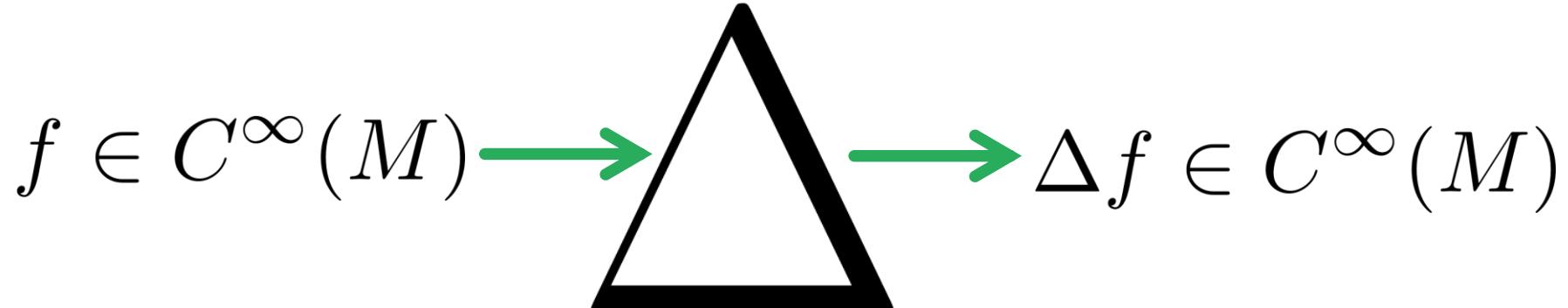


Discrete Laplacians

Justin Solomon
MIT, Spring 2017



Our Focus

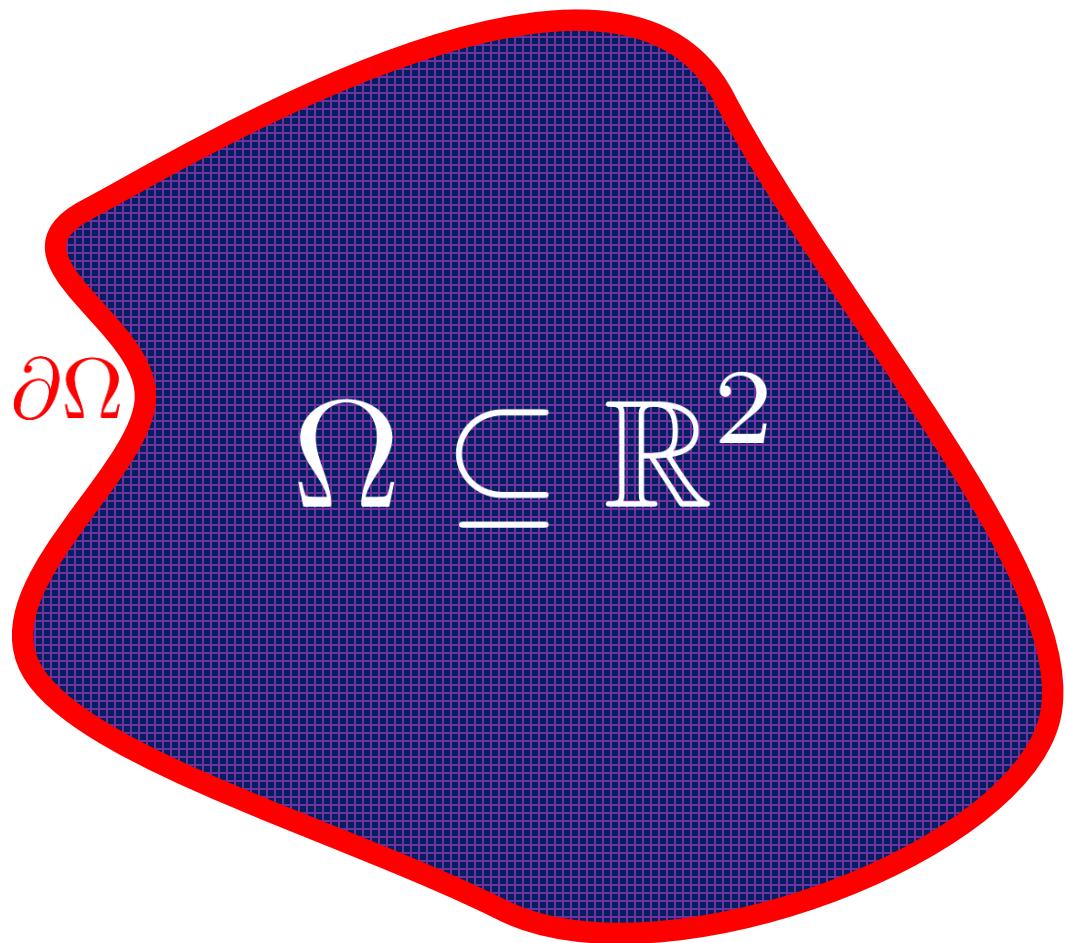


Computational
version?

The Laplacian

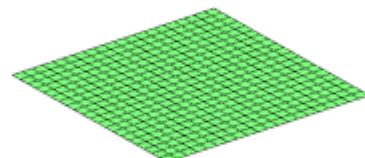
Recall:

Planar Region



Wave equation:

$$\frac{\partial^2 u}{\partial t^2} = \Delta u$$
$$\Delta := \sum_i \frac{\partial^2}{\partial x_i^2}$$



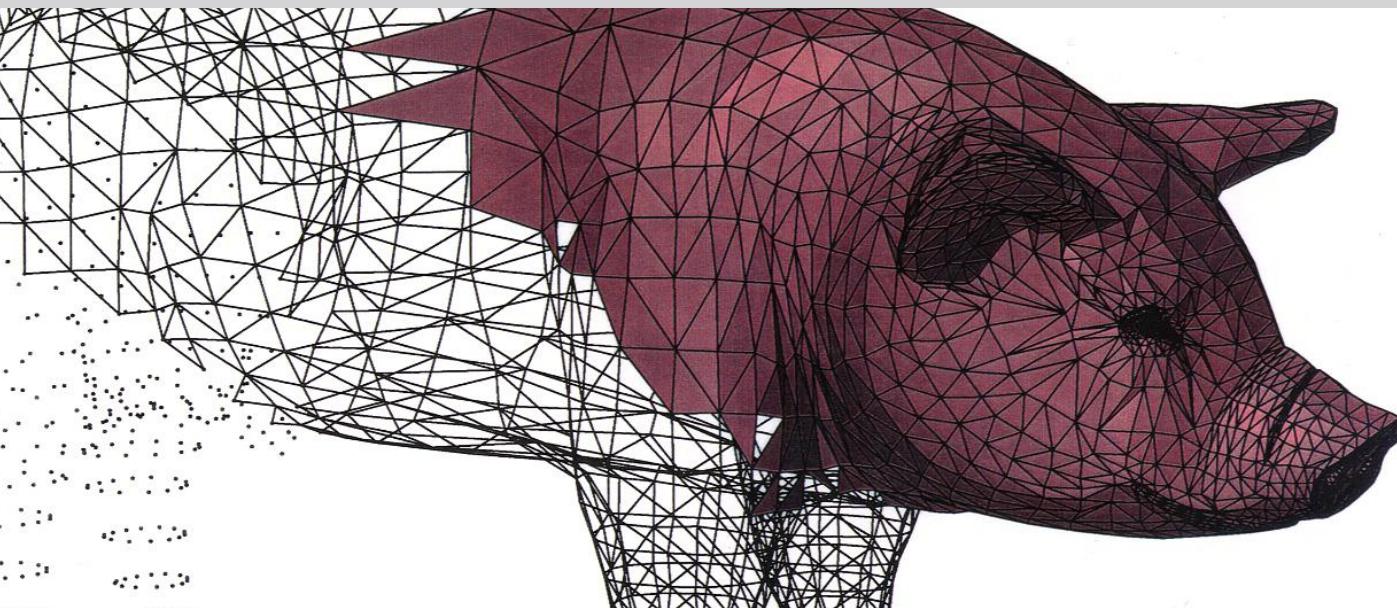
Discretizing the Laplacian

$$\Delta f = \frac{1}{\sqrt{|g|}} \partial_i \left(\sqrt{|g|} g^{ij} \partial_j f \right)$$

?!

Problem

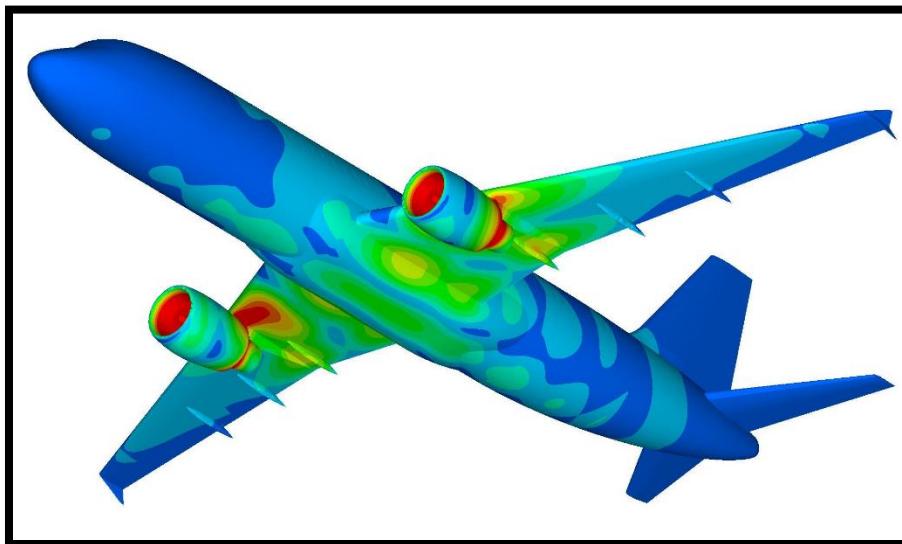
Laplacian is a *differential* operator!



Today's Approach

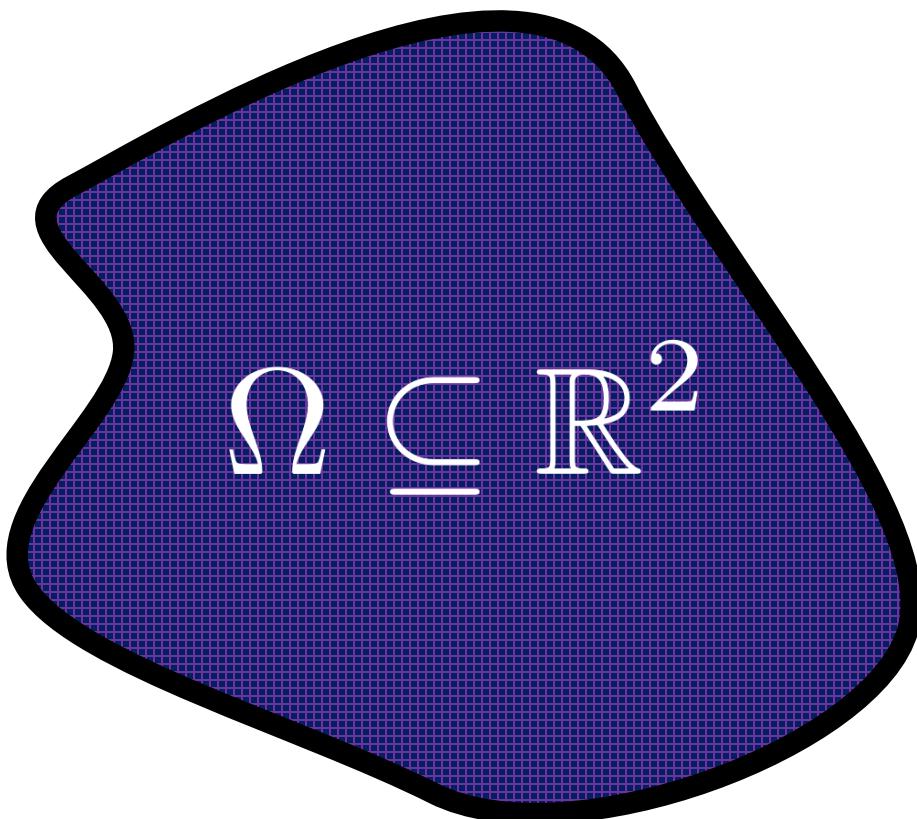
First-order Galerkin

Finite element method (FEM)



Integration by Parts to the Rescue

$$\int_{\Omega} f \Delta g \, dA = \text{boundary terms} - \int_{\Omega} \nabla f \cdot \nabla g \, dA$$



A GUIDE TO INTEGRATION BY PARTS:

GIVEN A PROBLEM OF THE FORM:

$$\int f(x) g(x) dx = ?$$

CHOOSE VARIABLES u AND v SUCH THAT:

$$u = f(x)$$
$$dv = g(x) dx$$

NOW THE ORIGINAL EXPRESSION BECOMES:

$$\int u dv = ?$$

WHICH DEFINITELY LOOKS EASIER.

ANYWAY, I GOTTA RUN.

BUT GOOD LUCK!

Slightly Easier?

$$\int_{\Omega} f \Delta g \, dA = \text{boundary terms} - \int_{\Omega} \nabla f \cdot \nabla g \, dA$$

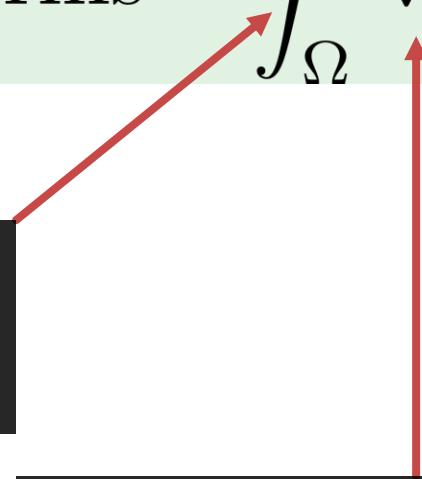
Laplacian
(second derivative)

Gradient
(first derivative)

Slightly Easier?

$$\int_{\Omega} f \Delta g \, dA = \text{boundary terms} - \int_{\Omega} \nabla f \cdot \nabla g \, dA$$

One derivative,
one integral



Gradient
(first derivative)

Kinda-sorta cancels out?

Overview:

Galerkin FEM Approach

$$g = \Delta f$$

$$\implies \int \psi g \, dA = \int \psi \Delta f \, dA = - \int (\nabla \psi \cdot \nabla f) \, dA$$

Overview:

Galerkin FEM Approach

$$g = \Delta f$$

$$\implies \int \psi g \, dA = \int \psi \Delta f \, dA = - \int (\nabla \psi \cdot \nabla f) \, dA$$

Approximate $f \approx \sum_i a_i \psi_i$ and $g \approx \sum_i b_i \psi_i$

$$\implies \text{Linear system } \sum_i b_i \langle \psi_i, \psi_j \rangle = - \sum_i a_i \langle \nabla \psi_i, \nabla \psi_j \rangle$$

Overview:

Galerkin FEM Approach

$$g = \Delta f$$

$$\implies \int \psi g \, dA = \int \psi \Delta f \, dA = - \int (\nabla \psi \cdot \nabla f) \, dA$$

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$$\implies \text{Linear system } \sum_i b_i \langle \psi_i, \psi_j \rangle = - \sum_i a_i \langle \nabla \psi_i, \nabla \psi_j \rangle$$

Mass matrix: $M_{ij} := \langle \psi_i, \psi_j \rangle$

Stiffness matrix: $L_{ij} := \langle \nabla \psi_i, \nabla \psi_j \rangle$

$$\implies Mb = La$$

Which basis?

Important to Note

Not the only way

to approximate the Laplacian operator.

- Divided differences
- Higher-order elements
- Boundary element methods
- Discrete exterior calculus
- ...

But this method is worth knowing,
so we'll do it in detail!

L^2 Dual of a Function

Function

$$f : M \rightarrow \mathbb{R}$$



Operator

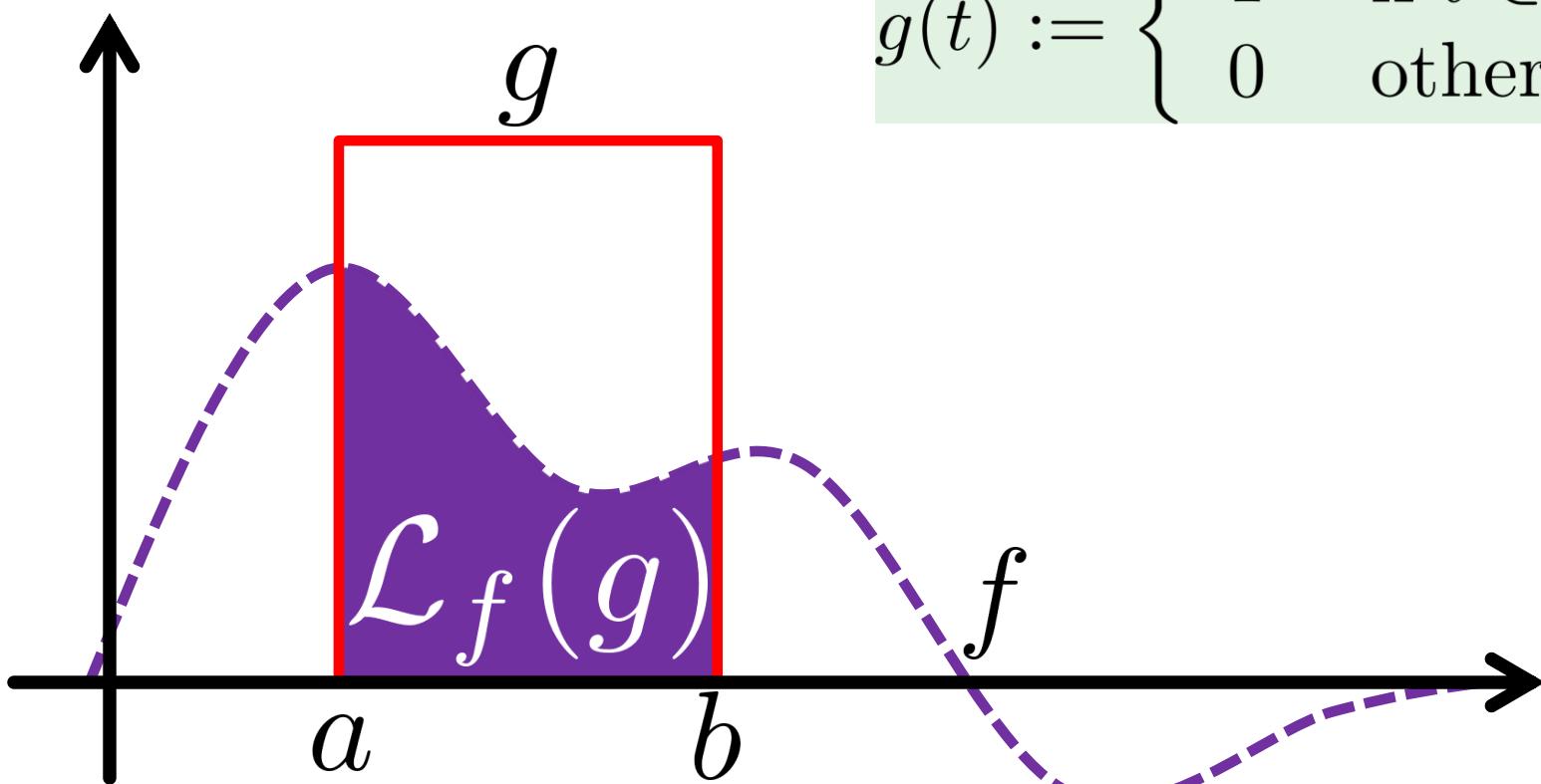
$$\mathcal{L}_f : L^2(M) \rightarrow \mathbb{R}$$

$$\mathcal{L}_f[g] := \int_M f(x)g(x) dA$$



“Test function”

Observation



Can recover function from dual

Dual of Laplacian

Space of test functions (no boundary!):

$$\{g \in L^\infty(M) : g|_{\partial M} \equiv 0\}$$

$$\begin{aligned}\mathcal{L}_{\Delta f}[g] &= \int_M g \Delta f \, dA \\ &= - \int_M \nabla g \cdot \nabla f \, dA\end{aligned}$$

Use Laplacian without evaluating it!

Galerkin's Approach

Choose one of each:

- Function space
- Test functions

Often the same!

One Derivative is Enough

$$\mathcal{L}_{\Delta f}[g] = - \int_M \nabla g \cdot \nabla f \, dA$$

First Order Finite Elements

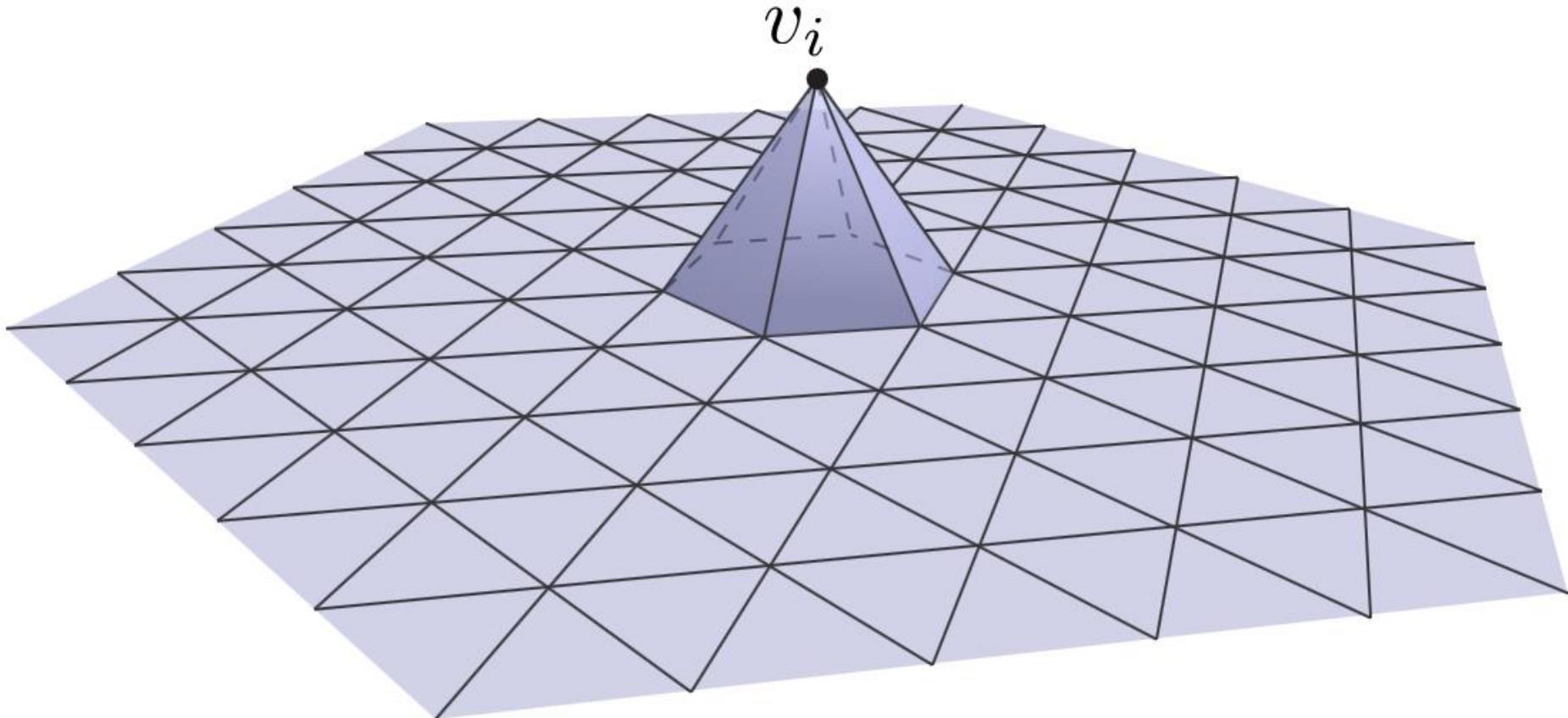
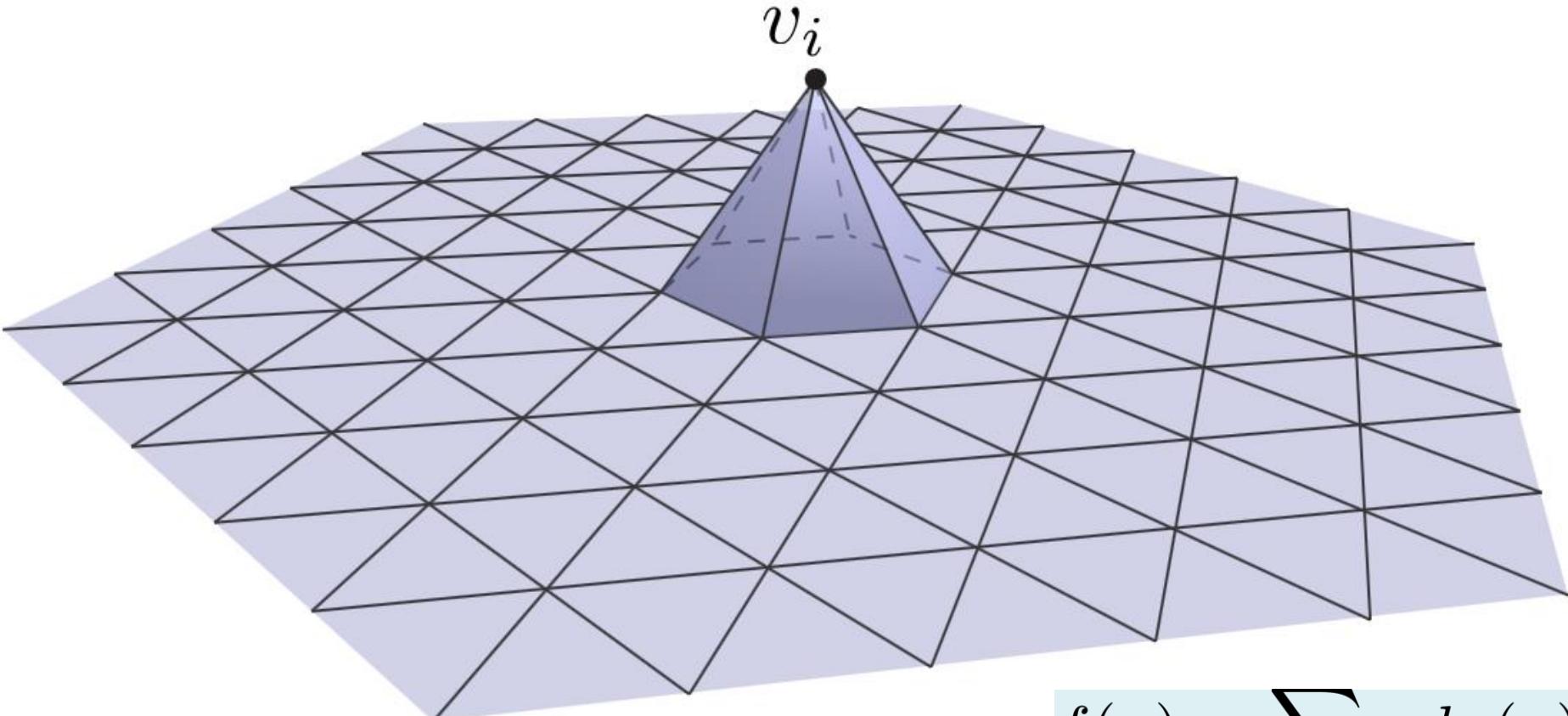


Image courtesy K. Crane, CMU

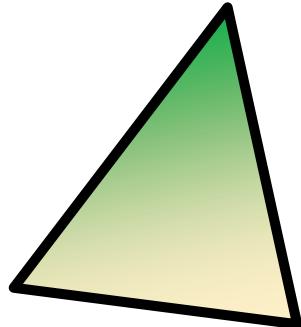
One “hat function” per vertex

Representing Functions



$$f(x) = \sum_i a_i h_i(x)$$
$$a \in \mathbb{R}^{|V|}$$

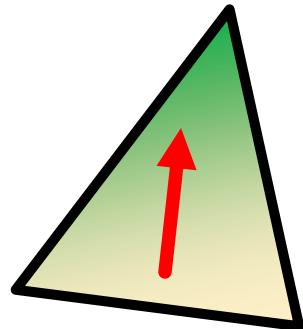
What Do We Need



$$\mathcal{L}_{\Delta f}[g] = - \int_M \nabla g \cdot \nabla f \, dA$$

Linear combination of hats
(piecewise linear)

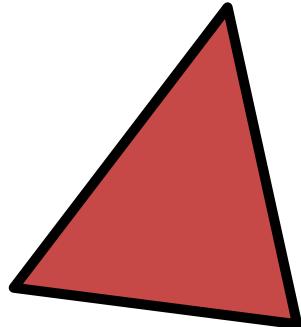
What Do We Need



$$\mathcal{L}_{\Delta f}[g] = - \int_M \nabla g \cdot \nabla f \, dA$$

One vector per face

What Do We Need

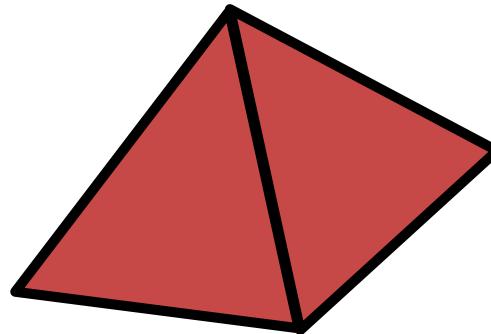


$$\mathcal{L}_{\Delta f}[g] = - \int_M \nabla g \cdot \nabla f \, dA$$

 One scalar per face

A mathematical equation representing a discrete operator $\mathcal{L}_{\Delta f}$ acting on a function g . The equation is
$$\mathcal{L}_{\Delta f}[g] = - \int_M \nabla g \cdot \nabla f \, dA$$
. A green arrow points from the text "One scalar per face" to the term $\nabla g \cdot \nabla f$, indicating that each face in the mesh has a corresponding scalar value.

What Do We Need

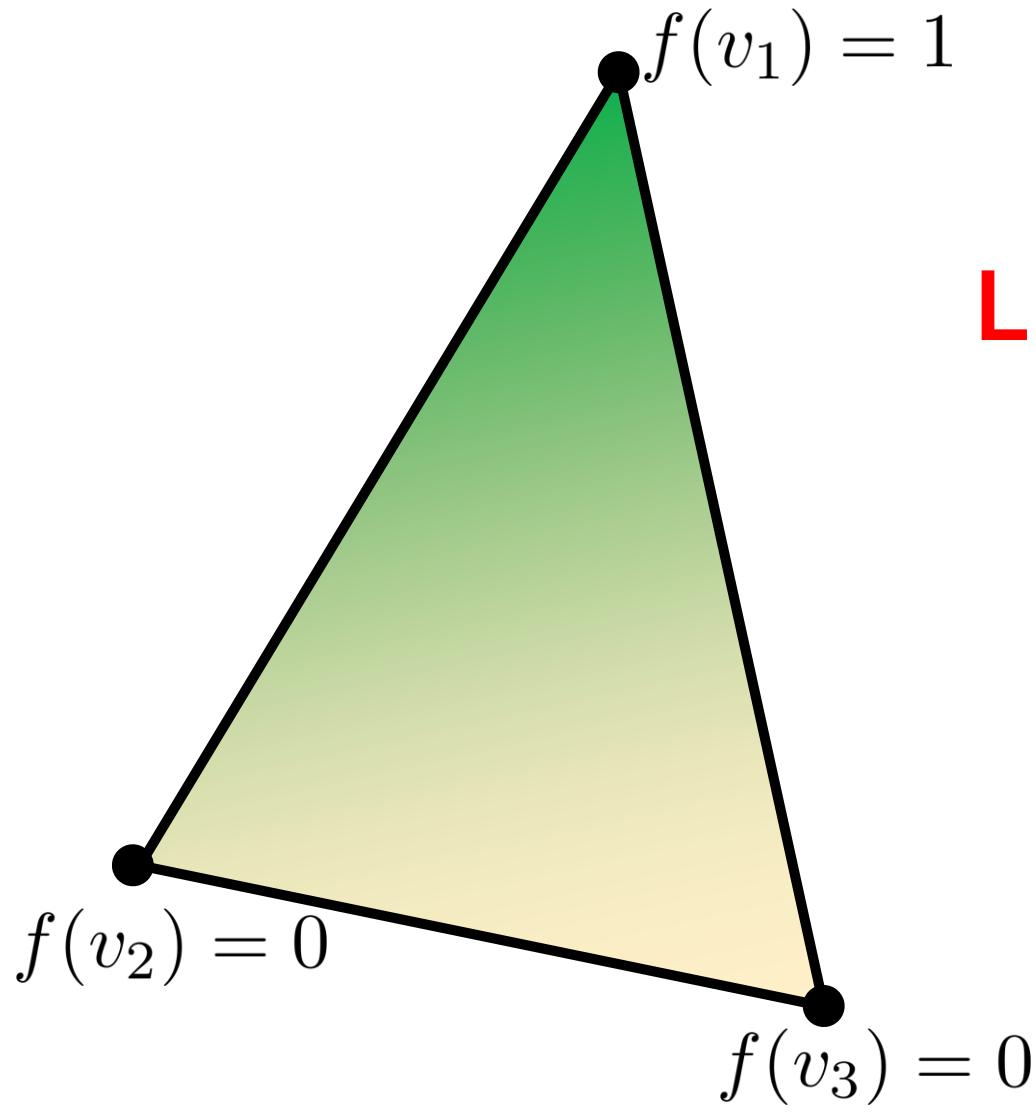


$$\mathcal{L}_{\Delta f}[g] = - \int_M \nabla g \cdot \nabla f \, dA$$



Sum scalars per face
multiplied by face areas

Gradient of a Hat Function



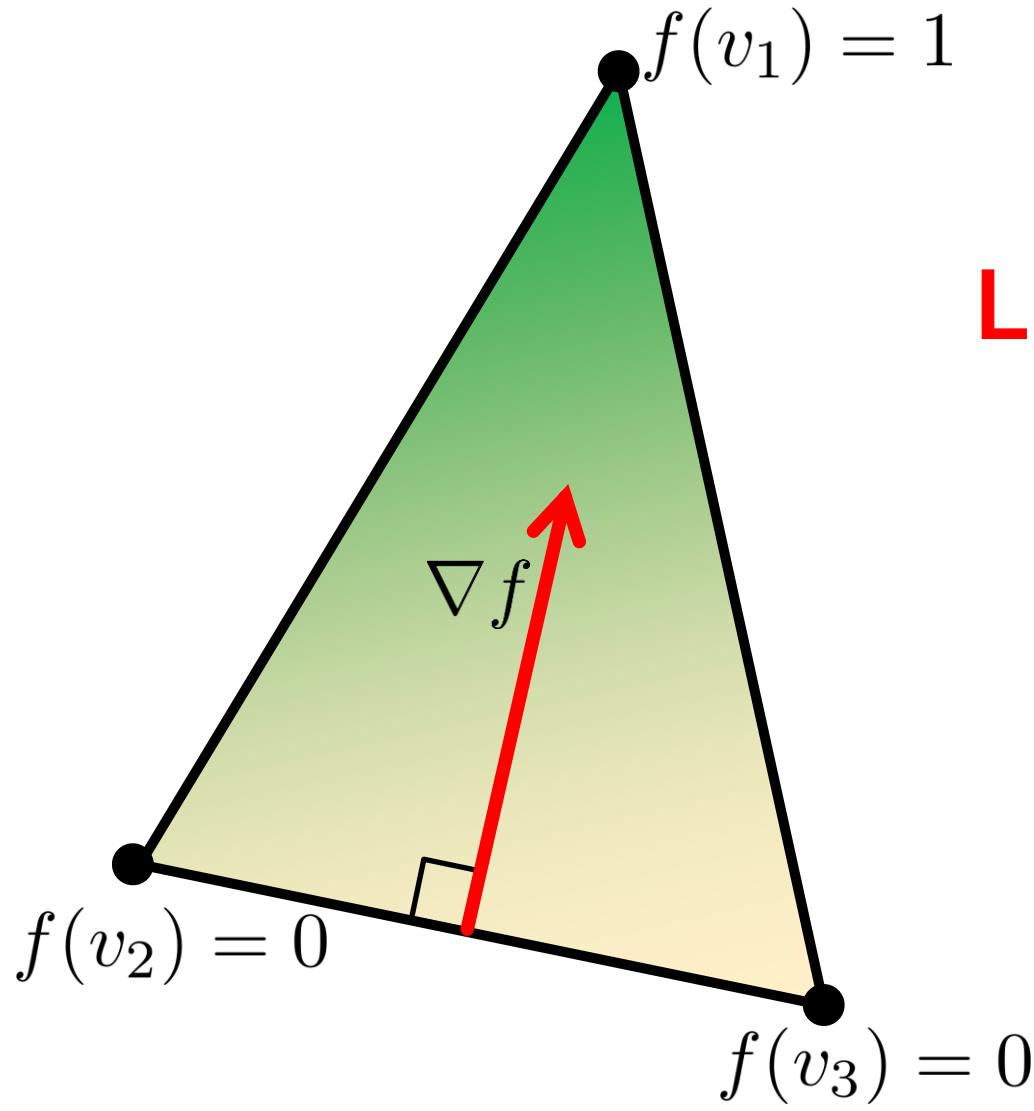
Linear along edges

$$\nabla f \cdot (v_1 - v_3) = 1$$

$$\nabla f \cdot (v_1 - v_2) = 1$$

$$\nabla f \cdot n = 0$$

Gradient of a Hat Function



Linear along edges

$$\nabla f \cdot (v_1 - v_3) = 1$$

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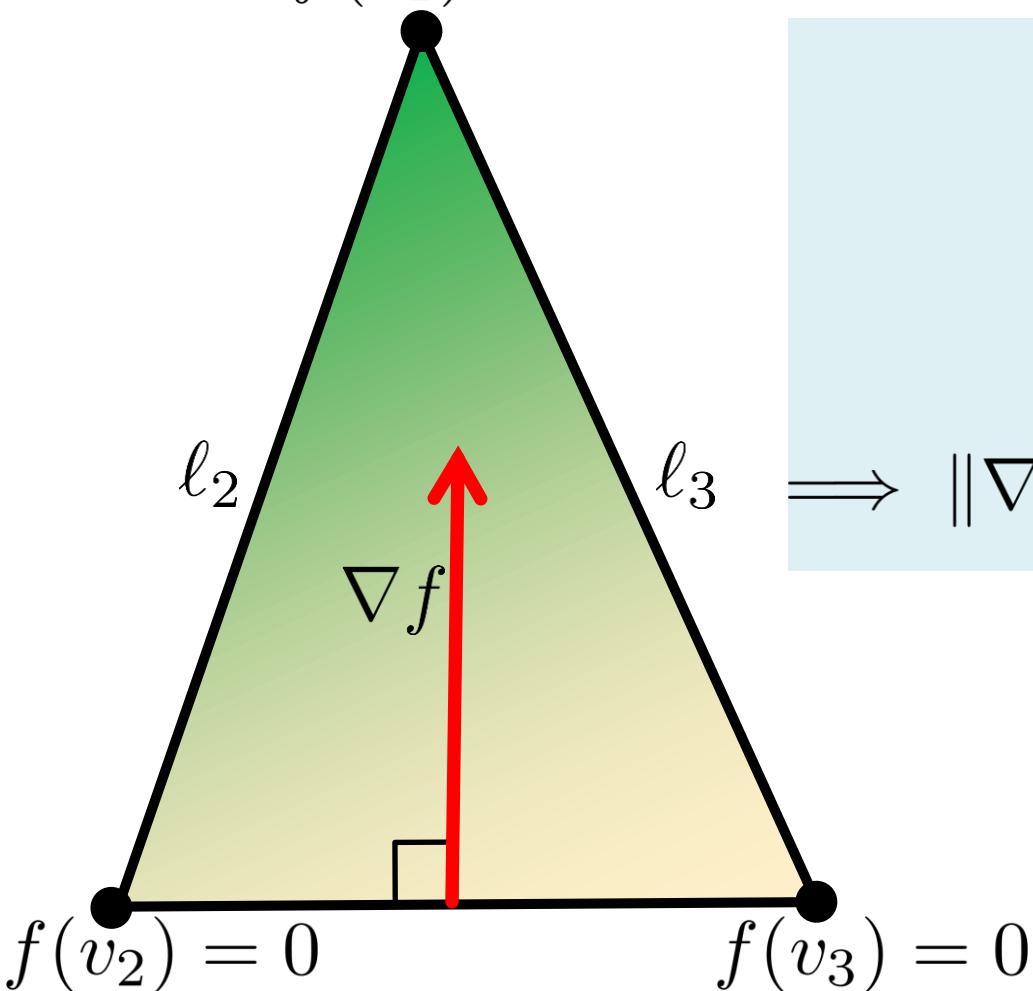
$$\nabla f \cdot n = 0$$



$$\nabla f \cdot (v_2 - v_3) = 0$$

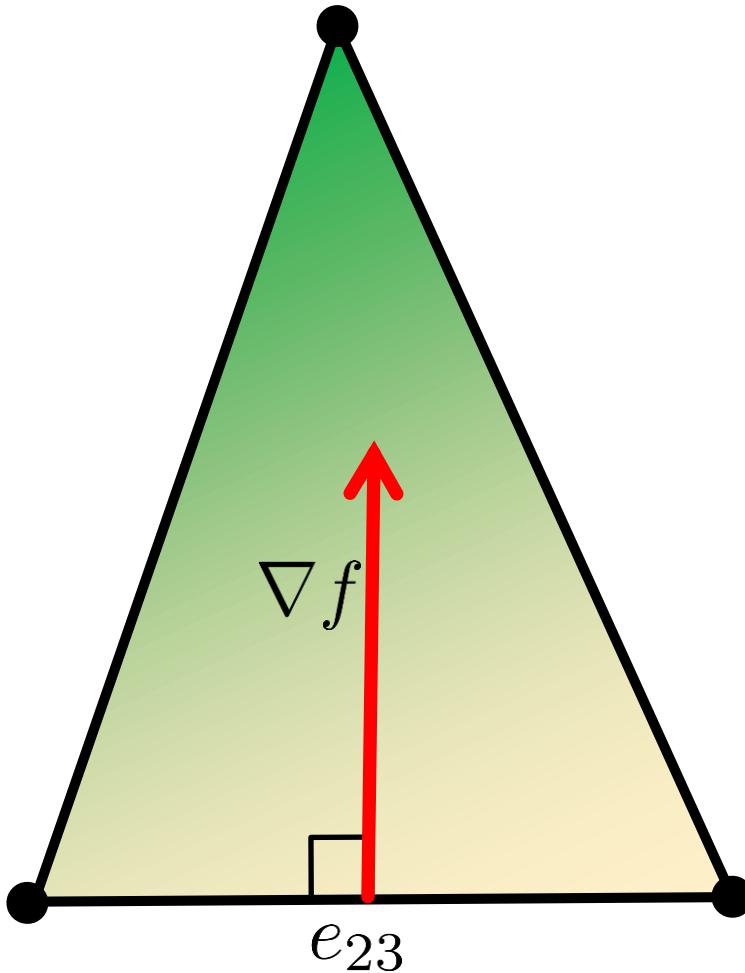
Gradient of a Hat Function

$$f(v_1) = 1$$



$$\begin{aligned} 1 &= \nabla f \cdot (v_1 - v_3) \\ &= \|\nabla f\| \ell_3 \cos\left(\frac{\pi}{2} - \theta_3\right) \\ &= \|\nabla f\| \ell_3 \sin \theta_3 \\ \Rightarrow \|\nabla f\| &= \frac{1}{\ell_3 \sin \theta_3} = \frac{1}{h} \end{aligned}$$

Gradient of a Hat Function



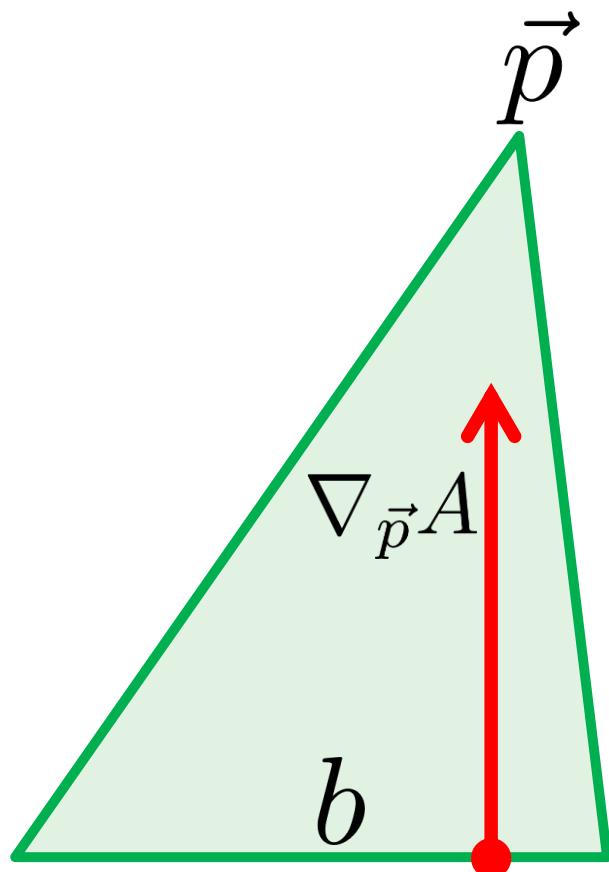
$$\|\nabla f\| = \frac{1}{\ell_3 \sin \theta_3} = \frac{1}{h}$$

$$\nabla f = \frac{e_{23}^\perp}{2A}$$

Length of e_{23} cancels
“base” in A

Recall:

Single Triangle: Complete

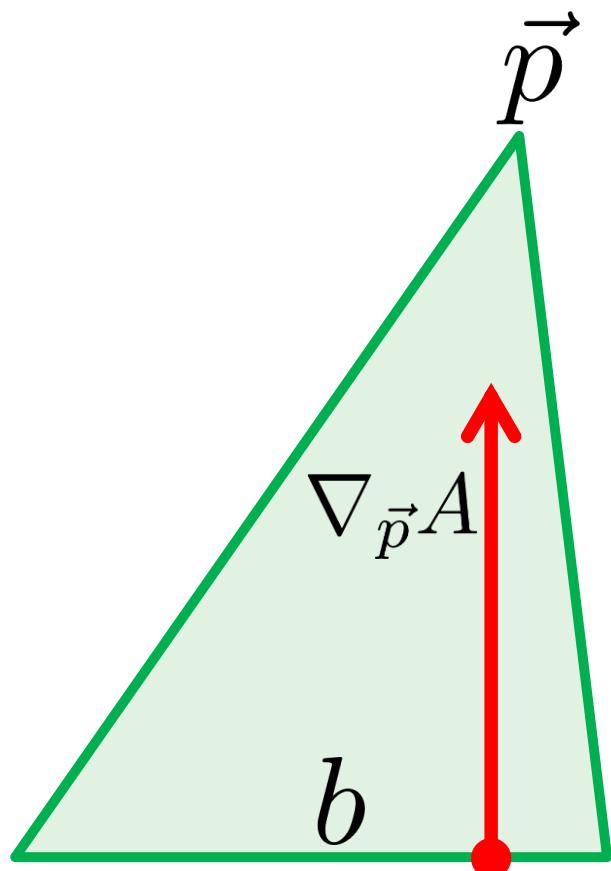


$$\vec{p} = p_n \vec{n} + p_e \vec{e} + p_\perp \vec{e}_\perp$$
$$A = \frac{1}{2} b \sqrt{p_n^2 + p_\perp^2}$$
$$\nabla_{\vec{p}} A = \frac{1}{2} b \vec{e}_\perp$$

Similar expression

Recall:

Single Triangle: Complete



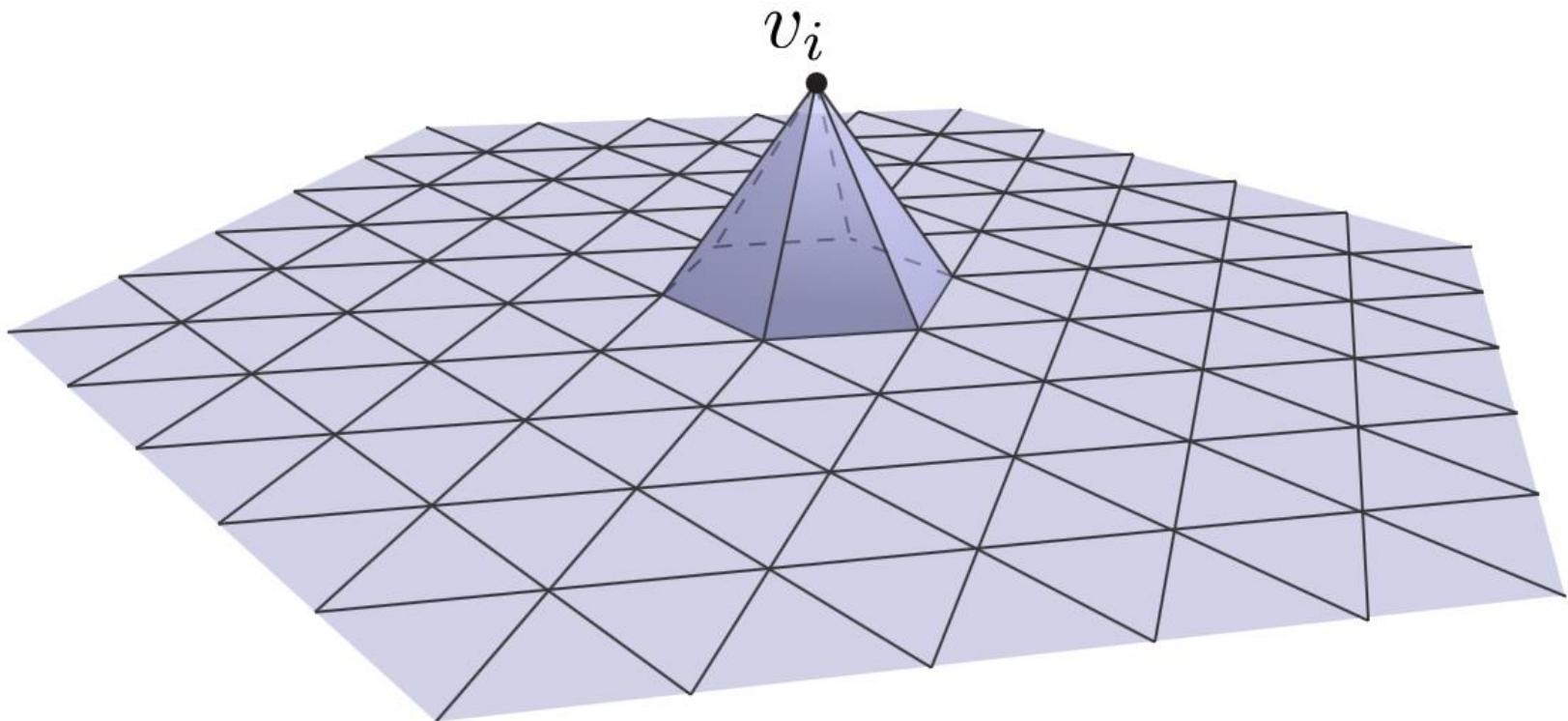
$$\vec{p} = p_n \vec{n} + p_e \vec{e} + p_\perp \vec{e}_\perp$$
$$A = \frac{1}{2} b \sqrt{p_n^2 + p_\perp^2}$$
$$\nabla_{\vec{p}} A = \frac{1}{2} b \vec{e}_\perp$$

$$\nabla f = \frac{\vec{e}_{23}^\perp}{2A} = \frac{\vec{e}_\perp}{h} = \frac{\nabla_{\vec{p}} A}{A}$$

Similar expression

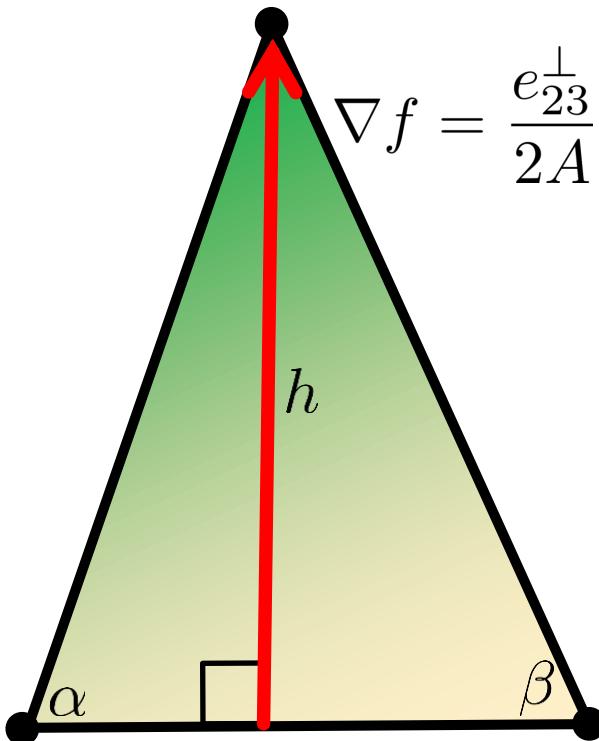
What We Actually Need

$$\mathcal{L}_{\Delta f}[g] = - \int_M \boxed{\nabla g \cdot \nabla f} dA$$



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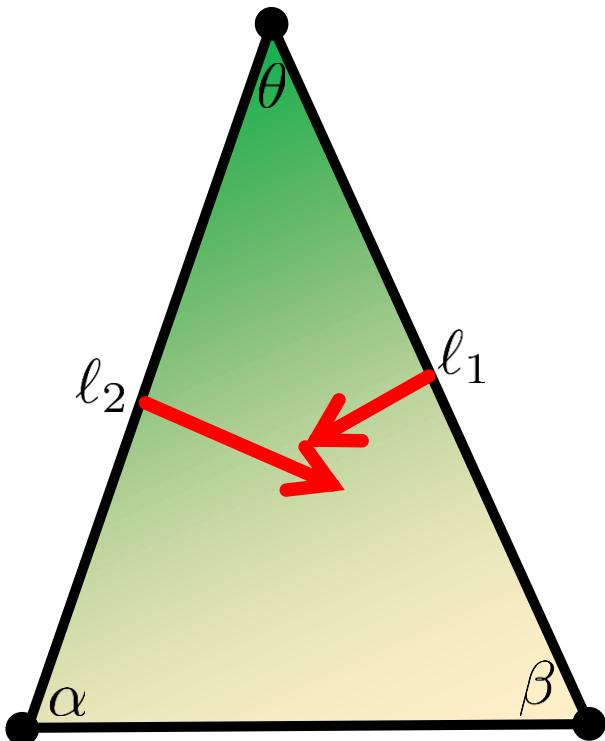
Case 1: Same vertex

$$\begin{aligned}\int_T \langle \nabla f, \nabla f \rangle dA &= A \|\nabla f\|^2 \\ &= \frac{A}{h^2} = \frac{b}{2h} \\ &= \frac{1}{2}(\cot \alpha + \cot \beta)\end{aligned}$$

What We Actually Need

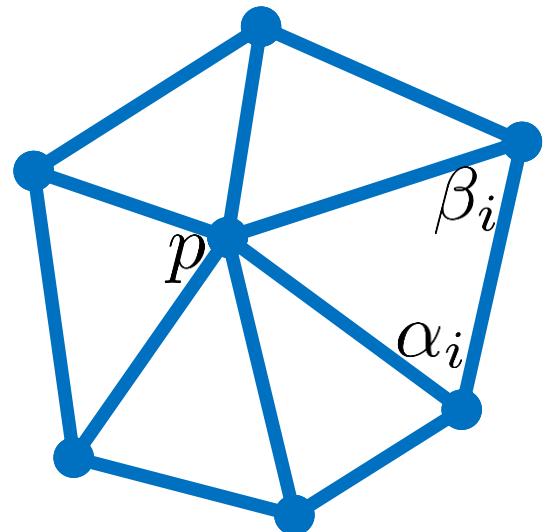
$$\mathcal{L}_{\Delta f}[g] = - \int_M \boxed{\nabla g \cdot \nabla f} dA$$

Case 2: Different vertices

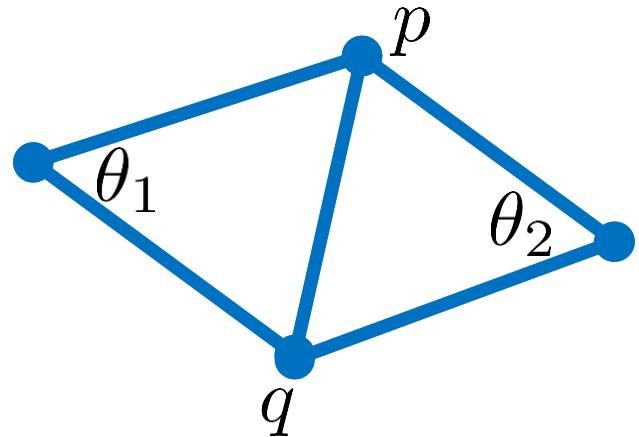


$$\begin{aligned}\int_T \langle \nabla f_\alpha, \nabla f_\beta \rangle dA &= A \langle \nabla f_\alpha, \nabla f_\beta \rangle \\&= \frac{1}{4A} \langle e_{31}^\perp, e_{12}^\perp \rangle = -\frac{\ell_1 \ell_2 \cos \theta}{4A} \\&= \frac{-h^2 \cos \theta}{4A \sin \alpha \sin \beta} = \frac{-h \cos \theta}{2b \sin \alpha \sin \beta} \\&= -\frac{\cos \theta}{2 \sin(\alpha + \beta)} = -\frac{1}{2} \cot \theta\end{aligned}$$

Summing Around a Vertex



$$\langle \nabla h_p, \nabla h_p \rangle = \frac{1}{2} \sum_i (\cot \alpha_i + \cot \beta_i)$$

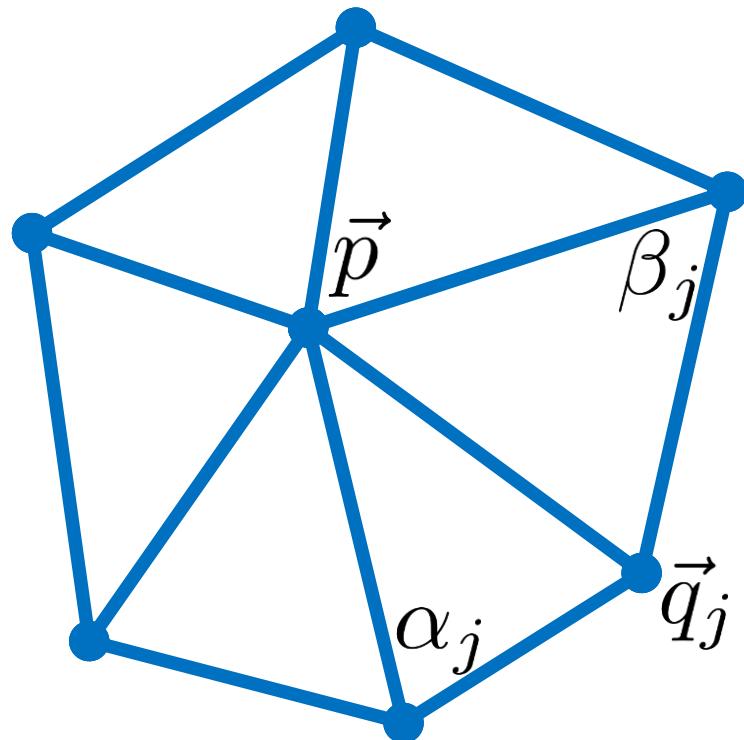


$$\langle \nabla h_p, \nabla h_q \rangle = \frac{1}{2}(\cot \theta_1 + \cot \theta_2)$$

Recall:

Summing Around a Vertex

$$\nabla_{\vec{p}} A = \frac{1}{2} \sum_j (\cot \alpha_j + \cot \beta_j) (\vec{p} - \vec{q}_j)$$

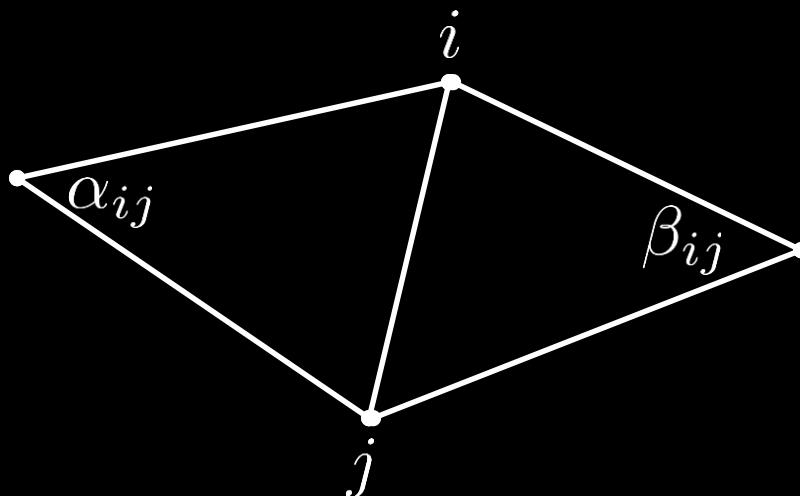


$$\nabla_{\vec{p}} A = \frac{1}{2} ((\vec{p} - \vec{r}) \cot \alpha + (\vec{p} - \vec{q}) \cot \beta)$$

Same weights up
to sign!

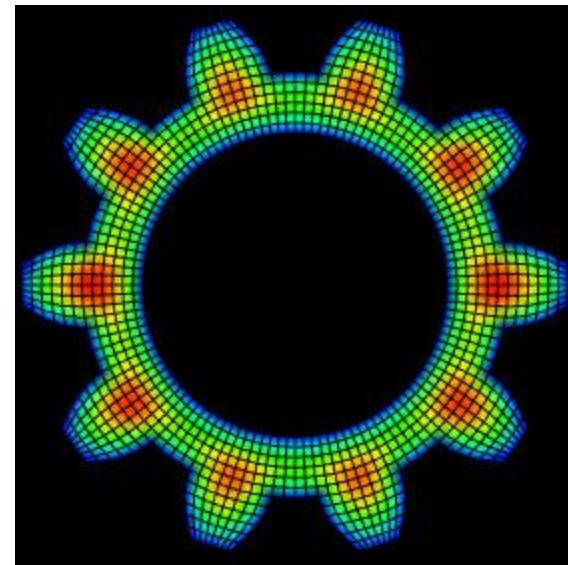
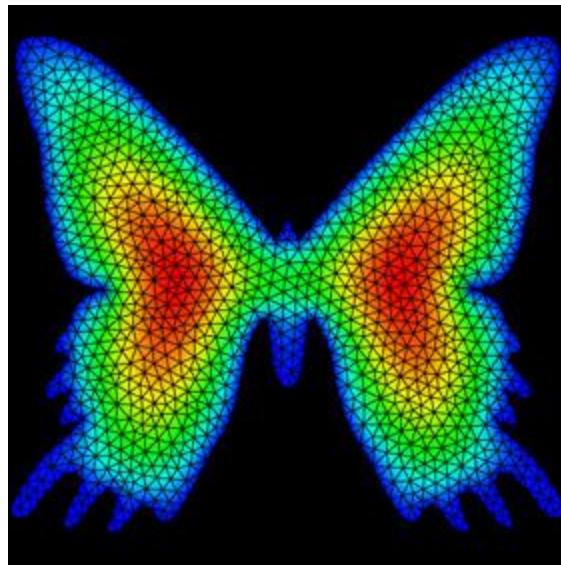
THE COTANGENT LAPLACIAN

$$L_{ij} = \begin{cases} \frac{1}{2} \sum_{k \sim i} (\cot \alpha_{ik} + \cot \beta_{ik}) & \text{if } i = j \\ -\frac{1}{2} (\cot \alpha_{ij} + \cot \beta_{ij}) & \text{if } i \sim j \\ 0 & \text{otherwise} \end{cases}$$



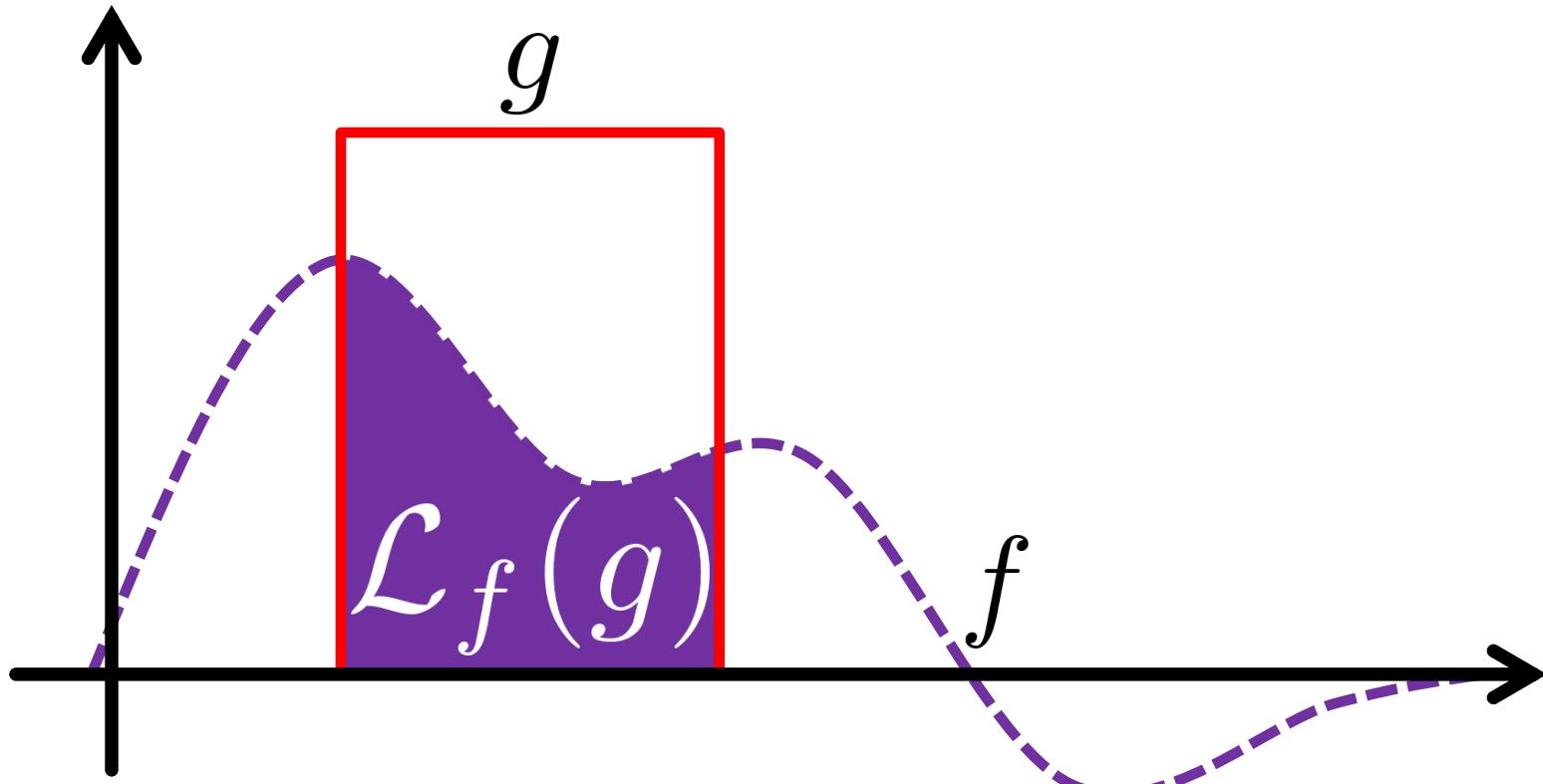
Poisson Equation

$$\Delta f = g$$



Weak Solutions

$$\int_M \phi \Delta f \, dA = \int_M \phi g \, dA \quad \forall \text{ test functions } \phi$$



FEM Hat Weak Solutions

$$\int_M h_i \Delta f \, dA = \int_M h_i g \, dA \quad \forall \text{ hat functions } h_i$$

$$\begin{aligned}\int_M h_i \Delta f \, dA &= - \int_M \nabla h_i \cdot \nabla f \, dA \\ &= - \int_M \nabla h_i \cdot \nabla \sum_j a_j h_j \, dA \\ &= - \sum_j a_j \int_M \nabla h_i \cdot \nabla h_j \, dA \\ &= \sum_j L_{ij} a_j\end{aligned}$$

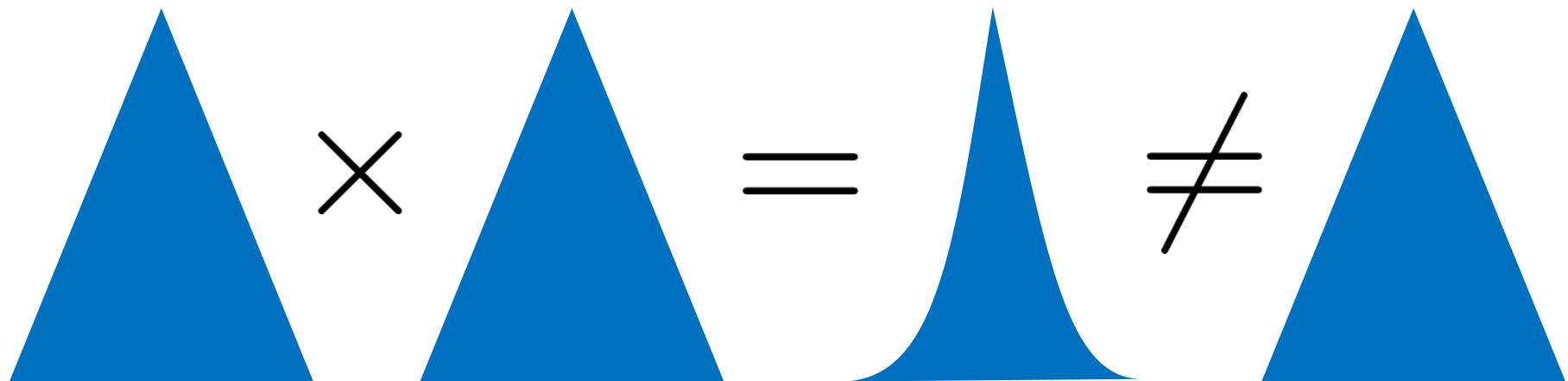
Stacking Integrated Products

$$\begin{pmatrix} \int_M h_1 \Delta f dA \\ \int_M h_2 \Delta f dA \\ \vdots \\ \int_M h_{|V|} \Delta f dA \end{pmatrix} = \begin{pmatrix} \sum_j L_{1j} a_j \\ \sum_j L_{2j} a_j \\ \vdots \\ \sum_j L_{|V|j} a_j \end{pmatrix} = L\vec{a}$$

Multiply by Laplacian matrix!

Problematic Right Hand Side

$$\int_M h_i \Delta f \, dA = \int_M h_i g \, dA \quad \forall \text{ hat functions } h_i$$



Product of hats is quadratic

A Few Ways Out

- Just do the integral
“Consistent” approach
- Approximate some more
- Redefine g

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“Consistent” approach
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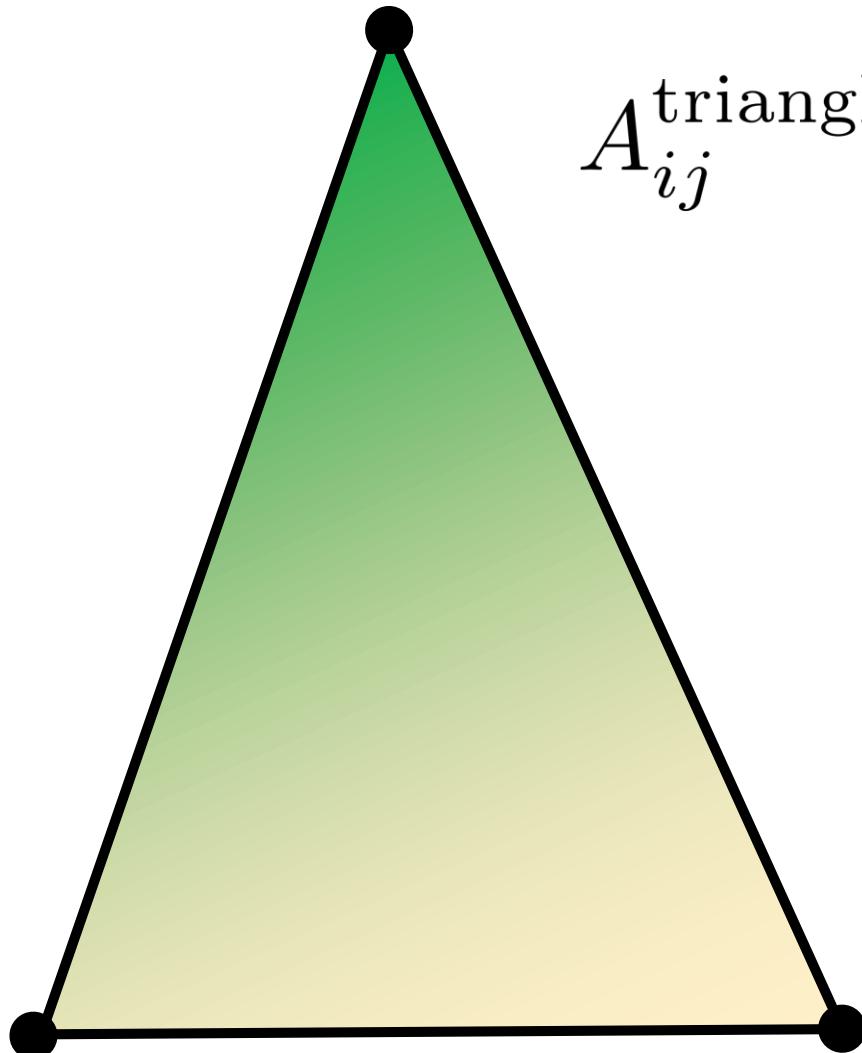
The Mass Matrix

$$A_{ij} := \int_M h_i h_j \, dA$$

- **Diagonal elements:**
Norm of h_i
- **Off-diagonal elements:**
Overlap between h_i and h_j

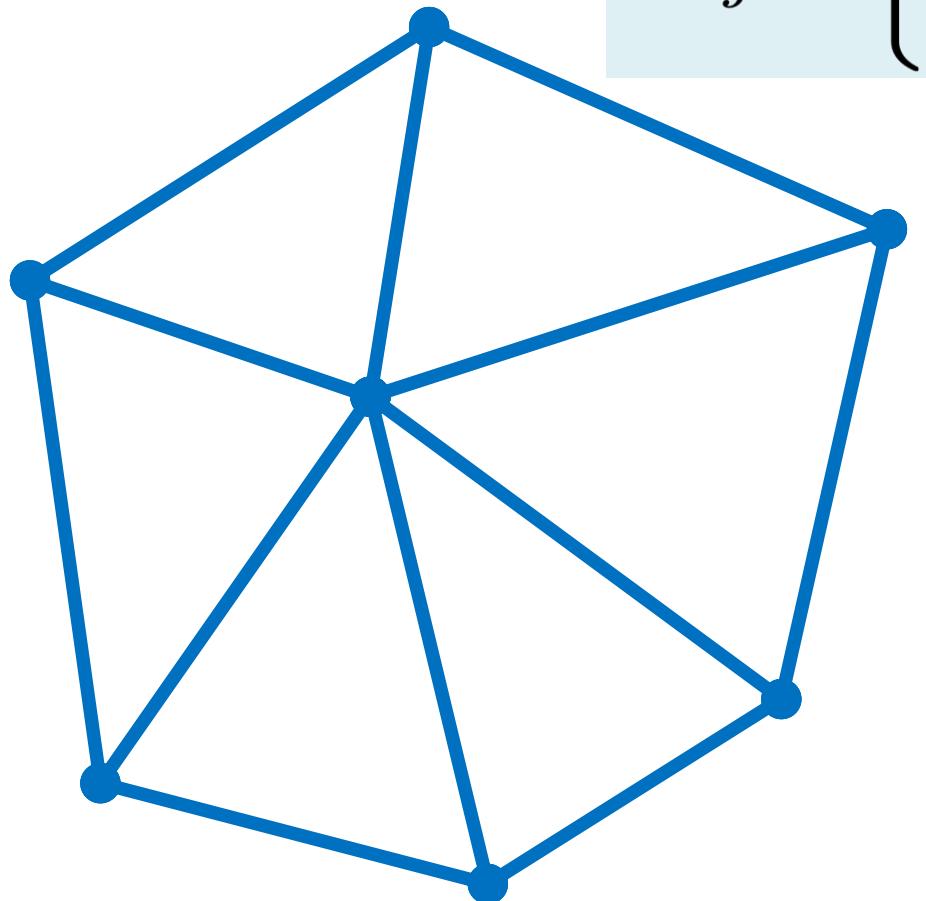
Consistent Mass Matrix

$$A_{ij}^{\text{triangle}} = \begin{cases} \frac{\text{area}}{6} & \text{if } i = j \\ \frac{\text{area}}{12} & \text{if } i \neq j \end{cases}$$



Non-Diagonal Mass Matrix

$$M_{ij} = \begin{cases} \frac{\text{one-ring area}}{6} & \text{if } i = j \\ \frac{\text{adjacent area}}{12} & \text{if } i \neq j \end{cases}$$



Properties of Mass Matrix

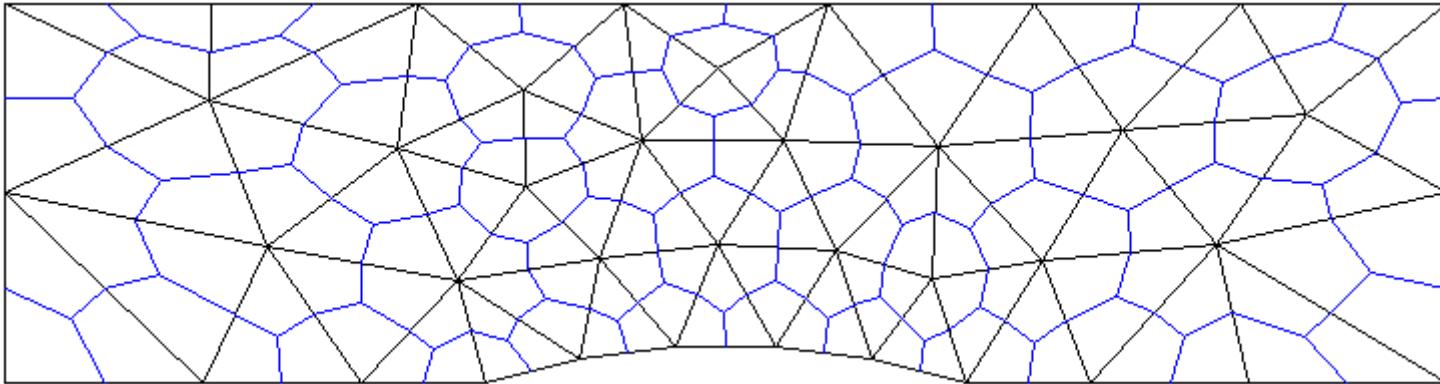
- Rows sum to one ring area / 3
- Involves only vertex and its neighbors
- Partitions surface area

Issue: Not diagonal!

Use for Integration

$$\begin{aligned}\int_M f &= \int_M \sum_j a_j h_j(\cdot 1) \\ &= \int_M \sum_j a_j h_j \sum_i h_i \\ &= \sum_{ij} A_{ij} a_j \\ &= \mathbf{1}^\top A \vec{a}\end{aligned}$$

Lumped Mass Matrix

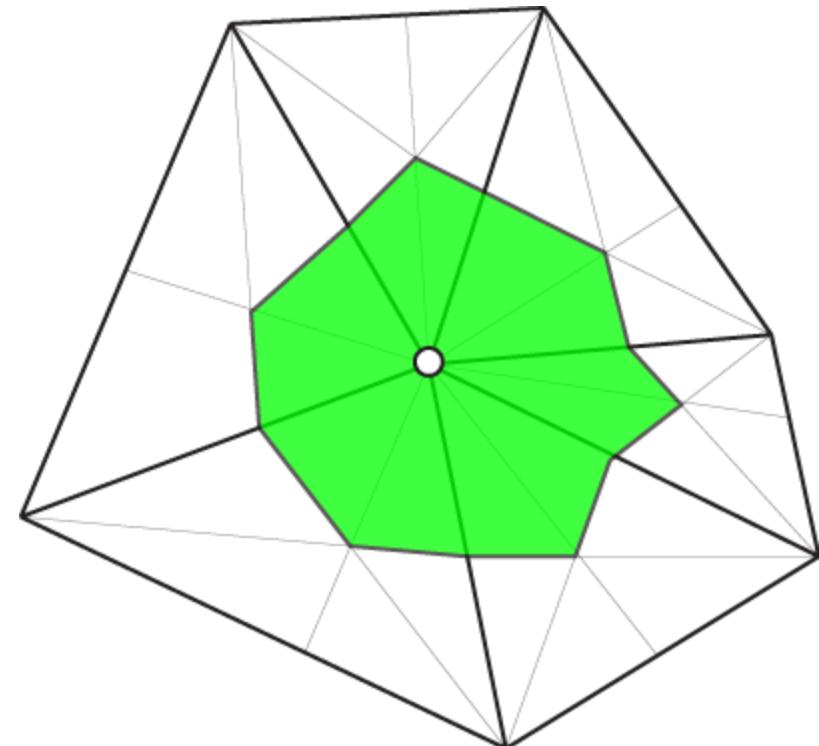
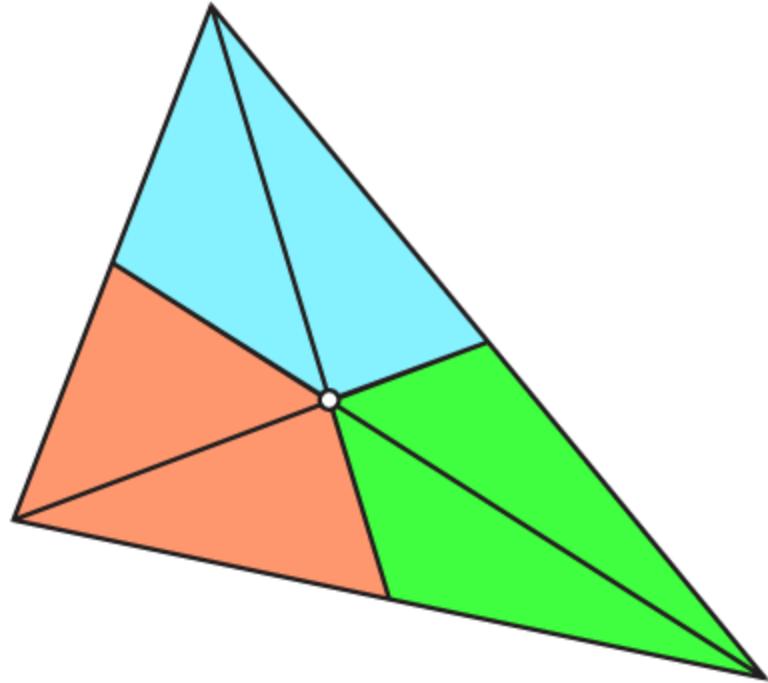


$$\tilde{a}_{ii} := \text{Area}(\text{cell } i)$$

Won't make big difference for smooth functions

Approximate with diagonal matrix

Simplest: Barycentric Lumped Mass



<http://www.alecjacobson.com/weblog/?p=1146>

Area/3 to each vertex

Ingredients

- **Cotangent Laplacian L**

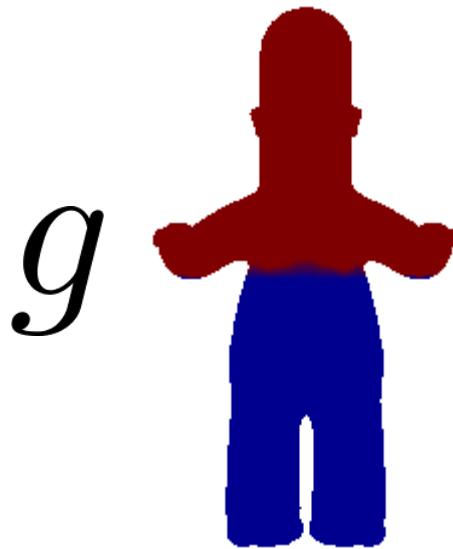
Per-vertex function to integral of its
Laplacian against each hat

- **Area weights A**

Integrals of pairwise products of hats
(or approximation thereof)

Solving the Poisson Equation

$$\Delta f = g \rightarrow \vec{L} \vec{f} = \vec{A} \vec{g}$$



g



f

Must integrate
to zero

Determined up
to constant

Important Detail: Boundary Conditions

$$\Delta f(x) = g(x) \quad \forall x \in \Omega$$

$$f(x) = u(x) \quad \forall x \in \Gamma_D$$

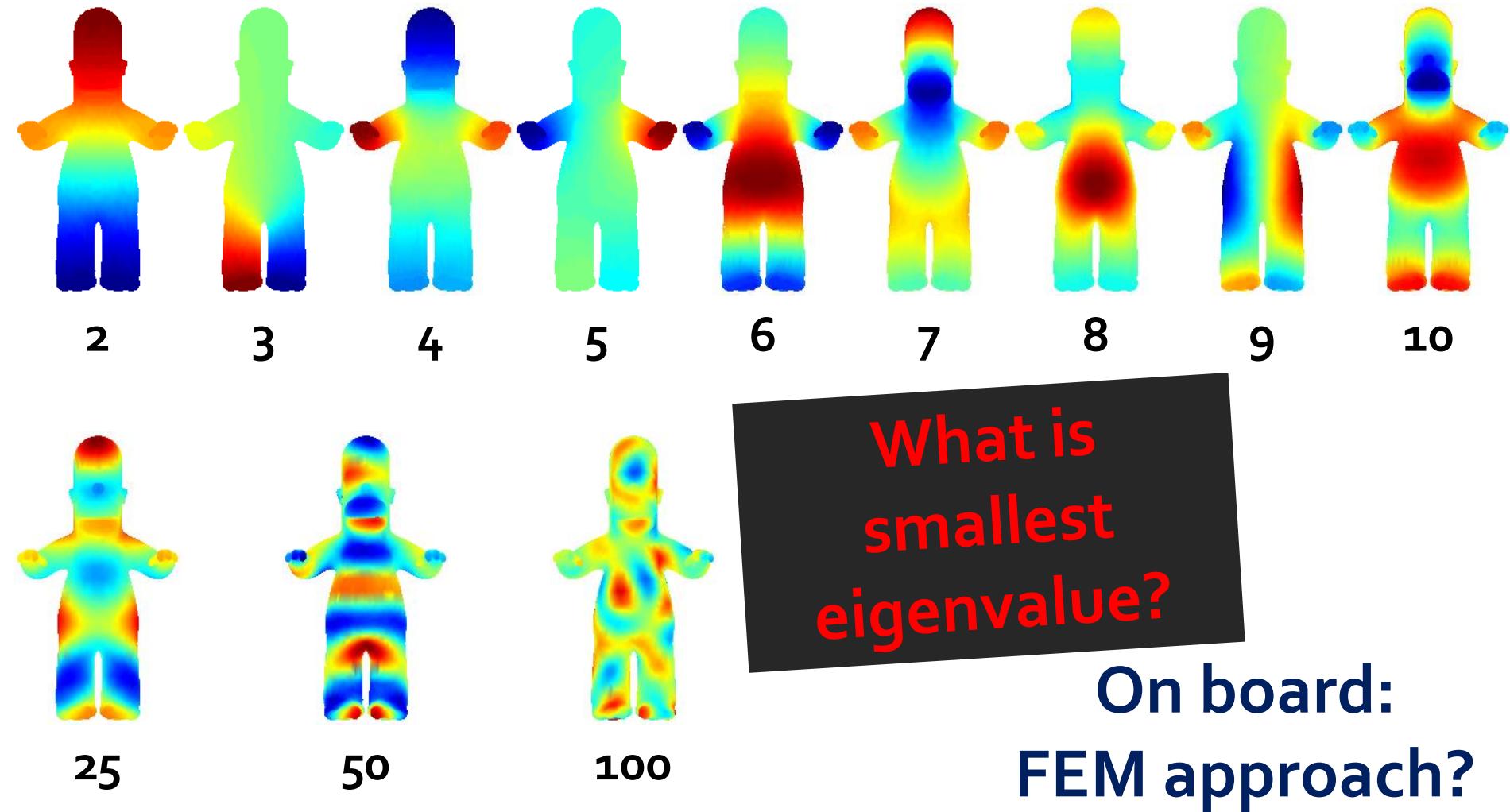
$$\nabla f \cdot n = v(x) \quad \forall x \in \Gamma_N$$

**Strong
form**

$$\int_{\Omega} \nabla f \cdot \nabla \phi = \int_{\Gamma_N} v(x) \phi(x) d\Gamma - \int_{\Omega} f(x) \phi(x) d\Omega$$
$$f(x) = u(x) \quad \forall x \in \Gamma_D$$

Weak form

Eigenhomers



Higher-Order Elements

The Table | Legend | Background | Download | Credits | Contact

https://www.femtable.org | finite element method

Periodic Table of the Finite Elements

The $\mathcal{P}_r \Lambda^k$ family The $\mathcal{P}_r \Lambda^k$ family The $\mathcal{Q}_r \Lambda^k$ family The $\mathcal{S}_r \Lambda^k$ family

		$k=0$	$k=1$	$k=2$	$k=3$		
$n=1$							
$n=2$							
$n=3$							
$n=1$							
$n=2$							
$n=3$							
$n=1$							
$n=2$							
$n=3$							
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$n=2$							
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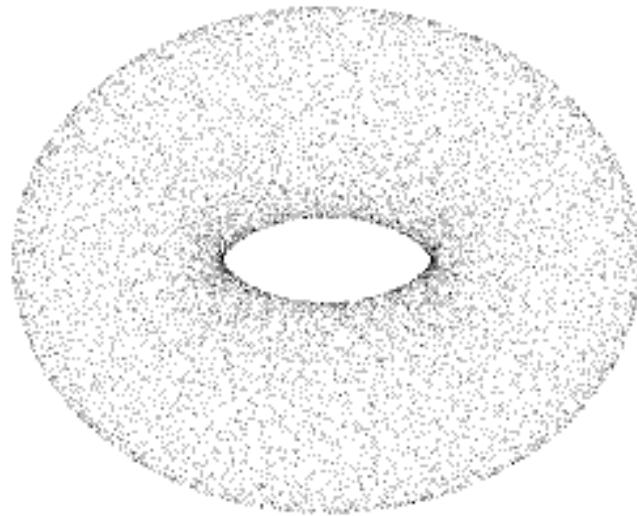
Point Cloud Laplace: Easiest Option

$$W_{ij} = \exp\left(-\frac{\|x_i - x_j\|^2}{t}\right)$$

$$D_{ii} = \sum_j W_{ji}$$

$$L = D - W$$

$$Lf = \lambda Df$$



“Laplacian Eigenmaps for Dimensionality Reduction and Data Representation”
Belkin & Niyogi 2003

Point Cloud Laplace: Easiest Option

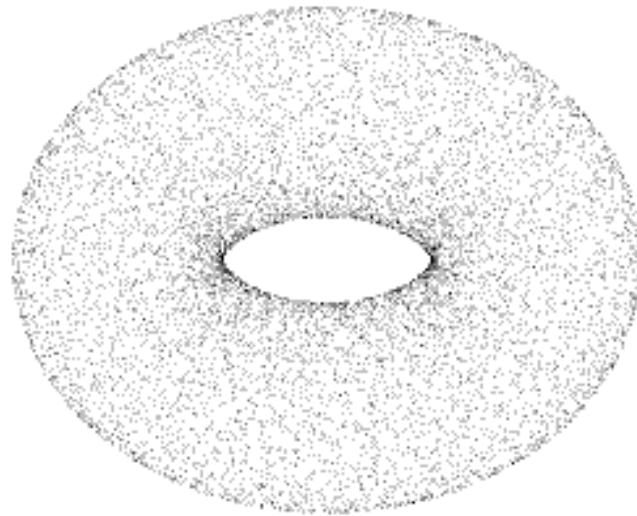
$$W_{ij} = \exp\left(-\frac{\|x_i - x_j\|^2}{t}\right)$$

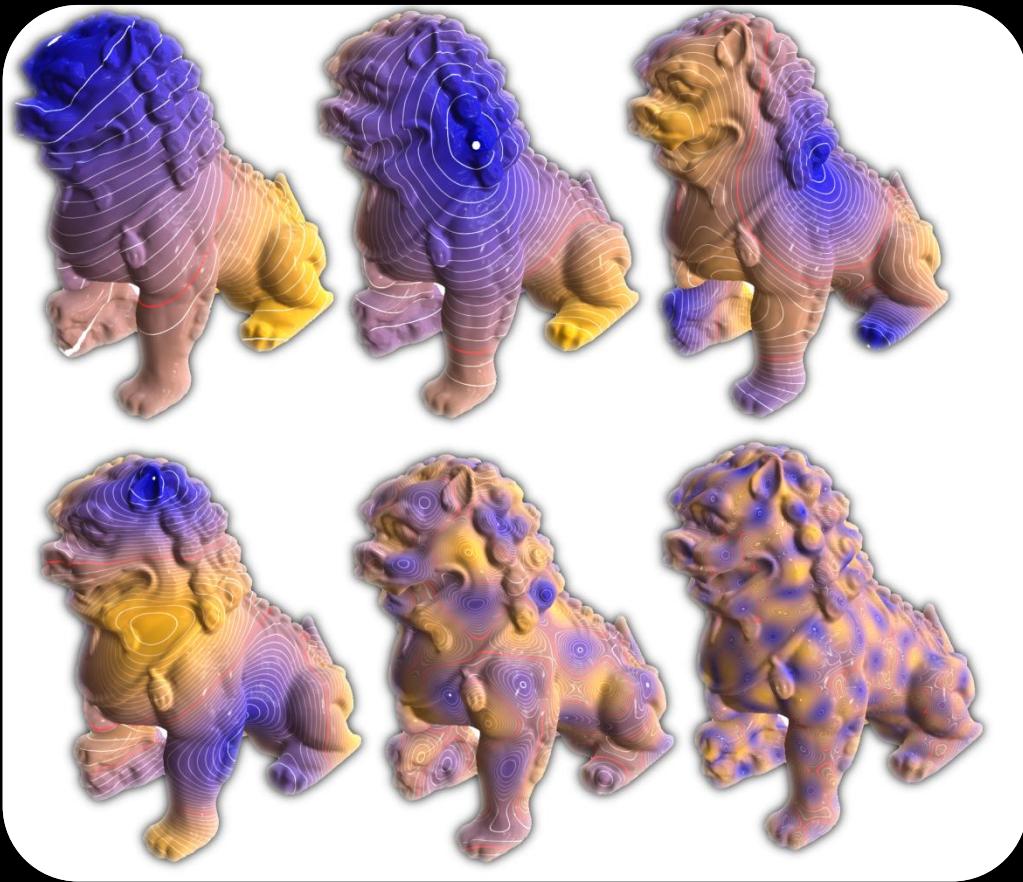
Tricky parameter to choose

$$D_{ii} = \sum_j W_{ji}$$

$$L = D - W$$

$$Lf = \lambda Df$$





Discrete Laplacians

Justin Solomon
MIT, Spring 2017

