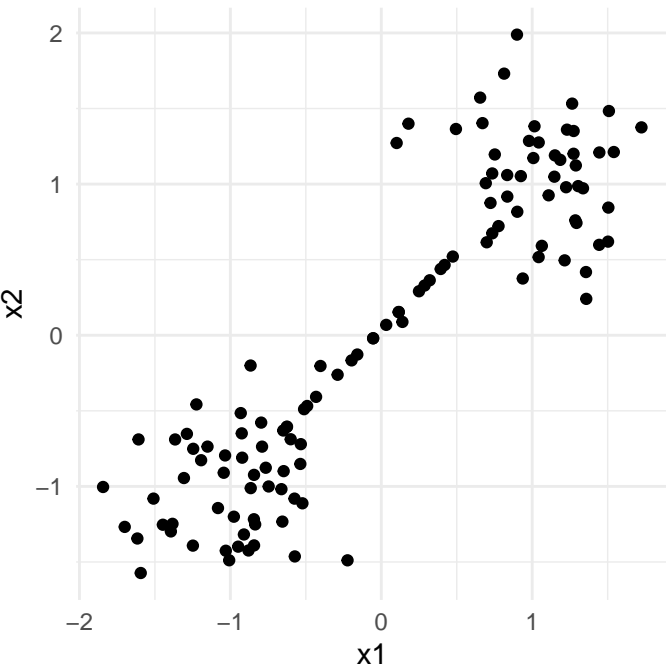


Nuisance observations



Nuisance variables

