

DIAN MAULIDA

FINAL PROJECT MACHINE LEARNING DEVELOPER

Image Classification

August, 2021



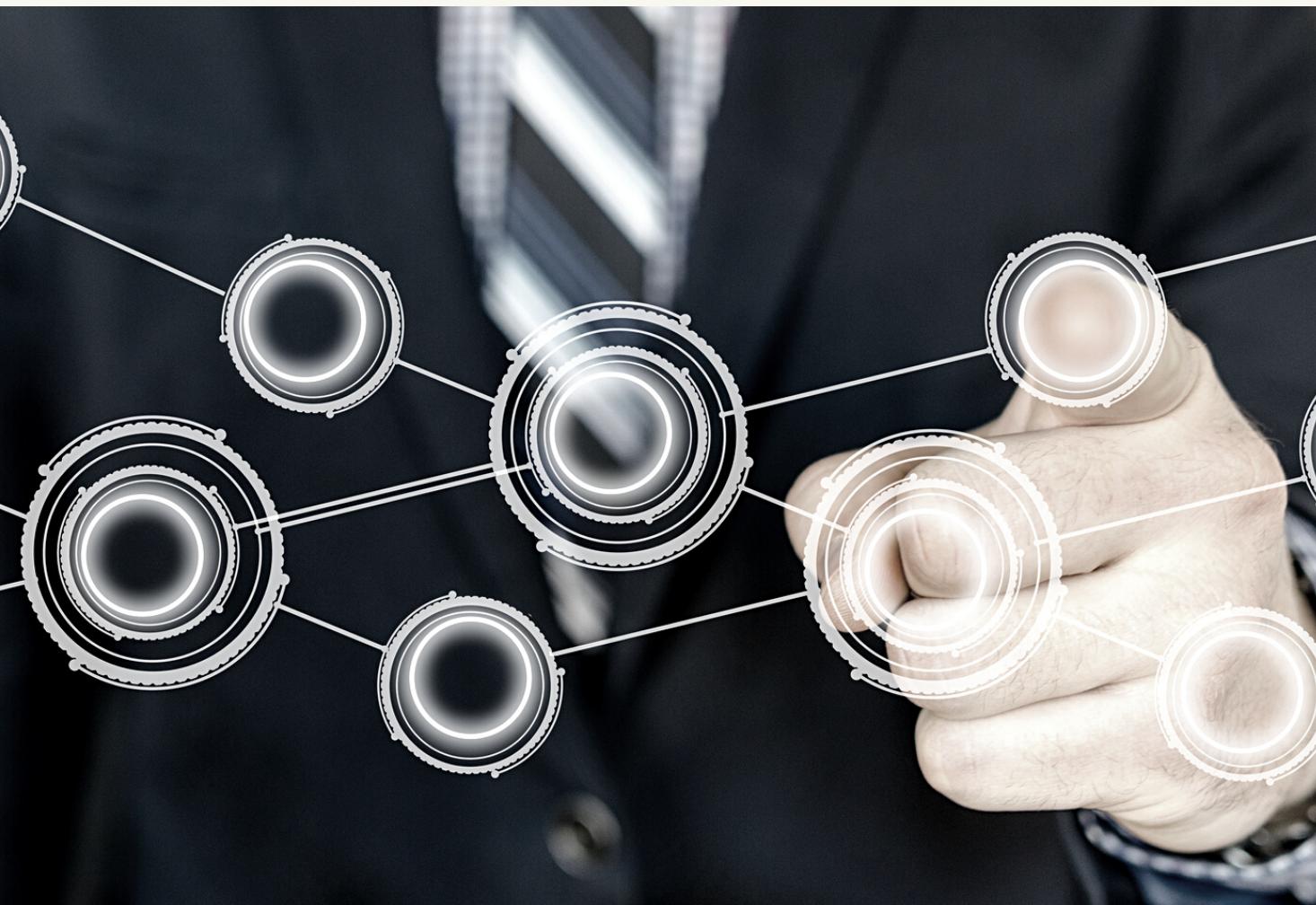
PURPOSE

CREATE AN ARTIFICIAL NEURAL NETWORK PROGRAM USING TENSORFLOW THAT IS ABLE TO RECOGNIZE THE SHAPE OF A HAND THAT FORMS SCISSORS, ROCK, OR PAPER.

Dataset:

<https://github.com/dicodingacademy/assets/releases/download/release/rockpaperscissors.zip>

STAGES



1

Import TensorFlow on
Google Colab

2

Download dataset
and extract files by
zip method

3

Augment and
separate data

4

Build a sequential
model

5

Train the model to get
the desired accuracy

6

Test the model

PROGRAM SYNTAX



+ Kode + Teks

Final Submission - Machine Learning Developer

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Hubungan | ↗ ↘ ↙ ↖ ↛ ↜ ↝ ↞ ↞ ↞ ↞

▼ Mengimport Tensorflow

```
[ ] import tensorflow as tf
from tensorflow.keras.optimizers import RMSprop
from tensorflow.keras.preprocessing.image import ImageDataGenerator
```

▼ Mengakses Dataset

Mengunduh dataset

```
[ ] !wget --no-check-certificate \
https://github.com/dicodingacademy/assets/releases/download/release/rockpaperscissors.zip
--2021-07-28 04:58:20-- https://github.com/dicodingacademy/assets/releases/download/release/rockpaperscissors.zip
Resolving github.com (github.com)... 140.82.112.4
Connecting to github.com (github.com)|140.82.112.4|:443... connected.
HTTP request sent, awaiting response... 302 Found
Location: https://github-releases.githubusercontent.com/389502449/e56456b9-62a2-4c27-9318-e26876f42b7d?X-Amz-Algorithm=AWS4-HMAC-SHA256&X-Amz-Credential=AKIAIWNJYAX4CSVEH53A%2F20210728%2Fus-east-1%2Faws%2F际
--2021-07-28 04:58:20-- https://github-releases.githubusercontent.com/389502449/e56456b9-62a2-4c27-9318-e26876f42b7d?X-Amz-Algorithm=AWS4-HMAC-SHA256&X-Amz-Credential=AKIAIWNJYAX4CSVEH53A%2F20210728%2Fus-east-1%2Faws%2F际
Resolving github-releases.githubusercontent.com (github-releases.githubusercontent.com)... 185.199.108.154, 185.199.109.154, 185.199.110.154, ...
```

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```
[ ] --2021-07-28 04:58:20-- https://github-releases.githubusercontent.com/389502449/e56456b9-62a2-4c27-9318-e26876f42b74?X-Amz-Algorithm=AWS4-HMAC-SHA256&X-Amz-Credential=AKIAIWNJYAX4CSVEH53A%2F2
[ ] Resolving github-releases.githubusercontent.com (github-releases.githubusercontent.com)... 185.199.108.154, 185.199.109.154, 185.199.110.154, ...
[ ] Connecting to github-releases.githubusercontent.com (github-releases.githubusercontent.com)|185.199.108.154|:443... connected.
[ ] HTTP request sent, awaiting response... 200 OK
[ ] Length: 322873683 (308M) [application/octet-stream]
[ ] Saving to: 'rockpaperscissors.zip.1'

[ ] rockpaperscissors.z 100%[=====] 307.92M 150MB/s in 2.0s
[ ] 2021-07-28 04:58:22 (158 MB/s) - 'rockpaperscissors.zip.1' saved [322873683/322873683]

Mengekstrak file zip

[ ] import zipfile
[ ] import os

[ ] local_zip = '/content/rockpaperscissors.zip.'
[ ] zip_ref = zipfile.ZipFile(local_zip, 'r')
[ ] zip_ref.extractall('/content')
[ ] zip_ref.close()

▼ Melakukan Augmentasi & Pemisahan Data

Membuat folder

[ ] folder_kertas = os.path.join('/content/rockpaperscissors/paper')
[ ] folder_batu = os.path.join('/content/rockpaperscissors/rock')
[ ] folder_gunting = os.path.join('/content/rockpaperscissors/scissors')

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[ ] folder_batu = os.path.join('/content/rockpaperscissors/rock')
[ ] folder_gunting = os.path.join('/content/rockpaperscissors/scissors')

[ ] print('Jumlah gambar kertas:', len(os.listdir(folder_kertas)))
[ ] print('Jumlah gambar batu:', len(os.listdir(folder_batu)))
[ ] print('Jumlah gambar gunting:', len(os.listdir(folder_gunting)))

[ ] Jumlah gambar kertas: 712
[ ] Jumlah gambar batu: 726
[ ] Jumlah gambar gunting: 750

Menampilkan nama file

[ ] file_kertas = os.listdir(folder_kertas)
[ ] print("Kertas:", file_kertas[:3])
[ ] file_batu = os.listdir(folder_batu)
[ ] print("Batu:", file_batu[:3])
[ ] file_gunting = os.listdir(folder_gunting)
[ ] print("Gunting:", file_gunting[:3])

[ ] Kertas: ['RFXh2XIDlH7xb0th.png', 'aJeRpPY3UVBErDTY.png', 'HuunhoTMXTrSTZ2.png']
[ ] Batu: ['Shrgl23ISlh4Yu.png', 'goBJj8kMSQbpQZT.png', 'Khsb4fyDizjyXfbP.png']
[ ] Gunting: ['pjOgxx8uf2XPdfu.png', 'xPMvBwgZrdijzTm.png', 'dpmWj9s5ily8GuyY.png']

Mengelompokkan data

[ ] base_dir = "/content/rockpaperscissors/rps-cv-images/"
[ ] train_dir = os.path.join(base_dir, "train")
[ ] validation_dir = os.path.join(base_dir, "val")
```

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```
[ ] os.listdir("/content/rockpaperscissors/rps-cv-images/train")
[ ] os.listdir("/content/rockpaperscissors/rps-cv-images/val")
[ ] ['rock', 'scissors', 'paper']

[ ] # membuat direktori kertas pada direktori data training
[ ] train_kertas = os.path.join(train_dir, "kertas")

[ ] # membuat direktori batu pada direktori data training
[ ] train_batu = os.path.join(train_dir, "batu")

[ ] # membuat direktori gunting pada direktori data training
[ ] train_gunting = os.path.join(train_dir, "gunting")

[ ] # membuat direktori kertas pada direktori data validasi
[ ] validation_kertas = os.path.join(validation_dir, "kertas")

[ ] # membuat direktori batu pada direktori data validasi
[ ] validation_batu = os.path.join(validation_dir, "batu")

[ ] # membuat direktori gunting pada direktori data validasi
[ ] validation_gunting = os.path.join(validation_dir, "gunting")

[ ] train_datagen = ImageDataGenerator(
[ ]     rescale=1./255,
[ ]     rotation_range=20,
[ ]     horizontal_flip=True,
[ ]     shear_range = 0.2,
[ ]     fill_mode = 'nearest')

[ ] test_datagen = ImageDataGenerator(
[ ]     rescale=1./255,
```

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```
[ ] test_datagen = ImageDataGenerator(
[ ]     rescale=1./255,
[ ]     rotation_range=20,
[ ]     horizontal_flip=True,
[ ]     shear_range = 0.2,
[ ]     fill_mode = 'nearest')

[ ] train_generator = train_datagen.flow_from_directory(
[ ]     train_dir, # direktori data latih
[ ]     target_size=(150, 150), # mengubah resolusi seluruh gambar menjadi 150x150 piksel
[ ]     batch_size=4,
[ ]     # karena ini merupakan masalah klasifikasi 3 kelas maka menggunakan class_mode = 'categorical'
[ ]     class_mode='categorical')

[ ] validation_generator = test_datagen.flow_from_directory(
[ ]     validation_dir, # direktori data validasi
[ ]     target_size=(150, 150), # mengubah resolusi seluruh gambar menjadi 150x150 piksel
[ ]     batch_size=4, # karena ini merupakan masalah klasifikasi 3 kelas maka menggunakan class_mode = 'categorical'
[ ]     class_mode='categorical')

[ ] Found 1314 images belonging to 3 classes.
[ ] Found 874 images belonging to 3 classes.
```

▼ Membangun model sequential

```
[ ] model = tf.keras.models.Sequential([
[ ]     tf.keras.layers.Conv2D(16, (3,3), activation='relu', input_shape=(150, 150, 3)),
[ ]     tf.keras.layers.MaxPooling2D(2, 2),
[ ]     tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
[ ]     tf.keras.layers.MaxPooling2D(2,2),
[ ]     tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
```

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```
[ ] tf.keras.layers.Conv2D(32, (3,3), activation='relu'),
tf.keras.layers.MaxPooling2D(2,2),
tf.keras.layers.Flatten(),
tf.keras.layers.Dense(128, activation='relu'),
tf.keras.layers.Dense(512, activation='relu'),
tf.keras.layers.Dense(3, activation='softmax')

])

model.summary()

Model: "sequential_4"
Layer (type)          Output Shape         Param #
=====
conv2d_12 (Conv2D)    (None, 148, 148, 16) 448
max_pooling2d_12 (MaxPooling) (None, 74, 74, 16) 0
conv2d_13 (Conv2D)    (None, 72, 72, 32) 4640
max_pooling2d_13 (MaxPooling) (None, 36, 36, 32) 0
conv2d_14 (Conv2D)    (None, 34, 34, 32) 9248
max_pooling2d_14 (MaxPooling) (None, 17, 17, 32) 0
flatten_4 (Flatten)   (None, 9248) 0
dense_12 (Dense)     (None, 128) 1183872
dense_13 (Dense)     (None, 512) 66048
dense_14 (Dense)     (None, 3) 1539
=====
Total params: 1,265,795
Trainable params: 1,265,795
Non-trainable params: 0
```

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```
[ ] Non-trainable params: 0
```

```
[ ] model.compile(loss='categorical_crossentropy',
optimizer='adam',
metrics=['accuracy'])

▼ Melatih Model
```

```
[ ] history = model.fit(
train_generator,
steps_per_epoch=25,
epochs=25,
validation_data=validation_generator,
validation_steps=5,
verbose=2)

Epoch 1/25
25/25 - 4s - loss: 1.1223 - accuracy: 0.4200 - val_loss: 1.1010 - val_accuracy: 0.2500
Epoch 2/25
25/25 - 3s - loss: 1.0956 - accuracy: 0.3400 - val_loss: 1.1047 - val_accuracy: 0.4500
Epoch 3/25
25/25 - 3s - loss: 1.0990 - accuracy: 0.3300 - val_loss: 1.0888 - val_accuracy: 0.2500
Epoch 4/25
25/25 - 3s - loss: 1.0874 - accuracy: 0.3800 - val_loss: 1.0844 - val_accuracy: 0.3500
Epoch 5/25
25/25 - 3s - loss: 1.0578 - accuracy: 0.4000 - val_loss: 1.0258 - val_accuracy: 0.4500
Epoch 6/25
25/25 - 3s - loss: 0.9288 - accuracy: 0.5400 - val_loss: 0.5230 - val_accuracy: 0.8500
Epoch 7/25
25/25 - 3s - loss: 0.7408 - accuracy: 0.6500 - val_loss: 0.7552 - val_accuracy: 0.6000
Epoch 8/25
25/25 - 3s - loss: 0.8035 - accuracy: 0.5900 - val_loss: 0.4993 - val_accuracy: 0.8000
```

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```
[ ] Epoch 8/25
25/25 - 3s - loss: 0.8035 - accuracy: 0.5900 - val_loss: 0.4993 - val_accuracy: 0.8000
Epoch 9/25
25/25 - 3s - loss: 0.6916 - accuracy: 0.7100 - val_loss: 0.4634 - val_accuracy: 0.8000
Epoch 10/25
25/25 - 3s - loss: 0.4375 - accuracy: 0.8300 - val_loss: 0.4894 - val_accuracy: 0.8000
Epoch 11/25
25/25 - 3s - loss: 0.3574 - accuracy: 0.8900 - val_loss: 0.1804 - val_accuracy: 1.0000
Epoch 12/25
25/25 - 3s - loss: 0.4304 - accuracy: 0.8400 - val_loss: 0.6513 - val_accuracy: 0.6500
Epoch 13/25
25/25 - 3s - loss: 0.4091 - accuracy: 0.8300 - val_loss: 0.4847 - val_accuracy: 0.8500
Epoch 14/25
25/25 - 3s - loss: 0.4589 - accuracy: 0.8200 - val_loss: 1.0738 - val_accuracy: 0.6000
Epoch 15/25
25/25 - 3s - loss: 0.5101 - accuracy: 0.8200 - val_loss: 0.7095 - val_accuracy: 0.8000
Epoch 16/25
25/25 - 3s - loss: 0.3397 - accuracy: 0.8800 - val_loss: 0.3620 - val_accuracy: 0.8000
Epoch 17/25
25/25 - 3s - loss: 0.3242 - accuracy: 0.8500 - val_loss: 0.6020 - val_accuracy: 0.8000
Epoch 18/25
25/25 - 3s - loss: 0.4697 - accuracy: 0.8700 - val_loss: 0.9349 - val_accuracy: 0.6500
Epoch 19/25
25/25 - 3s - loss: 0.3596 - accuracy: 0.8600 - val_loss: 0.7038 - val_accuracy: 0.9000
Epoch 20/25
25/25 - 3s - loss: 0.3279 - accuracy: 0.8600 - val_loss: 0.4830 - val_accuracy: 0.9000
Epoch 21/25
25/25 - 3s - loss: 0.1874 - accuracy: 0.9286 - val_loss: 0.6608 - val_accuracy: 0.8500
Epoch 22/25
25/25 - 3s - loss: 0.2862 - accuracy: 0.8900 - val_loss: 0.7463 - val_accuracy: 0.8500
Epoch 23/25
25/25 - 3s - loss: 0.3023 - accuracy: 0.9100 - val_loss: 0.5648 - val_accuracy: 0.9000
Epoch 24/25
25/25 - 3s - loss: 0.1870 - accuracy: 0.9500 - val_loss: 0.9981 - val_accuracy: 0.6500
Epoch 25/25
25/25 - 3s - loss: 0.3465 - accuracy: 0.8800 - val_loss: 0.0840 - val_accuracy: 1.0000
```

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```
[ ] import numpy as np
from google.colab import files
```

```
[ ] import numpy as np
from google.colab import files
from keras.preprocessing import image
import matplotlib.pyplot as plt
import matplotlib.image as mpimg
import matplotlib.pyplot as plt
import matplotlib.image as mpimg
%matplotlib inline

uploaded = files.upload()

for fn in uploaded.keys():

    # predicting images
    path = fn
    img = image.load_img(path, target_size=(150,150))
    imgplot = plt.imshow(img)
    x = image.img_to_array(img)
    x = np.expand_dims(x, axis=0)

    images = np.vstack([x])
    classes = model.predict(images, batch_size=10)

    print(fn)
    if classes[0][0]==1:
        print('paper')
    elif classes[0][1]==1:
        print('rock')
    else:
        print('scissors')
```

Choose Files No file chosen Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable.

Saving 0ePX1wuCc3et7leL.png to 0ePX1wuCc3et7leL.png
0ePX1wuCc3et7leL.png
scissors

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RESULT

The prediction results of the model are shown in the image on the side.

After inputting the test image, the program can predict the image correctly with an accuracy above

95%*

The screenshot shows a Jupyter Notebook cell. The code in the cell is:

```
[ ] print(fn)
if classes[0][0]==1:
    print('paper')
elif classes[0][1]==1:
    print('rock')
else:
    print('scissors')
```

Below the code, there is a file upload interface with the placeholder "Choose Files" and a note: "Upload widget is only available when the cell has been executed in the current browser session. Please rerun this cell to enable." A file named "0ePX1wuCc3et7leL.png" is listed under "Saving".

The output of the code is "scissors". Below the output is a plot of a hand showing the "scissors" gesture against a green background. The plot has axes ranging from 0 to 140.

*based on my review rating

THANK YOU

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Pictures & design by Canva