other functions?

Example: Let f(xiy) = x2y and suppose x and y are also functions:

x(sit) = st To find of and of, we can just plug in:

 $f(s,t)=(st)^2\cdot e^{st}$ This looks like a tedious pain. ⇒ of/os = Let's use the Chain Rule!

