Universitatea Babeș-Bolyai, Facultatea de Matematică și Informatică

Secția: Informatică engleză Curs: Dynamical Systems

Primăvara 2025

## Lecture 14 - List of problems

- **1.** How many solutions has the following problem: a)  $x'' + t^2x = 0$ , x(0) = 0? b)  $x'' + t^2x = 0$ , x(0) = 0, x'(0) = 0? c)  $x'' + t^2x = 0$ ; x(0) = 0, x'(0) = 0, x''(0) = 1?  $\diamond$
- **2.** Find a range of values for h such that the attractor equilibrium point of  $x' = x^2 + 5x + 6$  is also an attractor fixed point of the discrete dynamical system associated to the Euler's numerical formula with stepsize h > 0 for the given differential equation.  $\diamond$ 
  - 3. We consider the pray-predator system

$$\dot{x} = x(1-y), \quad \dot{y} = -y(2-x).$$

- (a) Find the expression of a first integral in  $(0, \infty) \times (0, \infty)$ . Check it using the corresponding first order partial differential equation.
  - (b) If (2,1) is an equilibrium point, is it hyperbolic?  $\diamond$
- **4.** Let  $a_{11}, a_{12}, a_{21}, a_{22} \in \mathbb{R}$  be such that  $a_{12} \neq 0$ . Show that the roots of the characteristic equation corresponding to the second-order difference equation obtained by reducing the linear system

$$x_{k+1} = a_{11}x_k + a_{12}y_k, \quad y_{k+1} = a_{21}x_k + a_{22}y_k$$

are the eigenvalues of the matrix associated to this system.  $\diamond$ 

**5.** Prove that the map  $f: \mathbb{R} \to \mathbb{R}$ ,  $f(x) = m + \varepsilon \sin x$ , where m > 0 and  $0 < \varepsilon < 1$ , has a unique fixed point which is a global attractor. The equation  $x = m + \varepsilon \sin x$  is known as *Kepler equation* and arises in the study of planetary motion.  $\diamond$