

W-11

Example problems of DFT:

⑥ 1DFT of  $2\pi \delta(\omega - \omega_0) = ?$

$$\frac{1}{2\pi} \int_{-\pi}^{\pi} 2\pi \delta(\omega - \omega_0) e^{j\omega n} d\omega$$

$$= \int_{-\pi}^{\pi} \delta(\omega - \omega_0) e^{j\omega n} d\omega$$

$$= e^{j\omega_0 n} \Big|_{\omega = \omega_0}$$

$$= e^{j\omega_0 n}$$

$$e^{j\omega_0 n} \longleftrightarrow 2\pi \delta(\omega - \omega_0)$$

⑦

DTFT of  $\cos(\omega_0 n) = ?$

$$\cos(\omega_0 n) = \frac{e^{j\omega_0 n} + e^{-j\omega_0 n}}{2}$$

$$\longleftrightarrow \frac{1}{2} \cdot 2\pi \delta(\omega - \omega_0)$$

$$+ \frac{1}{2} 2\pi \delta(\omega + \omega_0)$$

$$= \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$

$$\cos(\omega_0 n) \longleftrightarrow \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$

⑧ 1DTFT of  $\left(1 - ae^{-jn}\right)^2 ; |a| < 1$ .

$$x(n) = a^n u(n)$$

$$X(n) = \frac{1}{1 - ae^{-jn}}$$

$$\begin{aligned} \frac{d x(n)}{dn} &= \frac{(1 - ae^{-jn}) \cdot 0 - \frac{d}{dn}(1 - ae^{-jn}) \cdot 1}{(1 - ae^{-jn})^2} \\ &= -\frac{(-ae^{-jn}(-j))}{(1 - ae^{-jn})^2} \end{aligned}$$

$$\frac{d X(n)}{dn} = \frac{-jae^{-jn}}{(1 - ae^{-jn})^2}$$

$$\Rightarrow \boxed{\frac{j d X(n)}{dn} = \frac{ae^{-jn}}{(1 - ae^{-jn})^2}}$$

$$n x(n) \quad n a^n u(n).$$

$$n a^n u(n) \rightarrow \frac{ae^{jn}}{(1 - ae^{-jn})^2}$$

$$+ -na^n u(n) \leftarrow \frac{-ae^{-jn}}{(1 - ae^{-jn})^2}$$

$$= \frac{(1 - ae^{-jn}) - 1}{(1 - ae^{-jn})^2}$$

$$= \frac{1}{1 - ae^{-jn}} - \frac{1}{(1 - ae^{-jn})^2}$$

$$\downarrow a^n u(n) - \tilde{x}(n)$$

$$\Rightarrow -n a^n u(n) = a^n u(n) - \tilde{u}(n)$$

$$\Rightarrow \tilde{u}(n) = a^n u(n) + n a^n u(n)$$

$$= a^n u(n) [1+n]$$

$$(n+1)a^n u(n) \longleftrightarrow \frac{1}{(1-a e^{-j\omega})^2}$$

→ IDTFT of given quantity

$$\frac{1}{(1-a e^{-j\omega})^2} = \frac{1}{(1-a e^{-j\omega})} \times \frac{1}{(1-a e^{-j\omega})}$$

$$\leftrightarrow a^n u(n) * a^n u(n)$$

$$= \sum_{k=-\infty}^{\infty} a^k u(k) a^{n-k} u(n-k)$$

$$= a^n \sum_{k=-\infty}^{\infty} u(k) u(n-k)$$

$$= a^n \sum_{k=0}^n 1 \quad \text{for } n > 0$$

$$= (n+1) a^n u(n) \quad \text{for } n > 0$$

→ IDTFT of given signal.

⑨ DTFT of  $u(n) = ?$

$$u(n) = \begin{cases} 1, & n \geq 0 \\ 0, & n < 0 \end{cases}$$

$$= x(n) + y(n)$$

$$x(n) = \frac{1}{2} + n,$$

$$y(n) = \frac{1}{2}, n > 0$$

$$= -\frac{1}{2}, n < 0$$

$$x(n) = \frac{1}{2}, 1 \leftrightarrow 2\pi \delta(\omega)$$

$$\Rightarrow \frac{1}{2} \leftrightarrow \pi \delta(\omega)$$

$$\Rightarrow x(n) = \pi \delta(n)$$

$$y[n] - y[n-1] = \delta(n).$$

$$\gamma(n)(1 - e^{-jn}) = 1$$

$$\Rightarrow \gamma(n) = \frac{1}{1 - e^{-jn}}$$

$$u(n) = x(n) + y(n)$$

$$\Rightarrow u(n) = x(n) + \gamma(n)$$

$$\Rightarrow \boxed{u(n) = \pi \delta(n) + \frac{1}{1 - e^{-jn}}}$$

DTFT of unit step signal

$$y(n) = \sum_{k=-\infty}^n x(k)$$

$$x(n) \leftrightarrow x(n)$$

$$y(n) \leftrightarrow ?$$

accumulation  
property  
of DTFT

Similar to integrator  
for CT signals.

$$\begin{aligned}
 y(n) &= \sum_{k=0}^n x(k) \\
 &\quad \because x(n) * u(n) \\
 &= \sum_{k=-\infty}^n x(k) u(n-k) \\
 &= \sum_{k=-\infty}^n x(n) \\
 y(n) &= x(n) u(n) \\
 &= x(n) \left\{ \pi s(n) + \frac{1}{1 - e^{-jn}} \right\} \\
 &= \pi x(n) \delta(n) + \frac{x(n)}{1 - e^{-jn}}
 \end{aligned}$$

$y(n) = \pi x(n) \delta(n) + \frac{x(n)}{1 - e^{-jn}}$

DTFT of accumulator.

#### L-64. Examples problems DTFT:

(10) Impulse response:

$$\underline{y(n) - \gamma_1 y(n-1) + \gamma_2 y(n-2) = x(n)}$$

Difference equation

Frequency response = ?

$$h(n) = ?$$

Taking DTFT on both sides

$$y(n) - \gamma_1 y(n) e^{-jn} + \gamma_2 y(n) e^{-j2n} = x(n)$$

$$y(n)(1 - \gamma_1 e^{-jn} + \gamma_2 e^{-j2n}) = x(n)$$

$$\frac{y(n)}{x(n)} = \frac{1}{1 - \gamma_1 e^{-jn} + \gamma_2 e^{-j2n}} = H(n)$$

Freq response

$$H(n) = \frac{1}{(1 - \gamma_1 e^{-jn})(1 - \gamma_2 e^{-jn})}$$

↳ P.F expansion

$$= \left\{ \frac{\gamma_2}{1 - \gamma_2 e^{-jn}} - \frac{\gamma_3}{1 - \gamma_3 e^{-jn}} \right\}$$

$\frac{1}{1 - ae^{-jn}}$   
[IDFT  
 $a^n u(n)$ ].

$$\left\{ \gamma_2 (1 - \gamma_2)^n u(n) - \gamma_3 (1 - \gamma_3)^n u(n) \right\}$$

$$h(n) = 3 \left(\frac{1}{2}\right)^n u(n) - 2 \left(\frac{1}{3}\right)^n u(n)$$

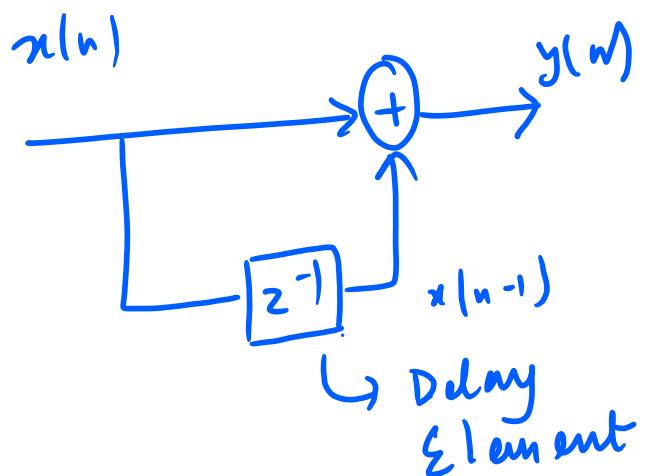
↳ impulse response of LTI system described by D.E.

(ii) Consider LTI system in Figure

$$H(n) = ?$$

$$h(n) = ?$$

3 dB frequency = ?



$$y(n) = x(n) + x(n-1)$$

DE for above system.

To find  $h(n)$ , let  $x(n) = \delta(n)$

$$h(n) = \delta(n) + \delta(n-1)$$

$$h(0) = \delta(0) + \delta(-1) \\ = 1$$

$$h(1) = 1$$

$$h(n) = 0 \quad \text{for } n \neq 0 \text{ or } 1$$

$$h(n) = \begin{cases} 1, & 0 \leq n \leq 1 \\ 0, & \text{otherwise} \end{cases}$$

Impulse response.

Taking DTFT

$$x(n) + e^{-jn} x(n) = h(n)$$

$$x(n)(1 + e^{-jn}) = h(n)$$

$$\Rightarrow H(n) = \frac{h(n)}{x(n)} = 1 + e^{-jn}$$

$$= e^{-jn/2} \{ e^{jn/2}, e^{-jn/2} \}$$

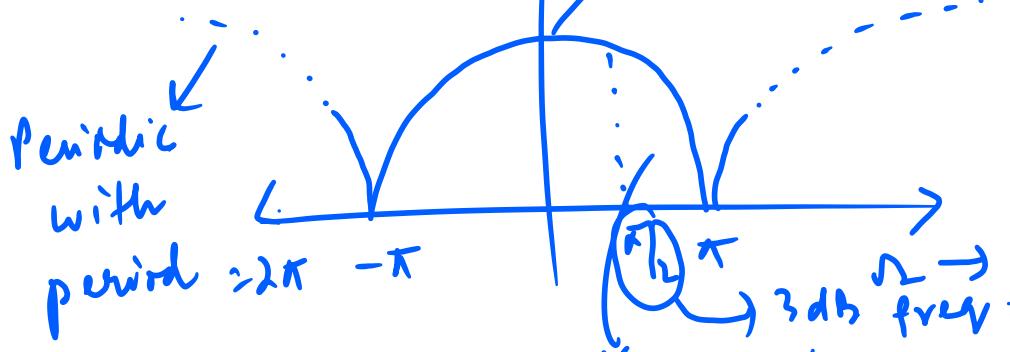
$$H(n) = e^{-jn/2} 2 \cos(n/2)$$

Freq response of given LTI system  $\rightarrow$  Periodic with

$$|H(n)| = 2 \left| \cos\left(\frac{n}{2}\right) \right| \quad \text{period} = 2\pi$$

$\downarrow$  Mag response

$$|H(n)| = 2$$



Non ideal D.T. lowpass filter.

3 dB freq = ?

$$\begin{aligned} \max |H(n)| &= |H(0)| \\ &= 2 |\cos 0| = 2 \end{aligned}$$

$$\begin{aligned} H(n_0) &> \frac{1}{\sqrt{2}} \max |H(n)| \\ &> \frac{1}{\sqrt{2}} \times 2 = \sqrt{2} \end{aligned}$$

$$2 \cos(n_0/2) > \sqrt{2}$$

$$\cos(n_0/2) > \frac{1}{\sqrt{2}}$$

$$\Rightarrow \frac{n_0}{2} > \frac{\pi}{4}$$

$$\Rightarrow n_0 > \frac{\pi}{2}$$

$$2 \text{ dB freq} = \pi/2$$

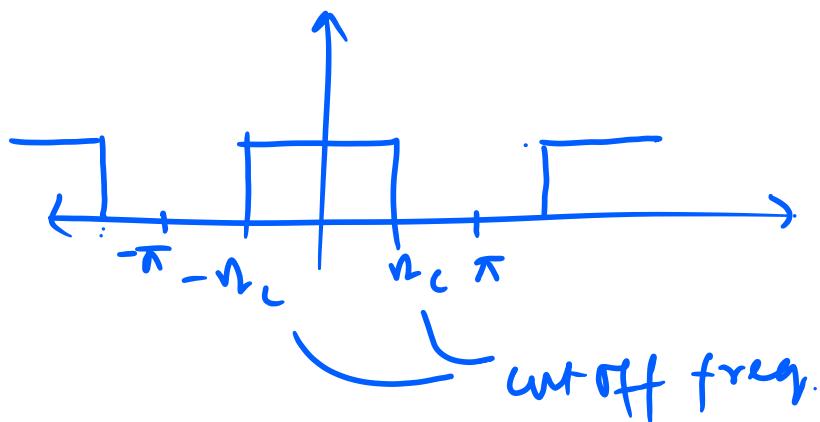
$$3 \text{ dB BW} = \pi/2$$

(12) HPF from LPF:

Let  $h(n)$  = impulse response of an ideal LPF Cutoff  $= w_c$

$$(-1)^n h(n) = \tilde{h}(n)$$

$$\tilde{H}(n) = ?$$



$$\begin{aligned}\tilde{h}(n) &= (-1)^n h(n) \\ &= (e^{j\pi})^n h(n) \\ &= e^{jn\pi} h(n) \\ &= e^{jn\omega_0 n} h(n)\end{aligned}$$

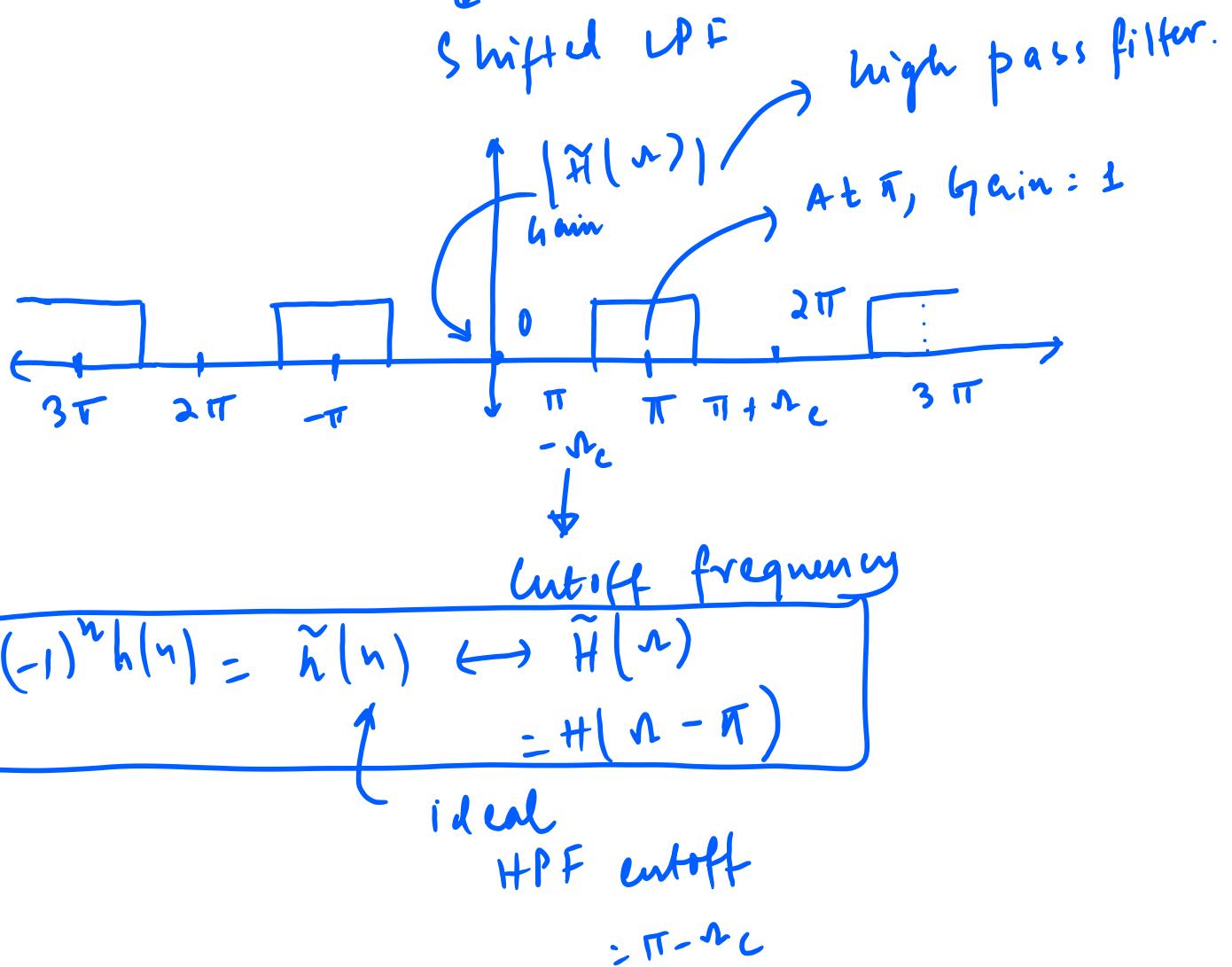
$e^{jn\omega_0 n} \rightarrow$  modulation property

$$h(n) \leftrightarrow H(n)$$

$$e^{jn\omega_0 n} \leftrightarrow H(n - n_0)$$

$$\boxed{\text{DTFT} \bar{H} = H(n - \tau)}$$

$$\tilde{H}(n) = H(n - \pi)$$



L-65 Example problems (DTFT)

(13)  $y(n) = -\sum_{k=1}^n a_k y(n-k) + \sum_{k=0}^M b_k x(n-k)$

DE for LTI system LPF

What is corresponding DE for HPF?

Taking DTFT,

$$y(n) + \sum_{k=1}^N a_k e^{jkn} x(n) = \sum_{k=1}^M b_k e^{jkn} x(n)$$

$$H(n) = \frac{y(n)}{x(n)}$$

Transfer function

$$= \frac{\sum_{k=1}^M b_k e^{-jkn}}{1 + \sum_{k=1}^N a_k e^{-jkn}}$$

To get HPF, shift by  $\pi$

$$\Rightarrow \Omega \rightarrow \Omega - \pi$$

$$\tilde{H}(n) = \frac{\sum_{k=1}^M b_k e^{j k (\Omega - \pi)}}{1 + \sum_{k=1}^N a_k e^{-j k (\Omega - \pi)}} \\ = \frac{\sum_{k=1}^M b_k (e^{j\pi})^k e^{-jkn}}{1 + \sum_{k=1}^N a_k (e^{j\pi})^k e^{-jkn}}$$

$$\tilde{H}(n) = \frac{y(n)}{x(n)} = \frac{\sum_{k=1}^M (-1)^k a_k e^{-jkn}}{1 + \sum_{k=1}^N (-1)^k b_k e^{-jkn}}$$

$$\Rightarrow Y(z) \left( 1 + \sum_{k=1}^N (-1)^k b_k e^{-jk\pi} \right)$$

$$= x(z) \sum_{k=1}^N a_k (-1)^k e^{-jk\pi}$$

inverse DTFT

$$\Rightarrow y(n) = - \sum_{k=1}^N (-1)^k b_k y(n-k)$$

$$+ \sum_{k=1}^N (-1)^k a_k x(n-k)$$

difference equation of HPF.

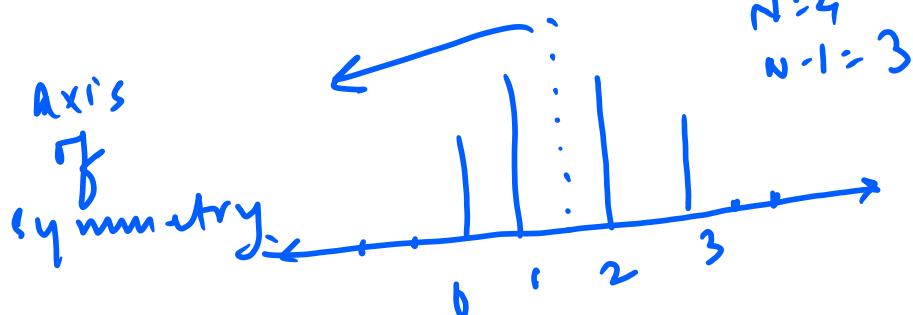
⑭ Consider impulse response  $h(n)$

$$h(n) = \text{real}$$

$$h(n) = 0, n < 0 \text{ or } n > N$$

Non-zero only for  $0 \leq n \leq N-1$ .

$$h(n) = h(N-1-n)$$



$$h(0) = h(3-0) \\ = h(3)$$

$$h(1) = h(3-1) = h(2)$$

Find phase response of  $\theta(n)$ .  
=?

$$h(n) = h(N-1-n)$$

↳ reverse the flip by  $n$  + delay  
by  $N-1$

$$\tilde{h}(n) = h(-n) \quad = \text{same filter.}$$

$$\Rightarrow \tilde{H}(\omega) = H(-\omega)$$

Time reversal  
property

Delay by  $N-1$

$$\tilde{\tilde{h}}(n) = \tilde{h}(n-(N-1))$$

$$= h(N-1-n)$$

$$= h(n)$$

$$\tilde{\tilde{H}}(\omega) = \tilde{H}(\omega) e^{-j(N-1)\omega}$$

$$= H(-\omega) e^{-j(N-1)\omega}$$

$$= H^*(\omega) e^{-j(N-1)\omega}$$

$$\begin{aligned} (1) &\leftarrow = |H(\omega)| e^{-j\theta(\omega)} e^{-j(N-1)\omega} \\ \text{from } & \\ \text{symmetry } &\leftarrow = H(\omega) \boxed{= H(\omega) e^{j\theta(\omega)}} \\ \text{of filter} & \quad \quad \quad (2) \end{aligned}$$

Equating phases of both terms, we have

$$-\theta(\omega) - (N-1)\omega = \theta(\omega)$$

$$\Rightarrow 2\theta(\omega) = -(N-1)\omega$$

linear phase:  $\boxed{\theta(\omega) = -\frac{1}{2}(N-1)\omega} \rightarrow$  linear phase constraint.

(B)

Sampling: C.T  $\rightarrow$  D.Tconsider  $RC = 2$ 

DT filter obtained by

Sampling impulse response with

sampling intervals

 $T_s$ .

→ Impulse response of Transfer function.

$$y(t) + RC \frac{dy(t)}{dt} = x(t)$$

$$\Rightarrow Y(s) + 2sY(s) = X(s) \quad \left. \begin{array}{l} \text{given} \\ RC = 2 \end{array} \right\}$$

$$\Rightarrow (1+2s)Y(s) = X(s)$$

$$\Rightarrow \frac{Y(s)}{X(s)} = \frac{1}{1+2s} = \frac{1}{2(s+\frac{1}{2})}$$

$$\Rightarrow H(s) = \frac{1}{2} e^{-\frac{t}{2}} u(t).$$

taking inverse

 $h(n) = \text{samped version of } h(t).$ 

$$\tilde{h}(n) = h(nT_s)$$

$$= \frac{1}{2} e^{-nT_s/2} u(nT_s)$$

$$= \frac{1}{2} e^{-nT_s/2} u(n)$$

$$\tilde{h}(n) = \frac{1}{2} (e^{-T_s/2})^n u(n) = \frac{1}{2} a^n u(n)$$

↑ Impulse response of  
equivalent DT system

Z-transform

$$\tilde{H}(z) = \frac{1}{1 - e^{-T_s/2} z^{-1}}$$

↑ Transfer function of equivalent  
DT system.

$$\tilde{H}(z) = \frac{1}{1 - e^{-T_s/2} e^{-jn\omega}}$$

$$\frac{y(n)}{x(n)} = \frac{1}{1 - e^{-T_s/2} e^{-jn\omega}}$$

$$\Rightarrow y(n) (1 - e^{-T_s/2} e^{-jn\omega}) = x(n)$$

$$\Rightarrow \boxed{y(n) - e^{-T_s/2} y(n-1) = x(n)}$$

↓ DT system equivalent  
DT system

L-66 Example problems.

(b) Consider the C.T system with

$$H(s) = \frac{1}{(s+2)(s+3)}$$

sample with duration  
 $= T_s$

what is  $H_d(s)$  DTFT of resulting system?

$$H(s) = \frac{1}{(s+2)(s+3)}$$

$$= \frac{1}{s+2} - \frac{1}{s+3}$$

$$\hookrightarrow e^{-2t} u(t) - e^{-3t} u(t)$$

$$h(t) = (e^{-2t} - e^{-3t}) u(t)$$

↳ impulse response

$$h(nT_s) = h_d(n) \xrightarrow{\text{DT impulse response}}$$

$$(e^{-2nT_s} - e^{-3nT_s}) u(nT_s)$$

$$= e^{-2nT_s} u(n) - e^{-3nT_s} u(n)$$

$$= (e^{-2T_s})^n u(n) - (e^{-3T_s})^n u(n)$$

$$H_d(z) = \frac{1}{1 - e^{-2T_s} z^{-1}} - \frac{1}{1 - e^{-3T_s} z^{-1}}$$

Substitute  $z = e^{j\omega}$

$$H_d(\omega) = \frac{1}{1 - e^{-2T_s} e^{-j\omega}}$$

$$- \frac{1}{1 - e^{-3T_s} e^{-j\omega}}$$

↳ frequency response of  
corresponding DT system.

(17) Consider LTI system with IIR  $h(n)$



Infinite impulse response

Find FIR (Finite Impulse Response) approximation s.t.

$$\tilde{h}(n) = 0, n < 0$$

$$\text{such that } \int_{-\pi}^{\pi} |H(\omega) - \tilde{H}(\omega)|^2 d\omega$$

↑ non-zero only for  $0 \leq n \leq N-1$

But

FIR  
approximation to  
given IIR

Observe

$$h(n) \leftrightarrow H(\omega)$$

$$\tilde{h}(n) \leftrightarrow \tilde{H}(\omega)$$

$$\Rightarrow h(n) - \tilde{h}(n) \leftrightarrow H(\omega) - \tilde{H}(\omega)$$

from Linearity

Parseval's theorem

$$\frac{1}{2\pi} \int_{-\infty}^{\infty} |H(\omega) - \tilde{H}(\omega)|^2 d\omega$$

$$= \sum_{n=-\infty}^{\infty} |h(n) - \tilde{h}(n)|^2$$

$$\tilde{h}(n) = 0$$

$$\text{Do not depend on } \tilde{h}(n) = \sum_{n=-\infty}^{-1} |h(n)|^2 + \sum_{n=N}^{\infty} |h(n)|^2 = c$$

$$+ \sum_{n=0}^{N-1} (h(n) - \tilde{h}(n))^2$$

To minimise error

minimise this to minimise original error.

always 0

min occurs when

$$h(n) = \tilde{h}(n)$$

$$0 \leq n \leq N-1$$

Best FIR approximation to  $h(n)$  given IIR

$$\tilde{h}(n) = \begin{cases} 0, & n < 0 \\ 1, & n \geq N-1 \\ h(n), & 0 \leq n \leq N-1 \end{cases}$$

filter.

This minimises the squared error of the frequency response.

(19)

DFT

↳ Discrete Fourier Transform

$$x(n) = \sin\left(\frac{\pi}{2}n\right) \quad 1 \leq n \leq 3$$

$$h(n) = 2^n \quad 1 \leq n \leq 3.$$

$$\underline{N=4}$$

$$\text{length} = 4$$

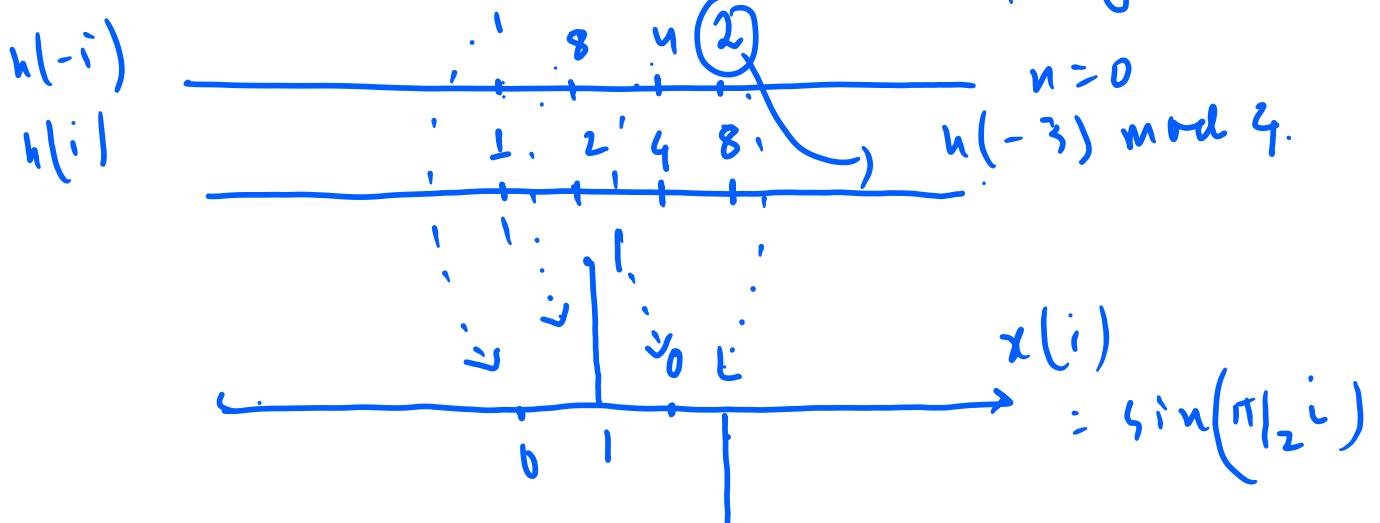
$$y(n) = x(n) \circledast h(n)$$

↳ circular convolution

$$y(n) = \sum_{i=0}^{N-1} x(i) h(n-i) \bmod N.$$

↳ circular convolution

Convolution by wrapping around



$$y(0) = \sum_{i=0}^3 x(i) h(-i) \bmod 4$$

$$= x(0) h(0) + x(1) h(-1) \bmod 4$$

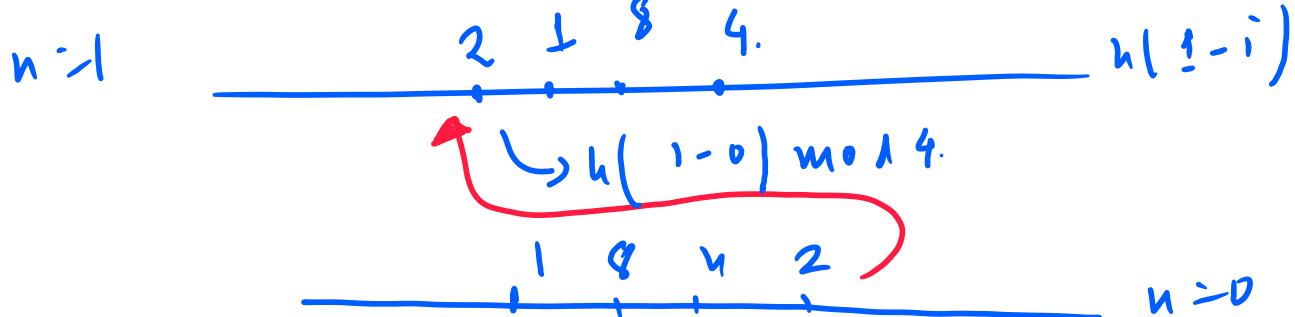
$$+ x(2) h(-2) \bmod 4 + x(3) h(-3) \bmod 4$$

$$= x(0) h(0) + x(1) h(3) + x(2) h(2) \\ + x(3) h(1)$$

$$= 0 \times 1 + 1 \times 8 + 0 \times 4 + (-1 \times 2)$$

$$= 1 \times 8 - 1 \times 2$$

$$= 6$$



$$\begin{aligned}
 y(1) &= x(0) h(1) + x(1) h(0) \text{ mod } 4 \\
 &\quad + x(2) h(-1) \text{ mod } 4 \\
 &\quad \times x(3) h(-2) \\
 &= x(0) h(1) + x(1) h(0) \\
 &\quad + x(2) h(3) + x(3) h(2) \\
 &= 1 \times 1 - 4 \times 1 \\
 &\quad + 2 \times 3 + 3 \times 2 = -3
 \end{aligned}$$

$$y(2) = 2 \times 1 + 8 \times (-1)$$

$$= 2 - 8 = -6$$

$$y(3) = 4 \times 1 + 1 \times (-1)$$

$$= 4 - 1$$

$$= 3.$$

$$y(n) = \underbrace{(-1)^n}_{0 \leq n \leq 3}$$

• How to find a circular comb of given signals.

L-67. Example problems (DFT):

$$x(u) = \sin(\pi l_2 u) \quad 0 \leq u \leq 3.$$

$$= 0, \pm 1, -1$$

$$h(n) = 1, 2, 4, 8 \dots$$

$$y(u) = x(u) \otimes h(u)$$

↳ circular convolution

Evaluate circular convolution using DFT

DFT

$$W_N = W_4 = e^{-j2\pi/4} = e^{-j\pi/2}$$

$$= e^{-j\pi/2} = -j$$

$$X(k) = \sum_{n=0}^{N-1} x(n) W_N^{kn}$$

$$= x(0) + x(1) W_N^k + x(2) W_N^{2k} + x(3) W_N^{3k}$$

$$X(k) = W_N^k - W_N^{3k}$$

$$H(k) = \sum_{n=0}^{N-1} h(n) W_N^{nk}$$

$$= 1 + 2W_N^k + 4W_N^{2k} + 8W_N^{3k}$$

$$Y(k) = X(k) H(k)$$

$$= (W_N^k - W_N^{3k}) \times (1 + 2W_N^k + 4W_N^{2k} + 8W_N^{3k})$$

$$W_N^{nk} = (e^{-j2\pi/n})^{nk}$$

$$= e^{-j2\pi k} = 1$$

$$W_N^{nk} = 1$$

$\hookrightarrow N=4$   
in this example

$$Y(k) = (W_N^k - W_N^{3k}) (1 + 2W_N^k + 4W_N^{2k} + 8W_N^{3k})$$

$$= w_N^k - w_N^{3k} + 2w_N^{2k} - 2 + 4w_N^{3k} - 4w_N^k + 8$$

$$- 8w_N^{2k}$$

$$y(k) = b - 3w_N^k - 6w_N^{2k} + 3w_N^{3k}$$

$$= y(0) + y(1)w_N^k + y(2)w_N^{2k} + y(3)w_N^{3k}$$

$$y(0) = b$$

$$y(1) = -3$$

$$y(2) = -b$$

$$y(3) = 3$$

Time Domain evaluation.

(19) DFT of  $e^{j\omega_0 n}$        $0 \leq n \leq N-1$

$$\omega_0 = \frac{2\pi k}{N}$$

$$X(k) = \sum_{n=0}^{N-1} x(n) w_N^{kn}$$

$$= \sum_{n=0}^{N-1} e^{j\omega_0 n} w_N^{kn}$$

$$= \sum_{n=0}^{N-1} \left( e^{j\omega_0} w_N^k \right)^n$$

$$= \frac{1 - e^{j\omega_0 N}}{1 - e^{j\omega_0}} w_N^{NK}$$

$$\begin{aligned}
 &= \frac{1 - e^{j\omega_0 N} e^{-j\frac{2\pi}{N} k N}}{1 - e^{j\omega_0} e^{-j\frac{2\pi}{N} k N}} \\
 &\stackrel{k}{=} \frac{1 - e^{-j(\omega_0 - 2\pi k/N)^N}}{1 - e^{-j(\omega_0 - 2\pi k/N)}} \\
 &= \frac{e^{j(\omega_0 - 2\pi k/N)^{N/2}}}{e^{j(\omega_0 - 2\pi k/N)^{N/2}} - e^{-j(\omega_0 - 2\pi k/N)^{N/2}}} \\
 &\times \frac{e^{-j(\omega_0 - 2\pi k/N)^{N/2}}}{e^{-j(\omega_0 - 2\pi k/N)^{N/2}} - e^{-j(\omega_0 - 2\pi k/N)^{N/2}}} \\
 x(k) &= e^{j(\omega_0 - \frac{2\pi k}{N}) \frac{(N-1)}{2}} \times \frac{\sin\left((\omega_0 - \frac{2\pi k}{N}) \frac{N}{2}\right)}{\sin\left((\omega_0 - \frac{2\pi k}{N}) \frac{1}{2}\right)}
 \end{aligned}$$

Kth DFT coefficient

L-48 Example problems for discrete Fourier transforms.

(20) DFT, IDFT in MATRIX form

$$\bar{x} = \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix} \rightarrow N \times 1 \text{ vector} = N \text{ samples}$$

$$\bar{x} = \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}$$

↓  
DFT  
coefficients

Express :  $\bar{x} = W_N \bar{z}$

$\bar{z} = \tilde{W}_N^{-1} \bar{x}$

DFT Matrix

IDFT Matrix.

Linear Transformations.

DFT given as

$$x(k) = \sum_{n=0}^{N-1} z(n) W_N^{kn}$$

$$x(0) = z(0) + z(1) + \dots + z(N-1)$$

$$x(1) = z(0) + z(1) W_N + z(2) W_N^2 + \dots + z(N-1) W_N^{N-1}$$

$$x(2) = z(0) + z(1) W_N^2 + z(2) W_N^4 + \dots + z(N-1) W_N^{2(N-1)}$$

$$x(N-1) = z(0) + z(1) W_N^{N-1} + z(2) W_N^{2(N-1)} + \dots + z(N-1) W_N^{(N-1)^2}$$

Write in matrix form

$$\begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix} = \underbrace{\begin{bmatrix} 1 & 1 & \dots & 1 \\ 1 & w_N & w_N^2 & \dots & w_N^{N-1} \\ 1 & w_N^2 & w_N^4 & \dots & w_N^{2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w_N^{N-1} & w_N^{2(N-1)} & \dots & w_N^{(N-1)^2} \end{bmatrix}}_T \begin{bmatrix} z(0) \\ z(1) \\ \vdots \\ z(N-1) \end{bmatrix}$$

$N \times N$  matrix  $\xrightarrow{\text{DFT}}$   $N \times 1$  signal vector

$w_N = e^{-j2\pi/N}$

$$\overline{x} = w_N \bar{x}$$

$$\begin{aligned} z(n) &= \frac{1}{N} \sum_{k=0}^{N-1} x(k) w_N^{-kn} \\ &= \frac{1}{N} \sum_{k=0}^{N-1} x(k) e^{j2\pi kn/N} \end{aligned}$$

$$\begin{bmatrix} z(0) \\ z(1) \\ \vdots \\ z(N-1) \end{bmatrix} = \frac{1}{N} \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & w_N^{-1} & w_N^{-2} & \dots & w_N^{-(N-1)} \\ 1 & w_N^{-2} & w_N^{-4} & \dots & w_N^{-2(N-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & w_N^{-(N-1)} & w_N^{-2(N-1)} & \dots & w_N^{-(N-1)^2} \end{bmatrix} \begin{bmatrix} x(0) \\ x(1) \\ \vdots \\ x(N-1) \end{bmatrix}$$

$N \times 1$  Signals vector  $\xrightarrow{\tilde{w}_N = N \times N \text{ DFT matrix}}$   $N \times 1$  DFT vector

$$\boxed{\bar{x} = \tilde{w}_N \bar{x}} \rightarrow ②$$

From ①, ②

$$\bar{x} = \tilde{w}_N^{-1} \bar{x} = \tilde{w}_N w_N \bar{x}$$

$$\Rightarrow \bar{x} = \tilde{w}_N w_N \bar{x}$$

$$\boxed{\tilde{w}_N w_N = I}$$

$$\tilde{w}_N^{-1} = \tilde{w}_N^{-1}$$

$$\tilde{w}_N^{-1} = w_N^{-1}$$

$$w_N(2,3) = w_N^2 = w_N(3,2)$$

$$w_N(i,j) = w_N(j,i).$$

$$\boxed{w_N = w_N^T}$$

Prop 1

$$\tilde{w}_N^{-1} = w_N^{-1}$$

Prop 2

$$\Rightarrow w_N = w_N^T$$

$$\tilde{w}_N(i,j) = \tilde{w}_N(j,i)$$

$$\Rightarrow \tilde{w}_N = \tilde{w}_N^T$$

Prop 3  $\epsilon_x$   $w_N(2,3) = w_N^2$   
 $= e^{j\pi/N}$   
 $\tilde{w}_N(2,3) = 1/N w_N^{-2}$

$$= \frac{1}{N} e^{j\frac{4\pi}{N}}$$

$$\Rightarrow \tilde{W}_N(2,3) = \frac{1}{N} (W_N(2,3))^*$$

- $\tilde{W}_N = \frac{1}{N} W_N^*$
- $= \frac{1}{N} (W_N^T)^*$

$\tilde{W}_N = \frac{1}{N} W_N^H$

Prop 4

$$\tilde{W}_N^H \tilde{W}_N = I_{N \times N}$$

$$\Rightarrow \frac{1}{N} W_N^H W_N = I$$

$$\Rightarrow \boxed{W_N^H W_N = N I}$$

$\downarrow$   
 $N \times N$  identity matrix

$$W_N^{-1} = \frac{1}{N} W_N^H$$

$$= \frac{1}{N} W_N^*$$

Sx:

$N=4$ , DFT, 1 DFT matrices.

$$W_4 = e^{-j2\pi l u} = e^{-j\pi/2}$$

$$= -j$$

$$\overline{W}_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & W_N^1 & W_N^2 & W_N^3 \\ 1 & W_N^2 & W_N^4 & W_N^6 \\ 1 & W_N^3 & W_N^6 & W_N^9 \end{bmatrix} \rightarrow N=4$$

$$= \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

$4 \times 4 \text{ DFT matrix}$

$$\tilde{W}_N = \frac{1}{4} W_4^*$$

$$= \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & j & -1 & -j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

$4 \times 4 \text{ IDFT matrix}$

$$\tilde{W}_N = \frac{1}{\sqrt{N}} W_N^*$$

$$\tilde{W}_N \tilde{W}_N^* = I$$

$$\tilde{W}_N^* \tilde{W}_N = N I_{N \times N}$$


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HW → verify these properties in MATLAB