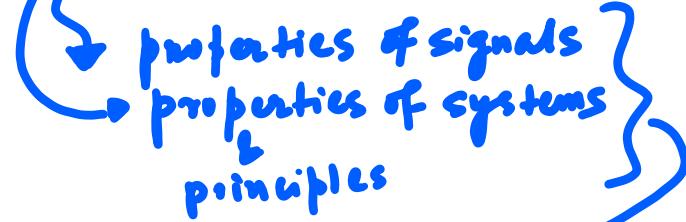


SIGNALS AND SYSTEMS

Unit 1



signals interaction
b/w signals
and systems

Electrical Engineering

→ Power systems
→ Smart Grid

Electronic
systems

TV, Mobile phones

Communication
systems

(3G, 4G wireless
wifi systems)

Instrumentation & Control (eg- airport)

AIM → properties of both continuous / discrete
signals + systems

SIGNAL → Physical quantity

↳ that conveys information
about phenomenon.

↳ Typically exhibits variation
in space or time

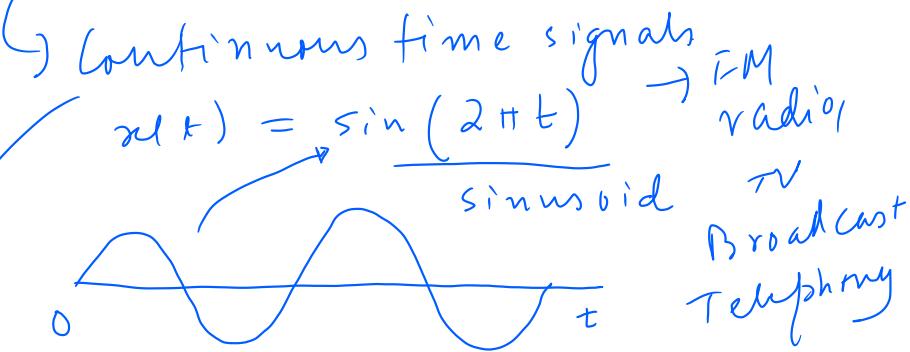
Image ↳ eg EM wave

Speech signal.

Video → Space + Time varying

$x(t), y(t)$ ↳ Time varying
signals.
function of time

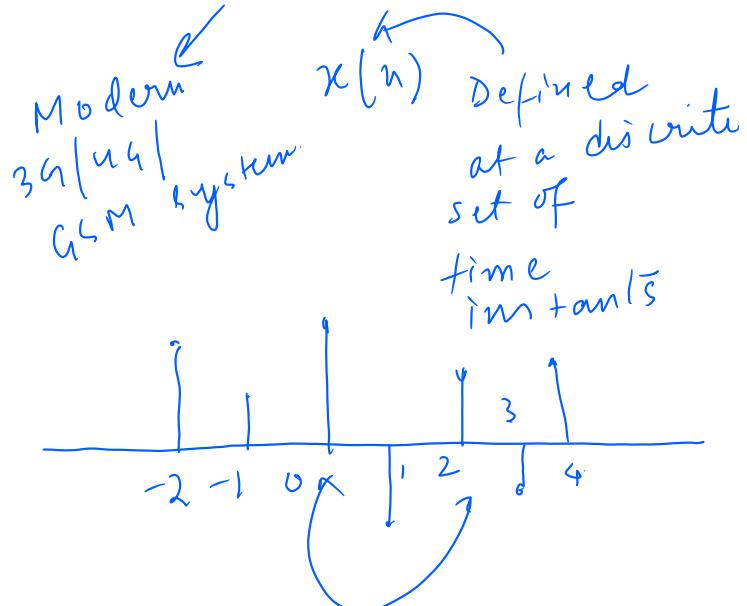
Classification of signals.



→ Defined for all time events in an interval.

$$[t_1, t_2]$$

→ Discrete time signals.



Defined only at discrete time instants

$$x(-2), x(-1), x(0), x(1), x(2),$$

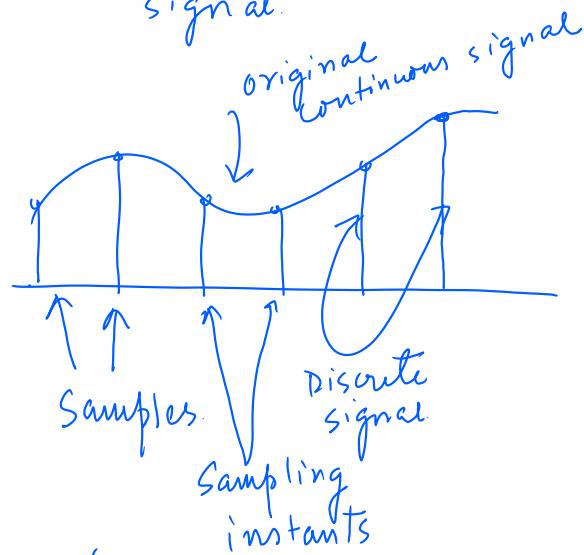
Sequence or Series of Numbers

Time series

Discrete Time signal

Discrete time Signal

can be obtained by suitably sampling a continuous time signal.



$$x(n) = \begin{cases} \left(\frac{1}{2}\right)^n, & n \geq 0 \\ 0, & \text{otherwise} \end{cases}$$

1
 .125 .0625 .03125 ...
 0 1 2 3 n

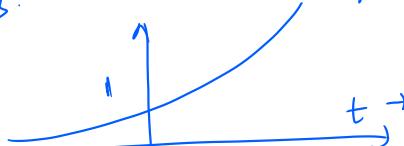
discrete time signal

Lec-02 Analog & Digital Signals

Analog signal \rightarrow Continuous time signal

$x(t)$ can take values belonging to an interval $[a, b]$

$\sin(2\pi ft)$
 infinitely possible values e^{-t} $t \in (0, \infty)$



takes all values in interval 0 to ∞

DIGITAL SIGNAL
 Discrete time signal $x[n]$
 that can take discrete set of
 values or finite values.

$$x(n) \in \{-1, 1\}$$

$x[n]$ either equals

-1 or +1
 can take only one
 of two values.
 DIGITAL
 COMMUNICATION
 SYSTEM.

REAL AND COMPLEX SIGNALS

$$x(t), x[n] \in \mathbb{R}.$$

signals that
 take values
 belonging to
 set of real
 numbers. — REAL
 SIGNALS.

$$\text{eg: } \begin{cases} \sin(2\pi ft) \\ e^t \end{cases} \quad \begin{cases} \text{Real} \\ \text{signals.} \end{cases}$$

$$x(t), x[n] \in \mathbb{C} \quad \text{Complex numbers.}$$

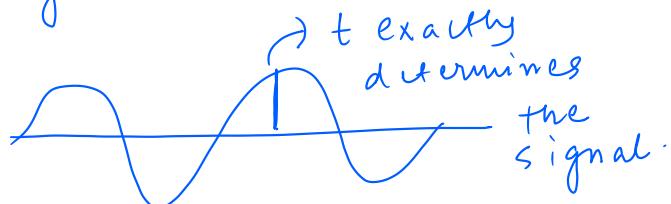
signals that take
 complex values.
 (belonging to
 set of complex
 numbers) → COMPLEX
 SIGNALS.

(eg) $x(t) = e^{j2\pi ft}$
 $= \cos(2\pi ft) + j \sin(2\pi ft)$
 complex sinusoid where $j = \sqrt{-1}$

DETERMINISTIC AND RANDOM SIGNALS

$n(t)$ or $n(n)$ that is completely specified at any given instant of time

eg: $\sin 2\pi ft, e^t$



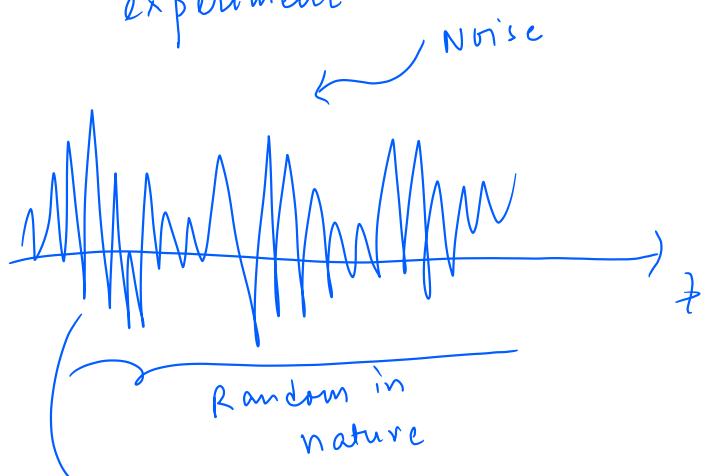
RANDOM SIGNAL

takes random values at different time instants.

Ex

$$\underline{n[n]} = \begin{cases} +1, & \text{if outcome} \\ & = \text{heads} \\ -1, & \text{if outcome} \\ & = \text{tails} \end{cases}$$

Represents a coin toss experiment



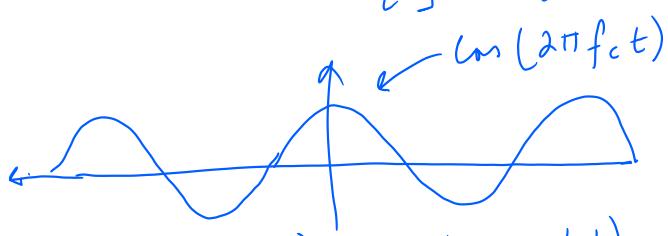
→ Fundamentally important to understand noise to characterise and analyse behaviour of systems.

→ Noise limits the performance of systems.

EVEN AND ODD SIGNALS

even signal : $x(t) = x[-t]$

$$x[n] = x[-n]$$



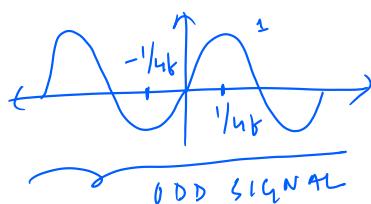
$$\cos(2\pi ft) = \cos(-2\pi ft)$$

Even signal

odd signal $\Rightarrow x(-t) = -x(t)$

$$x[-n] = -x[n]$$

$$x(t) = \sin(2\pi ft)$$



$$\sin(2\pi ft) = -\sin(-2\pi ft)$$

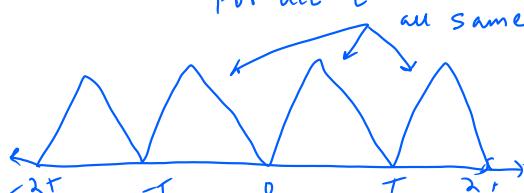
Odd signal

PERIODIC AND APERIODIC SIGNALS

very important classification

$x(t)$ is periodic if there exist a time period T such that $x(t+T) = x(t)$

For all t



eg $\sin(2\pi t)$

$$\begin{aligned} &= \sin(2\pi(t + 1)) \\ &= \sin(2\pi t + 2\pi) \\ &= \sin(2\pi t) \end{aligned}$$

$T = 1$ is period of $\sin(2\pi t)$

Fundamental Period

If T is a period of the periodic signal then mT is also a period for any integer m .

$$x(t + mT) = x(t)$$

$\underbrace{\hspace{10em}}$
For all t

Fundamental Period $T =$

smallest time period s.t.

$$x(t + T) = x(t)$$

$\underbrace{\hspace{10em}}$
For all t

→ All other periods
are multiples of fundamental period.

(eg): $\sin(2\pi t)$

↳ $T=1$ is a fundamental period

$$mT : 2T, 3T, -T, -2T$$

$\underbrace{\hspace{10em}}$
periods

For a discrete signal (periodic)

$$x(n+N) = x(n)$$

$\underbrace{\hspace{10em}}$
For all n .

→ Period of discrete time signal.

Smallest N for which this holds = Fundamental period N_0 .

Lec-3 ENERGY AND POWER SIGNALS

$$E = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

(↑ energy of signal)

$$\Rightarrow = \sum_{n=-\infty}^{\infty} |x(n)|^2$$

If energy is finite
 \Rightarrow Energy signal

$$0 < E < \infty$$

(eg) $e^{-t} u(t)$

$$e^{-n} u[n]$$

POWER $P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} |x(t)|^2 dt$

$\Rightarrow = \lim_{N \rightarrow \infty} \frac{1}{2N+1} \sum_{n=-N}^{N} |x(n)|^2$

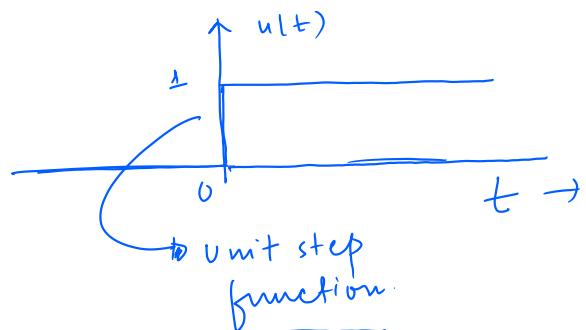
If power is finite $0 < P < \infty$
 \Rightarrow power signal

(eg) $\sin(2\pi f t)$

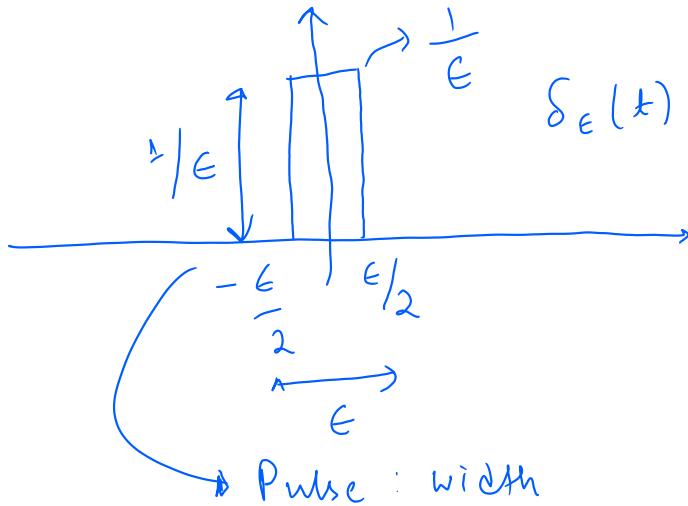
IMPORTANT CONTINUOUS TIME SIGNALS

Unit step signal

$$u(t) = \begin{cases} 1, & t \geq 0 \\ 0, & t < 0 \end{cases}$$



Unit impulse function.



$$\text{Area under pulse} = \epsilon \cdot \frac{1}{\epsilon} = 1.$$

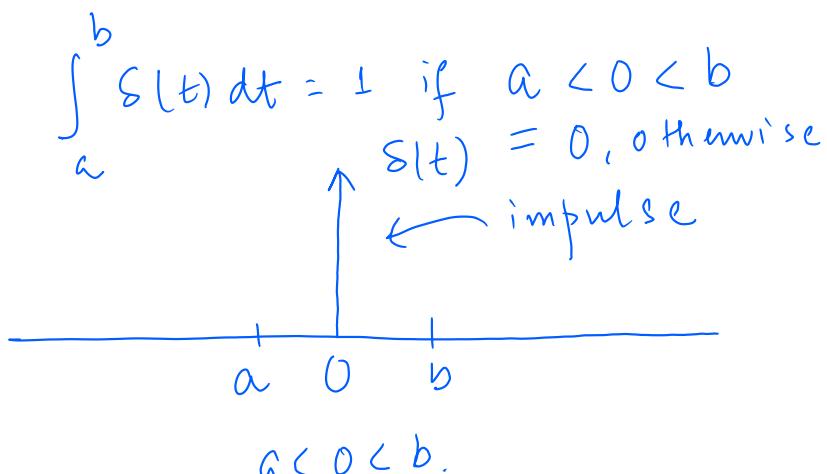
$$\int_{-\infty}^{\infty} \delta_\epsilon(t) dt = 1.$$

$\delta(t) = \lim_{\epsilon \rightarrow 0} \delta_\epsilon(t)$

As $\epsilon \rightarrow 0$,
width $\epsilon \rightarrow 0$
height $\frac{1}{\epsilon} \rightarrow \infty$

impulse function

But, area = 1
= constant



$$\text{Properties } \int_{-\infty}^{\infty} x(t) \delta(t) dt = x(0)$$

Similarly

$$\int_{-\infty}^{\infty} x(t) \delta(t - t_0) dt = x(t_0)$$

↑ $\delta(t - t_0)$

$t = t_0$

impulse shifted to $t = t_0$

OTHER PROPERTIES OF IMPULSE

FUNCTION

$$\delta(at) = \frac{1}{|a|} \delta(t)$$

$$\delta(-t) = \delta(t)$$

$$x(t) \delta(t) = x(0) \delta(t)$$

Further,

$$\int_{-\infty}^{\infty} x(z) \delta(t-z) dz = x(t)$$

$\Rightarrow z - t = \tilde{t}$

$z = \tilde{t} + t$

$dz = d\tilde{t}$

$$\int_{-\infty}^{\infty} x(\tilde{t} + t) \delta(-\tilde{t}) d\tilde{t}$$

$\downarrow = \delta(\tilde{t})$

$$= \int_{-\infty}^{\infty} x(\tilde{t} + t) \delta(\tilde{t}) d\tilde{t}$$

$$= x(\tilde{t} + t) \Big|_{\tilde{t}=0}$$

$$= x(t)$$

$$\boxed{\int_{-\infty}^{\infty} x(z) \delta(t-z) dz = x(t)}$$

Sifting property of the impulse function

Complex exponential

$$x(t) = e^{j\omega_0 t} = \cos(\omega_0 t) + j \sin(\omega_0 t)$$

$$j = \sqrt{-1}$$

$$|x(t)| = \sqrt{\cos^2 \omega_0 t + \sin^2 \omega_0 t}$$

$$e^{j2\pi f_0 t} = e^{j\omega_0 t}$$

$$f_0 = \frac{\omega_0}{2\pi}$$

\leftarrow rad/s. (angular frequency)
 Hz (Radians / sec) frequency

$$\boxed{\text{Period } T = 1/f_0 = 2\pi/\omega_0}$$

$$f_0 = 5 \text{ Hz.}$$

$$\Rightarrow T = 1/5 = 0.2 \text{ s.}$$

General complex exponential

$$s = \sigma + j\omega.$$

$$x(t) = e^{st}$$

$$= e^{(\sigma + j\omega)t}$$

$$= e^{\sigma t} (\cos(\omega t) + j \sin(\omega t))$$

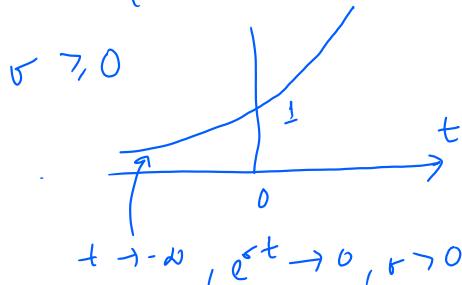
General complex exponential

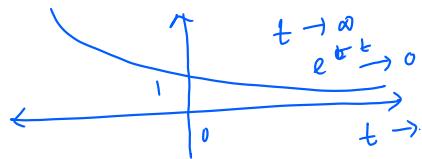
14-04

* REAL exponential signals

"exponential" signals \downarrow always +ve signal

$$x(t) = e^{\sigma t} > 0$$





e^{st} for $s < 0$
Decreasing
 function

SINUSOIDAL SIGNAL

$$x(t) = A \cos(\omega_0 t + \theta)$$

↑ amplitude ↑ phase offset
 angular freq.
 (rad/s)

$f_0 = \frac{\omega_0}{2\pi}$
 fundamental frequency

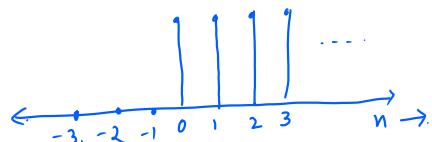
↓ Periodic signal.

BASIC DISCRETE TIME

SIGNALS

$$u[n] = \begin{cases} 1, n \geq 0 \\ 0, n < 0 \end{cases}$$

unit step function.



UNIT IMPULSE FUNCTION

$$\delta(n) = \begin{cases} 1, n=0 \\ 0, n \neq 0 \end{cases}$$

$$\sum_{n=-\infty}^{\infty} \delta(n) = 1$$

$$\sum_{k=-\infty}^{\infty} x(k) \delta(n-k) = x(n)$$

Sifting property
 for discrete time signals.

$$\delta(n) = u(n) - u(n-1)$$

$$u(n) = \sum_{k=-\infty}^n \delta(k)$$

COMPLEX Exponential

DISCRETE TIME

$$x(n) = e^{j\Omega_0 n}$$

$$= \cos(\Omega_0 n) + j \sin(\Omega_0 n)$$

$$\text{Periodic? } f_0 = \frac{\Omega_0}{2\pi}$$

$$e^{j2\pi f_0 n} = e^{j2\pi f_0 (n+N)}$$

$$= e^{j2\pi f_0 n} e^{j2\pi f_0 N}$$

1

$$e^{j2\pi f_0 N} = 1$$

Periodic if

$$f_0 N = k$$

$$\Rightarrow f_0 = \frac{k}{N}$$

Rational Number

Therefore, $e^{j\Omega_0 n}$ is periodic

$$\text{only if } \Omega_0 / 2\pi = m/N$$

\uparrow
Rational Number

EE-05 Memory | Memory-less and Causal | Non Causal Systems

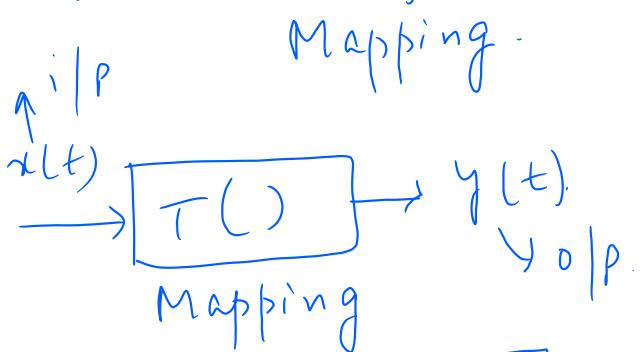
* CLASSIFICATION OF SYSTEMS.

System Representation
→ "System"

Mathematical Model for
a physical process / Device
that describes the o/p signal
for any given input signal

$$y(t) = T(x(t))$$

↓ Captures
o/p the system input
signal · Transformation signal



$$y[n] : T(x[n])$$

Discrete time.

$$x[n] \rightarrow [T(\cdot)] \rightarrow y[n]$$

CLASSIFICATION OF SYSTEMS

SYSTEMS WITH MEMORY AND MEMORYLESS SYSTEMS

Memoryless system

→ output depends only on current input or i/p at current time instant

$$\text{(eg)} \quad y(t) = kx(t)$$

$v(t) = R i(t)$
↓ ↓
voltage Resistance

$$y[n] = kx[n]$$

Memoryless systems.

Systems with Memory

↳ o/p

$y(t_0)$ at time t_0 depends NOT only on $x(t_0)$.

but also $x(t)$ for $t < t_0$.

↳ $y(t_0)$ depends also on past values

of signal $x(t)$.

(Ex)

$$v(t) = \frac{1}{C} \int_{-\infty}^t i(z) dz$$

↓
voltage ↓
 current
↓
Capacitance

→ Capacitor is a system with memory

Causal AND Non Causal

SYSTEMS

Causal: Output depends only on $x(t)$,
 "Causality" $t \leq t_0$

"Principle" → O/P depends only on PAST values of $x(t)$ and NOT future values of $x(t)$.

Non Causal \Rightarrow system is

NOT Causal.

\rightarrow O/P signal depends also on future values of input signal.

$$y(t) = \int_{-\infty}^t x(z) dz$$

depends on $x(z)$ Causal System.
 $z \leq t$

$$y[n] = \frac{1}{2N+1} \sum_{k=-N}^N x(n+k)$$

↓

$y[n]$ depends on

$x[n-N], x[n-N+1]$
... $x[n+N]$

→ depends also on
future values of $x[n]$,

Hence, NON-CAUSAL.