

NPTEL MOOC, JAN-FEB 2015
Week 4, Module 3

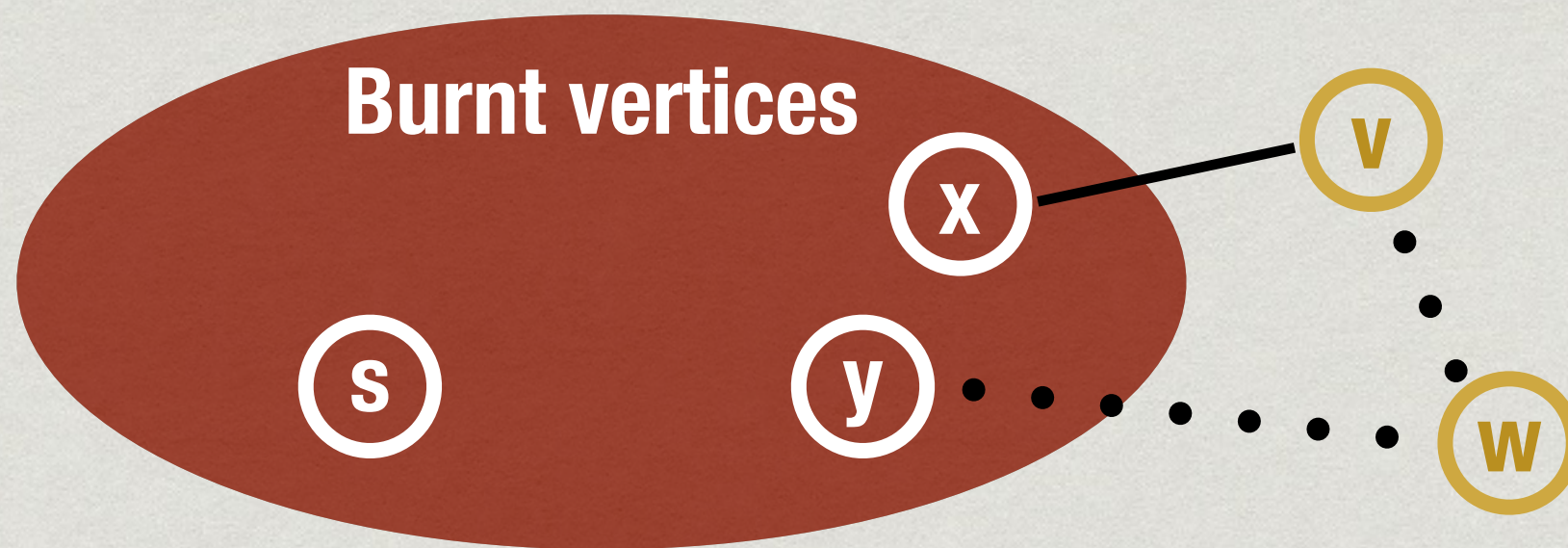
DESIGN AND ANALYSIS OF ALGORITHMS

Negative edges: Bellman-Ford algorithm

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Correctness for Dijkstra's algorithm

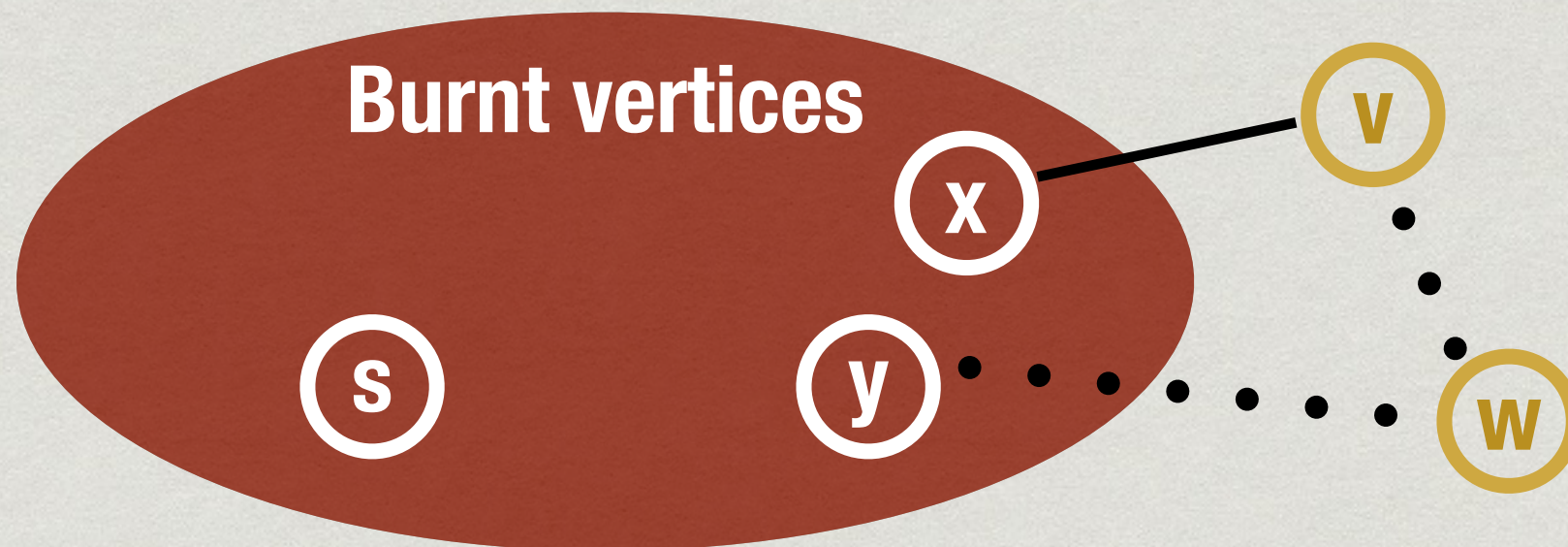
- * By induction, assume we have identified shortest paths to all vertices already burnt



- * Next vertex to burn is v , via x
- * Cannot later find a shorter path from y to w to v

Negative weights

- * Our correctness argument is no longer valid



- * Next vertex to burn is v, via x
- * Might find a shorter path later with negative weights from y to w to v

Negative weights ...

- * **Negative cycle:** loop with a negative total weight
 - * Problem is not well defined with negative cycles
 - * Repeatedly traversing cycle pushes down cost without a bound
- * With negative edges, but no negative cycles, shortest paths do exist

About shortest paths

- * Shortest paths will never loop
 - * Never visit the same vertex twice
 - * At most length $n-1$
- * Every prefix of a shortest path is itself a shortest path
 - * Suppose the shortest path from s to t is
$$s \rightarrow v_1 \rightarrow v_2 \rightarrow v_3 \dots \rightarrow v_m \rightarrow t$$
 - * Every prefix $s \rightarrow v_1 \rightarrow \dots \rightarrow v_r$ is a shortest path to v_r

Updating Distance()

- * When vertex j is “burnt”, for each edge (j,k) update
$$\text{Distance}(k) = \min(\text{Distance}(k), \text{Distance}(j) + \text{weight}(j,k))$$
- * Refer to this as $\text{update}(j,k)$
- * Dijkstra’s algorithm
 - * When we compute $\text{update}(j,k)$, $\text{Distance}(j)$ is always guaranteed to be correct distance to j
- * What can we say in general?

Properties of update(j,k)

update(j,k):

$$\text{Distance}(k) = \min(\text{Distance}(k), \text{Distance}(j) + \text{weight}(j,k))$$

- * $\text{Distance}(k)$ is no more than $\text{Distance}(j) + \text{weight}(j,k)$
- * If $\text{Distance}(j)$ is correct and j is the second-last node on shortest path to k , $\text{Distance}(k)$ is correct
- * Update is safe
 - * $\text{Distance}(k)$ never becomes “too small”
 - * Redundant updates cannot hurt

Updating Distance() ...

update(j,k):

$\text{Distance}(k) = \min(\text{Distance}(k), \text{Distance}(j) + \text{weight}(j,k))$

- * Dijkstra's algorithm performs a particular “greedy” sequence of updates
 - * Computes shortest paths without negative weights
- * With negative edges, this sequence does not work
- * Is there some sequence that does work?

Updating distance() ...

- * Suppose the shortest path from s to t is

$$s \rightarrow v_1 \rightarrow v_2 \rightarrow v_3 \dots \rightarrow v_m \rightarrow t$$

- * If our update sequence includes ..., $\text{update}(s, v_1)$, ..., $\text{update}(v_1, v_2)$, ..., $\text{update}(v_2, v_3)$, ..., $\text{update}(v_m, t)$, ..., in that order, $\text{Distance}(t)$ will be computed correctly
- * If $\text{Distance}(j)$ is correct and j is the second-last node on shortest path to k , $\text{Distance}(k)$ is correct after $\text{update}(j, k)$

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1
...
update(s, v_1)
...
update(v_1, v_2)
...
update(v_2, v_3)
...
update(v_m, t)
...

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1	Iteration 2
...	...
update(s, v_1)	update(s, v_1)
...	...
update(v_1 , v_2)	update(v_1 , v_2)
...	...
update(v_2 , v_3)	update(v_2 , v_3)
...	...
update(v_m , t)	update(v_m , t)
...	...

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1	Iteration 2	...
...
update(s,v ₁)	update(s,v ₁)	...
...
update(v ₁ ,v ₂)	update(v ₁ ,v ₂)	...
...
update(v ₂ ,v ₃)	update(v ₂ ,v ₃)	...
...
update(v _m ,t)	update(v _m ,t)	...
...

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1	Iteration 2	...	Iteration $n-1$
...
update(s, v_1)	update(s, v_1)	...	update(s, v_1)
...
update(v_1, v_2)	update(v_1, v_2)	...	update(v_1, v_2)
...
update(v_2, v_3)	update(v_2, v_3)	...	update(v_2, v_3)
...
update(v_m, t)	update(v_m, t)	...	update(v_m, t)
...

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1	Iteration 2	...	Iteration n-1
...
update(s,v ₁)	update(s,v ₁)	...	update(s,v ₁)
...
update(v ₁ ,v ₂)	update(v ₁ ,v ₂)	...	update(v ₁ ,v ₂)
...
update(v ₂ ,v ₃)	update(v ₂ ,v ₃)	...	update(v ₂ ,v ₃)
...
update(v _m ,t)	update(v _m ,t)	...	update(v _m ,t)
...

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1	Iteration 2	...	Iteration n-1
...
update(s,v₁)	update(s,v ₁)	...	update(s,v ₁)
...
update(v ₁ ,v ₂)	update(v₁,v₂)	...	update(v ₁ ,v ₂)
...
update(v ₂ ,v ₃)	update(v ₂ ,v ₃)	...	update(v ₂ ,v ₃)
...
update(v _m ,t)	update(v _m ,t)	...	update(v _m ,t)
...

Bellman-Ford algorithm

- * Initialize $\text{Distance}(s) = 0$, $\text{Distance}(u) = \infty$ for all other vertices
- * Update all edges $n-1$ times!

Iteration 1	Iteration 2	...	Iteration n-1
...
update(s,v₁)	update(s,v ₁)	...	update(s,v ₁)
...
update(v ₁ ,v ₂)	update(v₁,v₂)	...	update(v ₁ ,v ₂)
...
update(v ₂ ,v ₃)	update(v ₂ ,v ₃)	...	update(v ₂ ,v ₃)
...
update(v _m ,t)	update(v _m ,t)	...	update(v_m,t)
...

Bellman-Ford algorithm

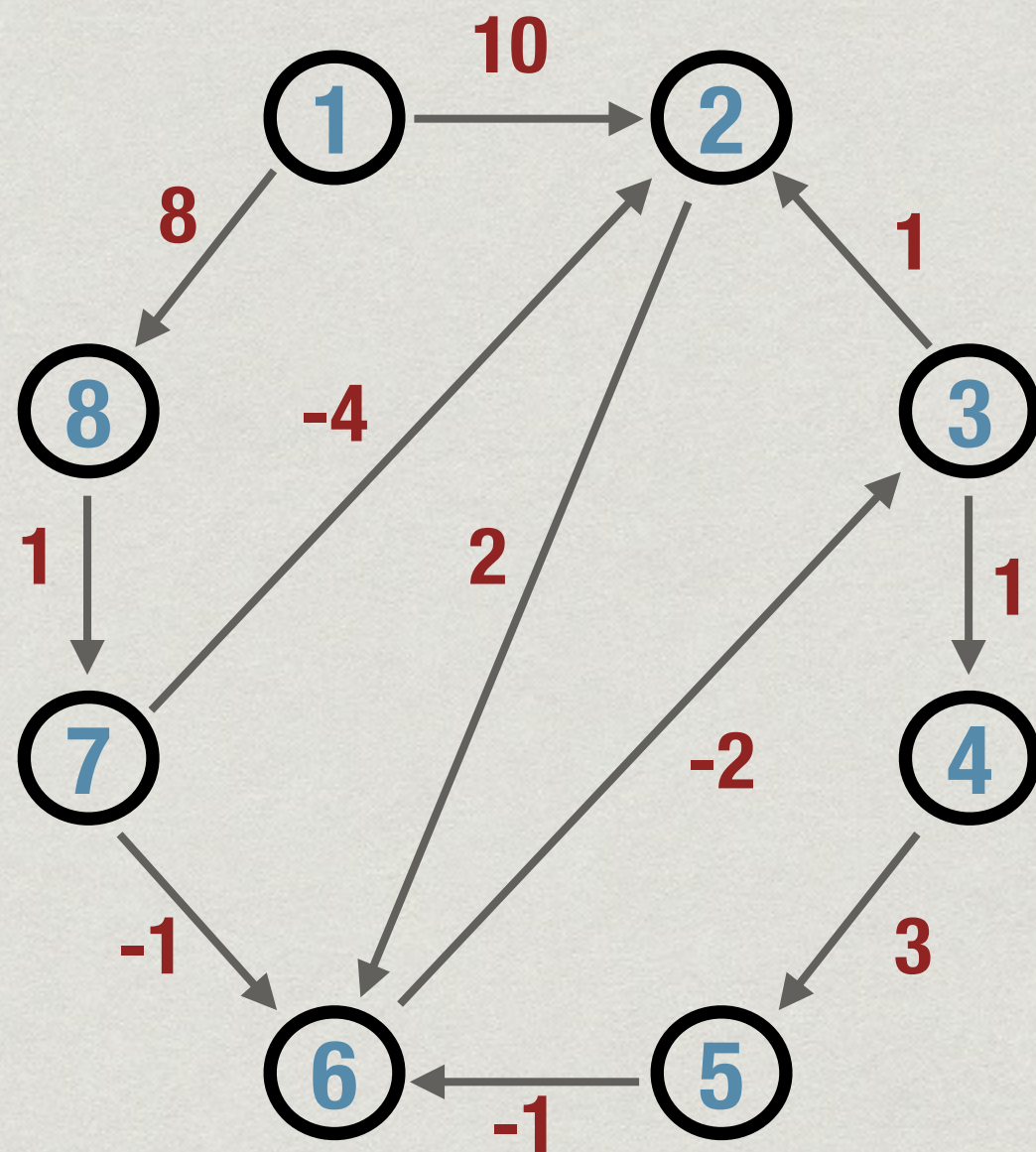
```
function BellmanFord(s) //source s, with -ve weights

for i = 1 to n
    Distance[i] = infinity

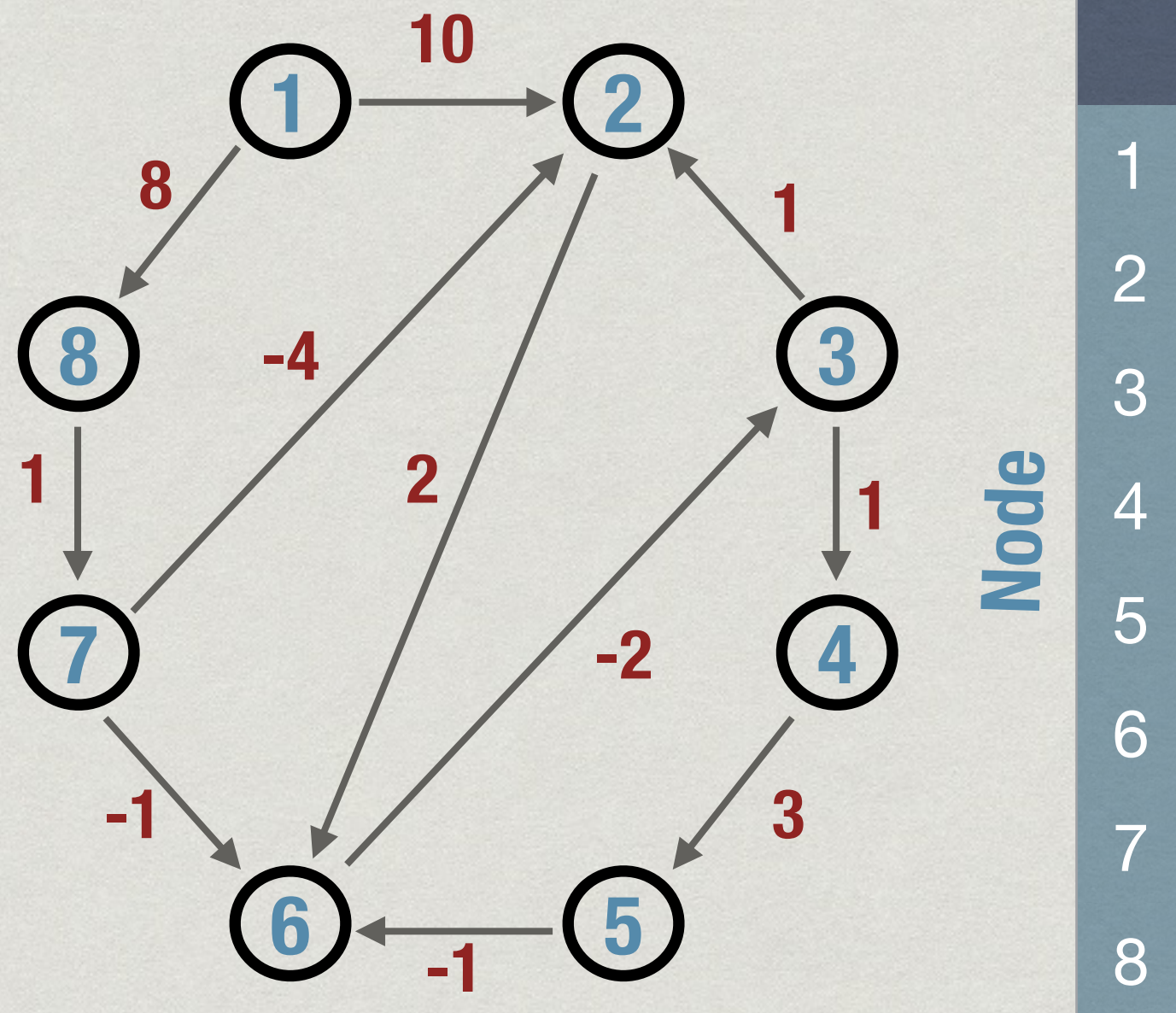
Distance[s] = 0

for i = 1 to n-1 //repeat n-1 times
    for each edge(j,k) in E
        Distance(k) = min(Distance(k),
                           Distance(j) + weight(j,k))
```


Example

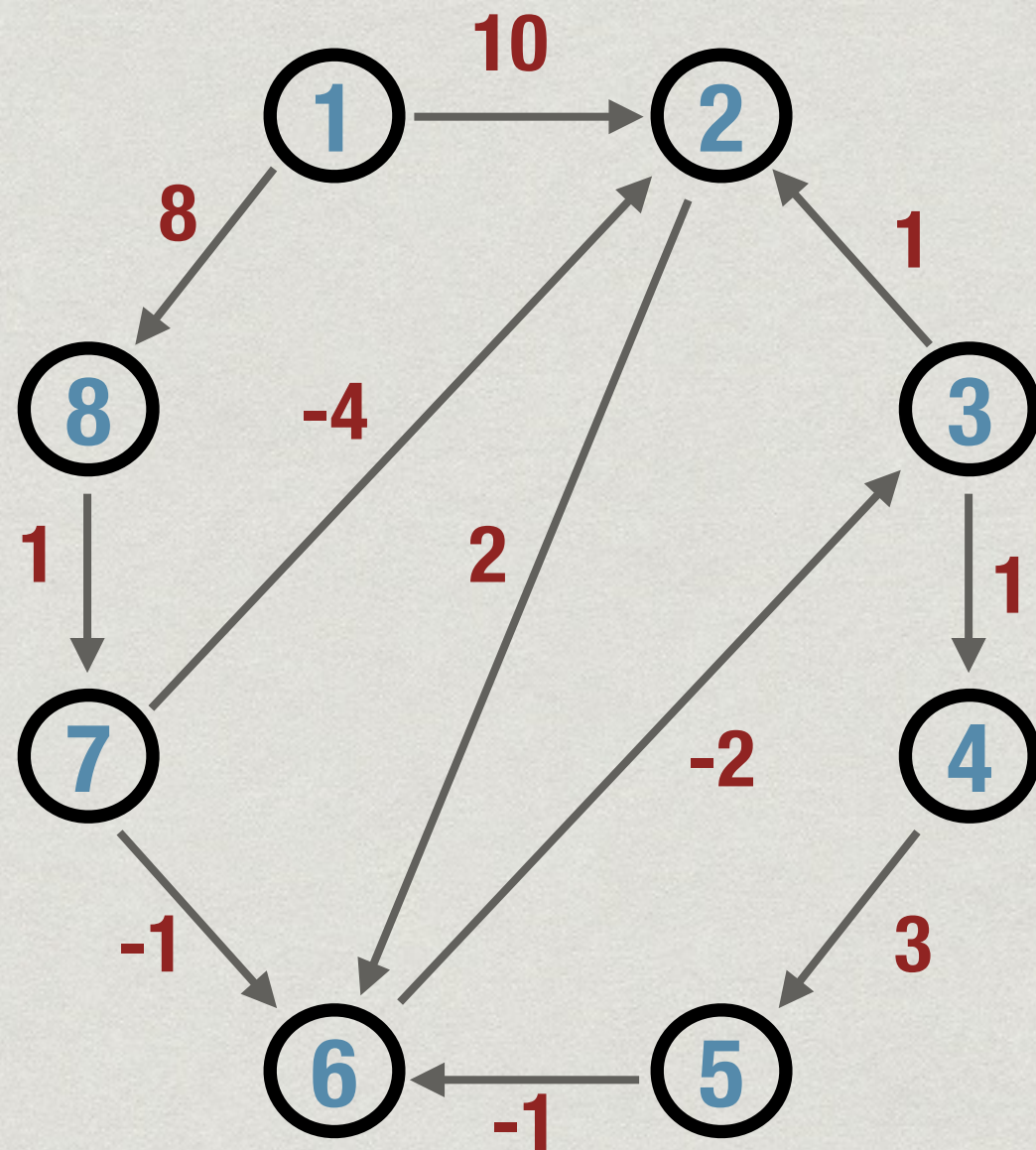


Example



Example

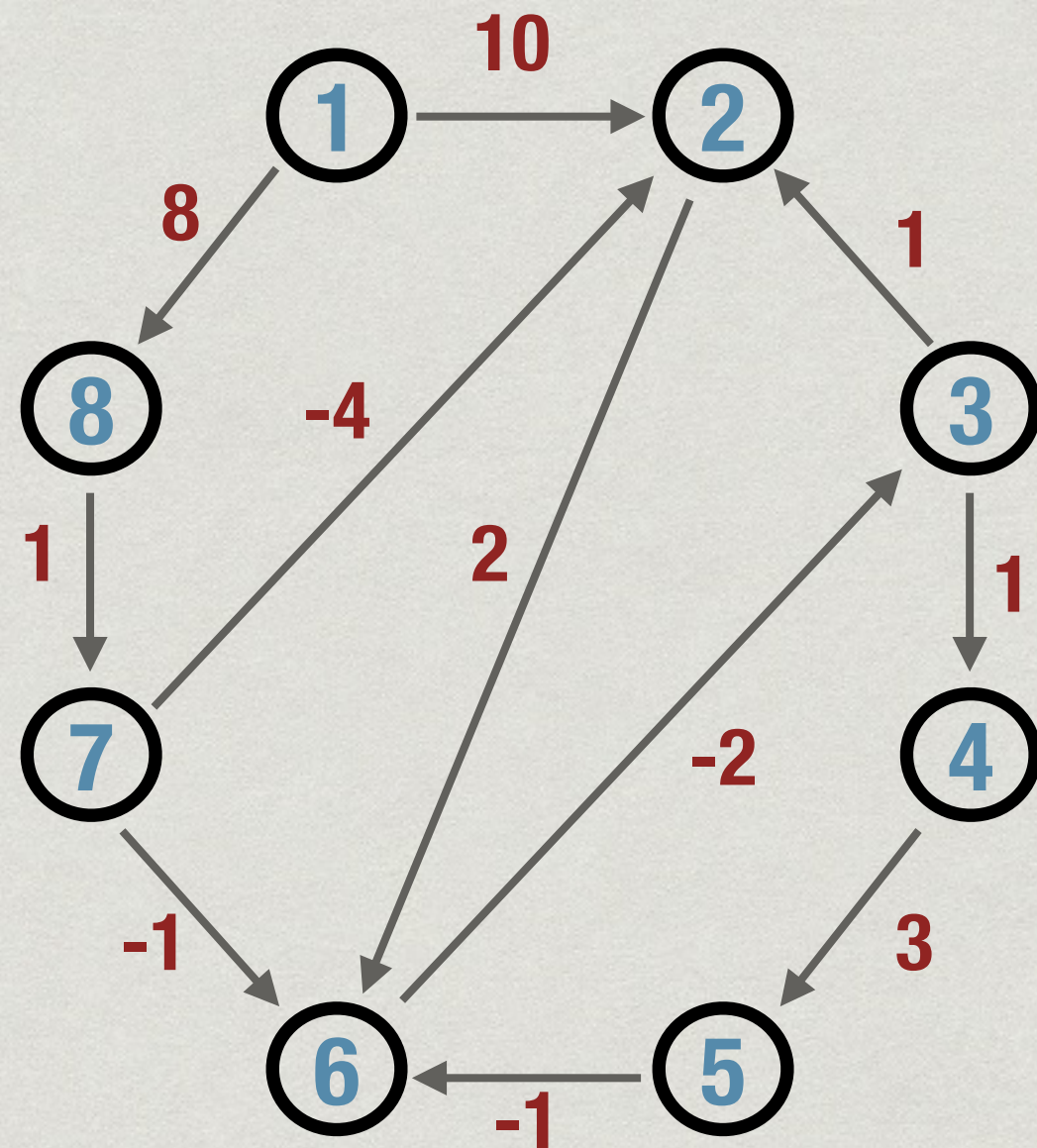
Iteration



Node

	0
1	0
2	∞
3	∞
4	∞
5	∞
6	∞
7	∞
8	∞

Example

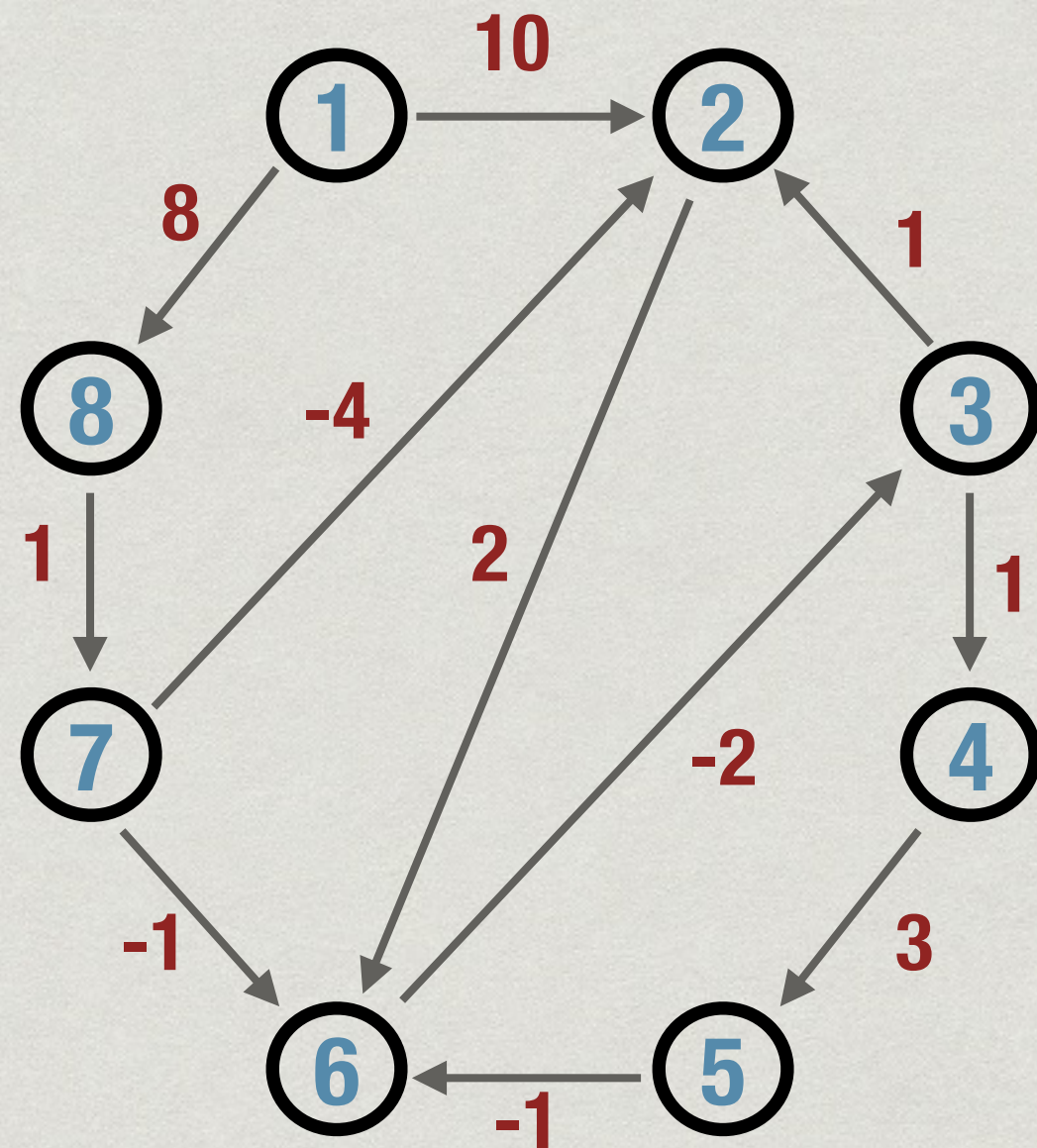


Iteration

Node

	0	1
1	0	0
2	∞	10
3	∞	∞
4	∞	∞
5	∞	∞
6	∞	∞
7	∞	∞
8	∞	8

Example

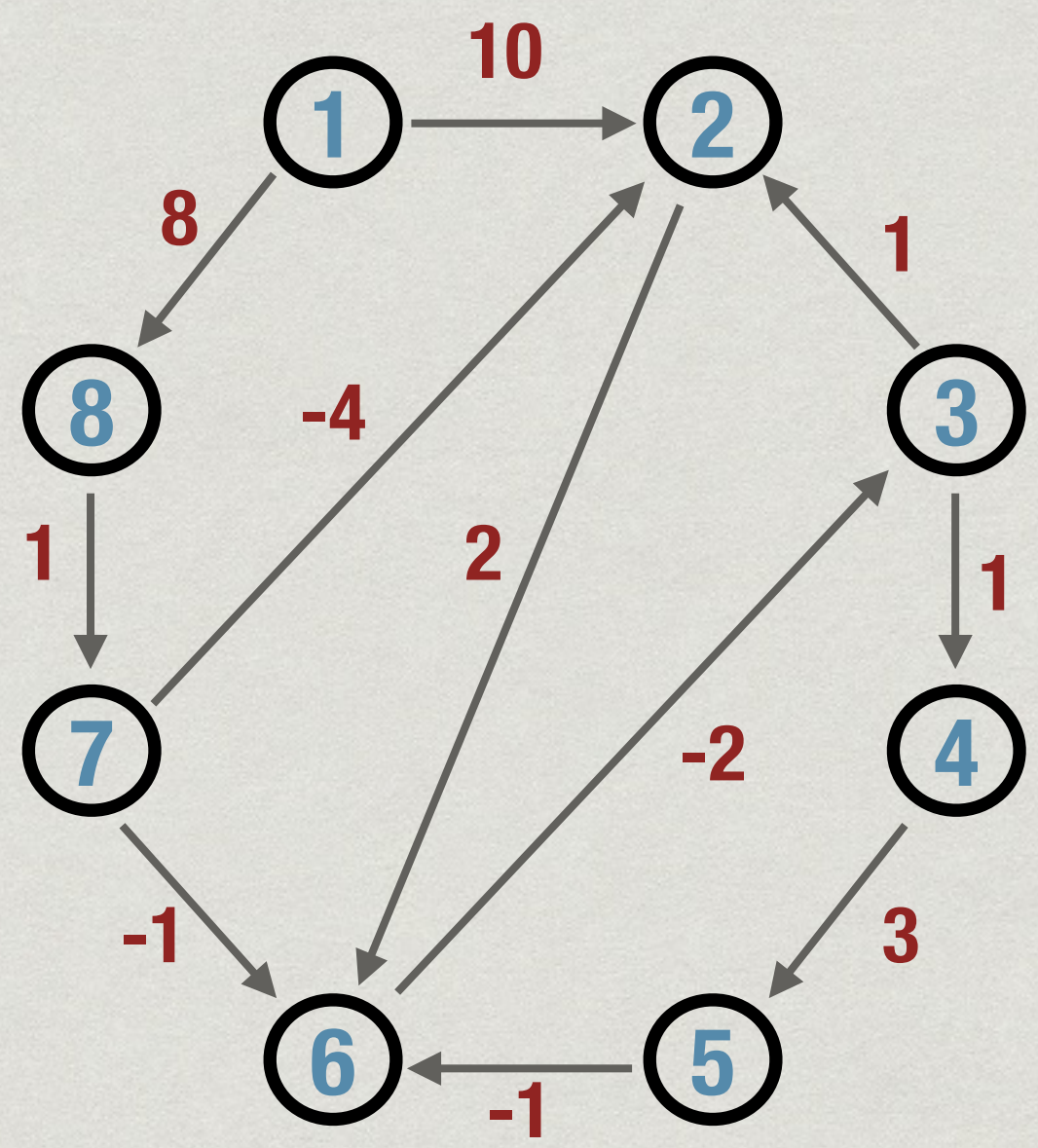


Node

Iteration

	0	1	2
1	0	0	0
2	∞	10	10
3	∞	∞	∞
4	∞	∞	∞
5	∞	∞	∞
6	∞	∞	12
7	∞	∞	9
8	∞	8	8

Example

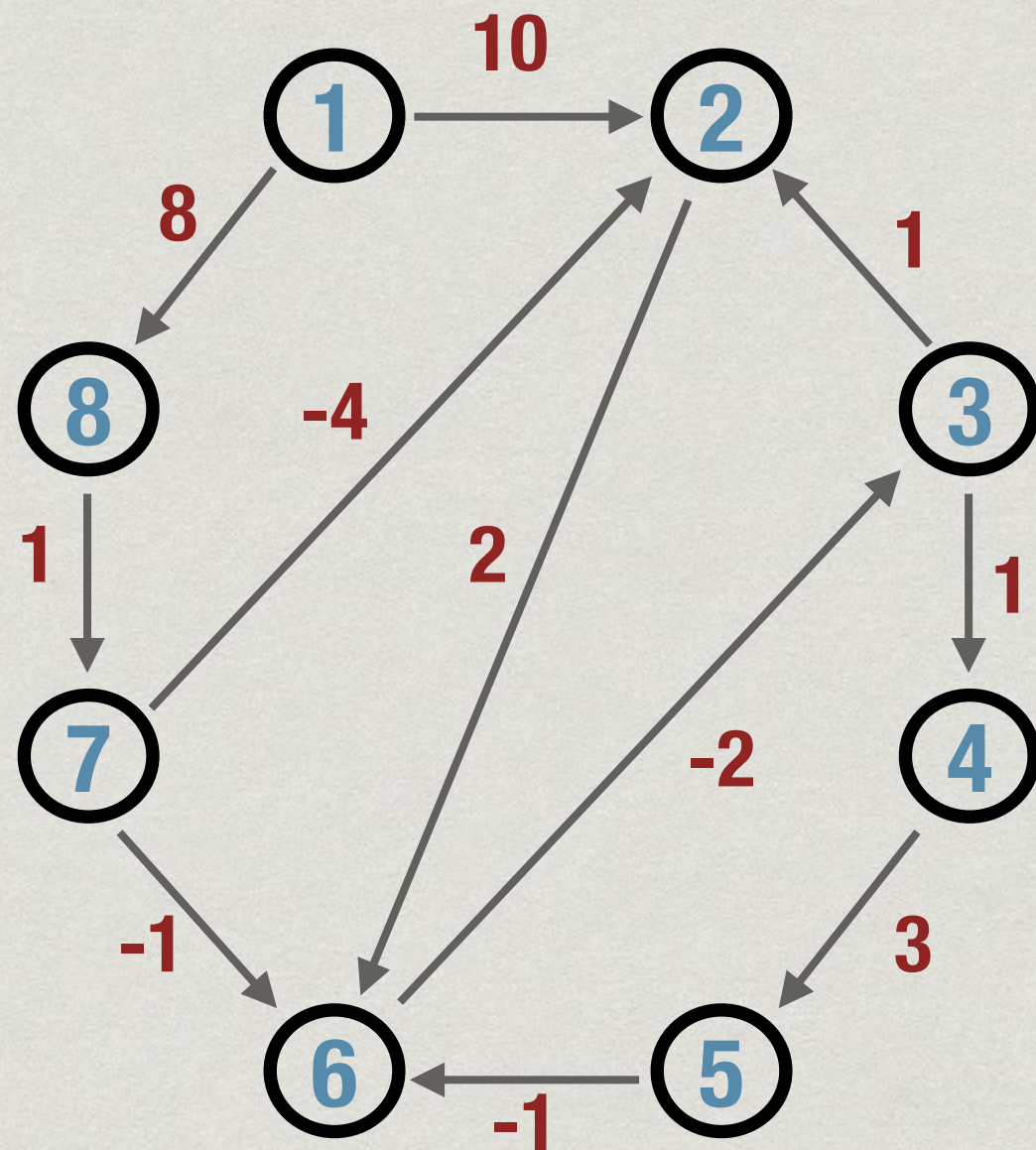


Node

Iteration

	0	1	2	3
1	0	0	0	0
2	∞	10	10	5
3	∞	∞	∞	10
4	∞	∞	∞	∞
5	∞	∞	∞	∞
6	∞	∞	12	8
7	∞	∞	9	9
8	∞	8	8	8

Example

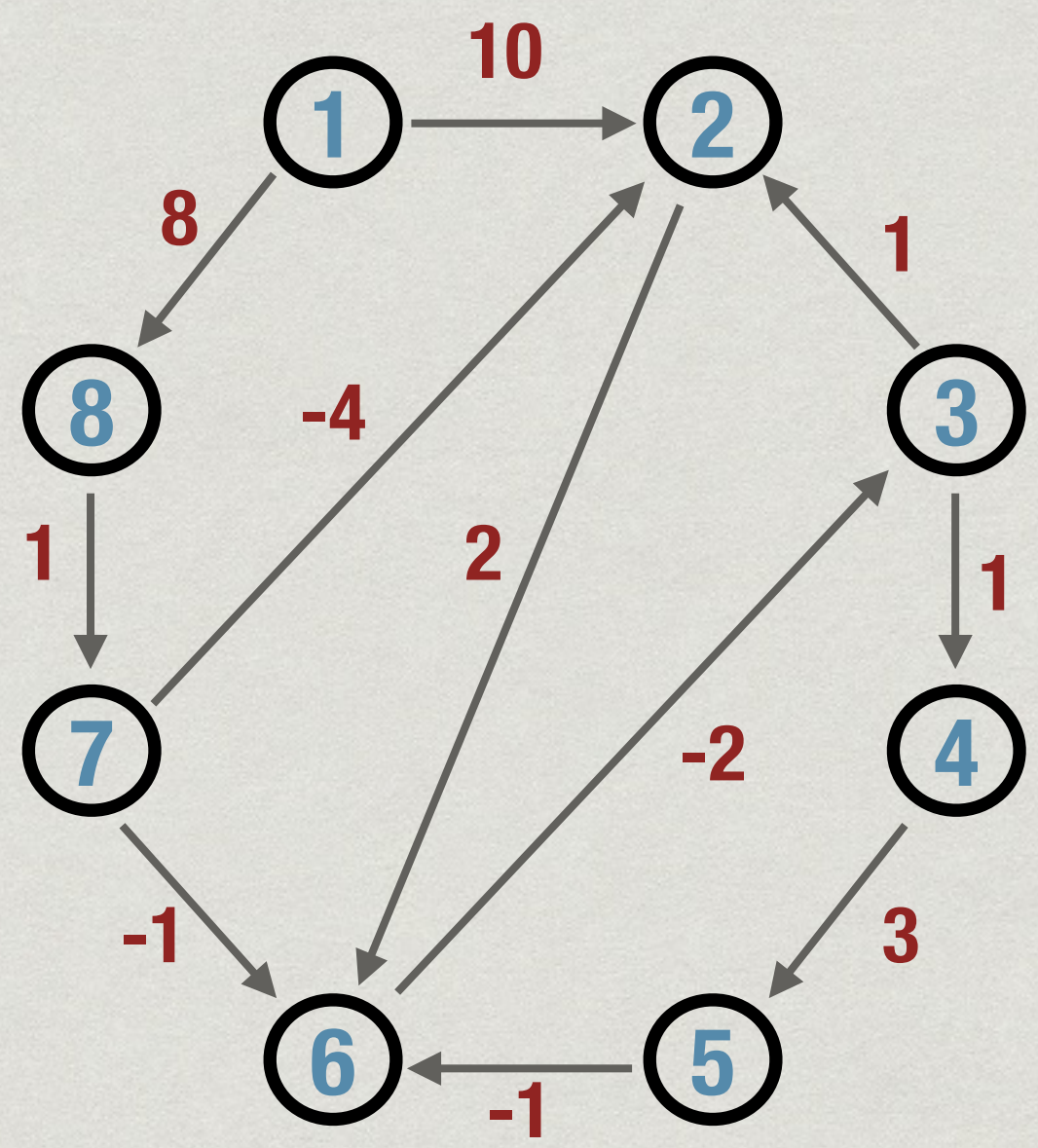


Node

Iteration

	0	1	2	3	4
1	0	0	0	0	0
2	∞	10	10	5	5
3	∞	∞	∞	10	6
4	∞	∞	∞	∞	11
5	∞	∞	∞	∞	∞
6	∞	∞	12	8	7
7	∞	∞	9	9	9
8	∞	8	8	8	8

Example

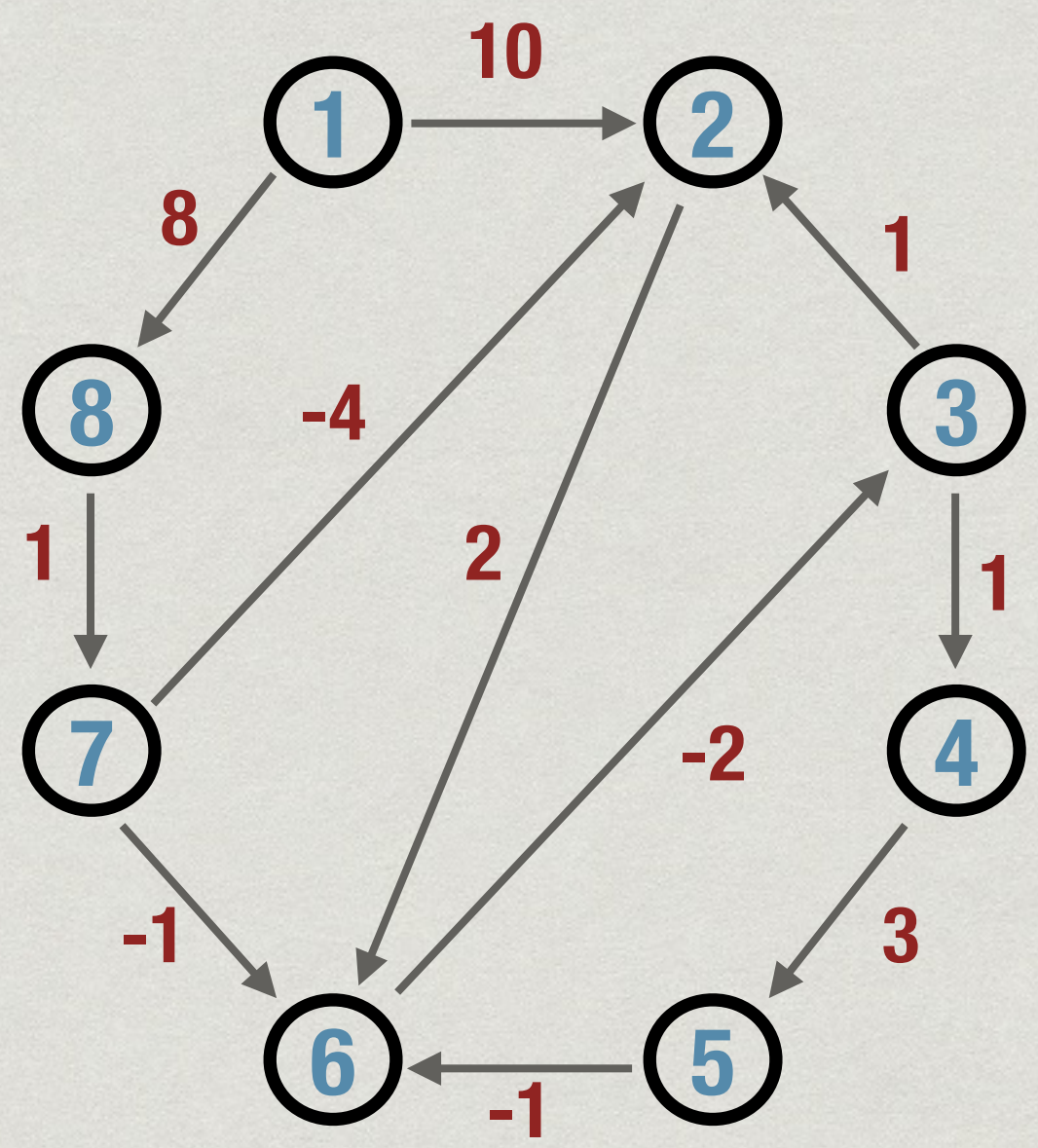


Node

Iteration

	0	1	2	3	4	5
1	0	0	0	0	0	0
2	∞	10	10	5	5	5
3	∞	∞	∞	10	6	5
4	∞	∞	∞	∞	11	7
5	∞	∞	∞	∞	∞	14
6	∞	∞	12	8	7	7
7	∞	∞	9	9	9	9
8	∞	8	8	8	8	8

Example

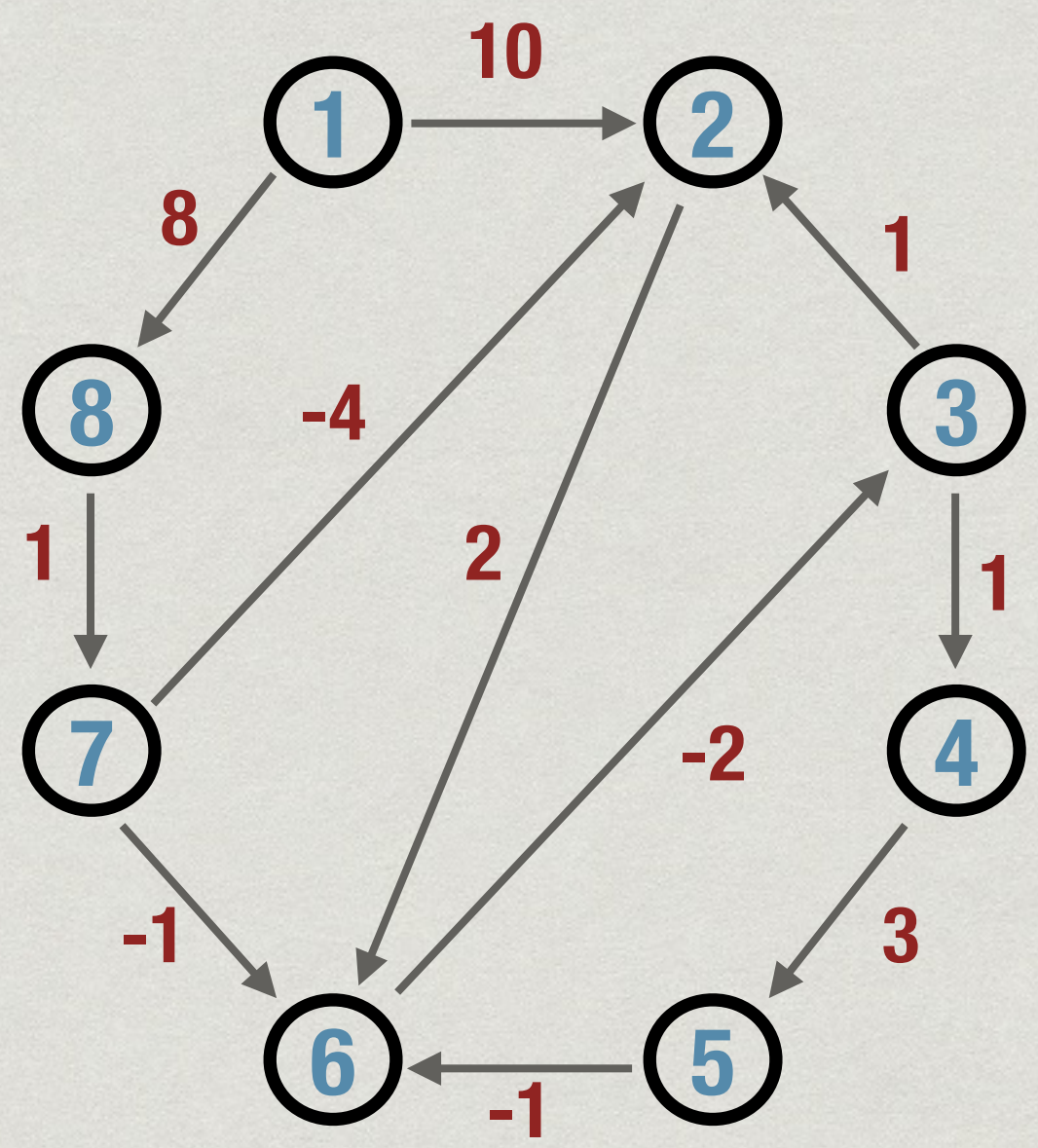


Node

Iteration

	0	1	2	3	4	5	6
1	0	0	0	0	0	0	0
2	∞	10	10	5	5	5	5
3	∞	∞	∞	10	6	5	5
4	∞	∞	∞	∞	11	7	6
5	∞	∞	∞	∞	∞	14	10
6	∞	∞	12	8	7	7	7
7	∞	∞	9	9	9	9	9
8	∞	8	8	8	8	8	8

Example



Node

Iteration

	0	1	2	3	4	5	6	7
1	0	0	0	0	0	0	0	0
2	∞	10	10	5	5	5	5	5
3	∞	∞	∞	10	6	5	5	5
4	∞	∞	∞	∞	11	7	6	6
5	∞	∞	∞	∞	∞	14	10	9
6	∞	∞	12	8	7	7	7	7
7	∞	∞	9	9	9	9	9	9
8	∞	8	8	8	8	8	8	8

Complexity

- * Outer loop runs n times
- * In each loop, for each edge (j,k) , we run $\text{update}(j,k)$
 - * Adjacency matrix — $O(n^2)$ to identify all edges
 - * Adjacency list — $O(m)$
- * Overall
 - * Adjacency matrix — $O(n^3)$
 - * Adjacency list — $O(mn)$