NPTEL MOOC, JAN-FEB 2015 Week 2, Module 7

DESIGNAND ANALYSIS OF ALGORITHMS

Quicksort

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Merge Sort: Shortcomings

- * Merging A and B creates a new array C
 - * No obvious way to efficiently merge in place
- * Extra storage can be costly
- * Inherently recursive
 - * Recursive call and return are expensive

Alternative approach

- * Extra space is required to merge
- * Merging happens because elements in left half must move right and vice versa
- * Can we divide so that everything to the left is smaller than everything to the right?
 - * No need to merge!

Divide and conquer without merging

- * Suppose the median value in A is m
- * Move all values ≤ m to left half of A
 - * Right half has values > m
 - * This shifting can be done in place, in time O(n)
- * Recursively sort left and right halves
- * A is now sorted! No need to merge
 - * $t(n) = 2t(n/2) + n = O(n \log n)$

Divide and conquer without merging

- * How do we find the median?
 - * Sort and pick up middle element
 - * But our aim is to sort!
- * Instead, pick up some value in A pivot
 - * Split A with respect to this pivot element

- * Choose a pivot element
 - * Typically the first value in the array
- * Partition A into lower and upper parts with respect to pivot
- * Move pivot between lower and upper partition
- * Recursively sort the two partitions

| 43 | 32 | 22 | 78 | 63 | 57 | 91 | 13 |
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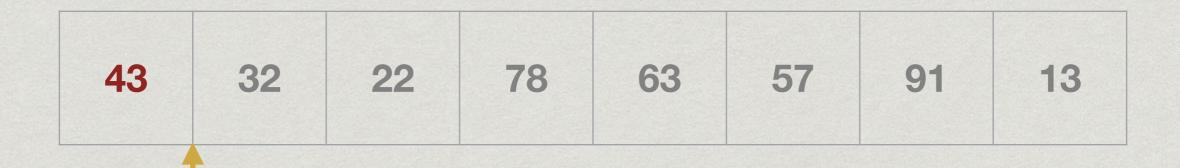
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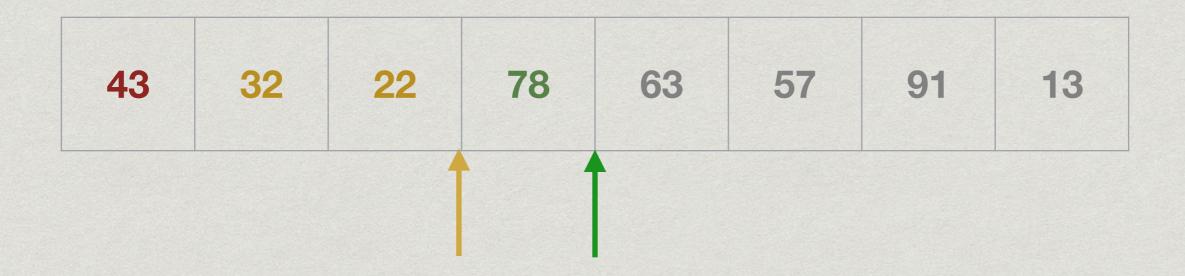
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Quicksort: Implementation

```
Quicksort(A,l,r) // Sort A[l..r-1]
  if (r - l <= 1)) return; // Base case
  // Partition with respect to pivot, a[l]
  yellow = l+1;
   for (green = l+1; green < r; green++)
     if (A[green] <= A[l])
         swap(A, yellow, green);
        yellow++;
   swap(A,1,yellow-1); // Move pivot into place
  Quicksort(A,1,yellow); // Recursive calls
   Quicksort(A, yellow+1, r);
```

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