Convolution Filtering (Data set: BOS)										
	k = 2 d = (2, 0)	k = 2 d = (2, 1)	k = 2 d = (3, 0)	k = 3 d = (2, 0)	k = 3 d = (2, 1)	k = 3 d = (3, 0)	k = 5 d = (2, 0)	k = 5 d = (2, 1)	k = 5 d = (3, 0)	
BOSTAXI_256 _256_S										
BOSTAXI_256 _256_S_nonN eg										
out_Identity_1. 0E+6_e1.0E-1						3	- Ballet	- Ballan	- 3	
out_Identity_1. 0E+6_e1.0E-1 _nonNeg									- Aller	
out_ldentity_1. 0E+8_e1.0E-1									-	
out_Identity_1. 0E+8_e1.0E-1 _nonNeg										
out_ldentity_1. 0E+8_e1.0E-3						- 80	-	-	- Allen	
out_Identity_1. 0E+8_e1.0E-3 _nonNeg			-			-	-	**	-	

Bilateral Filtering				,				,	,	
					d = 3 s = 300	d = 5 s = 10	d = 5 s = 50	d = 5 s = 70	d = 5 s = 150	d = 5 s = 300
BOSTAXI_256_2 56_S										
BOSTAXI_256_2 56_S_nonNeg										
	. /	. /	. /	. /	. /		. /	. /	. /	. / *
out_Identity_1.0E +6_e1.0E-1										
out_Identity_1.0E +6_e1.0E-1_non Neg										
out_Identity_1.0E +8_e1.0E-1										
out_Identity_1.0E +8_e1.0E-1_non Neg										
out_Identity_1.0E +8_e1.0E-3										
out_Identity_1.0E +8_e1.0E-3_non Neg						+				

d = 9 s = 10	d = 9 s = 50	d = 9 s = 70	d = 9 s = 150	d = 9 s = 300	d = 50 s = 10	d = 50 s = 50	d = 50 s = 70	d = 50 s = 150	d = 50 s = 300
				-					
1	1	. /	1	1.1	. /		. /		
				-					
. /	1.1	1.1	1	1.1	. /				
				- and the					
				- Total					
- Andrews									
				-				-	