## projekt06

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## 1 Problem wieloagentowy

## 1.0.1 Autorzy:

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Tematyką szóstego, i tym samym ostatniego, projektu są problemy wieloagentowe. Środowisko, które wybrałyśmy to Simple Reference z PettingZoo. Jest ono cześcią nastawionego na komunikację agentów zestawu Multi Particle Environments (MPE).

Wybranym przez nas algorytmem rozwiązującym problem jest DQN z biblioteki stable\_baselines3.

```
[28]: from pettingzoo.mpe import simple_reference_v3
```

```
[29]: env = simple_reference_v3.env(render_mode="human")
  env.reset(seed=42)

for agent in env.agent_iter():
    observation, reward, termination, truncation, info = env.last()

    if termination or truncation:
        action = None
    else:
        action = env.action_space(agent).sample()

        env.step(action)
    env.close()
```

Dodajemy wszystkie potrzebne importy.

```
[30]: import supersuit as ss
from stable_baselines3 import DQN
from pettingzoo.mpe import simple_reference_v3
from pettingzoo.utils.conversions import aec_to_parallel
import matplotlib.pyplot as plt
import numpy as np
```

Inicjalizujemy środowisko PettingZoo i konwertujemy do ParallelEnv. Następnie korzystamy z wrapperów supersuit do wyrównania przestrzeni obserwacji i akcji. Potrzebna jest także konwersja środowiska do formatu kompatybilnego z Gym.

```
[31]: env = simple_reference_v3.env()
  parallel_env = aec_to_parallel(env)

parallel_env = ss.pad_observations_v0(parallel_env)
  parallel_env = ss.pad_action_space_v0(parallel_env)

env = ss.pettingzoo_env_to_vec_env_v1(parallel_env)
  env = ss.concat_vec_envs_v1(env, 4, num_cpus=1, base_class="stable_baselines3")
```

Dostosowujemy hiperparametry modelu DQN oraz ustawiamy liczbę timesteps na 10 000.

## Using cpu device

time/	1 1
episodes	12
fps	1521
time_elapsed	1 0 1
	400
<pre>total_timesteps train/</pre>	1 400 1
learning_rate	0.001
l loss	0.373
n_updates	0.373     37
time/	l l
episodes	16
fps	1516
time_elapsed	0
total_timesteps	400
rollout/	1 1
exploration_rate	0.406
time/	1
episodes	20
fps	1491
time_elapsed	0
total_timesteps	600
train/	i i
l learning_rate	0.001
l loss	0.155
n_updates	62
   time/	 
episodes	24
	1487
fps	0
time_elapsed	
total_timesteps	600
rollout/	
exploration_rate	0.208
time/	
episodes	28
l fps	1462
time_elapsed	0
total_timesteps	800
train/	1
<pre>learning_rate</pre>	0.001
loss	0.15

```
| n_updates | 87 |
| time/
   episodes | 32 |
 fps | 1460 |
| time_elapsed | 0 |
 total_timesteps | 800 |
| rollout/
   exploration_rate | 0.01
   episodes | 36
fps | 1452
| time/
 fps
 time_elapsed | 0
   total_timesteps | 1000
| train/
   learning_rate | 0.001
   loss
              0.0844
   n_updates | 112
| time/
time_elapsed | 0 |
 total_timesteps | 1000 |
| rollout/ |
   exploration_rate | 0.01
| time/
  episodes | 44
   fps
              | 1454
  time_elapsed | 0
   total_timesteps | 1200
| train/
   learning_rate | 0.001
   loss
               0.093
   n_updates | 137
| time/
   episodes
            | 48 |
   fps | 1452 |
 time_elapsed | 0 |
   total_timesteps | 1200 |
```

rollout/	1	
exploration_rate	0.01	
time/	1	
episodes	52	
fps	1449	
time_elapsed	1 0	
total_timesteps	1400	
train/	1	
<pre>learning_rate</pre>	0.001	
loss	0.15	
n_updates	162	
time/	1	
episodes	56 l	
fps	1448	
time_elapsed	0	
total_timesteps	1400	
rollout/	1	
exploration_rate	0.01	
time/	1	
episodes	60	
fps	1411	
time_elapsed	1	
total_timesteps	1600	
train/	1	
learning_rate	0.001	
loss	0.107	
n_updates	187	
time/	1	
episodes	64 l	
fps	1410	
time_elapsed	1	
total_timesteps	1600	
rollout/	1	
ovaloration rate	0.01	
${\tt exploration\_rate}$		
time/	1	
. <del>.</del>	   68	
time/	   68   1417	

```
total_timesteps | 1800
| train/
   learning_rate
                0.001
   loss
                 0.0757
 n_updates | 212
| time/
   episodes
               | 72
   fps
               | 1416 |
   time_elapsed | 1
   total_timesteps | 1800 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes
                | 76
 fps
                | 1418
   time_elapsed | 1
   total_timesteps | 2000
| train/
   learning_rate
                0.001
   loss
                 0.104
   n_updates | 237
| time/
   episodes
fps
               | 80 |
               | 1417 |
   time_elapsed | 1
   total_timesteps | 2000 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes | 84
 fps
                 | 1412
 time_elapsed | 1
   total_timesteps | 2200
| train/
   learning_rate
                 0.001
   loss
                 0.174
                | 262
   n_updates
| time/
               - 1
```

```
episodes | 88 |
fps | 1411 |
   time_elapsed | 1
   total_timesteps | 2200 |
| rollout/
    exploration_rate | 0.01
| time/
   episodes
                | 92
                 | 1410
   fps
   time_elapsed | 1
   total_timesteps | 2400
| train/
   learning_rate
                 0.001
   loss
                 0.194
   n_updates
                | 287
| time/
  episodes | 96 |
fps | 1409 |
 time_elapsed | 1
   total_timesteps | 2400 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes | 100
   fps
                 | 1407
   time_elapsed | 1
   total_timesteps | 2600
| train/
   learning_rate | 0.001
   loss
                 0.137
   n_updates
| 1406 |
 time_elapsed | 1 |
   total_timesteps | 2600 |
| rollout/
   exploration_rate | 0.01
```

time/	1 1
episodes	108
fps	1380
time_elapsed	2
total_timesteps	2800
train/	
l learning_rate	0.001
loss	0.268
n_updates	337
time/	l l
episodes	112
fps	1378
time_elapsed	2
total_timesteps	2800
rollout/	 
exploration_rate	0.01
time/	0.01
episodes	116
fps	1314
time_elapsed	1 2
total_timesteps	3000
train/	1 3000 1
	1 0 001 1
learning_rate	0.001
loss	0.19
n_updates	362   
time/	
episodes	120
fps	1312
time_elapsed	2
total_timesteps	3000
rollout/	
exploration_rate	0.01
time/	1
episodes	124
fps	1280
time_elapsed	2
total_timesteps	3200
train/	
learning_rate	0.001
loss	0.17
. ====	1

```
| n_updates | 387 |
| time/
   episodes | 128 |
 fps | 1280 |
| time_elapsed | 2 |
 total_timesteps | 3200 |
| rollout/ |
   exploration_rate | 0.01
   | time/
 fps
 time_elapsed | 2
   total_timesteps | 3400
| train/
   learning_rate | 0.001
   loss
              0.117
   n_updates | 412
| time/
time_elapsed | 2 |
 total_timesteps | 3400 |
| rollout/ |
   exploration_rate | 0.01
| time/
  episodes | 140
   fps
              | 1241
  time_elapsed | 2
   total_timesteps | 3600
| train/
   learning_rate | 0.001
   loss
              0.141
   n_updates | 437
 _____
| time/
  episodes
           | 144 |
  fps | 1241 |
 time_elapsed | 2 |
  total_timesteps | 3600 |
```

rollout/		ا ا
exploration_rate	0.01	1
time/	1	1
episodes	148	1
fps	1223	1
time_elapsed	3	1
total_timesteps	3800	1
train/	1	1
learning_rate	0.001	.
loss	0.306	i
n_updates	462	- 1
time/	150 l	
episodes	152	
fps	1221	
	3	
total_timesteps	3800	
rollout/		!
exploration_rate	0.01	!
time/		!
episodes	156	. !
fps	1202	. !
time_elapsed	3	!
total_timesteps	4000	. !
train/	1	. !
learning_rate	0.001	
loss	0.188	3
n_updates	487 	ا 
time/		
episodes	160	
fps	1201	
time_elapsed	3	
total_timesteps	4000	
rollout/	1	
exploration_rate	0.01	- 1
time/	1	1
episodes	164	1
fps	1179	
time_elapsed	3	1

```
total_timesteps | 4200
| train/
   learning_rate
                0.001
   loss
                 0.278
 n_updates | 512
| time/
               | 168 |
   episodes
   fps
               | 1178 |
 time_elapsed | 3 |
 total_timesteps | 4200 |
| rollout/
   exploration_rate | 0.01
| time/
 episodes
fps
                | 172
                | 1165
   time_elapsed | 3
   total_timesteps | 4400
| train/
   learning_rate
                0.001
   loss
                 0.309
   n_updates | 537
| time/
   episodes
fps
              | 176 |
               | 1164 |
   time_elapsed | 3
   total_timesteps | 4400 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes | 180
l fps
                | 1150
 time_elapsed | 3
   total_timesteps | 4600
| train/
   learning_rate
                 0.001
   loss
                0.259
                | 562
   n_updates
| time/
               - 1
```

```
episodes | 184 |
fps | 1149 |
   time_elapsed | 4
    total_timesteps | 4600 |
| rollout/
    exploration_rate | 0.01
| time/
   episodes | 188
                | 1130
   fps
   time_elapsed | 4
   total_timesteps | 4800
| train/
    learning_rate
                0.001
   loss
                1 0.29
   n_updates
                | 587
| time/
 episodes | 192 |
fps | 1129 |
 time_elapsed | 4
   total_timesteps | 4800 |
| rollout/
    exploration_rate | 0.01
| time/
   episodes | 196
   fps
                | 1110
   time_elapsed | 4
   total_timesteps | 5000
| train/
   learning_rate | 0.001
   loss
                 0.376
   n_updates
fps
               | 1109 |
 time_elapsed | 4 |
   total_timesteps | 5000 |
| rollout/
   exploration_rate | 0.01
```

+ima/	1 1
time/   episodes	204
	1118
fps	
time_elapsed	4
total_timesteps	5200
train/	
learning_rate	0.001
loss	0.369
n_updates	637
time/	l l
episodes	208
l fps	1118
time_elapsed	4
	5200
rollout/	1
exploration_rate	0.01
time/	1
episodes	212
fps	1127
time_elapsed	4
total_timesteps	5400
train/	1
learning_rate	0.001
loss	0.131
n_updates	662
   time/	 I I
episodes	216
- ·	1127
fps   time_elapsed	4
	5400
total_timesteps	
rollout/	1
exploration_rate	0.01
time/	1
episodes	220
fps	1136
<pre>time_elapsed</pre>	4
total_timesteps	5600
train/	1
learning_rate	0.001
loss	0.136

```
| n_updates | 687 |
| time/
   episodes | 224 |
 fps | 1135 |
| time_elapsed | 4 |
 total_timesteps | 5600 |
| rollout/ |
   exploration_rate | 0.01
   ____ue | 0.01

ne/ |
episodes | 228

fps | 11/2
| time/
 fps
 time_elapsed | 5
   total_timesteps | 5800
| train/
   learning_rate | 0.001
   loss
                0.38
   n_updates | 712
| time/
| episodes | 232 |
| fps | 1142 |
 time_elapsed | 5
 total_timesteps | 5800 |
| rollout/ |
   exploration_rate | 0.01
| time/
   episodes | 236
   fps
                | 1151
  time_elapsed | 5
   total_timesteps | 6000
| train/
   learning_rate | 0.001
   loss
                0.233
   n_updates | 737
| time/
   episodes
             | 240 |
   fps | 1151 |
 time_elapsed | 5 |
   total_timesteps | 6000 |
```

   rollout/	 
exploration_rate	0.01
time/	1
episodes	244
fps	1156
<pre>time_elapsed</pre>	5
total_timesteps	6200
train/	1 1
learning_rate	0.001
loss	0.394
	762   
   time/	 I
episodes	248
fps	1156
time_elapsed	5 l
total_timesteps	6200
rollout/	1 1
exploration_rate	0.01
time/	1 1
episodes	252
fps	1161
time_elapsed	5
total_timesteps	6400
train/	
learning_rate	0.001
l loss	0.105
n_updates 	787         
   time/	 I
episodes	256
fps	1161
time_elapsed	5
total_timesteps	6400
	·
rollout/	1 1
exploration_rate	0.01
time/	1 1
episodes	260
fps	1168
time_elapsed	5

```
total_timesteps | 6600
| train/
   learning_rate
                 0.001
   loss
                 0.268
 n_updates | 812
| time/
   episodes
               | 264 |
               | 1168 |
   fps
   time_elapsed | 5
 total_timesteps | 6600 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes
                | 268
 fps
                | 1177
   time_elapsed | 5
   total_timesteps | 6800
| train/
   learning_rate
                 0.001
   loss
                 0.218
   n_updates | 837
| time/
   episodes
fps
              | 272 |
               | 1176 |
   time_elapsed | 5
   total_timesteps | 6800 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes | 276
 fps
                 | 1183
 time_elapsed | 5
   total_timesteps | 7000
| train/
   learning_rate
                 0.001
   loss
                 0.295
                862
   n_updates
| time/
               - 1
```

```
episodes | 280 |
fps | 1183 |
   time_elapsed | 5
   total_timesteps | 7000 |
| rollout/
    exploration_rate | 0.01
| time/
   episodes | 284
   fps
                | 1187
   time_elapsed | 6
   total_timesteps | 7200
| train/
   learning_rate
                0.001
   loss
                0.318
   n_updates
                | 887
| time/
 episodes | 288 |
fps | 1187 |
 time_elapsed | 6
   total_timesteps | 7200 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes | 292
   fps
                | 1190
   time_elapsed | 6
   total_timesteps | 7400
| train/
   learning_rate | 0.001
   loss
                 0.229
   n_updates
fps
               | 1190 |
 time_elapsed | 6 |
   total_timesteps | 7400 |
| rollout/
   exploration_rate | 0.01
```

time/	1
episodes	300
fps	1197
time_elapsed	6
total_timesteps	7600
train/	1
<pre>learning_rate</pre>	0.001
loss	0.457
n_updates	937
time/	I
episodes	304
fps	1197
time_elapsed	6 l
total_timesteps	7600
rollout/	1
exploration_rate	0.01
time/	1
episodes	308
fps	1198
time_elapsed	6
total_timesteps	7800
train/	1
learning_rate	0.001
loss	0.716
n_updates	962
time/	1
episodes	312
fps	1198
time_elapsed	6 l
total_timesteps	7800
rollout/	
exploration_rate	0.01
time/	1
episodes	316
fps	1203
<pre>time_elapsed</pre>	6
<pre>total_timesteps</pre>	8000
train/	1
<pre>learning_rate</pre>	0.001
loss	0.329

```
| n_updates | 987 |
| time/
   episodes | 320 |
 fps | 1203 |
| time_elapsed | 6 |
 total_timesteps | 8000 |
| rollout/
   exploration_rate | 0.01
   | time/
 fps
 time_elapsed | 6
   total_timesteps | 8200
| train/
   learning_rate | 0.001
   loss
               0.778
   n_updates | 1012
| time/
episodes | 328 |
fps | 1208 |
 time_elapsed | 6 |
 total_timesteps | 8200 |
| rollout/ |
   exploration_rate | 0.01
| time/
  episodes | 332
   fps
               | 1212
  time_elapsed | 6
   total_timesteps | 8400
| train/
   learning_rate | 0.001
   loss
               0.525
   n_updates | 1037
| time/
   episodes
            | 336 |
   fps | 1212 |
 time_elapsed | 6 |
   total_timesteps | 8400 |
```

   rollout/		 
exploration_rate	0.01	1
time/		-
episodes	340	
fps	1214	
<pre>time_elapsed</pre>	7	
total_timesteps	8600	
train/		
<pre>learning_rate</pre>	0.001	- 1
loss	0.285	- 1
n_updates 	1062	 
   time/		
cime/   episodes	344 l	
episodes	1214	
time_elapsed	7	
time_elapsed     total_timesteps		
   rollout/	 	 
exploration_rate	0.01	
time/	1	- 1
episodes	348	
fps	1218	
time_elapsed	7	
total_timesteps	8800	1
train/		1
learning_rate	0.001	1
loss	0.396	
n_updates	1087	 
time/		
episodes	352	
fps	1218	
time_elapsed	7	
total_timesteps	8800	
   rollout/	 I	 I
exploration_rate	0.01	
time/	1 0.01	 
•	   356	
episodes	1 1222	 
fps	· _	l I
time_elapsed	7	I

```
total_timesteps | 9000
| train/
   learning_rate
                0.001
   loss
                 0.248
 n_updates | 1112
| time/
   episodes
               | 360 |
   fps
               | 1222 |
 time_elapsed | 7 |
 total_timesteps | 9000 |
| rollout/
   exploration_rate | 0.01
| time/
 episodes | 364
fps | 1223
                | 1223
   time_elapsed | 7
   total_timesteps | 9200
| train/
   learning_rate
                0.001
   loss
                 0.958
   n_updates | 1137
| time/
   episodes | 368 |
fps | 1223 |
   time_elapsed | 7
   total_timesteps | 9200 |
| rollout/
   exploration_rate | 0.01
| time/
          episodes | 372
fps
                | 1225
 time_elapsed | 7
   total_timesteps | 9400
| train/
   learning_rate
                 0.001
   loss
                 0.314
                | 1162
   n_updates
| time/
```

```
episodes | 376 |
fps | 1224 |
   time_elapsed | 7
   total_timesteps | 9400 |
| rollout/
    exploration_rate | 0.01
| time/
   episodes | 380
                 | 1228
   fps
   time_elapsed | 7
   total_timesteps | 9600
| train/
   learning_rate
                 0.001
   loss
                 | 0.301
   n_updates
                | 1187
| time/
  episodes | 384 |
fps | 1228 |
 time_elapsed | 7
   total_timesteps | 9600 |
| rollout/
   exploration_rate | 0.01
| time/
   episodes | 388
   fps
                 | 1231
   time_elapsed | 7
   total_timesteps | 9800
| train/
   learning_rate | 0.001
   loss
                 0.445
   n_updates
| 1230 |
 time_elapsed | 7 |
   total_timesteps | 9800 |
| rollout/
   exploration_rate | 0.01
```

[32]: <stable\_baselines3.dqn.dqn.DQN at 0x78fb1b617250>

Następnie testujemy wytrenowany model. Oprócz tego wygładzamy wyniki za pomocą średniej kroczącej.

```
[33]: obs = env.reset()
      total_rewards = []
      num_episodes = 1000
      for i in range(num_episodes):
          total_reward = 0
          done = [False for _ in range(env.num_envs)]
          while not all(done):
              action, _states = model.predict(obs)
              obs, rewards, done, info = env.step(action)
              total_reward += sum(rewards)
          total_rewards.append(total_reward)
      env.close()
      def moving_average(data, window_size):
          return np.convolve(data, np.ones(window_size)/window_size, mode='valid')
      window_size = 50
      smoothed_rewards = moving_average(total_rewards, window_size)
```

Na koniec wizualizacjemy krzywą uczenia.

```
[34]: plt.plot(total_rewards, alpha=0.3, label='Total Reward per Episode')
plt.plot(smoothed_rewards, label=f'Moving Average (window size={window_size})')
plt.xlabel('Episode')
```

```
plt.ylabel('Total Reward')
plt.title('Learning Curve')
plt.legend()
plt.show()
```

