

EnOcean Equipment Profiles (EEP)

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      2. D2-01: Electronic switches and dimmers with Energy Measurement and Local Control
             ■ D2-01-00: Type 0x00
             ■ D2-01-01: Type 0x01 (description: see table)
             ■ D2-01-02: Type 0x02 (description: see table)
             ■ D2-01-03: Type 0x03 (description: see table)
             ■ D2-01-04: Type 0x04 (description: see table)
             ■ D2-01-05: Type 0x05 (description: see table)
             ■ D2-01-06: Type 0x06 (description; see table)
             ■ D2-01-07: Type 0x07 (description: see table)
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             ■ D2-01-09: Type 0x09 (description: see table)
             ■ D2-01-0A: Type 0x0A (description: see table)
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D2-01-11: Type 0x11 (description: see table)

      3. D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke
             ■ D2-02-00: Type 0x00
             ■ D2-02-01: Type 0x01 (description: see table)
             ■ D2-02-02: Type 0x02 (description: see table)
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             ■ D2-03-00: Type 0x00
             ■ D2-03-10: Mechanical Handle
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             ■ D2-04-00: Type 0x00
             ■ D2-04-01: Type 0x01 (description: see table)
             ■ D2-04-02: Type 0x02 (description: see table)
             D2-04-03: Type 0x03 (description: see table)D2-04-04: Type 0x04 (description: see table)
             ■ D2-04-05: Type 0x05 (description: see table)
             ■ D2-04-06: Type 0x06 (description: see table)
             ■ D2-04-07: Type 0x07 (description: see table)
             ■ D2-04-08: Type 0x08 (description: see table)
             ■ D2-04-09: Type 0x09 (description: see table)
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             ■ D2-04-1A: Type 0x1A (description: see table)
             ■ D2-04-1B: Type 0x1B (description: see table)
             ■ D2-04-1C: Type 0x1C (description: see table)
             ■ D2-04-1D: Type 0x1D (description: see table)
             ■ D2-04-1E: Type 0x1E (description: see table)
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             ■ D2-05-00: Type 0x00
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7. D2-10: Room Control Panels with Temperature & Fan Speed Control, Room Status Information
               and Time Program
                   ■ D2-10-00: Type 0x00
                   ■ D2-10-01: Type 0x01
                   ■ D2-10-02: Type 0x02
            8. D2-20: Fan Control
                   ■ D2-20-00: Type 0x00
                   ■ D2-20-01: Type 0x01
■ D2-20-02: Type 0x02
            9. D2-30: Floor Heating Controls and Automated Meter Reading
                   D2-30-00: Type 0x00
                   D2-30-01: Type 0x01 (description: see table)
                   D2-30-02: Type 0x02 (description: see table)
                   ■ D2-30-03: Type 0x03 (description: see table)
                   ■ D2-30-04: Type 0x04 (description: see table)
                   ■ D2-30-05: Type 0x05 (description: see table)
                   D2-30-06: Type 0x06 (description: see table)
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                   ■ D2-31-00: Type 0x00
                   ■ D2-31-01: Type 0x01 (description: see table)
           11. D2-32: A.C. Current Clamp
                   ■ D2-32-00: Type 0x00
■ D2-32-01: Type 0x01
■ D2-32-02: Type 0x02
           12. D2-40: LED Controller Status
                   ■ D2-40-00: Type 0x00
                   ■ D2-40-01: Type 0x01
           13. D2-A0: Standard Valve
                   ■ D2-A0-01: Valve Control (BI-DIR)
3. Appendix
      1. RPS Teach-in
      2. 1BS Teach-in
      3. 4BS Teach-in
      4. Smart Ack Teach-in (without repeater)
      5. Smart Ack Teach-in (with repeater)
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            1. General
            2. XML file
```

1) Introduction

1.1) Terms, Abbreviations

15. Revision

1BS	EnOcean 1 Byte Communication
4BS	EnOcean 4 Byte Communication
BAS	Building Automation System
Choice	Unique identification of EnOcean radio telegram types (RPS, 1BS, 4BS,); equivalent with RORG
Client	Bidirectional Smart Ack Device
Data	Payload of ERP telegrams or ESP packets
EEP	EnOcean Equipment Profiles
ERP	EnOcean Radio Protocol
ESP	EnOcean Serial Protocol
HTML	Hyper Text Markup Language; HTML can be displayed using a internet browser
MSC	Manufacturer Specific Communication
N/A	Not applicable

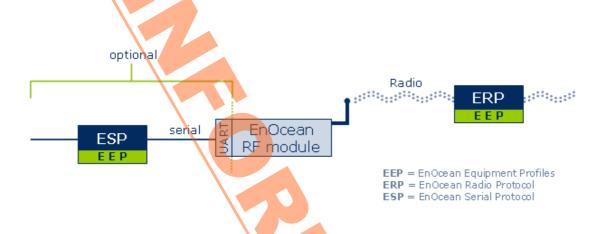
ORG	Organizational number for EnOcean radio telegram types (out-dated with EEP 2.1; used for ESP2 interface)
RORG	Radio ORG = organization number for EnOcean radio telegram types (new with EEP 2.1); equivalent with 'Choice'
RMCC	Remote Management Control Commands
RPC	Remote Procedure Calls
RPS	EnOcean telegram type for Repeated Switch Communication
Smart Ack	Smart Acknowledge EnOcean standard for energy-optimized bidirectional transmission
UART	Universal Asynchronous Receiver Transmitter
VLD	EnOcean Variable Length Data telegram
XML	Extensible Markup Language; designed to transport and store data
XSL	Extensible Stylesheet Language; XML based language to visualize XML (data)



1.2) General

The EnOcean radio protocol (ERP) is optimized to transmit information with utmost reliability using extremely little power while ensuring that the products of customers applying EnOcean technology are compatible with each other. Only the very shortest transmission period (< 1ms) for an EnOcean telegram allows the design of, for example, a battery-free radio switch, which can produce a full radio command with just approx. 50 µWs (50 µJ) of energy. At the same time, the reliability of the system increases, as the possibility of data collision is strongly reduced. Every data bit in the radio telegram is essential. For each '0' or '1' state, content descriptions are definied, which must be followed by the sender and the receiver likewise. Depending on the telegram type and the function of the device the user data (payload) is defined in:

EEP (EnOcean Equipment Profiles)



The ERP specification defines the structure of the entire radio telegram. The user data embedded in this structure is defined by the EEP.

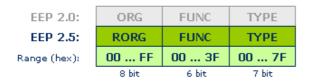
The objective of interoperability is easier to reach with as less profiles as required. Therefore, it is EnOcean Alliance's goal to configure each profile as universally as possible, to target a spectrum of devices in the building automation sector for all manufacturers.

It is of high interest to the EnOcean Alliance that Alliance members verify new devices or newly joined companies verify their products against the existing EEP Profiles and adopt these during testing. Every newly defined EEP would increase diversity and therefore decrease interoperability.

The technical characteristics of a device define three profile elements, which make up the organizational description of all profiles:

- 1. The ERP radio telegram type (RORG)
- 2. Basic functionality of the data content (FUNC)
- 3. Type of device in its individual characteristics (TYPE)

Therefore, every EEP profile has a number, reflecting these three components:



Every field is represented by a hexadecimal number, where the maximum value is limited by the available bits.

Before the definition of a new profile existing profiles should be checked first for suitability. A new profile is to be defined only if the existing profiles would not be adequate.

Once a new profile is to be developed it should be submitted to the TWG of the EnOcean Alliance. The information to

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be provided is

- the XML-data, plus
- the profile as text in a pdf-file (the .pdf-data is to be generated from the XML-data)

The TWG will review and ratify the profile. Following the recommendation by the TWG the BoD will disapprove or approve the profile.

When defining a new profile rules, abbreviations and terms as per this document have to be applied.

To maintain the XML-data and the linked pdf-document in a proper way a document maintenance process is defined. For details refer to appendix 3.14 Data + document maintenance process.

1.3) What's new in EEP 2.6.3?

New 4BS profiles:

- A5-09-0A Hydrogen Gas Sensor
- A5-09-0B Radioactivity Sensor
- A5-12-10 Current meter 16 channels
- A5-30-05 Single Input Contact, Retransmission, Battery Monitor
- A5-3F-7F Universal (resubmitted profile)

New VLD profiles:

- D2-32-xx A.C. Current Clamp
- D2-40-xx LED Controller Status

Modified profiles:

- A5-20-04: Description of Teach-In process; Tx delay
- D2-01-xx: CMD 0x05

1.4) Telegram types (RORG)

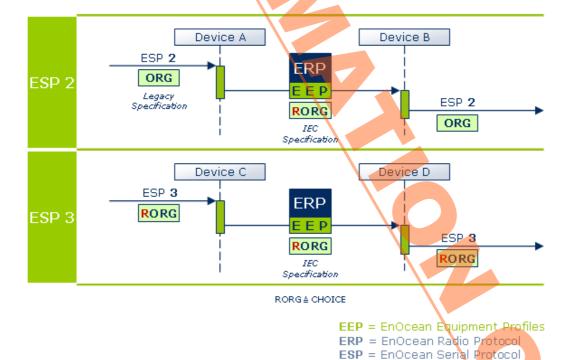
The various Radio-Telegram types are grouped **ORG**anizationally.

The specifications of ERP (EnOcean Radio Protocol) and of ESP (EnOcean Serial Protocol) group telegram types by 'CHOICE' number. 'RORG' at EEP 2.1(2.5) corresponds to 'CHOICE'.

The following RORG are used in EEP 2.5:

Telegram	RORG	ORG				
RPS	F6	05	Repeated Switch Communication			
1BS	D5	06	1 Byte Communication			
4BS	A5	07	4 Byte Communication			
VLD	D2	=RORG	Variable Length Data			
MSC	D1	=RORG	Manufacturer Specific Communication			
ADT	A6	=RORG	Adressing Destination Telegram			
SM_LRN_REQ	C6	=RORG	Smart Ack Learn Request			
SM_LRN_ANS	C7	=RORG	Smart Ack Learn Answer			
SM_REC	A7	=RORG	Smart Ack Reclaim			
SYS_EX	C5	=RORG	Remote Management			
SEC	30	=RORG	Secure telegram			
SEC_ENCAPS	31	=RORG	Secure telegram with R-ORG encapsulation			

For compatibility reasons, the old ORG values on the serial ESP2 interfaces remain valid. However, on the air interface, each ESP2 telegram is transported with the appropriate RORG (= CHOICE).

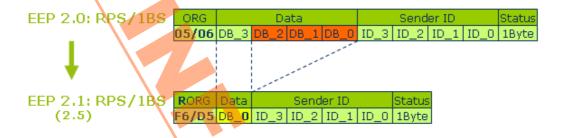


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1.5) EEP modifications at RPS and 1BS data telegram

Both telegram types carry a one byte payload (DB_0) on the wireless interface (ERP).

EEP 2.0 follows the specification of the serial interface / ESP2, which defines the payload to be carried in DB_3 (see succeeding figure). The trailing bytes, DB_2, DB_1 and DB_0 are marked as 'unused'.



For orthogonal data structural reasons, this deviation will be avoided with EPP 2.1, 2.5 and future versions. The new ESP3 serial interface already respects this

For reasons of compatibility of end devices, the ESP2 interface remains unaltered, i.e. the DB_0 byte (radio) will continue to be transferred as a DB_3 byte (serial) (including the 3 unused bytes).

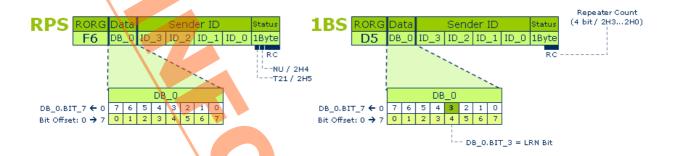
The conversation has to happen on the application layer as the XML-data structure of EEP 2.1 / 2.5 only refers to the DB_0 byte.

As a consequence of this modification the LRN bit is now described in a row for the 1BS and 4BS telegram types as standardized with the DB_0.BIT_3 position.

EEP 2.6.3 Specification

1,6) Structure and addressing of the telegram types

1.6.1) RPS / 1BS



The RPS and the 1BS telegrams offer only 1 byte user data. These two telegrams differ in the respective learning operations (the 1BS has a LRN bit), and in the way the status byte is used.

Comment for RPS status bits:

T21 = 0 = PTM switch module of type 1 / synonymous for module PTM1xx

T21 = 1 = PTM switch module of type 2 / synonymous for module PTM2xx

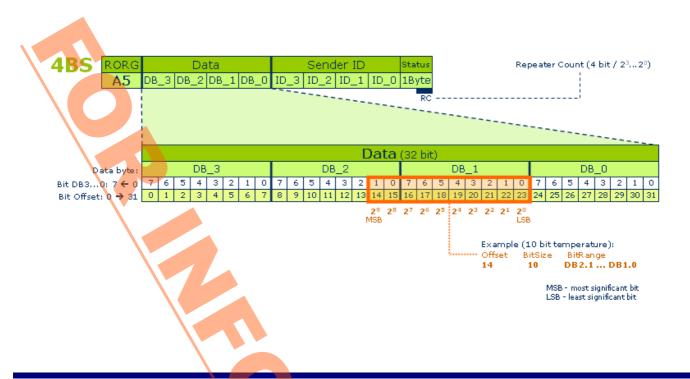
NU = 1 = N-message (N = normal)

NU = 0 = U-message (U = unassigned)

1.6.2) 4BS

A 4BS telegram carries a payload of 4 bytes. The sequence of the 4 data bytes is historically reversed, so that DB_3 appears first and DB_0 last on the radio interface. The bits are addressed in the sequence of the data flow, however (offset). Hence, DB_3.BIT_7 has the offset position 0 and DB_0.BIT_3 (LRN bit) has the offset position 28. The actual content-bits in a byte are not affected by this, i.e., they are described from right (2H0) to left (2H7) in the ascending order.

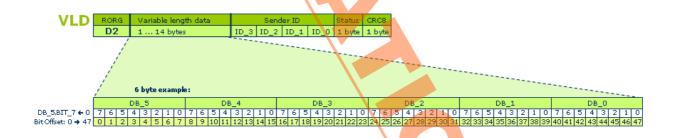
The example of a 10-bit temperature profile (see below) illustrates the binary valuation of the individual bits, so that a number range from 0 ... 1023 can be addressed.



1.6.3) VLD

VLD telegrams carry a variable payload between one and 14 bytes, depending on their design. The teach-in process applies the Smart Ack procedure (see appendices 3.4 and 3.5).

The example following displays a VLD telegram with 6 bytes user data. DB_5.BIT_7 is the first transmitted bit with offset 0.



1.7) Teach-in procedures

The 'Teach-in' defines the mutual communication between wireless devices in an 868 (315) MHz radio network. The 'Teach-in' defines to which transmitter(s) a receiver needs to listen to.

For this purpose of a determined relationship between transmitter and receiver each transmitting device has a unique Sender-ID which is part of each radio telegram. The receiving device detects from the Sender-ID whether the device is known, i.e., was already learned, or unknown.

A telegram with unknown Sender-ID is disregarded.

The 'teach-in' process is different for each telegram type (RPS, 1BS, 4BS, Smart Ack), but the following points are valid for all telegrams:

- First, the receiver must be switched into learning mode. Now, the Sender-ID of an arriving telegram is interpreted as an authorized information source and will be stored at the receiver. The further steps of 'teach-in' are defined by the device type or the telegram type. Thus, normal data telegrams or special teach-in telegrams can be used. Frequently, a learn button triggers the teach-in process.
- The telegram of the respective transmitter should be triggered at least once (by pressing the desired switch

- rocker or triggering a sensor).
- The bits of the payload (data bytes) can have multiple functions depending on the interpretation set by identification or status bits. Only in the 1BS and 4BS telegram the 'LRN BIT' DB_0.BIT_3 is reserved exclusively and must not be used elsewhere.

The following issues are relevant for a number of application but not mandatory for specification perspective:

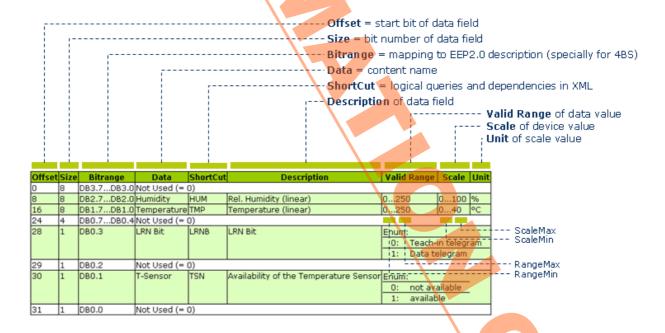
- To prevent unwanted devices from being learned the input sensitivity of the receiver is often restricted, and thus an IN-ROOM operation is created. Typically, the device to be learned is placed close by the receiver.
- Dolphin-based transmitters (e.g. TCM 300 or TCM 2x with Dolphin library) can also be switched into the learn-mode via a remote management command. This remote 'teach-in' mode can only be activated within the first 30 min after receiver power-up. To avoid inadvertent learning the transmitter telegrams have to be triggered 3 times within 2 seconds.

For further details on the 'Teach-in' processes refer to appendices 3.1 to 3.6.

1.8) Viewing XML-data

- The XML-file and all the associated files (CSS, DTD, XSL) and the 'graphics' folder must be stored in the same directory.
- The XML-file is best opened using an Internet browser, generating an HTML-view which displays the describing chapters, graphics and data tables.
- Mozilla Firefox V3.6 or upwards is recommended for optimum screen and print view.

The following example illustrates the HTML-view of the XML-data of a 4BS telegram (= payload of 32 bits).

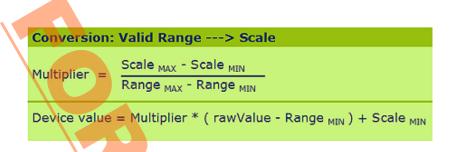


Data ranges unused are displayed in the table as white rows.

The 'Bit range' column displays the starting-point and the end-point of the respective data.

The 'Valid range', 'Scale' and 'Unit' columns are displayed separately only for measurement values. However, these 3 columns are merged into one if the data comes from an enumeration (enum).

Assuming a linear conversion between the value to be measured and the 'valid range' of data the resolution can be calculated as follows:

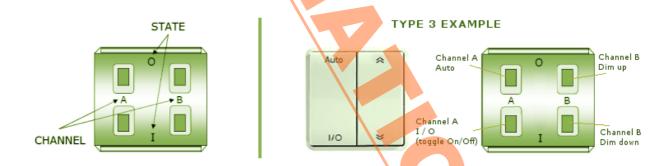


F6: RPS Telegram

Repeated Switch Communication Note for all F6-RPS EEP usage on ERP 2 Submitted by EnOcean ERP 2 (EnOcean Radio Protocol 2) is the radio protocol with FSK encoding. It is compatible on the application level with ERP 1. With ERP 2 all EPPs, Protocols (Security / Smart Acknowledge) can be used as it was before. Only difference are the RPS profiles. The ERP 2 (EnOcean Radio Protocol 2) – does not use the RPS telegrams as ERP 1 did. The biggest difference is the usage of the Status Field. The Status field in ERP 2 is defined as a repeater count field (also other position in the telegram). Other functionalities and fields T21 and NU are not present any more. Therefore a new encoding was developed. EEP describe an equipment – device – application. The meaning of the data did not change only the coding. The logic and semantic of the application is still the same. So it is defined that RPS profiles on ERP 2 have different coding of the actual telegram data, but the logic is same on ERP 1 and ERP 2. The new coding is published as new profiles. This is required to keep the same interfaces on the EEP processing (e.g. existing gateways / IP gateways – we do not want have additional information which radio protocol was used – ERP1/ERP2). The exact details are listed below. The profiles are defined in way that a seamless translation between ERP 1 and ERP 2 vice versa is possible without contextual information, what profile it is in particular.

F6-02: Rocker Switch, 2 Rocker

For clarification reasons the following picture shows a PTM200 transmitter module from EnOcean GmbH which transmits RPS telegrams and is one possibility to be used in applications that require an EEP F6-02-xx. Please note that PTM200 does not support transmission of teach-in telegrams.



The button naming used below is referring to CHANNEL and STATE of the PTM200. Thus "Button AI" means STATE "I" on CHANNEL "A".

There are two different message types, the N-message and the U-message, which need to be identified from the Status Field of an EnOcean RPS telegram. For that reason not only the data bytes are given for each EEP but the T21 and NU bits of the Status Field are listed as well.

RORG	F6	RPS Telegram			
FUNC	02	Rocker Switch, 2 Rocker			
TYPE	01	Light and Blind Control - Application Style 1			

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset		Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	3	DB0.7DB0.5		R1	Description	Enum		Journal	Oilit
			action			0:	Button AI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						1:	Button A0: "Switch light off" or "Move blind open"	"Dim light up"	or
						2:	Button BI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						3:	Button B0: "Switch light off" or "Move blind open"	"Dim light up"	or
3	1	DB0.4	Energy Bow	EB		Enum	<u>:</u>		
						0:	released		
						1:	pressed		
4	3	DB0.3DB0.1		R2		Enum			
			action			0:	Button AI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						1:	Button A0: "Switch light off" or "Move blind open"	"Dim light up"	or
						2:	Button BI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or
						3:	Button B0: "Switch light off" or "Move blind open"	"Dim light up"	or
7	1	DB0.0	2nd Action	SA		Enum			
						0:	No 2nd action		
						1:	2nd action valid		

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data		ShortCut	Description	Valid Range	Scale	Unit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	У	R1		3: 3:	button or 4 ttons	
3	1	DB0.4	Energy Bow		EB			eased essed	_
4	4	DB0.3DB0.0	Not Used (= 0)						

RORG	F6	RPS Telegram			
FUNC	02	Rocker Switch, 2 Rocker			
TYPE	02	Light and Blind Control - Application Style			

This EEP definition is based on the assumption that a RPS switch module (e.g. PTM200) is installed in an I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset Size Data Value

2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	3	DB0.7DB0.5	Rocker 1st	R1		Enum:			
			action			0:	Button AI:		
							"Switch light on" or '	'Dim light up"	or
							"Move blind open"		
						1:	Button A0:	Discouling to	
							"switch light off" or " "Move blind closed"	DIM light dow	n" or
		\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \				2:	Button BI:		
							"Switch light on" or '	'Dim light up"	or
							"Move blind open"	,	
						3:	Button B0:		
							"Switch light off" or '	`Dim light dow	n" or
_				_			"Move blind closed"		
3	1	DB0.4	Energy Bow	ЕВ		Enum:			
						0:	released		
						1:	pressed		
4	3	DB0.3DB0.1		R2		Enum:			
			action			0:	Button AI:		
							"Switch light on" or ' "Move blind open"	Dim light up"	or
						1:	Button A0:		
						1.	"switch light off" or "	Dim light dow	n" or
							"Move blind closed"	3	
						2:	Button BI:		
							"Switch light on" or '	'Dim light up"	or
							"Move blind open"		
						3:	Button B0: "Switch light off" or "	'Dim light daw	n" or
				· ·			"Move blind closed"	חווט ilgnt dow	11 01
7	1	DB0.0	2nd Action	SA		Enum:			
,	_	220.0	ZIId ACCOII	5/1		0:	No 2nd action		
						1:	2nd action valid		
						1.	Zilu action valid		

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	Shor	tCut	Desc	ription	Valid Range	Scale	Unit
0	3		Number of buttons pressed simultaneously (other bit combinations are not valid)	R1		/		3: 3	o buttor or 4 uttons	1
3	1	DB0.4	Energy Bow	EB			(eleased ressed	_
4	4	DB0.3DB0.0	Not Used (= 0)							

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	03	Light Control - Application Style 1

Submitter: Servodan

Definition of Auto, I/O for Rocker switch, Dim control (PTM200)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Of	ffset	Size	Bitr	ange	Data	ShortCut	Description		Valid Range	Scale	Unit
0		8	DB0.7.	DB0.0	Rocker	RA		Enum:			
					action			0x30:	Button A0: Set the controller in a	automatic mode	е
								0x10:	Button A1: Set the controller in r toggles between switch light on and sw	,	and
								0x70:	Button B0: Dim light up		
								0x50:	Button B1: Dim light down		

RORG	F6	RPS Telegram
FUNC	02	Rocker Switch, 2 Rocker
TYPE	04	Light and blind control ERP2

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum:
						0: released
						1: pressed
1	1	DB0.6	Button coding	ВС	Signalize button coding	Enum:
						0: button
2	2	DB0.5DB0.4	Not Used $(= 0)$))		
4	1	DB0.3	BI	RBI	State I of the rocker B	Enum:
						0: not pressed
						1: pressed
5	1	DB0.2	B0	RB0	State 0 of the rocker B	Enum:
						0: not pressed
					\	1: pressed
6	1	DB0.1	AI	RAI	State I of the rocker A	Enum:
						0: not pressed
						1: pressed
7	1	DB0.0	A0	RA0	State 0 of the rocker A	Enum:
						0: not pressed
						1: pressed

F6-03: Rocker Switch, 4 Rocker

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	01	Light and Blind Control - Application Style 1

This EEP definition is based on the assumption that a RPS switch module is installed in a 0-STATE up position! Application Style 1 is widely used in EU but may be found in other markets as well.

Statusfield:

I	Off	set	Size	Data	Value
I	2	\	1	T21	0
I	3	1	1	NU	1

Datafie	_									
Offset		Bitrange	Data	1	Description		Valid Range	Scale	Unit	
0	3	DB0.7DB0.5		R1		Enum	!			
			action			0:	Button AI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
							1:	Button A0: "Switch light off" or "Move blind open"	"Dim light up"	or
			1/5			2:	Button BI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
						3:	Button B0: "Switch light off" or "Move blind open"	"Dim light up"	or	
						4:	Button CI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
						5:	Button C0: "Switch light off" or "Move blind open"	"Dim light up"	or	
						6:	Button DI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
						7:	Button D0: "Switch light off" or "Move blind open"	"Dim light up"	or	
3	1	DB0.4	Energy Bow	EB		Enum	:			
						0:	released pressed			
4	3	DB0.3DB0.1	Rocker 2nd	R2		Enum				
			action			0:	Button AI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
						1:	Button A0: "Switch light off" or "Move blind open"	"Dim light up"	or	
						2:	Button BI: "Switch light on" or "Move blind closed"		n" or	
						3:	Button B0: "Switch light off" or "Move blind open"	"Dim light up"	or	
						4:	Button CI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
						5:	Button CO: "Switch light off" or "Move blind open"	"Dim light up"	or	
						6:	Button DI: "Switch light on" or "Move blind closed"	"Dim light dow	n" or	
						7:	Button D0: "Switch light off" or "Move blind open"	"Dim light up"	or	
7	1	DB0.0	2nd Action	SA		Enum				
						0:	No 2nd action			
						1:	2nd action valid			

Statusfield:

Offset Size Data Value

2	1	T21	0
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	3	DB0.7DB0.5		R1		Enum:			
	/		simultaneously			0:	no Butto pressed		
						1:	2 buttor pressed		
						2:	3 buttor pressed		
						3:	4 buttor pressed		
						4:	5 buttor pressed		
						5:	6 buttor pressed		
						6:	7 buttor pressed		
						7:	8 buttor pressed		
3	1	DB0.4	Energy Bow	EB		Enum:			
						0:	released	<u></u>	
						1:	pressed		
4	4	DB0.3DB0.0	Not Used (= 0)						

RORG	F6	RPS Telegram
FUNC	03	Rocker Switch, 4 Rocker
TYPE	02	Light and Blind Control - Application Style 2

A This EEP definition is based on the assumption that a RPS switch module is installed in a I-STATE up position! Application Style 2 is typically used in US and CAN but may be found in other markets as well.

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	1

Datafield:

DB0.7DB0.5 Rocker 1st action R1 Bnum: O: Button AI: "Switch light on" or "Dim light up" or "Move blind open" 1: Button A0: "Switch light off" or "Dim light down" or "Move blind closed" 2: Button BI: "Switch light off" or "Dim light up" or "Move blind open" 3: Button B0: "Switch light off" or "Dim light down" or "Move blind closed" 4: Button CI: "Switch light on" or "Dim light up" or "Move blind open" 5: Button C0: "Switch light off" or "Dim light down" or "Move blind closed"	0 3	DB0.7DB0.5	Rocker 1st	R1				
			action		0: 1: 2: 3:	Button AI: "Switch light on" or "Move blind open" Button A0: "Switch light off" or "Move blind closed" Button BI: "Switch light on" or "Move blind open" Button B0: "Switch light off" or "Move blind closed" Button CI: "Switch light on" or "Move blind open" Button CI: "Switch light on" or "Move blind open" Button CO: "Switch light off" or "Switch light	'Dim light dow 'Dim light up" 'Dim light dow 'Dim light up"	n" or or or

					7: Button "Switcl "Move	n light on" or "Dim light up" or blind open"
3	1	DB0.4	Energy Bow	EB	 num: 0: release 1: presse	
4	3	DB0,3DB0.1	Rocker 2nd action	R2	O: Button "Switcl "Move 1: Button "Switcl "Move 2: Button "Switcl "Move 3: Button "Switcl "Move 4: Button "Switcl "Move 5: Button "Switcl "Move 6: Button "Switcl "Move 7: Button "Switcl "Move	AI: In light on" or "Dim light up" or Is blind open" A0: In light off" or "Dim light down" or Is blind closed" BI: In light on" or "Dim light up" or Is blind open" B0: In light off" or "Dim light down" or Is blind closed" CI: In light on" or "Dim light up" or Is blind open" C0: In light off" or "Dim light down" or Is blind closed" DI: In light on" or "Dim light up" or Is blind closed" DI: In light on" or "Dim light up" or Is blind open" D0: In light off" or "Dim light down" or Is blind open" D0: In light off" or "Dim light down" or
7	1	DB0.0	2nd Action	SA	num:	blind closed" I action
						tion valid

Statusfield:

Offset	Size	Data	Value
2	1	T21	0
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	3	DB0.7DB0.5	Number of buttons pressed simultaneously	R1		Enum: 0: no button pressed 1: 2 buttons pressed 2: 3 buttons pressed 3: 4 buttons pressed 4: 5 buttons pressed 5: 6 buttons pressed 6: 7 buttons pressed 7: 8 buttons pressed
3	1	DB0.4	Energy Bow	EB		Enum: 0: released 1: pressed
1	4	DB0 3 DB0 0	Not Used (= 0)			

F6-04: Position Switch, Home and Office Application

RORG	F6	RPS Telegram
FUNC	04	Position Switch, Home and Office Application
TYPE	01	Key Card Activated Switch

Insertion of Key Card generates an N-Message, take-out a U-Message

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	Shor	tCut	Description	Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Key Card	KC			Enum:		
			\				112: inserted	d (0x70)

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Offset	Size	Bitrange	Data	ShortCut	De	cri	ption	Valid Range	Scale	Unit
0	8	DB0.7DB0.0	Key Card	KC		1.		Enum:		
								0: taken	out	_

RORG	F6	RPS Telegram	
FUNC	04	Position Switch, Home and Office	Application
TYPE	02	Key Card Activated Switch E	RP2

Submitter: EnOcean GmbH

When card is inserted field EBO and SOC are both having value 1. When take out, both are having value 0. This coding is required to have a context less translation of RPS profiles between ERP 1 and ERP 2.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	1	DB0.7	Energy Bow	EBO	State of the energy bow	Enum:
						0: taken out
						1: card inserted
1	1	DB0.6	Button coding	BC	Signalize button coding	Enum:
						0: button
2	3	DB0.5DB0.3	Not Used (= 0))		
5	1	DB0.2	State of card	SOC	State of the card	Enum:
						0: taken out
						1: card inserted
6	2	DB0.1DB0.0	Not Used (= 0	1)		

F6-05: Detectors

RORG	F6	RPS Telegram
FUNC	05	Detectors
TYPE	01	Liquid Leakage Sensor (mechanic harvester)

Submitter: Afriso / EnOcean

Description:

This profile is used for devices detecting leakage. It is commonly placed on ground where a leakage causes damage. The principle is that "paper rings" swell in water and trigger an ECO 200 (generator) based transmitter.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: NA Trigger event: (water detection) Teach-in method: RPS teach-in

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	1

Datafield:

Offset	Size	Bitrange	Data	ShortCut		Description	Val Ran		Scale	Unit
0	8	DB0.7DB0.0	Water	WAS	Alert	signal that the sensor detected	Enum:			
			sensor		water	l <mark>e</mark> akage		Water	,	
							0x11:	detect	ed	

F6-10: Mechanical Handle

RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
TYPE	00	Window Handle

Submitter: HOPPE AG

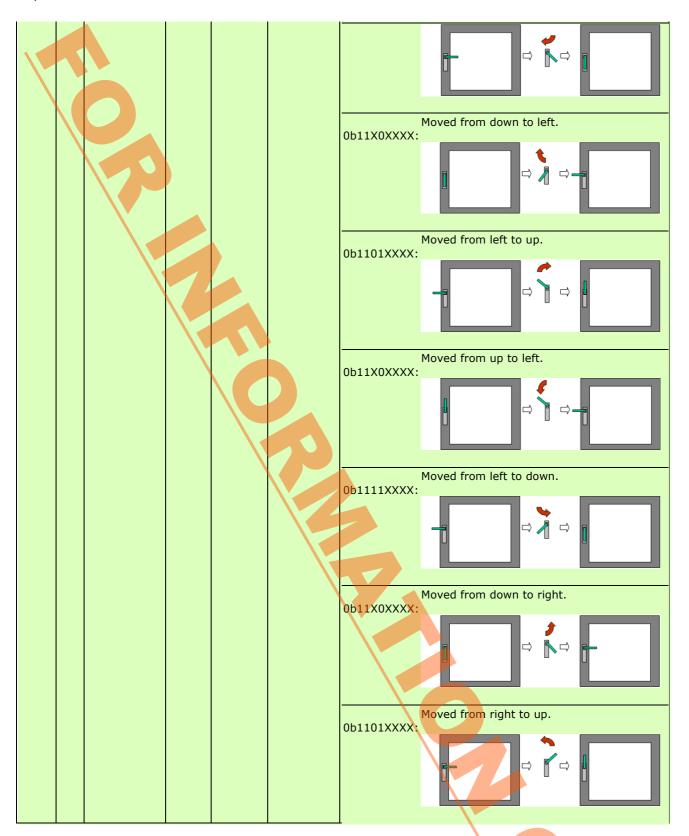
The bits marked with 'X' in DB_0 should not be checked. These bits can be '1' or '0' and should not be assumed to be a defined value, because both of them are allowed and not predictable!

Statusfield:

Offset	Size	Data	Value
2	1	T21	1
3	1	NU	0

Datafield:

Off	set	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	_		DB0.7DB0.0		WIN	Movement of the window handle	Enum: Moved from up to 0b11X0XXXX: Moved from right 0b1111XXXX:	left.	

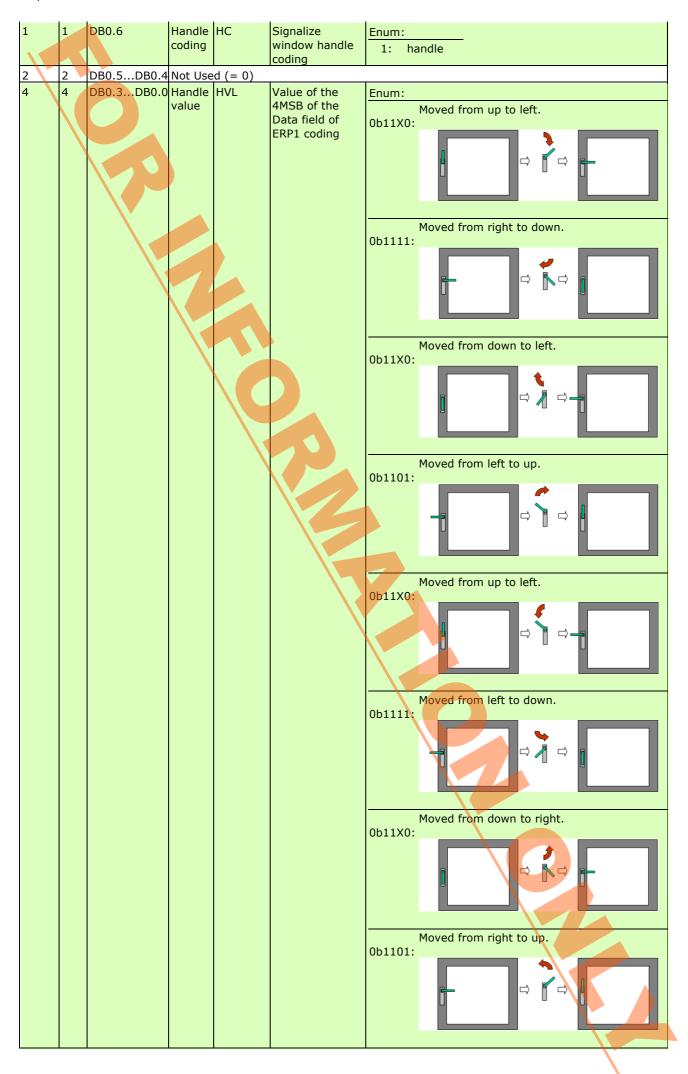


RORG	F6	RPS Telegram
FUNC	10	Mechanical Handle
TYPE	01	Window Handle ERP2

Submitter: HOPPE AG

 $\ensuremath{\mathsf{DB0.6}}$ – needs to show that RPS/ERP2 has a different coding as RPS/ERP1.

Offset S	Size	Bitrange	Data ShortCut	Description	Valid Range	Scale	Unit
0 1	L	DB0.7	Not Used (= 0)				



D5: 1B\$ Telegram

D5-00: Contacts and Switches

RORG	D5	1BS Telegram
FUNC	00	Contacts and Switches
TYPE	01	Single Input Contact
		7

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
4	1	DB0.3	Learn Button	LRN		Enum:
						0: pressed
						1: not pressed
7	1	DB0.0	Contact	СО		Enum:
						0: open
						1: closed

A5: 4BS Telegram

A5-02: Temperature Sensors

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	01	Temperature Sensor Range -40°C to 0°C

Offset	Size	Bitrange	Data	ShortCut	Descripti	ion	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)						
16	8	DB1.7DB1.0	Temperature	TMP	Temperature	(linear)	2550)	-400	°C
24	4	DB0.7DB0.4	Not Used (=	0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:			
							0:	Teach-ir	n telegra	m
							1:	Data tel	egram	
29	3	DB0.2DB0.0	Not Used (=	0)						

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	02	Temperature Sensor Range -30°C to +10°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)	-			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-30+10	°C
24	4	DB0.7DB0.4	Not Used (=	0)	-	_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	,	
						0: Teach-	in telegran	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	03	Temperature Sensor Range -20°C to +20°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+20	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	04	Temperature Sensor Range -10°C to +30°C

Offset	Size	Bitrange	Data	ShortCut	De	scription	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)			_		
16	8	DB1.7DB1.0	Temperature	TMP	Tempe	rature (linear)	2550	-10+30	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-	in telegrai	n
							1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram	1	
FUNC	02	Temperature Sensors	_/_	
TYPE	05	Temperature Sensor Range 0°C to	+4	0°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Ran	ge Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)			_	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teac	ch-in telegra	m
						1: Data	telegram	
29	3	DB0.2DB0.0	Not Used (=	0)				
29	3	DBU.ZDBU.U	Not Usea (=	0)			- 	4

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	06	Temperature Sensor Range +10°C to +50°C

Offse	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				

16	8		DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+10+50 °C
24	4		DB0.7DB0.4	Not Used (=	lot Used (= 0)			
28	1		DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
							0:	Teach-in telegram
		Δ					1:	Data telegram
29	3		DB0.2DB0.0	Not Used (=	0)		·	

RORG		A5	4BS Telegram
FUNC		02	Temperature Sensors
TYPE	,	07	Temperature Sensor Range +20°C to +60°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				-

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	08	Temperature Sensor Range +30°C to +70°C

Offset	Size	Bitrange	Data	ShortCut	Descripti	ion	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature	(linear)	2550	+30+70	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-	in telegran	n
							1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	09	Temperature Sensor Range +40°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+40+80	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	-in telegrar	n
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	0A	Temperature Sensor Range +50°C to +90°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+50+90	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegran	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	0B	Temperature Sensor Range +60°C to +100°C

Offset	Size	Bitrange	Data	ShortCu	ıt Desc	ription	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)			_		
16	8	DB1.7DB1.0	Temperature	TMP	Tempera	ture (linear)	2550	+60+100	ပ္
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-	-in telegram	
							1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram		
FUNC	02	Temperature Sensors	1	
TYPE	10	Temperature Sensor Range -60°C to	+2	0°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rai	nge Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)			1	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-60+20	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Te	ach-in telegra	m
						1: Da	ta telegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	11	Temperature Sensor Range -50°C to +30°C

Offset Size Bitrange Data ShortCut Description Valid Range Scale	Unit
--	------

0		16	;	DB3.7DB2.0	Not Used (=	0)					
16		8		DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-50+30 °C		
24		4		DB0.7DB0.4	Not Used (=	ot Used (= 0)					
28		1		DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
								0: Teach-	-in telegram		
	,							1: Data t	elegram		
29		3		DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram			
FUNC	02	Temperature Sensors			
TYPE	12	Temperature Sensor Range -40°C to +40°C			

Offset	Size	Bitrange	77	Data	S	hortCu	t Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not	Used (= 0)				
16	8	DB1.7DB1.0	Tem	peratu	ıre T	MP	Temperature (linear)	2550	-40+40	°C
24	4	DB0.7DB0.4	Not	Used (= 0					
28	1	DB0.3	LRN	Bit	L	.RNB	LRN Bit	Enum:		
				\	$\langle 1 \rangle$			0: Teach-	in telegra	m
								1: Data t	elegram	
29	3	DB0.2DB0.0	Not	Used (= 0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	13	Temperature Sensor Range -30°C to +50°C

Offset	Size	Bitrange	Data	ShortCut	Descrip	tion	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature	e (linear)	2550	-30+50	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-	-in telegrai	m
						\	1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)		•			

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	14	Temperature Sensor Range -20°C to +60°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-20+60	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		//
						0: Teach-	in telegrar	n
						1: Data to	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	15	Temperature Sensor Range -10°C to +70°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	-10+70	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data te	elegram	·
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	16	Temperature Sensor Range 0°C to +80°C

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+80	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram	
FUNC	02	Temperature Sensors	
TYPE	17	Temperature Sensor Range +10°C to -	+90°C

Offset	Size	Bitrange	Data	ShortCut	Description Valid		ge Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)	-			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+10+	90 °C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
					0: Teach-in telegra			
						1: Dat	ta telegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram					
FUNC	02	Temperature Sensors					
TYPE	18	Temperature Sensor Range +20°C to +100°C					

Off	set	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0		16	DB3.7DB2.0	Not Used (=	0)				
16		8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+20+100	°C
24		4	DB0.7DB0.4	Not Used (=	0)				
28		1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram		
		\setminus							
							1: Data to	elegram	
29		3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5		4BS Telegram
FUNC	02		Temperature Sensors
TYPE	19	Tem	perature Sensor Range +30°C to +110°C

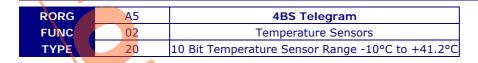
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+30+110	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegram	
						1: Data t	elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5	4BS Telegram
FUNC	02	Temperature Sensors
TYPE	1A	Temperature Sensor Range +40°C to +120°C

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature ((linear)	2550	+40+120	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	- /-	Enum:		
								-in telegram elegram	
29	3	DB0.2DB0.0	Not Used (=	0)					

RORG	A5	4BS Telegram				
FUNC	02	Temperature Sensors				
TYPE	1B	Temperature Sensor Range +50°C to +130°C				

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	16	DB3.7DB2.0	Not Used (=	0)		_				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	+50+130	°C		
24	4	DB0.7DB0.4	B0.7DB0.4 Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		-//		
						0: Teach-	in telegram			
						1: Data t	elegram			
29	3	DB0.2DB0.0	Not Used (=	0)						



Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
		\				0: Teach-	in telegram	_
		\				1: Data t	elegram	_
29	3	DB0.2DB0.0	Not Used (=	0)				

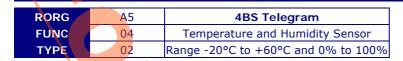
RORG	A5	`			4	38	Tele	egram			
FUNC	02				Temp	er	atur	e Senso	ors		
TYPE	30	10 Bit Te	emp	er	ature S	Ser	nsor	Range	-40°C t	:0 -	⊦62.3°C

Offset	Size	Bitrange	Data	ShortCut	Descriptio	n	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)					
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (li	inear)	10230	-40+62.3	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit			in telegram elegram	<u> </u>
29	3	DB0.2DB0.0	Not Used (=	0)				•	

A5-04: Temperature and Humidity Sensor

RORG	A5	4BS Telegram
FUNC	04	Temperature and Humidity Sensor
TYPE	01	Range 0°C to +40°C and 0% to 100%

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i telegrai 1: Data te	n	
29	1	DB0.2	Not Used (=	0)				
30	1	DB0.1	T-Sensor		Availability of the Temperature Sensor	Enum: 0: not ava 1: availabl	\ 	
31	1	DB0.0	Not Used (=	0)		•		



Submitter: Eltako

Description:

In contrast to EEP A5-04-01, the temperature range is extended: -20°C...+60°C.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval:

Trigger event: change in temperature, change in humidity

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	-20+60	°C
24	4	DB0.7DB0.4 Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach- telegra 1: Data t		
29	1	DB0.2	Not Used (=	0)				
30	1	DB0.1	T-Sensor	TSN	Availability of the Temperature Sensor	Enum: 0: not av 1: availal	ailable ole	
31	1	DB0.0	Not Used (=	0)				

			1		
RORG	A5	4BS Telegram			
FUNC	04	Temperature and Humidity Sensor			
TYPE	03	Range -20°C to +60°C 10bit-measurement and 0°	% to	100%	,

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: -

Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0255	0100	%
8	6	DB2.7DB2.2	Not Used (= 0))				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature (linear)	01023	-20+60	°C
24	4	DB0.7DB0.4	Not Used (= 0)	1				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data to	elegram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Telegram Type	TTP	Telegram Type	Enum:		
						0: Heartb	eat	
						1: Event	triggered	

A5-05: Barometric Sensor

RORG	A5	4B\$ Telegram			
FUNC	05	Barometric Sensor			
TYPE	01	Range 500 to 1150 hPa			

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: 20 seconds – 1 hour (one time configuration)

Trigger event: threshold/delta for observed value, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: -Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	6	DB3.7DB3.2	Not Used (= 0)	1				
6	10	DB3.1DB2.0	Barometer	BAR	Barometer (linear)	01023	5001150	hPa
16	12	DB1.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegram	1
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Telegram Type	TTP	Telegram Type	Enum: 0: Hearth 1: Event	eat triggered	

A5-06: Light Sensor

RORG	A5	4BS Telegram		
FUNC	06	Light Sensor		
TYPE	01	Range 300lx to 60.000lx		

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V	
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	30030000	lx	
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	60060000	lx	
24	4	DB0.7DB0.4	0B0.4 Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in	telegram		
	`					1: Data tele	gram		
29	2	DB0.2DB0.1	Not Used (= 0)						
31	1	DB0.0	Range select	RS	Range	Enum:			
						0: Range ac	c. to DB_1 (ILL	L1)	
						1: Range ac	c. to DB_2 (ILL		

RORG	A5	4BS Telegram			
FUNC	06	Light Sensor			
TYPE	02	Range 0lx to 1.020lx			

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL2	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Illumination	ILL1	Illumination (linear)	0255	01020	lx
24	4	DB0.7DB0.4	Not Used $(= 0)$					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegr	am	
29	2	DB0.2DB0.1	Not Used (= 0)	,				
31	1	DB0.0	Range select	RS	Range	Enum:		
						0: Range acc. to DB_1 (ILL1)		
						1: Range acc. to DB_2 (ILL2)		

RORG	A5	4BS Telegram
FUNC	06	Light Sensor
TYPE	03	10-bit measurement (1-Lux resolution) with range 0lx to 1000lx

Submitter: Lutuo Technology

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage (linear) 251255: reserved for error co	A	0250	05.0	V
8	10	DB2.7DB1.6	Illumination		Illumination (linear) DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	- //	01000	01000	lx
18	10	DB1.5DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		0: Teach- telegra 1: Data t		
29	3	DB0.2DB0.0	Not Used (= 0)					

A5-07: Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	07	Occupancy Sensor
TYPE	01	Occupancy with Supply voltage monitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage (OPTIONAL)		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	PIR Status	PIRS	PIR Status	Enum: 0127: PII 128255: PII	R off R on	
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram	
29	2	DB0.2DB0.1	Not Used (= 0)					
31	1	DB0.0	Supply voltage availability	SVA	Supply voltage availability at DB_3	supporte	oltage is	not

RORG	A5	4BS Telegram	
FUNC	07	Occupancy Sensor	
TYPE	02	Occupancy with Supply voltage m	onitor

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

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RORG	A5	4BS Telegram	//	
			- \	

FUNC	Occupancy Sensor	
TYPE	03	Occupancy with Supply voltage monitor and 10-bit illumination measurement

Submitter: Lutuo Technology

The transmission of "PIR off" telegrams is optional.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage (REQUIRED)	SVC	Supply voltage (linear); 251 – 255 reserved for error code	0250	05.0	V
8	10	DB2.7DB1.6	Illumination	ILL	Illumination (linear); DB2 = 8 MSB, DB1 = 2 LSB 1001: over range, 10021024: reserved	01000	01000	lx
18	6	DB1.5DB1.0	Not Used (= 0)					
24	1	DB0.7	PIR Status	PIRS	PIR Status	Enum:		
						1: Motion	detected	
						0: Uncerta status	in of occupa	ancy
25	3	DB0.6DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ii	n telegram	
						1: Data te	egram	
29	3	DB0.2DB0.0	Not Used (= 0)					

A5-08: Light, Temperature and Occupancy Sensor

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	01	Range Olx to 510lx, 0°C to +51°C and Occupancy Button

E.g. for ceiling suspended sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
					\'	1: Data te	legram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
						0: PIR on		
						1: PIR off		
31	1	DB0.0	Occupancy Button	осс		Enum:		
						0: Button	pressed	
						1: Button	released	

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	02	Range Olx to 1020lx, 0°C to +51°C and Occupancy Button

E.g. for wall mounted sensor.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V	
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01020	lx	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C	
24	4	DB0.7DB0.4	Not Used (= 0)	lot Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-	in telegra	m	
	· `					1: Data te	elegram		
29	1	DB0.2	Not Used (= 0)						
30	1	DB0.1	PIR Status	PIRS	PIR Status	Enum:			
						0: PIR on			
						1: PIR off			
31	1	DB0.0	Occupancy Button	OCC		Enum:			
						0: Button	pressed		
						1: Button	released		

RORG	A5	4BS Telegram
FUNC	08	Light, Temperature and Occupancy Sensor
TYPE	03	Range 0lx to 1530lx, -30°C to +50°C and Occupancy Butto

E.g. for outdoor sensor.

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
8	DB3.7DB3.0	Supply voltage	SVC	Supply voltage (linear)	0255	05.1	V
8	DB2.7DB2.0	Illumination	ILL	Illumination (linear)	0255	01530	lx
8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-30+50	°C
4	DB0.7DB0.4	Not Used (= 0)					
1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
			\		0: Teach-in telegram		
					1: Data t	elegram	
1	DB0.2	Not Used (= 0)	•				
1	DB0.1	PIR Status	PIRS	PIR Status	Enum:		
					0: PIR on		
					1: PIR off	f	
1	DB0.0	Occupancy Button	occ		Enum:		
					0: Button	pressed	
					1: Button	released	_
	8 8 8 4 1 1	8 DB3.7DB3.0 8 DB2.7DB2.0 8 DB1.7DB1.0 4 DB0.7DB0.4 1 DB0.3 1 DB0.2 1 DB0.1	8 DB3.7DB3.0 Supply voltage 8 DB2.7DB2.0 Illumination 8 DB1.7DB1.0 Temperature 4 DB0.7DB0.4 Not Used (= 0) 1 DB0.3 LRN Bit 1 DB0.2 Not Used (= 0) 1 DB0.1 PIR Status	8	8 DB3.7DB3.0 Supply voltage SVC Supply voltage (linear) 8 DB2.7DB2.0 Illumination ILL Illumination (linear) 8 DB1.7DB1.0 Temperature TMP Temperature (linear) 4 DB0.7DB0.4 Not Used (= 0) LRN Bit LRN Bit 1 DB0.3 LRN Bit LRN Bit 1 DB0.2 Not Used (= 0) 1 DB0.1 PIR Status PIRS PIR Status	B	B

A5-09: Gas Sensor

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	02	CO-Sensor 0 ppm to 1020 ppm

Submitter: Unitronic AG

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage (linear)	0255	05.1	V
8	8	DB2.7DB2.0	Concentration	Conc	Gas concentration	0255	01020	ppm
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+51	°C
24	4	DB0.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegran	1	

29	1	DB0.2	Not Used (= 0)	١	
30	1	DB0.1	T-Sensor	TSN	 Enum:
					0: Temperature Sensor not available
					1: Temperature Sensor available
31	1	DB0.0	Not Used (= 0)	1	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	04	CO2 Sensor

Offset	Siza	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0		DB3.7DB3.0			•	0200	0100	%	
8	8	DB2.7DB2.0	Concentration		Concentration (linear), increment = 10 ppm	0255	02550	ppm	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear), increment = 0.2 °C	0255	0+51.0	°C	
24	4	DB0.7DB0.4	Not Used $(=0)$)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
							0: Teach-i	n telegram	_
						1: Data tel	legram	_	
29	1	DB0.2	H-Sensor	HSN		Enum:			
						0: Humidit availabl	y Sensor not e		
						1: Humidit availabl	y Sensor e		
30	1	DB0.1	T-Sensor	TSN	\	Enum:			
						0: Temper availabl	ature Sensor e	not	
						1: Temper availabl	ature Sensor e		
31	1	DB0.0	Not Used (= 0)				•	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	05	VOC Sensor

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	VOC	Conc	VOC Concentration	065535	065535	ppb
16	8	DB1.7DB1.0	VOC ID	VOC_ID	VOC identification	Enum:		
						0: VOCT (to	tal)	
						1: Formalde	hyde	
						2: Benzene		
						3: Styrene		
						4: Toluene		
						5: Tetrachlo	roethylene	
						6: Xylene		
						7: n-Hexane		
						8: n-Octane		
						9: Cyclopent	tane	
						10: Methanol		
						11: Ethanol		

		la control de				
						12: 1-Pentanol
						13: Acetone
						14: ethylene Oxide
						15: Acetaldehyde ue
						16: Acetic Acid
						17: Propionice Acid
	1/4					18: Valeric Acid
	\					19: Butyric Acid
						20: Ammoniac
						22: Hydrogen Sulfide
						23: Dimethylsulfide
						24: 2-Butanol (butyl Alcohol)
						25: 2-Methylpropanol
						26: Diethyl ether
						255: ozone
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit LRN	В	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Not Used (= 0)			
30	2	DB0.1DB0.0	Scale Multiplier SCM		Scale Multiplier	Enum:
						0: 0.01
						1: 0.1
						2: 1
						3: 10

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	06	Radon

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Desci	ription	Valid Range	Scale	Unit
0	10	DB3.7DB2.6	Radon	Act	Radon activity (regulation 100 Bq/m3/24h)	ation is an average of	01023	01023	Bq/m3
10	18	DB2.5DB0.4	Not Use	ed (= 0)					
28	1		LRN Bit	LRNB	LRN Bit		tele	ch-in gram a telegram	1
29	3	DB0.2DB0.0	Not Use	ed (= 0)				•	

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	07	Particles

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	9	DB3.7DB2.7	Particles_10	PM10	Dust less than 10 µm (PM10)	0511	0511	μg/m3
9	9	DB2.6DB1.6	Particles_2.5	PM2.5	Dust less than 2.5 µm (PM2.5)	0511	0511	µg/m3
18	9	DB1.5DB0.5	Particles_1	PM1	Dust less than 1 µm (PM1)	0511	0511	µg/m3
27	1	DB0.4	Not Used (=	0)				
							,	

28	1 DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
					0: Teach-in telegram
					1: Data telegram
29	1 DB0.2	PM10 active	PM10a		Enum:
					0: PM10 not active
					1: PM10 active
30	1 DB0.1	PM2.5 active	PM2.5a		Enum:
					0: PM2.5 not active
					1: PM2.5 active
31	1 DB0.0	PM1 active	PM1a		Enum:
					0: PM1 not active
					1: PM1 active

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	08	Pure CO2 Sensor

Submitter: Afriso / EnOcean

Description

Pure CO2 sensor with 8 bit resolution and 0 - 2000ppm.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: change of value over threshold, heartbeat

Teach-in method: 4BS teach-in 2

Offset	Size	Bitrange	Data	ShortCut	Descripti	on	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Not Use	ed (= 0)					
16	8	DB1.7DB1.0	CO2	CO2	CO2 measure	ement	0255	02000	ppm
24	4	DB0.7DB0.4	Not Use	ed (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		Enum:		
							0: Teach-	in telegra	m
							1: Data te	elegram	
29	3	DB0.2DB0.0	Not Use	ed (= 0)		1			

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	09	Pure CO2 Sensor with Power Failure Detection

Submitter: Afriso / EnOcean

Description

Pure CO2 sensor with 8 bit resolution and 0 – 2000ppm.

1 digital Input – Power failure detection.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: change of value over threshold, heartbeat, change of digital Input

Teach-in method: 4BS teach-in 2

Remark

Power failure detection expresses that the device was cut from power source (unplugged / general power failure) and the device will probably stop functioning very soon. In this case the measured value CO2 is the last valid value.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Scale	Unit	
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						Range	
0	16	DB3.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	CO2	CO2	CO2 measurement	0255	02000 ppm
24	4	DB0.7DB0.4 Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teac	h-in telegram
						1: Data	telegram
29	1	DB0.2	Power Failure	PFD	Indicates if power supply has a	Enum:	
			detection		failure / is not available	0: Powe detec	er failure not
						1: Powe detec	er failure cted
30	2	DB0.1DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor
TYPE	0A	Hydrogen Gas Sensor

Submitter: SiMICS

Description

Hydrogen Gas Sensor with 16 bit resolution and 0-2000 ppm

<u>Data exchange</u> <u>Direction: unidirectional</u> Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in gas concentration and temp

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

<u>Security</u> Encryption supported: yes

Security level format: PSK, RLC, AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	16	DB3.7DB2.0	Concentration	Conc	Gas concentration	065535	065535	ppm
16	8	DB1.7DB1.0	Temperature	TEMP	Temperature (linear)	0255	-20+60	°C
24	4	DB0.7DB0.4	Supply voltage	SV	Supply voltage / super cap.	015	2.05.0	V
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0; Teach-in 1: Data tele	telegram egram	-
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Temp sensor availability	TSA	Temp sensor availability at TMP	0: Temp se supporte	nsor is	
31	1	DB0.0	Supply voltage availability	SVA	Supply voltage availability at SV	supporte	oltage is	:

RORG	A5	4BS Telegram
FUNC	09	Gas Sensor

0B Radioactivity Sensor TYPE

Submitter: SiMICS

Description

Radioactivity Sensor

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -

Trigger event: change in radioactivity level

Tx delay: -Rx timeout: -

<u>Teach-in</u> Teach-in method: 4BS teach-in 2

Security

Encryption supported: yes

Security level format: PSK, RLC, AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	DB3.7DB3.4	Supply voltage	SV	Supply voltage / super cap.	015	2.05.0	V
4	4	DB3.3DB3.0	Not Used (= 0)					
8	16	DB2.7DB1.0	Radioactivity		Radiation level	065535	06553	According to
24	4	DB0.7DB0.4	Scale Multiplier	SCM	Scale Multiplier	Enum: 0: 0.001 1: 0.01 2: 0.1 3: 1 4: 10 5: 100 6: 1000 7: 10000 8: 10000		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach	-in telegra telegram	ım_
29	2	DB0.2DB0.1	Value unit	VUNIT	The unit of the radiation level	Enum: 0: μSv/h 1: cpm 2: Bq/L 3: Bq/kg		
31	1		Supply voltage availability	SVA	Supply voltage availability at SV	Enum: 0: Suppl	y voltage i orted y voltage i	

A5-10: Room Operating Panel

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	01	Temperature Sensor, Set Point, Fan Speed and Occupancy Control

Submitter: Kieback + Peter GmbH

	Offs	set Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
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0	8		Turn-switch for fan speed	FAN	Turn-switch for fan speed	Enum: 210255: 190209: 165189: 145164: 0144:	Stage Auto Stage 0 Stage 1 Stage 2 Stage 3
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255 N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C
24	4		Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telego 1: Data	
29	2	DB0.2DB0.1	Not Used (= 0)				
31	1	DB0.0	Occupancy	occ	Occupancy button		n released n pressed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	02	Temperature Sensor, Set Point, Fan Speed and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:			
			speed			210255: Stage Auto			
						190209:	Stage 0		
						165189:	Stage 1		
						145164:	Stage 2		
						0144:	Stage 3		
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A	
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C	
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach- telegra 1: Data to			
29	2	DB0.2DB0.1	Not Used (= 0)						
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch Day/Night	Off	n I / Nigh		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	03	Temperature Sensor, Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)		_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
	`					0: Teach-i	n telegra	m
						1: Data te	egram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5			4BS Telegram
FUNC	10			Room Operating Panel
TYPE	04	Τe	emperat	ture Sensor, Set Point and Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN		Enum:		
			speed	A		210255:	Stage Auto	
						190209:	Stage 0	
						165189:	Stage 1	
						145164:	Stage 2	
						0144:	Stage 3	
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach		
							telegram	
29	3	DB0.2DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	05	Temperature Sensor, Set Point and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)					
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	5	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550)	0+40	°C
24	4	DB0.7DB0.4	DB0.7DB0.4 Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0:	Teach-i	n telegra	m
						1:	Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)					
			•						

3	1	1	DB0.0	Occupancy	occ	Occupancy button	Enum	:
							1:	Button released
							0:	Button pressed

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	06	Temperature Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)					
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	4	DB0.7DB0.4	Not Used $(= 0)$					
28	28 1 DB0.3 LR		LRN Bit LRN		LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegram		
29	2	DB0.2DB0.1	Not Used $(=0)$					
31	1	DB0.0	Slide switch	SLSW	Slide switch or Slide switch	Enum:		
	0/I			Day/Night	0: Position Off	I / Night	/	
					1: Position On	O / Day /	′	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	07	Temperature Sensor, Fan Speed Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:
			210255: Stage Auto			210255: Stage Auto
						190209: Stage 0
						165189: Stage 1
						145164: Stage 2
						0144: Stage 3
8	8	DB2.7DB2.0	Not Used (= 0)			
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550 0+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
					\	0: Teach-in telegram
						1: Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	08	Temperature Sensor, Fan Speed and Occupancy Control

Offset Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	Г

0	8	DB3.7DB3.0	Turn-switch for fan speed	FAN		Enum:							
	1					210255: Stage Auto							
						190209: Stage 0							
						165189: Stage 1							
						145164: Stage 2							
						0144: Stage 3							
8	8	DB2.7DB2.0	Not Used (= 0)	Used (= 0)									
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550 0+40 °C							
24	4	DB0.7DB0.4	Not Used (= 0)										
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:							
						0: Teach-in telegram							
						1: Data telegram							
29	2	DB0.2DB0.1	Not Used (= 0)	•									
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:							
						1: Button released							
						0: Button pressed							

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	09	Temperature Sensor, Fan Speed and Day/Night Co	ntrol

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit			
0	8	DB3.7DB3.0	Turn-switch for fan	FAN		Enum:				
			speed			210255:	Stage Auto			
					190209:	190209: Stage 0				
						165189:	Stage 1			
						145164:	Stage 2			
						0144:	Stage 3			
8	8	DB2.7DB2.0	Not Used (= 0)							
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40 °C			
24	4	DB0.7DB0.4	Not Used (= 0)							
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:				
						0: Teach telegr				
						1: Data t	elegram			
29	2	DB0.2DB0.1	Not Used (= 0)							
31	1	DB0.0	Slide switch 0/I	SLSW	Slide switch or Slide switch	Enum:				
					Day/Night	0: Position	on I / Night /			
						1: Positio	on O / Day /			

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0A	Temperature Sensor, Set Point Adjust and Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit				
0	8	DB3.7DB3.0	Not Used (= 0	Used (= 0)								
8	8	DB2.7DB2.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40) °C				
24	4	DB0.7DB0.4	Not Used (= 0))		_						
			•									

28	1	DB0.3		LRN Bit	LRNB	LRN Bit	Enum:						
							0: Teach-in telegram						
							1: Data telegram						
29	2	DB0.2	.DB0.1	Not Used (= 0	Not Used (= 0)								
31	1	DB0.0		Contact State	CTST	Contact state	Enum: 0: closed						
							1: open						

RORG		A5	4BS	Telegram
FUNC	`	10	Room C	perating Panel
TYPE		0В	emperature Senso	r and Single Input Contact

Offset	Size	Bitrange		Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	No	t Used (= 1	0)					
16	8	DB1.7DB1.0	Te	mperature	TMP	Temperature (linear)	255()	0+40	°C
24	4	DB0.7DB0.4	No	t Used (= (0)					
28	1	DB0.3	LR	N Bit	LRNB	LRN Bit	Enum:			
							0:	Teach-i	n telegra	m
				/			1:	Data te	legram	
29	2	DB0.2DB0.1	No	t Used (=	0)					
31	1	DB0.0	Со	ntact State	CTST	Contact state	Enum:			
							0:	closed		
							1:	open		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0C	Temperature Sensor and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	16	DB3.7DB2.0	Not Used (=	0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C	
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						0: Teach-in telegram			
						1: Data te	elegram		
29	2	DB0.2DB0.1	Not Used (=	0)					
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:			
						1: Button	released		
						0: Button	pressed		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	0D	Temperature Sensor and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Sca	ale	Unit
0	16	DB3.7DB2.0	Not Used (=	t Used (= 0)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+	-40	°C

24	4 DB0.7DB0.4 Not Used (= 0)								
28	1		DB0.3		LRN Bit	LRNB	LRN Bit	Enum	· · · · · · · · · · · · · · · · · · ·
								0:	Teach-in telegram
								1:	Data telegram
29	2		DB0.2	DB0.1	Not Used (=	0)			
31	1		DB0.0		Slide switch		Slide switch 0/I or Slide switch	Enum	:
		V					Day/Night	0:	Position I / Night /
									Off
								1:	Position O / Day /
									On

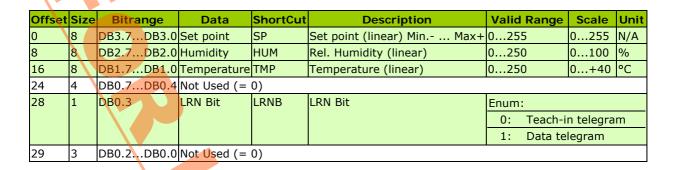
RORG	A5		4BS Telegram
FUNC	10		Room Operating Panel
TYPE	10	Tempera	ture and Humidity Sensor, Set Point and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)		_		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegra legram	m
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum: 1: Button 0: Button	released pressed	<u> </u>

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	11	Temperature and Humidity Sensor, Set Point and Day/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set point	SP	Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ii	n telegran	n
						1: Data tel	egram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Slide switch	SLSW	Slide switch 0/I or Slide switch	Enum:		
					Day/Night	0: Position	I / Night	/
						Off		
						1: Position	O / Day /	/
						On		

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	12	Temperature and Humidity Sensor and Set Point



RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	13	Temperature and Humidity Sensor, Occupancy Con	ıtrol

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
				\1		0: Teach-i	n telegra	m
						1: Data te	legram	
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram	
FUNC	10	Room Operating Panel	
TYPE	14	Temperature and Humidity Sensor, Day	/Night Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	l Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)					
8	8	DB2.7DB2.0	Humidity	HUM	Rel. Humidity (linear)	025	0	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	025	0	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum 0: 1:		n telegran egram	n
29	2	DB0.2DB0.1	Not Used (=	0)					
31	1	DB0.0	Slide switch		Slide switch 0/I or Slide switch Day/Night	0: 1:	Position Off	I / Night	,

RORG	A5	4BS Telegram

FUNC	10	Room Operating Panel
TYPE	15	10 Bit Temperature Sensor, 6 bit Set Point Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)				
8	6	DB2.7DB2.2	Set point		Set point (6 bit, linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		-in telegram elegram	
29	3	DB0.2DB0.0	Not Used (=	0)				

RORG	A5				4BS Telegram
FUNC	10	\			Room Operating Panel
TYPE	16	10 Bit T	emper	ature	Sensor, 6 bit Set Point Control;Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Not Used (=	0)		-	_	
8	6	DB2.7DB2.2	Set point	SP	Set point (linear) Min Max+	063	063	N/A
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.2	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
						1: Data telegram		
29	2	DB0.2DB0.1	Not Used (=	0)				
31	1	DB0.0	Occupancy	occ	Occupancy button	Enum:		
						1: Button	released	
						0: Button	pressed	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	17	10 Bit Temperature Sensor, Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rar	nge Scale	Unit
0	14	DB3.7DB2.2	Not Used (=	0)				
14	10	DB2.1DB1.0	Temperature	TMP	Temperature 10 bit (linear)	10230	-10+41.	2°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ach-in telegram ta telegram	1
29	2	DB0.2DB0.1	Not Used (=	0)		I. Da	ta telegram	
31	1	DB0.0	Occupancy	occ	Occupancy button		tton released	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	18	Illumination, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8	DB2.7DB2.0	Temp Setpoint	TMPSP	Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan Speed	FAN	Fan Speed	1: S 2: S 3: S 4: S 5: S	uto peed 0 peed 1 peed 2 peed 3 peed 4 peed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: D	each-in elegram ata elegram	
29	1	DB0.2	Not Used (= 0)					
30	1		Occupancy enable/disable	OED	Occupancy enable/disable; if occupancy is disabled ignore DB0.0 (occu. button)	1: O	ccupancy nabled ccupancy sabled	
31	1	DB0.0	Occupancy button	ОВ		1: B	utton ressed utton eleased	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	19	Humidity, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Temp Setpoint		Temperature Set point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 2: Speed 3: Speed 4: Speed 5: Speed 6: Speed	1 2 3 4	<u> </u>

						7:	Off	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:	
						0:	Teach-in telegram	
						1:	Data telegram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Occupancy button	ОВ		Enum:		
	`					0:	Button pressed	
						1:	Button released	
31	1	DB0.0	Occupancy	OED		Enum	:	
			enable/disable			0:	Occupancy enabled	
						1:	Occupancy disabled	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1A	Supply voltage monitor, Temperature Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	SV	0 5.0 V linear (super cap); 251-255 reserved for error code	0250	05	V
8	8	DB2.7DB2.0	Temp Setpoint	TMP Sp	Temperature Set Point (linear)	2500	0+40	°C
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25		DB0.6DB0.4		FAN	Fan Speed	2: Sp 3: Sp 4: Sp 5: Sp	eed 0 eed 1 eed 2 eed 3 eed 4 eed 5	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	tel	ach-in egram ta telegra	m
29	1	DB0.2	Not Used (= 0)	•				
30	1		Occupancy enable/disable	OED		en. 1: Oc	cupancy abled cupancy abled	
31	1	DB0.0	Occupancy button	ОВ		pre 1: Bu	tton essed tton eased	

RORG	A5	4BS Telegram		
FUNC	10	Room Operating Panel		

PE 1B

Supply Voltage Monitor, Illumination, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply Voltage	for error code		0250	05	V
8	8	DB2.7DB2.0	Illumination	ILL	Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24		DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum:		
						0: A	uto	
						1: S _I	peed 0	
						2: S _I	peed 1	
						3: S _I	peed 2	
						4: S	peed 3	
						5: S _l	peed 4	
						6: S	peed 5	
						7: O	ff	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							each-in	
						te	legram	
						1: D	ata telegrar	n
29	1	DB0.2	Not Used (= 0)					
30	1		Occupancy	OED		Enum:		
			enable/disable				ccupancy	
							nabled	
							ccupancy	
						di	sabled	
31	1	DB0.0	Occupancy button	ОВ		Enum:		
				\			utton	
							ressed	
							utton	
						re	leased	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1C	Illumination, Illumination Set Point, Temperature Sensor, Fan Speed and Occupancy Control

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination		Illumination (linear), 251: Over range, 252-255: reserved	0250	01000	lx
8	8	DB2.7DB2.0	Illumination Set Point	ILLSP		0250	01000	lx
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN		2: Spe 3: Spe	ed 0 ed 1 ed 2 ed 3	

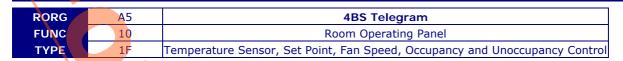
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						6: 7:	Speed 5 Off
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
· ·						1:	Data telegram
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Occupancy	OED		Enum	:
			enable/disable			0:	Occupancy enabled
						1:	Occupancy disabled
31	1	DB0.0	Occupancy button	ОВ		Enum	:
						0:	Button pressed
						1:	Button released

RORG	A5				4BS Telegram
FUNC	10				Room Operating Panel
TYPE	1D	Humidity,	Hun	nidity S	et Point, Temperature Sensor, Fan Speed and Occupancy Contro

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Humidity	HUM	Rel. Humidity (linear)	0250	0100	%
8	8	DB2.7DB2.0	Humidity Set Point	HUMSP	Humidity Set Point (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2500	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	3	DB0.6DB0.4	Fan speed	FAN	Fan Speed	Enum: 0: Auto 1: Speed 0 2: Speed 2 3: Speed 2 4: Speed 3 5: Speed 4 6: Speed 9 7: Off	1 2 3 4	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-i 1: Data te	n telegra legram	m
29	1	DB0.2	Not Used (= 0)	•				
30	1		Occupancy enable/disable	OED		0: Occupa enabled 1: Occupa disabled	ncy	
31	1	DB0.0	Occupancy button	ОВ			pressed released	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	1E	see A5-10-1B



Submitter: Distech Controls

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Turn-switch for fan	FAN	Turn-switch for fan speed	Enum:		
			speed			210255: S	tage auto	0
						190209: S	tage 0	
						165189: S	tage 1	
		\				145164: S	tage 2	
		•				0144: S	tage 3	
8	8	DB2.7DB2.0	Set Point	SP	Set point (linear) Min Max+	0255	0255	N/A
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	2550	0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	1	DB0.6	Temperature flag	TMP_F	Temperature flag	Enum:		
						1: Temper	ature	
						present		
						0: Temper	ature	
						absent		
26	1	DB0.5	Set point flag	SP_F	Set point flag	Enum:		
						-	nt presen	
						0: Set poi	nt absent	Ī
27	1	DB0.4	Fan speed flag	FAN_F	Fan speed flag	Enum:		
							ed prese	
						0: Fan spe	ed abser	nt
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	1	DB0.2	Not Used (= 0)					
30	1	DB0.1	Unoccupancy	UNOCC	Unoccupancy button	Enum:		
						0: Button	pressed	
						1: Button	released	
31	1	DB0.0	Occupancy	OCC	Occupancy button	Enum:		
						0: Button	pressed	
						1: Button	released	_
						0: Button 1: Button Enum: 0: Button	released pressed	d I

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	20	Temperature and Set Point with Special Heating State

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, User Activity.

This EEP defines a Room Operating Panel that contains a sensor for temperature measurement. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication intervall: 1200 s Trigger event: change of any input signal

Tx delay: n/a

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: 4BS teach-in 2 / Universal teach-in

Security Encryption supported: no

Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Vali	d Range	Scale	Unit
0	8	DB3.7DB3.0	Set Point	SP	Set point (linear) Min Max+	0255		0255	N/A
8	8	DB2.7DB2.0	Not Used $(= 0)$)					
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250		0+40	°C
24	1	DB0.7	Not Used (= 0)					
25	2	DB0.6DB0.5		SPM	Selection of heating	Enum:			
			mode		mode		Room tempe SP	erature define	ed by
							Frost protect	tion	
							Automatic co	ontrol (e.g. do	efined
							Reserved	,	
27	1	DB0.4	Battery state	BATT	Battery change needed	Enum:		<u></u>	
						0: E	Battery ok	<u></u>	
						1: i	Battery low		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
			\			0:	Teach-in tele	egram	
						1: [Data telegra	m	
29	2	DB0.2DB0.1	Not Used (= 0)				·	
31	1	DB0.0	User activity	ACT	User intervention action	Enum:			
					on device	0: 1	No user action	on	
						1: l	Jser interact	tion	

RORG	A5	4BS Telegram
FUNC	10	Room Operating Panel
TYPE	21	Temperature, Humidity and Set Point with Special Heating States

Submitter: MSR-Solutions GmbH, Wangen i.Allg.

Description:

Set Point for Heating Control, Temperature, Humidity, User Activity.

This EEP defines a Room Operating Panel that contains sensors for temperature and humidity. The set point selector knob determines the desired room temperature with the ability to set special set point modes for heating control. User activity and the sensor's battery state are indicated in the telegram.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication intervall: 1200 s Trigger event: change of any input signal

Tx delay: n/a

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: 4BS teach-in 2 / Universal teach-in

Security Encryption required: no

Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Set Point		Set point (linear) Min Max+	0255	0255	N/A
8	8	DB2.7DB2.0	Humidity	HUM	Rel. humidity (linear)	0250	0100	%
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0250	0+40	°C
24	1	DB0.7	Not Used (= 0)					

25	2	DB0.6DB0.5	Set point mode	SPM	Selection of heating mode	Enum: 0: Room temperature defined by SP 1: Frost protection
						Automatic control (e.g. defined by time program)
						3: Reserved
27	1	DB0.4	Battery state	BATT	Battery change needed	Enum:
						0: Battery ok
		· ·				1: Battery low
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram
						1: Data telegram
29	2	DB0.2DB0.1	Not Used (= 0))		
31	1	DB0.0	User activity	ACT	User intervention action on	Enum:
					device	0: No user action
						1: User interaction

A5-11: Controller Status

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	01	Lighting Controller

						1	1	
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Illumination	ILL	Illumination (linear)	0255	0510	lx
8	8	DB2.7DB2.0	Illumination Set Point	ISP	Illumination Set Point (Min Max.) (linear)	0255	0255	N/A
16	8	DB1.7DB1.0	Dimming Output Level	DIM	Dimming Output Level (Min Max.) (linear)	0255	0255	N/A
24	1	DB0.7	Repeater	REP	Repeater	Enum:		
						0: disab	led	
						1: enabl	ed	
25	1	DB0.6	Power Relay Timer	PRT	Power Relay Timer	Enum:		
						0: disab	led	
						1: enabl	ed	
26	1	DB0.5	Daylight	DHV	Daylight Harvesting	Enum:		
			Harvesting			0: disab	led	
						1: enabl	ed	
27	1	DB0.4	Dimming	EDIM	Dimming	Enum:		
						0: switc	hing load	1
						1: dimm	ing load	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach	n-in	
						telegi		
						1: Data	telegran	1
29	1	DB0.2	Magnet Contact	MGC	Magnet Contact	Enum:		
						0: open		
						1: close	d	
30	1	DB0.1	Occupancy	occ	Occupancy	Enum:		
						0: unoco	cupied	
						1: occup	oied	
		<u> </u>			·			

31	L	1	DB0.0	Power Relay	PWR	Power Relay	Enum:
		1					0: off
							1: on

RORG	A5	4BS Telegram		
FUNC	11	Controller Status		
TYPE	02	Temperature Controller Output		

Submitter: Thermokon Sensortechnik GmbH

						Valid		
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Control Variable	CVAR	Actual value of controller		0100	%
8	8	DB2.7DB2.0	FanStage	FAN	Actual value of fan	1: Stage 2: Stage 3: Stage	e 0 Manual e 1 Manual e 2 Manual e 3 Manual	
						17: Stage	e 0 Automat e 1 Automat e 2 Automat e 3 Automat vailable	ic ic
16	8	DB1.7DB1.0	Actual Setpoint	ASP	Occupied: Basic setpoint occupied + Setpoint shift + Sensor offset StandBy: Basic setpoint standBy + Setpoint shift Unoccupied: Basic setpoint unoccupied + setpoint shift	0255	0+51.2	°C
24	1	DB0.7	Alarm	ALR	In case of internal error alarm is set	Enum: 0: No ala 1: Alarm		
25	2	DB0.6DB0.5	Controller mode	СТМ	Actual state of controller	Enum: 1: Heatin 2: Coolir 3: Off		
27	1	DB0.4	Controller state	CST	Automatic control, or is controlled from another device	Enum: 0: Auton 1: Overr		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ı-in telegrar telegram	n
29	1	DB0.2	Energy hold-off	ERH	Stop control if window is opened	Enum: 0: Norm 1: Energ	y hold-off/	
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum: 0: Occup 1: Unocc 2: Stand 3: Frost	cupied	

RORG	A5	4BS Telegram
FUNC	11	Controller Status
TYPE	03	Blind Status

Submitter: PEHA / infrated

This controller status is specific for blinds, awning and shutter modules. All modules can use this 4BS telegram to send all information about the status, the position and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Blind/shutter pos.	BSP		0100	0100	%
8	1	DB2.7	Angle sign	AS		Enum:		
						0: Positive sign		
						1: Negative sig	n	
9	7	DB2.6DB2.0	Angle	AN	Angle in 2° steps (e.g. 0 = 0°, 90 = 180°)	0180	0360	0
16	1			PVF		Enum:		
			flag			0: No Position	value availab	le
						1: Position valu	ie available	
17	1		Angle value	AVF		Enum:		
			flag			0: No Angle val	lue available	
						1: Angle value	available	
18	2	DB1.5DB1.4	Error state	ES		Enum:		
						0: No error pre	sent	
						1: End-position configured	s are not	
						2: Internal failu	ıre	
						3: Not used		
20	2	DB1.3DB1.2	End-position	EP		Enum:		
						0: No End-posit	tion available	<u> </u>
						1: No End-posit	tion reached	
						2: Blind fully or	oen	
						3: Blind fully cl	osed	
22	2	DB1.1DB1.0	Status	ST		Enum:		
						0: No Status av	/ailable	
						1: Blind is stop	ped	
						2: Blind opens		
						3: Blind closes		
24	1	DB0.7	Service Mode	SM		Enum:		
						0: Normal mod	e	
						1: Service mod example for		
25	1	DB0.6		MOTP		Enum:		
			position			0: Normal mod		
						0% Blind ful		0%
						Blind fully cl		
						1: Inverse mod 100% Blind		n%
						Blind fully cl		2 70
26	2	DB0.5DB0.4	Not Used (= 0)					
28				LRNB	LRN Bit	Enum:		
						0: Teach-in tele	egram	
						1: Data telegra		
29	3	DB0.2DB0.0	Not Used (= 0)					
	1		. , ,				1	

RORG	A5	4BS Telegram

FUNC	11	Controller Status
TYPE	04	Extended Lighting Status

Submitter: PEHA / infrated

This status is an extended answer of new lighting-controllers. All modules can use this 4BS telegram to send all information about the status and errors of the module, if these data are available.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	8	DB3.7DB3.0	Parameter 1	P1		Enum:
						Mode 0: Dimm-Value (0 255)
						Mode 1: R - Red (0 255)
						Mode 2: Energy metering value (MSB 15 8)
						Mode 3: Not used
8	8	DB2.7DB2.0	Parameter 2	P2		Enum:
		\'				Mode 0: Lamp operating hours (MSB
		\				15 8)
						Mode 1: G - Green (0 255)
						Mode 2: Energy metering value (7 0 LSB)
						Mode 3: Not used
16	8	DB1.7DB1.0	Parameter 3	P3		Enum:
						Mode 0: Lamp operating hours (7 0
						LSB)
						Mode 1: B - Blue (0 255) Mode 2: Unit for energy values:
						Enum:
			\			0 = mW
						1 = W
						2 = kW 3 = MW
						4 = Wh
						5 = kWh
				1		6 = MWh
				\		7 = GWh 8 = mA
						9 = 1/10 A
						10 = mV
						11 = 1/10 V
						12 15 Not used
						Mode 3: Not used
24	1	DB0.7	Service Mode	SM		Enum:
						0: Normal mode
					· ·	1: Service mode is activated.
						(For example for maintenance)
25	1	DB0.6	, ,	OHF	For Mode 0	Enum:
			flag			0: No lamp operating hours available
						1: Lamp operating hours available
26	2	DB0.5DB0.4	Error state	ES		Enum:
						0: No error present
						1: Lamp-failure
						2: Internal failure
20	1	DB0 3	I DNI Dit	LDND	I DN D:+	3: Failure on the external periphery
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
						0: Teach-in telegram 1: Data telegram
29	2	DB0 2 DB0 1	Parameter Mode	PM		
23	2	DD0.2DD0.1	i arameter Mode	1.1.1		Enum: 0: 8 Bit Dimmer Value and Lamp
						operating hours
						1: RGB Value
						2: Energy metering value
						3: Not used

31	1	DB0.0	ST	Enum:	
				0: Lighting off	
				1: Lighting on	

A5-12: Automated Meter Reading (AMR)

The meter reading is represented by 3 data bytes, a divisor and a flag that indicates it as a cumulative or a current value. A 4 bit info field gives additional information and is TYPE specific.

RORG	A5	4BS Telegram			
FUNC	12	Automated Meter Reading (AMR)			
TYPE	00	Counter			
Submitter: Er	Ocean GmbH				

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading	MR	Current value or cumulative counter value	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Measurement channel	СН		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		-in telegram elegram	_
29	1	DB0.2	Data type (unit)		Current value or cumulative counter value		nt value	1 1/s
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for counter value	Enum: 0: x/1 1: x/10 2: x/100 3: x/1000	0167772 0167772 0167772 016777.2	.15

RORG	A5	4BS Telegram		
FUNC	12	Automated Meter Reading (AMR)		
TYPE	01	Electricity		

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	24	DB3.7DB1.0	Meter reading		current value in W or cumulative value in kWh	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		-in telegram elegram	
29	1	DB0.2	Data type (unit)		Current value or cumulative value	0: Cumul	lative value nt value	W

30	2 DB0.1DB0.0		DIV	Divisor for value	Enum	1:		
		(scale)			0:	x/1		
						0	.16777215	
					1:	x/10	_	
						0	.1677721.5	
					2:	x/100		
						0	.167772.15	
					3:	x/1000	_	
						0	.16777.215	

RORG	A5			4BS Telegram
FUNC	12		Automa	ted Meter Reading (AMR)
TYPE	02	1		Gas

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit			
0	24	DB3.7DB1.0	meter reading	MR	Cumulative value in m³ or Current value in liter/s	0167	777215	according to DIV	according to DT			
24	4	DB0.7DB0.4	Tariff info	TI		015		015	1			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:						
						0:	Teach-	in telegram				
						1:	Data to	elegram				
29	1	DB0.2	, ,	DT	Current value or cumulative	Enum:						
			(unit)					value	0:	Cumul	ative value	m³
				/								
				`		1:	Curren	it value	liter/s			
30	2	DB0.1DB0.0		DIV	Divisor for value	Enum:						
			(scale)			0:	x/1					
								0167772	15			
						1:	x/10		_			
								0167772	1.5			
						2:	x/100					
								0167772.	.15			
						3:	x/1000					
								016777.2	!15			

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	03	Water

Submitter: EnOcean GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Rai	nge Scale	Unit
0	24	DB3.7DB1.0	Meter reading		Cumulative value in m ³ or Current value in liter/s	016777	215 according to DIV	according to DT
24	4	DB0.7DB0.4	Tariff info	TI		015	015	1
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		ach-in telegram ta telegram	
29	1		Data type (unit)		Current value or cumulative value	0: Cu	mulative value rrent value	m³ Liter/s

30 2 DB0.1DB0.0 Divisor	DIV	Divisor for value	Enum:
(scale)			0: x/1
			016777215
			1: x/10
			01677721.5
			2: x/100
			0167772.15
			3: x/1000
			016777.215

RORG	A		4BS Telegram
FUNC	12	2/	Automated Meter Reading (AMR)
TYPE	04	1	Temperature and Load Sensor

Submitter: SIMICS, NTT East

Description

Temp and Load Sensor aimed for fridge and other application.

E.g. milk carton puts on this sensor in fridge. The sensor sends a signal of temp and remaining amount of milk (in gram). Since this sensor is battery-powered, battery level information is transmitted with Temp and Load information, too.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -Trigger event: load changed

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: yes

Security level format: RLC + AES128

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	14	DB3.7DB2.2	Meter reading	MR	Current value in gram	016383	016383	gram
14	2	DB2.1DB2.0	Not Used $(= 0)$)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-40+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegra	m
						1: Data t	elegram	
29	1	DB0.2	Not Used (= 0	1)				
30	2	DB0.1DB0.0	Battery Level	BL	Battery level	Enum:		
						0: 100-7	5%	
						1: 75-50	%	
						2: 50-25	2%	
						3: 25-0%		

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	05	Temperature and Container Sensor

Submitter: SIMICS, NTT East

Description

Temp and Container Sensor aimed for fridge and other application.

E.g. eggs or egg carton puts on the Container Sensor in fridge. The sensor sends a signal of temp and remaining of

eggs. Since this sensor is battery-powered, battery level information is transmitted with other information, too.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: -Trigger event: load changed

Tx delay: Rx timeout:

Teach-in

Teach-in method: 4BS teach-in 2

Security
Encryption supported: yes

Security level format: RLC + AES128

Location 0 - 9 are assigned as follows:

o	2	4	6	8
1	3	5	7	9

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	1	DB3.7	Position Sensor 0	PS0	Location 0	Enum:
						0: not possessed
						1: possessed
1	1	DB3.6	Position Sensor 1	PS1	Location 1	Enum:
						0: not possessed
_						1: possessed
2	1	DB3.5	Position Sensor 2	PS2	Location 2	Enum:
						0: not possessed
		552.4	D 0 0	DC2	2	1: possessed
3	1	DB3.4	Position Sensor 3	PS3	Location 3	Enum:
						0: not possessed
4	1	DB3.3	Position Sensor 4	DC4	Location 4	1: possessed
4	1	DB3.3	Position Sensor 4	P34	Location 4	Enum: 0: not possessed
						0: not possessed 1: possessed
5	1	DB3.2	Position Sensor 5	PS5	Location 5	Enum:
	_	553.2	l osition sensor s	1 33	Location 5	0: not possessed
						1: possessed
6	1	DB3.1	Position Sensor 6	PS6	Location 6	Enum:
						0: not possessed
						1: possessed
7	1	DB3.0	Position Sensor 7	PS7	Location 7	Enum:
						0: not possessed
						1: possessed
8	1	DB2.7	Position Sensor 8	PS8	Location 8	Enum:
						0: not possessed
						1: possessed
9	1	DB2.6	Position Sensor 9	PS9	Location 9	Enum:
						0: not possessed
						1: possessed

10	6	DB2.5DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	-40+40 °C
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0: Teach-	in telegram
						1: Data te	elegram
29	1	DB0.2	Not Used (= 0)				
30	2	DB0.1DB0.0	Battery Level	BL	Battery level	Enum:	
						0: 100-75	5%
						1: 75-509	%
						2: 50-25°	/ o
						3: 25-0%	

RORG	A5	4BS Telegram
FUNC	12	Automated Meter Reading (AMR)
TYPE	10	Current meter 16 channels

Submitter: Ewattch

Description

This profile is used for up to 16 channels current meters.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered Communication interval: can be defined by user Trigger event: 10 or 20 % delta for observed value

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

Security

Encryption supported: no Security level format: -

Recommendation

Channels not used should not be transmitted.

Appendix

Our new product is a 12 channels current meter. It is able to measure, using a maximum of 12 current transformers, the current (mA) or cumulative current (mAh) of all of his channels. It is however not sending data for not configured channels (e.g. channels 12 to 15). The meter is sending values every 5 or 10 seconds, and in order to improve accuracy, a current fluctuation of more than 10 or 20 % will trigger a new transmission of the corresponding channel.



0	24	DB3.7DB1.0	Meter reading	MR	Current value in mA or cumulative value in A.h	016777215	according to DIV	according to DT
24	4	DB0.7DB0.4	Measurement channel	СН	Channel no.	015	015	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	-	-in telegram elegram	_
29	1	DB0.2	Data type (unit)	DT	Current value or cumulative value	Enum: 0: Cumul	ative value nt value	A.h mA
30	2	DB0.1DB0.0	Divisor (scale)	DIV	Divisor for value	Enum: 0: x/1 1: x/10 2: x/100 3: x/1000	0167772 0167772 0167772	21.5

A5-13: Environmental Applications

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	01	Weather Station

A receiver that accepts EEP A5-13-01 at teach-in automatically needs to accept telegrams from the same ID that comply to the definitions of EEP A5-13-02 thru EEP A5-13-06. Different telegrams received from that ID need to be distinguished by their 4 bit identifiers.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Dawn sensor	DWS	Dawn sensor	0255	0999	lx
8	8	DB2.7DB2.0	Temperature	TMP	Outdoor Temp	0255	-40+80	°C
16	8	DB1.7DB1.0	Wind speed	WND	Wind speed	0255	070	m/s
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x1:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit		in telegrar elegram	n
29	1	DB0.2	Day / Night	D/N	Day / Night	Enum: 0: Day 1: Night		
30	1	DB0.1	Rain Indication	RAN	Rain Indication	Enum: 0: No Rai 1: Rain	h	
31	1	DB0.0	Not Used (= 0)					

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	02	Sun Intensity

Submitter: Elsner electronics

-											Α.
	Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Sc	ale	Unit	

0	8	DB3.7DB3.0	Sun – West	SNW	Sun - West,linear	0255	0150	klx	
8	8	DB2.7DB2.0	Sun – South	SNS	Sun - South,linear	0255	0150	klx	
16	8	DB1.7DB1.0	Sun – East	SNE	Sun - East,linear	0255	0150	klx	
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum:			
· ·						0x2:			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:			
						_	Teach-in elegram		
							Data elegram		
29	1	DB0.2	Hemisphere	HEM	0 = north $/ 1 = $ south, then swith Sun	Enum:			
					south to Sun North when in southern	0: 1	North		
					hemisphere	1: 5	South		
30	2	DB0.1DB0.0	B0.1DB0.0 Not Used (= 0)						

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	03	Date Exchange

Submitter: Elsner electronics

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Not Used	(= 0)				
3	5	DB3.4DB3.0	Day	DY	Day	131	131	N/A
8	4	DB2.7DB2.4	Not Used	(= 0)				
12	4	DB2.3DB2.0	Month	MTH	Month (1->January)	112	112	N/A
16	1	DB1.7	Not Used	(= 0)				
17	7	DB1.6DB1.0	Year	YR	Year (0->Year 2000)	099	20002099	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x3:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in teleg 1: Data telegram		
29	2	DB0.2DB0.1	Not Used	(= 0)				
31	1	DB0.0	Source	SRC	Source	0: Real Time Clo 1: GPS or equiva	ck llent (e.g. DCF77, W	/WV)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	04	Time and Day Exchange

Submitter: Elsner electronics

Recommendation: always transmit time in 24 hrs format

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	DB3.7DB3.5	Weekday		Weekday (1 -> Monday)	Enum: 1: Monday 2: Tuesday 3: Wednesday 4: Thursday 5: Friday 6: Saturday 7: Sunday		<u>/</u>
3	5	DB3.4DB3.0	Hour	HR	Hour	023	023	N/A

8	2 DB2.7DB2.6 Not Used (= 0)							
10	6	DB2.5DB2.0	Minute	MIN	Minute	059	059	N/A
16	2	DB1.7DB1.6	Not Used (=	: 0)			_	
18	6	DB1.5DB1.0	Second	SEC	Second	059	059	N/A
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x4:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegra 1: Data telegram	ım	
29	1	DB0.2	Time Format	TMF	Time Format	Enum: 0: 24 hours 1: 12 hours		
30	1	DB0.1	AM/PM	A/PM	AM or PM	Enum: 0: AM 1: PM		
31	1	DB0.0	Source	SRC	Source	Enum: 0: Real Time Clock 1: GPS or equivalent WWV)		77,

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	05	Direction Exchange

Offset	Size	Bitrange	Data	ShortCut	Description Valid Range Scale	Unit
0	8	DB3.7DB3.0	Elevation	ELV	Elevation (0° -> horizon) 0180 -90+90	0
8	7	DB2.7DB2.1	Not Used	(= 0)		
15	9	DB2.0DB1.0	Azimut	AZM	Azimuth (0° -> True north; clockwise) 0359 0359	0
24	4	DB0.7DB0.4	Identifier	ID	Identifier Enum:	
					0x5:	
28	1	DB0.3	LRN Bit	LRNB	LRN Bit Enum:	
					0: Teach-in telegrar	n
					1: Data telegram	
29	3	DB0.2DB0.0	Not Used	(= 0)		

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	06	Geographic Position Exchange

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	DB3.7DB3.4	Latitude(MSB)	LAT(MSB)	Latitude MSB	according to LAT(LSB)	according to LAT(LSB)	according to LAT(LSB)
4	4	DB3.3DB3.0	Longitude(MSB)			according to LOT(LSB)	according to LOT(LSB)	according to LOT(LSB)
8	8	DB2.7DB2.0	Latitude(LSB)	LAT(LSB)	Latitude LSB	04095	-90+90	0
16	8	DB1.7DB1.0	Longitude(LSB)	` ,	Longitude LSB	04095	-180+180	0
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x6:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele	telegram egram	

29 3 DB0.2...DB0.0 Not Used (= 0)

RORG	A5	4BS Telegram
FUNC	13	Environmental Applications
TYPE	10	Sun position and radiation

Submitter: NanoSense

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	DB3.7DB3.1	Sun Elevation		Sun Elevation (linear); 91 - 127: reserved	090	090	o
7	1	DB3.0	Day / Night	D/N	Day / Night	Enum:	_	
						0: Day	_	
						1: Night		
8	8	DB2.7DB2.0	Sun Azimuth		Sun Azimuth 181 - 255: reserved	0180	-90+90	o
16	8		Solar Radiation (MSB)			according to SRA (LSB)	according to SRA (LSB)	according to SRA (LSB)
24	4	DB0.7DB0.4	Identifier	ID	Identifier	Enum: 0x7:		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-ir	n telegram	
						1: Data tel	egram	
29	3	DB0.2DB0.0		SRA (LSB)	Solar Radiation (LSB) (Linear); 20012048: reserved	02000	02000	W/m2

A5-14: Multi-Func Sensor

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	01	Single Input Contact (Window/Door), Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		
29	2	DB0.2DB0.1	Not Used (= 0))				
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact closed 0b1: Contact open		

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	02	Single Input Contact (Window/Door), Supply voltage monitor and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Biţ	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram		
29	2	DB0.2DB0.1	Not Used $(= 0)$					
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contac 0b1: Contac		<u> </u>

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	03	Single Input Contact (Window/Door), Supply voltage monitor and Vibration

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm , Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error	0250	05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele		1
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Vibration	VIB		No vibrat 0b0: detected Vibration 0b1:		d
31	1	DB0.0	Contact	СТ		Enum: 0b0: Contact o 0b1: Contact o		-

RORG	A5	4BS Telegram	
FUNC	14	Multi-Func Sensor	
TYPE	04	Single Input Contact (Window/Door), Supply voltage monitor, Vibratio	n and Illumination

Submitter: Lutuo Technology

Purpose (eg): Ventilation, Lighting, Alarm , Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 – 255 reserved for error code	0250	05.0	V
8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx
16	12	DB1.7DB0.4	Not Used (= 0))				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in telegram		
		V				1: Data te	legram	
29	1	DB0.2	Not Used (= 0))				
30	1	DB0.1	Vibration	VIB		Enum:		
						No vibration 0b0: detected		
							n detected	<u></u>
						0b1:		
31	1	DB0.0	Contact	СТ		Enum:		
						0b0: Contact closed		
						0b1: Contact	open	

RORG	A5	4B\$ Telegram
FUNC	14	Multi-Func Sensor
TYPE	05	Vibration/Tilt, Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Supply voltage		Supply voltage / super cap. (linear); 251 - 255 reserved for error code		05.0	V
8	20	DB2.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in 1: Data tele		<u>1</u>
29	1	DB0.2	Not Used (= 0)				
30	1	DB0.1	Vibration	VIB		No vibration Ob0: detected Vibration Ob1:		d
31	1	DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	14	Multi-Func Sensor
TYPE	06	Vibration/Tilt, Illumination and Supply voltage monitor

Submitter: Lutuo Technology

Purpose (eg): Intrusion (breakage of glass), Calling system

	Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scal	e /	Unit
ĺ	0	8	DB3.7DB3.0	Supply	SVC	Supply voltage / super cap.	0250	05.0		V
				voltage		(linear);				
Į						251 – 255 reserved for error code				
					,	,				

8	8	DB2.7DB2.0	Illumination		Illumination (linear); 251 – over range, 252 - 255 reserved	0250	01000	lx				
16	12	DB1.7DB0.4	DB1.7DB0.4 Not Used (= 0)									
28	1	DB0.3	LRN Bit	N Bit								
29	1	DB0.2	Not Used (= 0)		•						
30	1	DB0.1	Vibration	VIB		No vibion obo: detected Vibration ob1:		d				
31	1	DB0.0	Not Used (= 0)		•						

A5-20: HVAC Components

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	01	Battery Powered Actuator (BI-DIR)

Submitter: Kieback + Peter GmbH

DIRECTION-1 = Transmit mode: Message from the actuator to the controller DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Current Value	CV	Current value	0100	0100	%
8	1	DB2.7	Service On	SO	Service On	Enum:	<u></u>	
						1: on		
9	1	DB2.6	Energy input enabled	ENIE	Energy input enabled	Enum:		
						1: true)	
10	1	DB2.5	Energy Storage	ES	Energy storage sufficiently	Enum:		
					charged	1: true	2	
11	1	DB2.4	Battery capacity	BCAP	Battery capacity; change	Enum:		
					battery next days	0: true	<u> </u>	
12	1	DB2.3	Contact, cover open	ССО	Contact, cover open	Enum:		
						1: true	•	
13	1	DB2.2	Failure temperature	FTS	Failure Temperature	Enum:		
			sensor, out off range		sensor, out off range	1: true		
14	1	DB2.1	Detection, window open	DWO	Detection, window open	Enum:		
						1: true	<u> </u>	
15	1	DB2.0	Actuator obstructed	ACO	Actuator obstructed	Enum:		
						1: true		
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+40	°C
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							ch-in	
							gram	
						1: Data	a telegra	m
29	3	DB0.2DB0.0	Not Used (= 0)					

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit	

		-		ı	1		1	
8	8	DB3.7DB3.0	or Temperature Setpoint	SP	Valve position or Temperature set point (linear); selection with DB1.2 Valve position 0100% in combination with compatible classic controllers the actuator used DB_3; Temperature set point: The actuator can be used as self-sufficient room controller (pi controller) without integration in automation systems. Wherever the user wants room conditions to be individually controlled, the actuator can work in combination with a wireless room device (RCU). Temperature actual from RCU = 0b0 (Room controller-unit), see DB1.0	0100 or 255	0100 or +40	% or °C
					Maintenance mode ('service on'): DB_2.BIT_5: energy memory sufficiently charged =1 DB_2.BIT_4: battery capacity changing battery in the next days, need changing batteries = 0 Status feedback signal (service on, DB_2.BIT_7			
16	1	DB1.7	Run init sequence	RIN	The limit switching measures the travel and signals when an end position has been reached. This end position (valve zero point) in the actuator is stored.	Enum: 1: tru	ie	
17	1	DB1.6	Lift set	LFS	Initialization, adjustment to the valve stroke. The Initialization is switched after receiving the command. The valve is completely opened and closed during initialization.	Enum: 1: tru	ie	
18	1	DB1.5	Valve open / maintenance	VO	After receiving an operation command, the actuator moves the valve in direction open or close. when reaching the end position, an automatic switch-off procedure is started. In service mode the valve can be set to open or closed always.	Enum: 1: tru	ue	
19	1	DB1.4	Valve closed	VC	valve closed	Enum: 1: tru	ıe	
20	1	DB1.3	Summer bit, Reduction of energy consumption	SB	The radio communication between the actuator and the controller is restricted, sleep mode is extended. This functionality can be used for battery powered actuators.	Enum: 1: tru		
21	1	DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	1: Te po	lve position -100%). Un spond to ntroller. mperature int 040°C it respond to om sensor a e internal P	set C. to
22	1	DB1.1	Set point inverse	SPN	Valve set point can be sent to the actuator normal or inverted. The selection is done by DB_1.Bit1. The implementation is done and is controlled in the actuator with DB_3. This function is used in	Enum: 1: tru	re	

23	1	DB1.0	Select function	RCU	dependence on the type of valve. RCU or 'Service on': After transmitting the command to the actuator, it can be send from the controller or a service device, the actuator sends a status feedback signal (service on, DB_2.BIT_7).	Enum: 0: 1:	RCUservice on
24	4	DB0.7DB0.4	Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	0: 1:	Teach-in telegram Data telegram
29	3	DB0.2DB0.0	Not Used (= 0)				

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	02	Basic Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

Basic Actuator can be used by any manufacturer for linear or rotary actuator.

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator. To use with a BAS/Gateway system;

max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual Value		Actual value (linear); can be a linear or rotation motion.	0100	0100	%
8	14	DB2.7DB1.2	Not Used	(= 0)				
22	1	DB1.1	Set point inverse		Set point inverse (Needs to be defined by manufacturer what zero(0) is equal to, and one(1) is equal to. Default state to be define as per product manufacturer	Enum: 1: tr	ue	
24	4	DB0.7DB0.4	Not Used	(= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1: D	each-in elegram ata elegram	
29	3	DB0.2DB0.0	Not Used	(= 0)				
DIRECT	ΓΙΟΝ-	2						

Offset	Size	Bitrange	Data	ShortCut	Description		Valid Range	Scale	Unit
0	8		Valve Set point	VSP	Valve set Point (linear)		0100	0100	%
8	8	DB2.7DB2.0	Not Used	d (= 0)					
16	6	DB1.7DB1.2	Not Used	d (= 0)					
22	1		Set point inverse		'Set point inverse' needs to be defin manufacturer what zero(0) is equal one(1) is equal to. Default state to per product manufacturer. It can se command to invert functionality of t some instance some equipment mig 100% to represent fully extracted, i retracted.	to, and be define as and a the unit. In and need	Enum; 1: tr	rue	
23	5	DB1.0DB0.4	Not Used	d (= 0)		·			

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used	d (= 0)			

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	03	Line powered Actuator (BI-DIR)

Submitter: Spartan Peripheral Devices

DIRECTION-1 = Transmit mode: Message from the actuator to the controller.

DIRECTION-2 = Receive mode: Commands from the controller to the actuator; max. reponse time 1 sec.

DIRECTION-1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Actual valve	AV	Actual valve	0100	0100	%
8	8	DB2.7DB2.0	Not Used (=	0)				
16	8	DB1.7DB1.0	Temperature	TMP	Temperature (linear)	0255	0+40	°C
24	4	DB0.7DB0.4	Not Used (=	0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-i	n telegra	m
						1: Data te	legram	
29	3	DB0.2DB0.0	Not Used (=	0)				

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8		Actuator or Temperature Setpoint	ATS		0100 or 255	0100 or +40	% or °C
8	8	DB2.7DB2.0	Temperature from RCU	TMPRC	Temperature actual from RCU = 0b0 (Room controller-unit)	2550	0+40	°C
16	5	DB1.7DB1.3	Not Used (= 0)				
21	1	DB1.2	Set Point Selection	SPS	Set Point Selection for DB3	(0-res con 1: Ter Set 0 res sen	uator Setpo 100%); Un pond to troller. nperature point +40°C; Un pond to roo sor and us ernal PI loo	it nit om e
22	1	DB1.1	Set Point Inverse		Valve set point can be sent to the actuator normal or inverted through BAS/Gateway controller. The selection is done by DB_1.Bit1. in the actuator with DB_3. This function is used in dependence on the type of valve.	Enum: 1: tru		
23	5	DB1.0DB0.4	Not Used (= 0)				
			•					

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	
						0:	Teach-in
							telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used (= 0))			

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	04	Heating Radiator Valve Actuating Drive with Feed and Room Temperature Measurement, Local Set Point Control and Display (BI-DIR)

Submitter: Holter Regelarmaturen GmbH & Co. KG

Description

The following document describes the communication between a controller and an intelligent heating radiator valve actuating drive with the following features:

- Feed temperature measurement
- Room temperature measurement
- Current position feedback
- Display
- Button
- On device temperature set point selection

In order to be able to process this information and control the actuator, every command has been included in this document. Each customer can use his own controller by implementing the EEP of this document.

Data exchange

Direction: bidirectional Addressing: unicast (ADT)

Communication trigger: event- & time-triggered

Communication interval: can be configured by the controller

Trigger event: a trigger event occurs when the button is pressed or the local set point is used

Tx delay: 550 ms is the maximum response time for Smart-Ack Devices and 1100 ms for devices which use the 4BS

teach-in method

Rx timeout: just 1 message per wake-up cycle

Teach-in

Teach-in method: Smart-Ack teach-in and 4BS teach-in Variation 3

Security

Encryption supported: no Security level format: -

Telegram Description of Direction 1 (Transmit mode / Message from the actuator to the controller)

This direction initializes the communication, shares the needed data and waits for an answer from the controller. This allows the device to work in deep sleep mode the rest of the time.

Each message from the actuator contains the following information:

• Current Position (CP)

The current position is a feedback value from the actuator. It indicates the actual per cent position of the valve. The value 0 % means that the valve is completely closed and 100 % completely open. The controller can use this information for the room temperature regulation.

- Temperature Set Point OR Feed Temperature (FTS)*
 - * This byte is shared by the Temperature Set Point and the Feed Temperature value. Only one of these values is sent in the same message. Which value is transmitted is indicated by DB0.1 (TS bit).

The feed temperature is the water temperature in the radiator input, which can be useful for implementing several features in the home automation system.

The temperature set point is only sent when the user specifies a new room temperature by using the local temperature set point on the device.

- Room Temperature (TMP) OR Failure Code (FC)*
- * This byte is shared by the Room Temperature and Failure Code Value. Only one of these values is sent in the same message. The value transmitted is indicated by DB0.0 (FL). By default it is the room temperature. The room temperature is the ambient temperature of the place in which the device is used and is measured by the actuator. This value is transmitted if no error occurred.

The Failure Code is transmitted instead of the Room Temperature if an error occurs.

Measurement Status (MST)

The temperature measurements (room and feed temperature) can be deactivated in order to reduce the energy consumption. This can be specified only by the controller i.e. to implement summer mode or to replace the internal room temperature measurement of the actuator by an external one.

Status Request (SRT)

The status request bit can be used to ask the controller about its status. If the controller does not send back the correct reply, the actuator will start its own room temperature regulation. With this feature, a frozen actuator would not interrupt the room temperature regulation.

• Teach-in Bit (LRNB)

For establishing the radio link between the controller and the actuator, a teachin message has to be sent from the actuator to the controller. If the binary value 0 is transmitted, the message will be identified as a teach-in one and will allow the controller to receive the EnOcean-ID of the actuator.

• Button Lock Status (BLS)

The button lock status can be set by the controller. This enables or disables the manual room temperature selection. If locked, the manual room temperature selection on the actuator will be disabled and the user will be notified with a symbol on the display.

• Temperature Selection (TS)

If the user specifies a temperature set point manually on the device, this will be sent to the controller and indicated on the temperature selection field (TS). It can indicate that the field FTS contains the temperature set point (binary value = 1) or the feed temperature (binary value = 0).

• Failure (FL)

Indicates the occurrence of a failure. The room temperature value is replaced by the failure code if the bit FL has the binary value 1.

Telegram Description of Direction 2 (Receive mode / Commands from the controller to the actuator)

The messages from the controller to the actuator are sent in this direction. A message in this direction has to be sent after receiving a message from the actuator, in order to achieve a successful communication. If the controller message is not received by the actuator in a specific time after a direction 1 message, no information will be received by the actuator. The time that the actuator will wait for a reply is defined by the Smart-Ack Teach-In process. For controllers which cannot use Smart-Ack, the 4BS Teach-in Variation 3 has to be used, with a maximum response time of 1100 ms.

Each message from the controller contains the following information:

• Valve Position (POS)

The valve position is a set point position for the valve. It indicates the per cent position of the valve, which the actuator has to reach. The value 0 % means that the valve is completely closed and 100 % completely open. The controller should be able to regulate the room temperature by adjusting this value.

• Temperature Set Point (TSP)

The controller can send the temperature set point to the actuator in order to allow the user to see the actual specified temperature in the device display. This value does not affect room temperature regulation.

• Measurement Control (MC)

The temperature measurements (room and feed temperature) can be deactivated in order to reduce energy consumption. This can be specified only by the controller i.e. to implement summer mode or to replace the internal room temperature measurement by the device with an external one. The measurement control bit enables the controller to activate or deactivate the measurements.

• Wake-up Cycle (WUC)

To save energy, the actuator works in deep sleep mode the most of the time. Nevertheless it has to wake up to communicate with the controller and to reach the valve position specified by the controller. The longer the actuator remains in deep sleep mode, the more energy efficient will be your batteries. If fast response is required, the actuator has to communicate more frequently with the controller and that is why it should use a shorter wake-up cycle. If a fast room temperature control is not required, the wake-up cycle should be set by the controller as long as possible.

• Display Orientation (DSO)

The heater valves can be installed in different directions. That is why it can be useful to have the option to choose the fitting display orientation. This feature makes reading the display easier.

Teach-in Bit (LRNB)

For establishing a radio link between the controller and the actuator, a teach-in telegram has to be sent from the controller to the actuator. If the binary value 0 is transmitted, the message will be identified as a teach-in one and will allow the device to receive the EnOcean-ID from the controller.

Button Lock Control (BLS)

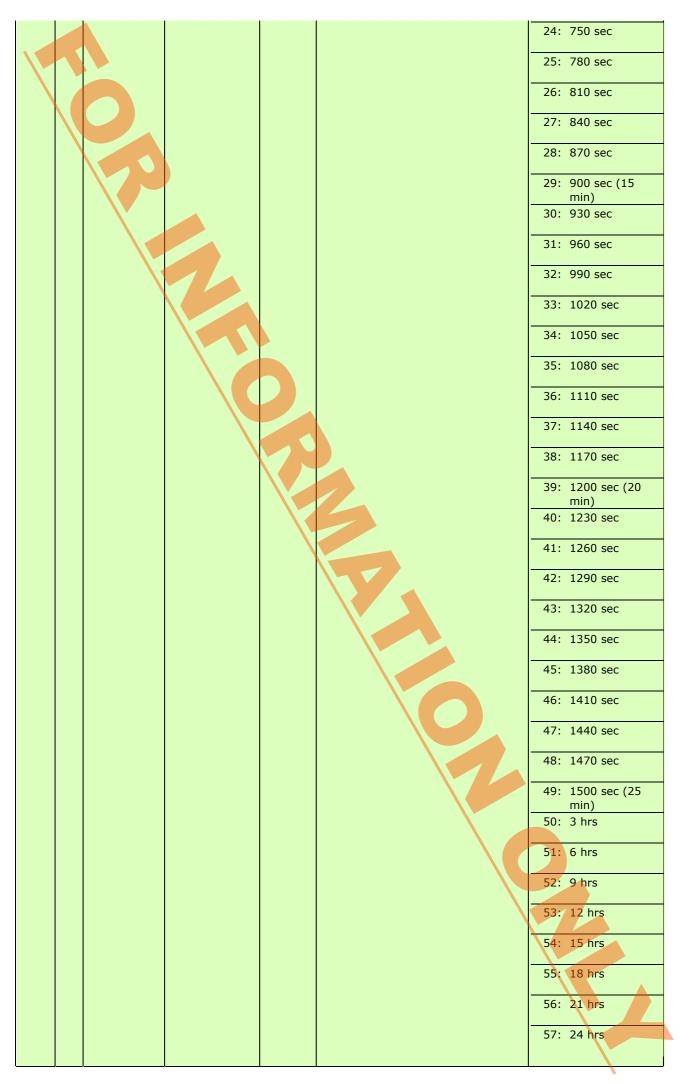
The button lock status can be set by the controller. This enables or disables the manual room temperature selection. If locked, the manual room temperature selection on the actuator will be disabled and the user will be notified with a symbol on the display.

- Service Command (SER)
 - In order to adapt the actuator to a new valve, the controller can order the execution of some functions of the actuator:
 - run initialisation: This function has to be executed for adapting the actuator to the length of the valve stroke.
 - open valve: To facilitate the installation or maintenance of the valve, the actuator can open the valve completely. After completely opening the valve it is necessary to run the initialisation.
 - close valve: Completely close the valve.

DIREC						Valid		
Offset	Size	Bitrange	Data	ShortCut	Description	Range	Scale	Unit
0	8	DB3.7DB3.0	Current Position	СР	Current valve position	0100	0100	%
8		DB2.7DB2.0	Temperature OR Temperature Set Point	FTS	Either current feed temperature value or temperature set point (defined by DB0.1)	0255	20 80 cf ⁻ %\$ ⁻ "" ⁻ 30	°C
16	8	DB1.7DB1.0	Room Temperature OR Failure Code	TMPFC	Current room temperature value (1030°C) OR Failure Code (Enum)	erro 18: Batt 19: Res 20: Fros prot 21 Res 32: 33: Bloc 34 Res 35: 36: End	surement or eery empty erved	80 °C
						37 Res 39: 40: No v 41 Res 48: 49: Not 50 Res 52: 53: No r fron		
24		DB0.7	Measurement Status		Shows if the temperature measurement (feed temperature and room temperature) is active	0: Active 1: Inactive		
25	1	DB0.6	Status Request		Request for status from the controller	Enum: 0: No cha	ange requested	
26	2	DB0.5DB0.4	Not Used (= 0)					
28		DB0.3	LRN Bit	LRNB	LRN Bit	1: Data t	-in telegram relegram	
29		DB0.2	Button Lock Status		Shows if all buttons on the actuator are locked	Enum: 0: Unlock 1: Locked		
30	1	DB0.1	Temperature Selection		Defines which temperature value is transmitted in DB2	Enum: 0: Feed t	emperature	

				1: Temperature set point
31	1 DB0.0	Failure	•	Enum:
			DB1.7-DB1.0 for Failure Code	0: No failure (TMP is transmitted)
				1: failure (FC is transmitted)

DIREC	RECTION-2											
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit				
)	8	DB3.7DB3.0	Valve Position	POS	Valve position	0100	0100	%				
3	8		Temperature Set		Temperature set point	0255	1030					
6	1	DB1.7	Not Used (= 0)									
7	1	DB1.6		MC	Control the temperature	Enum:						
		\	Control		measurement (feed temperature + room temperature)		able					
0		DD1 5 DD1 0	0.1	W///C			able					
8	6	DR1.2DR1.0	Wake-up Cycle	WUC	Defines the cyclic wake-up time	0: 10	sec					
							sec					
						2: 90 sec						
) sec					
						4: 150) sec					
						5: 180) sec					
						6: 210) sec					
) sec					
) sec					
						9: 300 mir 10: 330						
										11: 360		
								12: 390 sec				
						13: 420) sec					
						14: 450) sec					
						15: 480) sec					
						16: 510) sec					
						17: 540						
						18: 570						
						19: 600 mir 20: 630						
						21: 660						
						22: 69(\				
						23: 720	sec	7				



						58: 27 hrs 59: 30 hrs 60: 33 hrs 61: 36 hrs 62: 39 hrs 63: 42 hrs (max)
24	2	DB0.7DB0.6	Not Used (= 0)			1
26	2	DB0.5DB0.4		DSO	Adjusts the display orientation	Enum: 0: 0° 1: 90° 2: 180° 3: 270°
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	1	DB0.2	Button Lock Control	BLC	Set the button lock status	Enum: 0: Unlocked 1: Locked
30	2	DB0.1DB0.0	Service Command	SER	Initiates certain temporary service operations	Enum: 0: No change 1: Open valve 2: Run initialisation 3: Close valve

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	10	Generic HVAC Interface (BI-DIR)

Submitter: Intesis Software SL

Functions: Mode, Vane Position, Fan Speed, Sensors and On/Off: With this EEP plus the already existing EEP A5-10-03 and A5-20-11 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

C	ffset	Size	Bitrange	Data	ShortCut	Description	Valid Ran	ge Scale	Unit
O		8	DB3.7DB3.0	Mode		The modes are the same as in KNX and LON allowing a more transparent integration with this protocols and it has plenty of free positions for future expansion	1: H 2: M 3: C	eat orning 'armup pool ight Purge	

					5:	Precool
					6:	Off
					7:	Test
					8:	Emergency Heat
					9:	Fan only
					10:	Free cool
					11:	Ice
					12:	Max heat
		\			13:	Economic heat/cool
		· ·			14:	Dehumidification
					15:	(dry) Calibration
					16:	Emergency cool
					17:	Emergency
					18:	steam max cool
					19:	Hvc load
					20:	no load
					2130	reserved .
					31:	Auto Heat
					32:	Auto Cool
					3325	reserved
					255:	
8	4	DB2.7DB2.4	Vane	VPS	Enum:	
			position		0:	Auto
					1:	Horizontal
					2:	Pos2
					3:	Pos3
					4:	Pos4
					5:	Vertical
					6:	Swing
					710:	Reserved
					11:	Vertical swing
					12:	Horizontal swing
					13:	Horizontal and vertical swing
					14:	Stop swing

						15:	N/A		
12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1 is the lowest fan speed allowed by the AC and from there it increments with the value of this variable. Typically AC units have up to 5-6 speeds. Any speed higher than the maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A	114: 15:	Auto Up to 1 speeds lowest N/A	4 fan being 1	the
16	8	DB1.7DB1.0	Control variable	CVAR	Control variable; value 255 = auto	0100), 255	0100	%
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: 1:	Teach-ir Data tel	n telegrar egram	n
29	2	DB0.2DB0.1	Room	RO	The interfaces can automatically control the behaviour of the AC without integration in automation systems when linked to presence/movement sensors.	1: 2: 3:	perform Unoccup perform	(waiting action) bied (action) ed)	on
31	1	DB0.0	On/Off	OVI	On/Off	0: 1:		unit is no	ot

Size	Bitrange						
		Data	ShortCut		Valid I	Range	Scale Un
8	DB3.7DB3.0	Mode		and LON allowing a more transparent integration with this protocols and it	Enum: 0:	Auto	
					1:	Heat	
					2:	Morni	ng Warmup
					3:	Cool	
					4:	Night	Purge
					5:	Preco	ol
					6:	Off	
					7:	Test	
					8:	Emer	gency Heat
					9:	Fan o	nly
					10:	Free	cool
					11:	Ice	
					12:	Max h	eat
					13:		
					14:	Dehui (dry)	nidification
					15:	Calibr	ation
					and LON allowing a more transparent integration with this protocols and it has plenty of free positions for future expansion	and LON allowing a more transparent integration with this protocols and it has plenty of free positions for future expansion 2: 3: 4: 5: 6: 7: 8: 9: 10: 11: 12: 13: 14:	and LON allowing a more transparent integration with this protocols and it has plenty of free positions for future expansion 1: Heat 2: Mornii 3: Cool 4: Night 5: Precoi 6: Off 7: Test 8: Emerging 9: Fan off 10: Free off 11: Ice 12: Max has been to be a feat of the content of th

						16:	Emergency cool
	1					17:	Emergency steam
						18:	max cool
	\setminus					19:	Hvc load
	\					20:	no load
						2130:	reserved
						31:	Auto Heat
						32:	Auto Cool
		\				33254	reserved
						255:	N/A
						-	,
8	4	DB2.7DB2.4	Vane position	VPS		Enum:	
			position			0: <i>A</i>	Auto
						1: I	Horizontal
			· ·			2: [Pos2
						3: F	Pos3
						4: [Pos4
						5: \	/ertical
						6: 5	Swing
						710:	Reserved
							/ertical swing
						12: H	Horizontal swing
							Horizontal and Vertical swing
							Stop swing
						15: 1	N/A
						15. 1	47.1
12	4	DB2.3DB2.0	Fan Speed	FANSP	fan speed value goes from 1 to 14. 1 is the lowest fan speed allowed by	Enum:	\ .
					the AC and from there it increments	0: A	Auto
					with the value of this variable. Typically AC units have up to 5-6		Jp to 14 fan speeds
					speeds. Any speed higher than the	114: t	peing 1 the lowest
					maximum the AC allows would set it to the higher speed. 0 is auto and 15 is N/A		
16	8	DB1.7DB1.0	Control variable	CVAR	is N/A Control variable (linear); value 255 = auto	0100,	255 0100 %
24	4	DB0.7DB0.4		= 0)	June		
28	1	DB0.3		LRNB	LRN Bit	Enum; 0: Te	each-in telegram
							ata telegram
29	2	DB0.2DB0.1	Room occupancy	RO	Room occupancy	Enum:	
			оссирансу				ccupied
							candBy (waiting to erform action)

						2:	Unoccupied (action performed)
						3:	Off (no occupancy and no action)
31	1	DB0.0	On/Off	O/I	On/Off	Enum	:
						0:	off
						1:	on

RORG	A5	4BS Telegram
FUNC	20	HVAC Components
TYPE	11	Generic HVAC Interface – Error Control (BI-DIR)

Submitter: Intesis Software SL

Error Control: AC Error Code, Error States and Disablements. With this EEP plus the already existing EEP A5-10-03 and A5-20-10 all the information of AC indoor unit can be sent and received allowing a much easier and complete control of these units.

DIRECTION-1 = Receive mode: Commands received by the HVAC interface. DIRECTION-2 = Transmit mode: Commands sent by the HVAC interface.

DIRECTION-1

DIKECI	ION-	1						
Offset	Size	Bitrange	Data	ShortCut	Description	Vali Ran	Scale	Unit
0	23	DB3.7DB1.1	Not Used (= 0)					
23	1	DB1.0	External disablement	EXDS	External disablement	Enum: 0: 1:	Not disable Disabled	d
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1 DB0.3 LRN Bit LRNB		LRN Bit	Enum:				
				0:	Teach-in telegram			
					1:	Data telegram		
29	1	DB0.2		DRC	Disable remote controller	Enum:		
			controller		(When in receive mode it controls if the interface overwrites the remote	0:	Enable Rem controller	note
				controller commands.)	1:	Disable Remote controller		
30	1	DB0.1	Window contact	WC	Window contact	Enum:		
						0:	Windows opened	
						1:	Windows closed	
31	1	DB0.0	Not Used (= 0)					

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range S	cale	Unit
0	16	DB3.7DB2.0	Error Code		Error Code (DB3 HI,DB2 LO); generated by A.C.	065535 0	65535	N/A
16	4	DB1.7DB1.4	Reserved	RES	Reserved (0b0000)	Enum: : Reserve	ed	
20	1		Other disablement		Manufacturer defined. It is just to provide an extra "disablement signal" that could be used for other devices. People would not have to change anything then as this is already an established "signal"	Enum: 0: Not disa 1: Disable		
21	1		Window contact disablement	WCD	Window contact disablement	Enum: 0: Not disa	abled	

						1:	Disabled
22	1	DB1.1	Key card disablement	KCD	Key carddisablement	Enum 0:	
						1:	Disabled
23	1	DB1.0	External	ED	External disablement	Enum	
·			disablement			0:	Not disabled
						1:	Disabled
24	4	DB0.7DB0.4	Not Used (= 0)			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	
			0:	Teach-in telegram			
						1:	Data telegram
29	1	DB0.2	Remote	RCD	Remote controller Disablement	Enum	
	controller Disablement			(In transmit it sends the status of this parameter. If the manufacturer doesn't support this option, it will		Remote controller enabled	
					send allways 0, no matter what it receives.)	1:	Remote controller disabled
30	1	DB0.1	Window	WC	Window contact	Enum	
			contact			0:	Windows opened
						1:	Windows closed
31	1	DB0.0	Alarm State	AS	Alarm State	Enum	
						0:	Ok
						1:	Error

RORG	A5	4BS Telegram	
FUNC	20	HVAC Components	
TYPE 12 Temperature Controll		Temperature Controller I	input

Submitter: Thermokon Sensortechnik GmbH

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Control Variable override	CV	Actual value for controller	0255	0100	%
8	8	DB2.7DB2.0	FanStage override	FANOR	FanStage override	Enum:		
						0: Stage 0		
						1: Stage 1	<u> </u>	
						2: Stage 2	<u> </u>	
						3: Stage 3	3	
						31: auto		
						255: not ava	ilable	
16	8	DB1.7DB1.0	Setpoint shift	SPS	Actual set point could be shifted	0255	-10+10	°K
24	1	DB0.7	Fan override	FANOR	· ·	Enum:		
						0: Automa	itic	
						1: Overrid	e Fan DB2	
25	2	DB0.6DB0.5	Controller mode	СТМ		Enum:		
						0: Auto m	ode	
						1: Heating		
						2: Cooling		
						3: Off		
27	1	DB0.4	Controller state	CST	Controller state	Enum:		
						0: Automa	itic	
							e control	
						variable	e DB3	

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:
	1					0: Teach-in telegram
						1: Data telegram
29	1	DB0.2	Energy hold-off /	ERH	Energy hold-off / Dew	Enum:
,			Dew point		point	0: Normal
						1: Energy hold-off/ Dew point
30	2	DB0.1DB0.0	Room occupancy	RO	Actual room occupancy	Enum:
						0: Occupied
						1: Unoccupied
						2: StandBy
						3: Frost

A5-30: Digital Input

RORG	A5		4BS Tele	egram
FUNC	30		Digital 1	nput
TYPE	01	Single	Input Contac	, Battery Monitor

Offset	Size	Bitrange	Data	ShortCut	Descrip	tion	Valid Rand	ne Scale	Unit
0			Not Used (= 0)		Descrip		vana Kang	ge Scale	Oint
8	8	DB2.7DB2.0	Supply voltage	SVC	Supply voltag	ge (linear) <u>l</u> -	0120:	Battery LOV Battery OK	V
16	8	DB1.7DB1.0	Input State	IPS	Input State	<u> </u>		Contact clos	
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit			-in telegram telegram	<u> </u>
29	3	DB0.2DB0.0	Not Used (= 0)						

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	02	Single Input Contact

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale I	Unit
0	28	DB3.7DB0.4	Not Used (=	= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegran	n
						1: Data tele	egram	
29	2	DB0.2DB0.1	Not Used (=	= 0)				
31	1	DB0.0	Input State	IPS	Input State	Enum:		
						0: Contact	closed	
						1: Contact	open	

RORG	A5	4BS Telegram
FUNC	30	Digital Input

TYPE 03 4 Digital Inputs, Wake and Temperature

Submitter: Afriso / EnOcean

Description:

This is used for universal modules with 4 digital inputs and a room temperature. The wake input signal of the device is provided to show the telegram transmission trigger. The application meaning and exact data interpretation of the digital channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered Trigger event: wake event – application dependent

Teach-in method: 4BS teach-in 2

Appendix:

D1.4 – The Status of Wake signalizes the status of the WAKE PIN which has a special meaning in an ultra low application. Usually, by a status change of this input the module is triggered to perform a predefined operation.

Applications using this profile:

- water sensor conductive Wake Status = 0 (water detected)
- pressure gauge with minimum or maximum (wake signal, configurable if min or max)
- indication and individual switching points (digital channels show different areas)

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	8	DB3.7DB3.0	Not Used (= 0)				
8	8	DB2.7DB2.0	Temperature	TMP	Temperature (linear)	2550	040 °C
16	3	DB1.7DB1.5	Not Used (= 0)				
19	1	DB1.4	Status of Wake	WA0	Value of wake signal	Enum:	
						0: Low	
				\		1: High	
20	1	DB1.3	Digital Input 3	DI3	Digital Input 3	Enum:	
						0: Low	
						1: High	
21	1	DB1.2	Digital Input 2	DI2	Digital Input 2	Enum:	
						0: Low	
						1: High	
22	1	DB1.1	Digital Input 1	DI1	Digital Input 1	Enum:	
						0: Low	
						1: High	
23	1	DB1.0	Digital Input 0	DI0	Digital Input 0	Enum:	
					\	0: Low	
						1: High	
24	4		Not Used (= 0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
							telegram
						1: Data tele	egram
29	3	DB0.2DB0.0	Not Used (= 0)			N. Contraction of the contractio	

RORG	A5	4BS Telegram			
FUNC	30	Digital Input			
TYPE	04	3 Digital Inputs, 1 Digital Input 8 Bits			

Submitter: Afriso / EnOcean

Description:

This profile is used for universal module with 1 analog input (= 8 bits resolution digital) and 3 digital inputs. The application meaning and exact data interpretation of the input channels depends on the end application and is not defined in this profile documentation.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Trigger event: values have changed Teach-in method: 4BS teach-in 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid	Range	Scale	Unit
0	16	DB3.7DB2.0	Not Used (= 0)						
16	8	DB1.7DB1.0	Digital value-input	DV0	Digital value 1 byte	025	5	0255	N/A
24	4	DB0.7DB0.4	Not Used (= 0)						
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:		
						0:	Teach-i	n telegra	ım
						1:	Data tel	legram	
29 1 DB0.2 Digital Input 2 DI2 Measure				Measured digital Input 2	easured digital Input 2 Enum:				
					0:	Low	<u>-</u> '		
		\'				1:	High	_	
30	1	DB0.1	Digital Input 1	DI1	Measured digital Input 1	Enum	:		
						0:	Low	<u>-</u> '	
						1:	High	_	
31	1	DB0.0	Digital Input 0	DI0	Measured digital Input 0	Enum	:		
						0:	Low	=	
						1:	High		

RORG	A5	4BS Telegram
FUNC	30	Digital Input
TYPE	05	Single Input Contact, Retransmission, Battery Monitor

Submitter: ITEC

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval:

- retransmission: 5 ... 255 seconds (one time configuration)

- number of retransmission times: 0 ... 127 times (one time configuration)

- heartbeat: 60 ... 65535 seconds (one time configuration) Trigger event: digital input, retransmission, heartbeat

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: 4BS teach-in 2

<u>Security</u>

Encryption supported: no Security level format: -

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale	Unit
0	8	DB3.7DB3.0	Not Used (= 0)				
8	8	DB2.7DB2.0	Supply voltage		Supply voltage	0255 03.3 V	
16	1	DB1.7	Signal type	ST	Signal type	Enum: 0: Normal signal 1: Heart beat signal	
17	7	DB1.6DB1.0	Index of Signals	IOS		Enum: Increment a counter by new 0127: telegram	
24	4	DB0.7DB0.4	Not Used (= 0)	•			
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram	
29	3	DB0.2DB0.0	Not Used (= 0)	•	•		

A5-37: Energy Management

RORG	A5	4BS Telegram
FUNC	37	Energy Management
TYPE	01	Demand Response

Submitter: Echoflex Solutions Inc.

Purpose of EEP:

Demand Response is a developing standard to allow utility companies to send requests for reduction in power consumption during peak usage times. It is also used as a means to allow users to reduce overall power consumption as energy prices increase. Having an EEP for this will allow ease of integration with EnOcean products to this standard. The EEP was designed with a very flexible setting for the level (0-15) as well as a default level whereby the transmitter can specify a specific level for all controllers to use (0-100% of either maximum or current power output, depending on the load type). This EEP also includes a timeout setting to indicate how long the DR event should last if the DR transmitting device does not send heartbeats or subsequent new DR levels.

Description:

This EEP is included under a new function of Energy Management. Additional types could be added in future for power, voltage, and current data. The proposed EEP type 01 only deals with demand response activation at this point. Data Byte 3 is the default DR value for devices that implement a control algorithm that uses a set-point. It will be used for any controllers not supporting the current DR Level in the message and having an adjustable set-point.

Data Byte 2 is the default DR Level for any controllers not supporting the current DR Level in the message and having an adjustable control. It can be defined as either a percentage of the maximum power or a percentage of the current power, depending on the value of bit 7 in Data Byte 2. Bits 0 through 6 contain the percentage of power (either relative or absolute) that should be used. A value of 0 corresponds to 0% and a value of 100 corresponds to 100%. Any value higher that n100 should be interpreted as 100%. For example, if the current DR level is not supported by the controller and Data Byte 2 bit 7 is 0 and Data Byte 2 bits 0 through 6 are set to 55, then the controller should try to use 55% of its maximum power usage. In the case of a lighting load with 0-10V dimming, this would correspond to 5.5V on the dimming line. In the case of a heating controller with a maximum set back of 5 degrees C, this would correspond to a set back of 2.75 degrees C (this would most likely be rounded to 3).

Data Byte 1 is the timeout for this DR event. After this command is sent the controller will stay at the DR level for Data Byte 1 multiplied by 15 minutes. Once this time has elapsed the controller will return to normal operation. If Data Byte 1 is 0 then the controller will remain in the DR event until the next DR command is received. This timeout allows DR devices to leave or turn off after setting controllers into a DR state, thus the DR transmitter is not needed to take the devices out of the DR state and the controllers will automatically recover. For example a DR transmitter that only sends messages when a DR event is active could be used with the timeout to create a successful DR system.

Data Byte 0, Bits 7 through 4 make up a nibble that will be used as the DR level. Levels 0 through 15 will be possible using these bits. Bit 4 will be the lowest bit in this nibble and bit 7 will be the highest. If any level is not supported by a controller then that controller should use the default settings sent in this message or map the level to one that it supports.

Data Byte 0 Bits 2 and 1 indicate whether the power adjustment at start and end of the DR event should be randomized or not. This feature is intended to minimize rapid changes on the power distribution equipment by delaying each controller's response. If random start or end is enabled, each controller will delay starting or ending the DR event by a random time that will vary uniformly over a specific time period (for example, 5 seconds, or 15 minutes).. The maximum length of these random delays will depend on the implementation in the controller.

Data Byte 0, Bit 0 is the state for loads that are not adjustable for the default DR level. If a controller does not support the current DR level and does not have adjustable control then it should use this bit. The two states of this bit are defined as follows: 1 = maximum power usage by controller, 0 = minimum power usage by the controller. If for example lights are being controlled, then a setting of 1 will mean the lights should be ON, where as a setting of 0 will mean the lights should be OFF. For a thermostat application with non adjustable set back, a setting of 1 will mean that no set back should be applied, whereas a setting of 0 will mean that the full set back should be applied. This setting only applies to the maximum power usage of the controller, if for example the lights are currently off and the controller receives a DR event with this bit set, then the lights should not turn ON as the DR event has only set the maximum power usage for the device.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Temporary default	TMPD	New Temporary	0255	0255	N/A
					default DR set point			
					Min Max.			
					(linear)			
					•	•		

8	1	DB2.7	power usage	SPWRU		percentage power use. 1: Relative power DB_2.BIT_6 percentage power use.	5DB_2.BIT_0 of the maximu wer usage. Into 5DB_2.BIT_0 of the current	erpret as a
9	7	DB2.6DB2.0	Power Usage	PWRU	0% to 100% power usage in 1% increments; 101127 = interpreted as 100%	0100	0100	N/A
16	8	DB1.7DB1.0	Timeout Setting	TMOS	Time in 15 min. intervals; 0 = No time specified; 1255 = increasing 15 min. intervals. Max value: 3825 = 255*15	1255	153825	min
24	4	DB0.7DB0.4	DR Level	DRL	DR Level	015	015	N/A
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in te 1: Data telegra		
29	1	DB0.2	Random start delay	RSD		Enum: 0: False 1: True		
30	1	DB0.1	Randomized end delay	RED		Enum: 0: False 1: True		
31	1	DB0.0	Max/Min Power Usage for Default DR State	MPWRU		Enum: 0: Minimum Po 1: Maximum P	ower usage ower usage	-

A5-38: Central Command

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	08	Gateway

Communication between gateway and actuator uses byte DB $_3$ to identify Commands. Commands 0x01 to 0x7F shall be common to all types belonging to this profile. Commands 0x80 to 0xFE can be defined individually for each device type.

0x01 Switching

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x01:		
8	16	DB2.7DB1.0	Time	TIM	Time in $1/10$ seconds. $0 = no$ time specifed	165535 0.	16553.	5 s
24	4	DB0.7DB0.4	Not Used (= (0)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach telegr		

						1:	Data telegram
29	1	DB0.2	Lock/Unlock	LCK	Lock for duration time if time >0, unlimited time of no time specified. Locking may be cleared with "unlock". During lock phase no other commands will be accepted or executed	Enum 0: 1:	Unlock Lock
30	1	DB0.1	Delay or duration	DEL	Delay or duration (if Time > 0); 0 = Duration (Execute switching command immediately and switch back after duration) 1 = Delay (Execute switching command after delay)	Enum 0: 1:	Duration Delay
31	1	DB0.0	Switching Command	SW	Switching Command ON/OFF	Enum 0: 1:	Off On

0x02 Dimming

REMARK.

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Vali Rang	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum: 0x02	<u></u>	
8	8	DB2.7DB2.0	Dimming value	EDIM	Dimming value (absolute [0255] or relative [0100])	0255	0100	%
16	8	DB1.7DB1.0	Ramping time	RMP	Ramping time in seconds, 0 = no ramping, 1 255 = seconds to 100%	0255	0255	S
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	1:	Teach-in telegram Data telegram	
29	1	DB0.2	Dimming Range	EDIM R	Dimming Range	1:	Absolute value Relative value	
30	1	DB0.1	Store final value	STR	Store final value		No Yes	
31	1	DB0.0	Switching Command	SW	Switching Command ON/OFF		Off On	

0x03 Setpoint shift

Submitter: Thermokon Sensortechnik GmbH

Used for changing set point, for example summer / winter compensation

Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
					0x03:		
8	DB2.7DB2.0	Not Used ((= 0)				
8	DB1.7DB1.0	Setpoint	SP	Setpoint shift	0255	-12.712.8	K
4	DB0.7DB0.4	Not Used ((= 0)		_		
	8 8 8	8 DB3.7DB3.0 8 DB2.7DB2.0 8 DB1.7DB1.0	8 DB3.7DB3.0 Command 8 DB2.7DB2.0 Not Used (8 DB1.7DB1.0 Setpoint	8 DB3.7DB3.0 Command COM 8 DB2.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Setpoint SP	8 DB3.7DB3.0 Command COM Command ID 8 DB2.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Setpoint SP Setpoint shift	8 DB3.7DB3.0 Command COM Command ID Enum: 0x03: 8 DB2.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Setpoint SP Setpoint shift 0255	8 DB3.7DB3.0 Command COM Command ID Enum: 0x03: 8 DB2.7DB2.0 Not Used (= 0) 8 DB1.7DB1.0 Setpoint SP Setpoint shift 0255 -12.712.8

28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum	:
						0:	Teach-in telegram
						1:	Data telegram
29	3	DB0.2DB0.0	Not Used	(= 0)			

0x04 Basic Setpoint

Submitter: Thermokon Sensortechnik GmbH

Send a new basic set point via DDC to an actuator

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x04:		
8	8	DB2.7DB2.0	Not Used (= 0)				
16	8	DB1.7DB1.0	Basic Setpoint	BSP	Basic Setpoint	0255	0+51.2	°C
24	4	DB0.7DB0.4	Not Used $(= 0)$)				
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-	in telegrar	n
						1: Data te	elegram	
29	3	DB0.2DB0.0	Not Used $(= 0$					

0x05 Control variable

Submitter: Thermokon Sensortechnik GmbH

Set occupancy, energy holdoff and control directly actuator

Offset			Data	ShortCut	Description	Valid	Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:			
						0x05			
8	8	DB2.7DB2.0	Not Used (= 0)						
16	8	DB1.7DB1.0	Control variable override	CVOV	Control variable override	0255		0100	%
24			Not Used (= 0)						
25	2	DB0.6DB0.5	Controller mode	СМ	Controller Mode	1: H	Automatic selection Heating Cooling	mode	
27	1	DB0.4	Controller state	CS	Controller state		Automatic Override		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	$\overline{}$	Teach-in to		_
29	1	DB0.2	Energy hold off	ENHO	Energy Hold Off	1: E	Normal Energy ho	Idoff/ Dew	V
30	2	DB0.1DB0.0	Room occupancy	RMOCC	Room occupancy	1: l	Occupied Unoccupie Standby	d	<u> </u>

0x06 Fan stage

Submitter: Thermokon Sensortechnik GmbH

Set directly fan stage

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
	,					0x06:		
8	8	DB2.7DB2.0	Not Used (= 0)					
16	8	DB1.7DB1.0	FanStage override	FO	FanStage override	Enum:		
		No.				0: Stage 0		
						1: Stage 1		
						2: Stage 2		
						3: Stage 3		
						255: Auto		
24	4	DB0.7DB0.4	Not Used (= 0)					
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
						0: Teach-in	telegra	ım
						1: Data tele	egram	
29	3	DB0.2DB0.0	Not Used (= 0)				•	

0x07 Blind Central Command

Submitter: PEHA / infrated

With this central command all blinds, awnings and shutters can be manipulated.

Remarks for data table:

REMARK 1:

The angle is usually available in blinds and awning modules.

Normally, in shutter modules the angle value is ignored.

The angle value can be set from -180° (e.g. maximum slat angle at the fully SHUT position) to 180° (e.g. maximum slat angle at the fully OPEN position).

The byte is set with following rule:

Bit7: Sign of the slat angle (0 = positive value, 1 = negative value)

Bit6..0: Slat angle value in 2° steps (e.g. $50 = 100^{\circ}$)

REMARK 2:

If this function (Blind drives to position with angle value) is not supported or not configured, use following rule:

- Position is 0 to 49% -> The blind opens
- Position is 50 to 100% -> The blind closes.

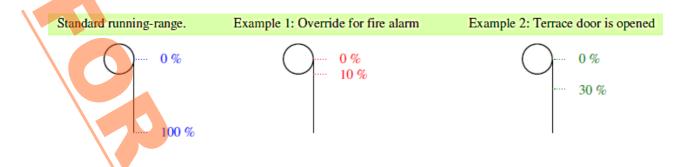
REMARK 3:

Conventional blinds and shutters can be configured with these 3 parameters to calculate the sufficiently accurate position and angle of the blind.

REMARK 4:

With this command you can adjust the minimal and maximal position of the blinds. So it's possible to override the running-range of blinds via a central control unit. Local operations are restricted and increase safety (e.g. to open blinds in case of wind or fire).

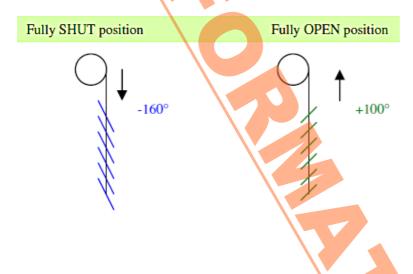
Condition: The Minimal value must be smaller or equal the maximal value.



Example to lock the local functionality: Drive the shutters to a define position and set the minimal and maximal values to this position.

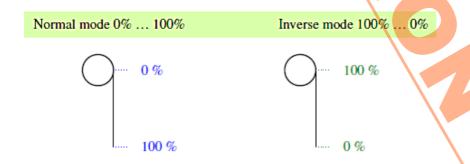
REMARK 5:

These to angle values describe the maximum slat angle at the fully SHUT position and the maximal slat angle at the fully OPEN position. With the time parameter, e.g.:



REMARK 6:

Set the position logic for the blind control and visualization.



Note: If the mode is changed, the minimum and maximal values (function 9) are converted as well!

REMARK 7:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

Note: Special functionality is in function "Status request (0)", the status is always sent.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	DB3.7DB3.0	Command	СОМ	Command ID	Enum:		
						0x07: Shutters / Blinds	\	

		552 552	la	54		_
8	8	DB2.7DB2.0	Parameter 1	P1	Function defined parameter value	Enum: Func. 00: not used
1					parameter raide	runc. oo not useu
						Func. 01: not used
						Func. 02: not used
						Func. 03: not used
		1				Func. 04: 0% 100% e.g.: 0% = Blind fully open / 100% = Blind fully closed
						Func. 05: 0 255 seconds
						Func. 06: 0 255 seconds
						Func. 07: Runtime value to close the blind
		\				0 255 seconds
						Func. 08: Runtime value for the sunblind reversion time This is the time to revolve the sunblind
						from one slat angle end position to the other end
						position: 0.0 25.5 seconds (0.1s steps)
						Func. 09: Set minimal position value 0 100%
						Func. 10: Angle at the fully SHUT position
				\		Bit7 0 = positive sign Bit7 1 = negative sign
						Bit60 0 90 Angle in 2° steps (e.g. 0 = 0°, 90 = 180°)
						Func. 11: Position logic
						0 = Highest position = 0% / Lowest position = 100%
						1 = Highest position = 100% / Lowest position = 0%
16	8	DB1.7DB1.0	Parameter 2	P2	Function defined	Enum:
					parameter value	Func. 00: not used
					· ·	Func. 01: not used
						Func. 02: not used
						Func. 03: not used
						Func. 04: Ángel (see remark 1) Bit7 0 = positive sign
						Bit7 1 = negative sign
						Bit60 0 90 Angle in 2° steps (e.g. 0 = 0°, 90 =
						180°)
						Func. 05: 0.0 25.5 seconds
						Func. 06: 0.0 25.5 seconds
						Func. 07: Runtime value to open the blind
						0 255 seconds
						Func. 08: not used
						Func. 09: Set maximal position value 0 100%

							Func. 10: Angle at the fully OPEN
							position
							Bit7 0 = positive sign
							Bit7 1 = negative sign
							Bit60 0 90
							Angle in 2° steps (e.g. 0 = 0°, 90 =
							180°)
						_	Func. 11: not used
24	4	DB0.7DB0.4	Function	FUNC		Enum:	
						0:	Do nothing, status request
						1:	Blind stops
						2:	Blind opens
						3:	Blind closes
						4:	Blind drives to position with angle value
							(see remark 2)
						5:	Blind opens for time (position value) and angle (angle value)
						6:	Blind closes for time (position value)
							and angle (angle value)
						7:	Set Runtime parameters (see remark 3)
						8:	Set angle configuration (see remark 3)
						9:	Set Min, Max values (see remark 4)
						10:	Set slat angle for SHUT and OPEN position (see remark 5)
						11:	Set position logic (see remark 6)
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:	
						0:	Teach-in telegram
						1:	Data telegram
29	1	DB0.2	Send status	SSF	see remark 7	Enum:	
	_		flag				
						1:	Send no status (e.g. Global central
							commands)
30	1	DB0.1	Pos. and	PAF		Enum:	
			Angle flag			0:	No Angle and position value available
						1:	Angle and position value available
31	1	DB0.0	Service	SMF		Enum:	
			Mode Flag			0:	Normal operation
						1:	Service mode: The module disables all
							senders, except this sender, which has
							set the service mode. (For example for
							maintenance)

RORG	A5	4BS Telegram
FUNC	38	Central Command
TYPE	09	Extended Lighting-Control

Submitter: PEHA / infratec

With this central command all lighting actors can be manipulated.

Remarks for data table:

REMARK 1:



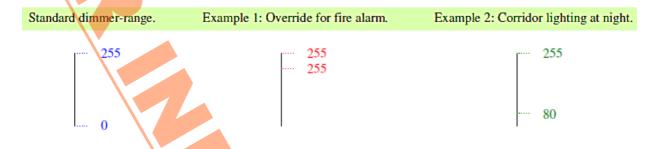
Set the RGB level for corresponding lighting-control. Devices without this feature ignore this command.

REMARK 2:

Up to 16 different scenes can be selected and configured.

REMARK 3:

Change the minimal and maximal dimmer-value. Example:



General for switchers:

The values 0 .. 127 are defined to "Off"

The values 128.. 255 are defined to "On".

RFMARK 4:

Example: If the lamp was replaced, the operating hours are reset to 0.

REMARK 5:

This function blocks all other commands from the other taught-in transmitters. The transmitter, which has called this function, must delete the blocking state, before the other transmitters can use the device again.

REMARK 6:

For important central commands, it's not necessary to send directly the statefeedback, e.g. when many modules are activated simultaneously.

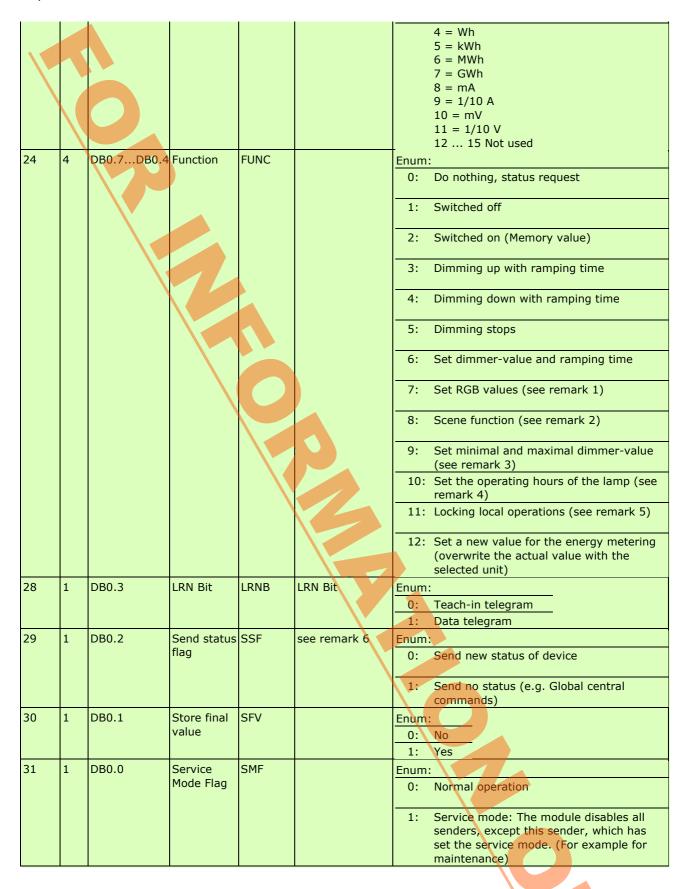
Note: Special functionality is in function "Status request (0)", the status is always sent.

REMARK 7:

Ramp time is the time needed to transition from minimum to maximum dimming levels.

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
		Bitrange DB3.7DB3.0		ShortCut P1	Description Function defined parameter value		sed sed sed sed sed sed sed	
						Func. 08: not us	sed	
						Func. 09: Dimm-Va Func. 10: Lamp op 158)		
						Func. 11: not us Func. 12: Energy n 158)	1	e (MSB

0	0	DD2 7 DD2 0	Do wa	מח	From orbital and a Committee	F
8	8	DB2.7DB2.0	Parameter 2	P2	Function defined parameter value	Func. 00: not used
						Func. 01: not used
						Func. 02: not used
						Func. 03: Ramping time (MSB 158) (65535 s)
						Func. 04: Ramping time (MSB 158) (65535 s)
						Func. 05: not used
						Func. 06: Ramping time (MSB 158) (65535 s)
		\	1			Func. 07: G - Green (0 255)
						Func. 08: not used
						Func. 09: Dimm-Value (0 255)
						Func. 10: Lamp operating hours (70 LSB)
						Func. 11: not used
						Func. 12: Energy metering value (70 LSB)
16	8	DB1.7DB1.0	Parameter	P3	Function defined	Enum:
			3		parameter value	Func. 00: not used
				\		Func. 01: not used
						Func. 02: not used
						Func. 03: Ramping time (70 LSB) (65535 s)
						Func. 04: Ramping time (70 LSB) (65535 s)
						Func. 05: not used
						Func. 06: Ramping time (70 LSB) (65535 s)
						Func. 07: B - Blue(0 255)
						Func. 08: Bit7: 0 = Drive to scene-value
						Bit7: 1 = Stores actual value in the scene Bit30: Scene number 0 15
						Func. 09: not used
						Func. 10: not used
						Func. 11: Blocks the local operations
						Enum: 0 = Unlock local operations
						1 = Locking switch on commands 2 = Locking switch off commands
						3 = Locking local operations
						Func. 12: Unit of energy metering value Enum: 0 = mW
						1 = W 2 = kW
						3 = MW



A5-3F: Universal

RORG	A5	4BS Telegram			
FUNC	3F	Universal			
TYPE	00	Radio Link Test (BI-DIR)			

Submitter: PROBARE

Units supporting the EEP Radio Link Test shall offer a functionality that allows for radio link testing between them

(Position A to Position B, point-to-point only). Testing shall be possible without the need for prior teach-in and as an option it shall cover two way communications.

Further, testing shall be backward compatible to existing EnOcean installations that support at least 1BS (RORG=0xD5) and 4BS (RORG=0xA5) EnOcean messages.

The main area of RLT application are in-field testing of radio links between portable test equipment placed at different locations as well as between portable test equipment and fixed installation, e.g. an EnOcean Gateway.

Functional description of RLT:

When two units perform radio link testing one unit needs to act in a mode called RLT Master and the other unit needs to act in a mode called RLT Slave. On a RLT enabled unit one or both modes may be supported. The mode(s) supported shall require explicitly activation at run time.

After activation a RLT Master listens for RLT_Query messages. On reception of at least one RLT_Query message a RLT Master responds with an RLT_Response message. Following that it starts transmission of RLT_MasterTest messages within a maximum time frame of 250ms and awaits the response from the RLT Slave for each RLT_MasterTest message sent. A radio link test communication consists of a minimum of 16 and a maximum of 256 RLT_MasterTest messages. Timing distance between individual RLT_MasterTest messages shall not exceed 250ms. When the radio link test communication is completed the RLT Master gets deactivated automatically.

After activation a RLT Slave periodically transmits RLT_Query messages (1 message / 2s). It stops transmission of RLT_Query messages as soon as it has received at least one RLT_Response message. It then waits for RLT_MasterTest messages from the same EnOcean ID and replies to them within a maximum delay of 100ms thru RLT_SlaveTest messages. If it does not receive RLT_MasterTest messages from the same EnOcean ID for a time period of 5s, the RLT Slave restarts periodic transmission of RLT_Query messages. The RLT Slave requires explicit deactivation.

RLT_Query Message

This Message is a "4BS Teach-In Query" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process.

RLT_Response Message

This Message is a "4BS Teach-In Response" message with FUNC, Type and Manufacturer ID set properly. For details please refer to the description of the 4BS teach-in process. As a RLT Master does accept teach-in of a RLT Slave only for the time period required by a single RLT communication it shall indicate the EEP to be supported but the EnOcean ID of the RLT Slave not to be stored permanently.

RLT_MasterTest_4BS

This is the 4BS message sent by the RLT Master during a radio link test communication DIRECTION- 1

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range Scale Unit
0	28	DB3.7DB0.4	Not Used (=	0)		
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teach-in telegram 1: Data telegram
29	2	DB0.2DB0.1	MSG_ID	MSGID	Message ID	Enum: 2:
31	1	DB0.0	MSG-Source	MSGS	Message Source	Enum: 0: RLT-Master

RLT_SlaveTest_4BS

This is the 4BS message sent by the RLT Slave in reply to an RLT_MasterTest_4BS message. DIRECTION- 2

Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale Unit
0	2		Sub-Telegram Counter		related to RLT_MasterTest_4BS message received Repeater level 2	Enum: 0: not s 1: 1 subteleg	

		la .				ı———		
							2 sub telegram	
							≥ 3 sub	
							telegram	
2	6	DB3.5DB3.0	RSSI Level in dBm	RSLV	related to RLT_MasterTest_4BS	Enum:		
					message received Repeater level 1		not	
						-	supported	
	\					0x01:	≥-31	dBm
						-	-32	<u> </u>
						0x02:		dBm
							≤-93	4D
8	8	DB2 7 DB2 0	Sub-Telegram	RSLV	Related to RLT_MasterTest_4BS	0x3F: Enum:		dBm
J	J	DD2.7DD2.0	Counter/RSSI	KSLV	message received Repeater level 1		See prev	_
			Level in dBm		(for details see DB3)			
16	8	DB1.7DB1.0	Sub-Telegram	RSLV	Related to RLT_MasterTest_4BS	Enum:		_
			Counter/RSSI Level in dBm		message received direct link	:	See prev	
24	4	DB0.7DB0.4	RSSI Level in dBm	RSLV	Non-EnOcean signal detection	Enum:		
					since last RLT_MasterTest message		not	
					RSSI Level with 6dB quantization steps	0x00:	supported	
						0x01:	≥ -31	dBm
							-3237	ubili
						0x02:	02 07	dBm
							-3843	
						0x03:	-4449	dBm
			\			0x04:	-4449	dBm
			,				-5055	
						0x05:		dBm
						0x06:	-5661	dBm
							-6267	abiii
						0x07:		dBm
						000.	-6873	dD
						0x08:	-7479	dBm
					· ·	0x09:	77 73	dBm
							-8085	_
						0x0A:	. 00	dBm
						0x0B:	≤ -92	dBm
28	1	DB0.3	LRN Bit	LRNB	LRN Bit	Enum:		
							Teach-in	
							telegram	
						1:	Data telegr	am
29	2	DB0.2DB0.1	MSG ID	MSGID		Enum:		
23	_	550.2550.1	50_15	. 13015		2:		
31	1	DB0.0	MSG-Source	MSGS		Enum:		
							RLT-Slave	

RLT_MasterTest_1BS

This is the 1BS message sent by the RLT Master during a radio link test communication.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

Range Scale of the Range	Offset Size Bitrange Data ShortCut Description Valid Range
--------------------------	--

	0	4	DB3.7DB3.4	RLT MSG-Counter MSB	MC-MSB	Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :
	4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum:
							0: Teach-in telegram
	`	\setminus					1: Data telegram
	5	2	DB3.2DB3.1	RLT MSG-Counter LSB	MC-LSB	Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :
Ī	7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum:
Ĺ							0: RLT Master

RLT_SlaveTest_1BS

This is the 1BS message sent by the RLT Slave in reply to an RLT_MasterTest_1BS message.

REMARK: The column 'Bitrange' is automatically generated from the telegram type and the offset. The column Bitrange shows currently DB_3 instead of DB_0. This isn't a bug in the XML, only a weakness of the formatting. AT THIS POINT, DB_0 WOULD BE CORRECT.

DIRECTION- 2

DIRECT	1011	_						
Offset	Size	Bitrange	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4		RLT MSG-Counter MSB		Round-trip, covering all RLT_x_1BS messages 4 bit MSB	Enum: :		
4	1	DB3.3	LRN Bit	LRNB	LRN Bit	Enum: 0: Teac teleg 1: Data		ım
5	2	DB3.2DB3.1	RLT MSG-Counter LSB		Round-trip, covering all RLT_x_1BS messages 2 bit LSB	Enum: :		
7	1	DB3.0	MSG-Source	MSGS	Message Source	Enum: 1: RLT-	Slave	

RORG	A5	4BS Telegram
FUNC	3F	Universal
TYPE	7F	Universal

Submitter: EnOcean GmbH

Description

This profile was intended for manufacturer specific applications. Every manufacturer may independently define the types within this profile.

This profile was replaced by the use of MSC-Telegrams with the advantage of more payloads and the manufacturer Id as identification. For future applications only use MSC-Telegrams.

This description is only necessary for legacy reasons.

Data exchange

Direction: unidirectional / bidirectional Addressing: unicast (ADT) / broadcast

Communication trigger: event- & time-triggered Communication interval: application specific

Trigger event: application specific

Tx delay: not specified Rx timeout: not specified

Teach-in

Teach-in method: 4BS teach-in

Security

Encryption supported: no Security level format: -

Offset	Size	Bitra	nge	Data	ShortCut	Description	Valid Ra	ange	Scale	Unit
0	28	DB3.7	DB0.4	undefined	undef	undefined				
28	1	DB0.3		LRN Bit	LRNB	LRN Bit	Enum:			
							0: Te	ach-in	telegra	m
							1: Da	Data telegram		
29	3	DB0.2	DB0.0	undefined	undef	undefined				

D2: VLD Telegram

D2-00: Room Control Panel (RCP)

The Communication is based on the Smart Ack concept. Some basics related hereto are included in this document for convenience but for details please consult the Smart Ack specification.

A Room Control Panel (RCP) compliant to this EEP offers the following features:

- Multi symbol, multi segment LC display (or equivalent)
- 1 temperature measurement channel, remote configurable
- 1 temperature set point control (e.g. key pad based)
- 1 fan speed control (e.g. key pad based)
- 1 presence control (e.g. key pad based)

Repeater operation shall work in compliance with the Smart Ack specification.

EEP 2.6.3 Specification © EnOcean Alliance

Use Case: Temperature Measurement Sensor termometry No significant temperature change → no telegram termometry No significant temperature change → no telegram termometry No significant temperature change → no telegram termometry No significant temperature Still no significant temperature change, but N change → no telegram measurements have been taken → we have to report that we are still "alive". termometry D termometry No significant temperature change → no telegram Now there is a significant temperature change. Therefore the measurement will be send termometry immediately.

REMARK:

The "alive"-meter will be reset.

Temperature measurement may be configured by the Gateway, see chapter "Message Type E - RCP Configuration".

termometry

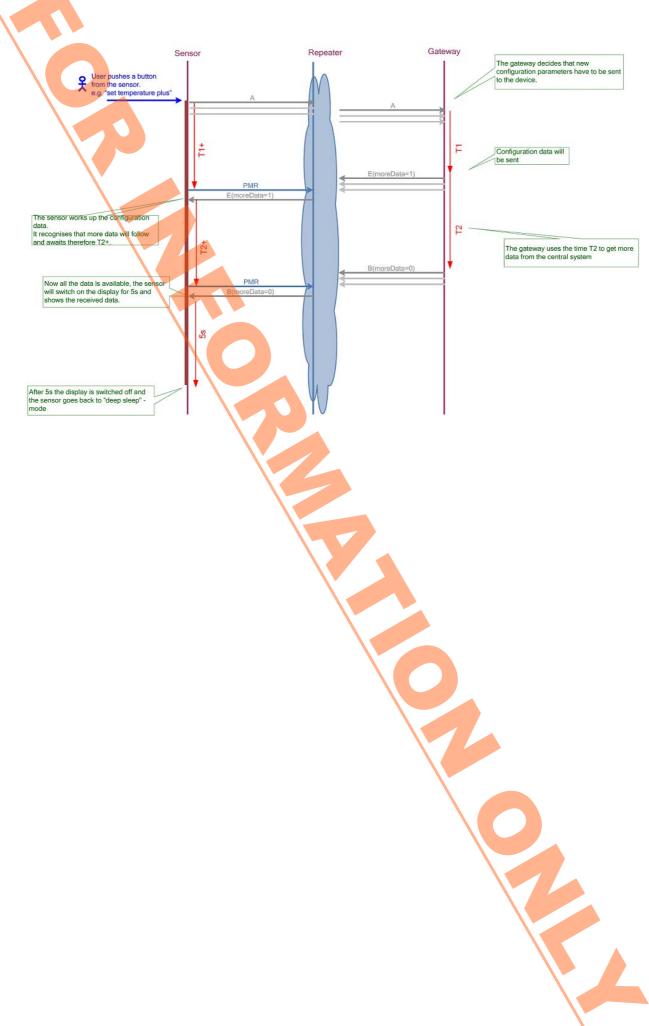
D

No significant temperature change → no telegram EEP 2.6.3 Specification © EnOcean Alliance

Use Case: User Interaction Gateway Depending on the set-up of the central system the gateway always knows the contents a sensor should represent or it first has to consult the central system. Repeater To increase the transmission reliability the telegram will be send three times. User pushes a button from the sensor. e.g. "set temperature plus" The sensor will be woken up by the key press from the "deep sleep" - mode. The gateway has T1 to provide to send an answer. The answer can include all already available data. If some data is still missing (because consulting with the coellral system is necessary) the agetway informs within the answer that in a short time (T2) more data will follow. Only on of the repeaters is assigned to this sensor as "post master. The last letegram for the transmitter rests on that postmaster. This post master is queried with "post master request". PMR will only be send once; Also like the answer from the postmaster. If the sensor become no answer it will repeat the PMR. B(moreData=1) Depending on the set-up of the system the actual status OR the through pressing a key changed status now will be communicated to the sensor. PMR B(moreData=1) After a lapse of time T1+ the sensor picks up the data from the 'postmaster' To increase the transmission reliability the telegram will be send three times. The sensor recognises that more data will follow and awaits therefore T2+ 2 In that example the gateway uses the time T2 to get more data from the central system B(moreData=0) Now all the data is available, the sensor will switch on the display for 5s and shows the received data. PMR B(moreData=0) To increase the transmission reliability the telegram will be se three times. User is pushing again at "plus" during the next 5s The gateway works up the new information; it will pass the information to the central The sensor updates the display content itself and represents that content now for 5s. The sensor sends the updated data to the gateway. The sensor doesn't expect a feedback; to increase the transmission reliability the telegram will be send three times. The gateway itself could be assigned to a sensor as a "postmaster". In that case the gateway will not send the answer immediately, instead it will provide it for the "post master request". After 5s the display is switched off and the sensor goes back to "deep sleep" - mode

EEP 2.6.3 Specification © EnOcean Alliance

Use Case: User Interaction including transfer of configuration data



RORG	D2	VLD Telegram
FUNC	00	Room Control Panel (RCP)
TYPE	01	RCP with Temperature Measurement and Display (BI-DIR)

Submitter: Fr. Sauter AG

Note: EEP Release 2.1, 2.5, and 2.6 reflected a wrong byte-order for all messages of this EEP!

Example Message Type A:

Instead of DB_1 = 0x01 DB_0 = 0x81 (which is correct for KP=1 and CV=1)

by mistake $DB_1 = 0x81 DB_0 = 0x11$ (which is wrong) was printed.

We apologize for the mistake.

Message type A / ID 01 (First User Action on RCP)

Direction: Sensor -> Gateway

Transaction Response: Message Type B or Type E

Chaining: No

Timing: T1+ = 170ms

	Ме	255	ag	је	A	1	ID	01	L							
Original Identifier:				Data	a[0							Data	a[1]]		
				DB	_1	1				_		DB	_0			
$DB_1.BIT_7 \leftarrow 0$	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	1
							MI		CV					ΚP		

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	5	Not Used (=	= 0)	_			
5	3	MsgId		Message Id; 0x01	Enum: 1: Message Id		
8	1	ConfigValid	CV		Configuration data not on the configuration data not on the configuration data value of the configuration data not only the configuration data value of the co	ot valid (e.g. never red	reived
9	2	Not Used (=	= 0)				
11		User Action	KP		0x03: not used 0x04: not used	Set Point "down" or "- Set Point "up" or "+"	_"

Message Type B / ID 02 (Display Content)

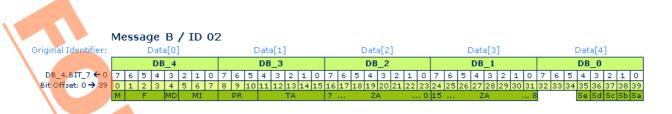
Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms





IMPORTANT NOTE:

The symbols Sa, Sb, Sc, Sd, Se are optional. One or more of those symbols are available on the display only if the manufacturer of a RCP implements them in a specific design. Thus, they are NOT mandatory for a RCP in order to comply with this EEP.

Offset	Size	Data	ShortCut	Description	Valid Range Scale	Unit
0	1	Fan manual	M	_	Enum:	
		\			0: Auto	
					1: Fan manual	
1	3	Fan	F		Enum:	
					0x00: Do not display	
					0x01: Speed Level 0	
					0x02: Speed Level 1	
			\		0x03: Speed Level 2	
					0x04: Speed Level 3	
					0x050x07: not used	
4	1	MoreData	MD		Enum:	
	_				0x00: no more data	
					0x01: more data will follow after T2+	
5	3	MsgId	MI	Message Id;0x02	Enum:	
3		Magra	1.17	Picssage Id, 0x02	2: Message Id	
0	2	Droconco	PR			
8	3	Presence	PK		Enum:	
					0x00: Do not display	
					0x01: Present 0x02: Not present	
					0x03: Night time reduction 0x040x07: not used	
1.1	_	Fig A T	Τ.			
11	5	Figure A Type	TA		Enum:	
					0x00: Do not display	00
					0x01: Room Temperature	°C
					0x02: Room Temperature	°F °C
					0x03: Nominal Temperature	°F
					0x04: Nominal Temperature	
					0x05: Delta Temperature Set P	
					0x06: Delta Temperature Set P 0x07: Delta Temperature Set	oint °F
					0x07: Delta Temperature Set Point(graphic)	
					0x08: Time 00:00 to 23:59 [24	h1
					0x09: Time 00:00 to 11:59 [AN	
					0x0A: Time 00:00 to 11:59 [PM	
					0x0B: Date 01.01 to 31.12 [DD	
					0x0C: Date 01.01 to 12.31 [MM	
					0x0D: Illumination (linear) 0 to	
					0x0E: Percentage 0 to 100	%
					0x0F: Parts per Million 0 to 999	
					0x10: Relative Humidity 0 to 10	
						rH
					not used	
					0x110x1F:	
16	16	Figure A Value	ZA	Format according to	Enum:	
				TA:	0x010x07: 0 4000 0.	010
				Byte-Order: Little-	0x080x0A: Time 0000 2359	
				Endian!	0x0B0x0C: Date 0101 3112	
					0x0D: 0 9999 lx	

					0x0E0x10: 0x0F:	0 10000 0 9999	0.01% ppm
32	3	Not Used $(= 0)$					
35	1	User Notification	Se	optional	0x0: Off 0x1: On		
36	1	Window	Sd	optional	Enum: 0x0: Closed 0x1: Opened	_	
37	1	Dew-Point	Sc	optional	Enum: 0x0: Warning 0x1: No warn		
38	1	Cooling	Sb	optional	Enum: 0x0: Off 0x1: On		
39	1	Heating	Sa	optional	Enum: 0x0: Off 0x1: On		

Message Type C / ID 03 (Repeated User Action on RCP)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No

Timing: may only be sent within 5s from latest receipt of a Message Type B

Message C / ID 03

Original Identifier:				•	a[0	•					1	at	a[1]						Data	a[2]]					ı	Dat	:a[3]		
				DB	_3							DB	_2	V						DB	_1					Data[3] DB_0 6 5 4 3 25 26 27 28: ZA						
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	o
Bit Offset: 0 🔿 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
			F				ΜI			PR				TA			7			Z	4			. 0	15			Z	Α			8

Offset	Size	Data	ShortCut	Description		Valid	Range	Scale	Unit
0	1	Not Used (= 0)							
1	3	Fan	F			Enum:			
						0x00:	n	o change	
						0x01:	S	peed Level 0	-
						0x02:		peed Level 1	
						0x03:	-	peed Level 2	
						0x04:		peed Level 3	<u>-</u> ,
						0x05:	$\overline{}$	peed Level Auto	<u>-</u> ,
						0x06	0x07: n	ot used	
4		Not Used (= 0)	1						
5	3	MsgId	MI	Message Id; 0x03		Enum:			
						3: M	lessage I	Id	
8	3	Presence	PR			Enum:			
						0x00:	n	o change	
						0x01:		resent	
					-	0x02:		lot present	
					=	0x03:		light time reduction	
						0x04	0x07: n	ot used	
11	_	Set Point A	TA			Enum:			
		Туре				0x00:	n	o change	

				0x010x04:	ot used	
				0x05: Te	emperature Set Poin ']	t
				0x060x1F:	ot used	
16	Set Point Value	A	Format according to TA: 0x05 [0.01°]	-1270+1270	-12.70+12.70	o
			Byte-Order: Little-Endian!			

Message Type D / ID 04 (Measurement Result)

Direction: Sensor -> Gateway

Fire and Forget Response: None Chaining: No Timing: None

	Μe	ess	ag	je 🛚	D	/	ID	0	4															
Original Identifier:				Dat	a[0]			4			- [Dat	a[1]]						Dat	a[2]		
				DB	_2							DB	_1							DB	_0			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🔿 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
							ΜI		7			١	۷A			0		T.	A		11	\	/A	8
							_					4												

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	5	Not Used (= 0)					
5	3	MsgId	MI	Message Id;0x04	Enum: 4: Message Id		
8	8	Channel A Value	, ,	Format according to TA: LSB (Bit 7 0)	04000	040.00	o
16	4	Channel A Type	ТА		0x010x0E: not use	rature [°C] d ement result not	valid
20	4	Channel A Value	, ,	See: VA (LSB) MSB (Bit 11 8)			

Message Type E / ID 05 (Sensor Configuration)

Direction: Gateway -> Sensor Reply to Message Type A

Response: None

Chaining: Up to 2 messages per chain

Timing: T2+ = 300ms



Offset	Size	Data	ShortCut	Description	Valid Range Scale	Unit
0	4	Not Used (= 0)		•		
4	1	MoreData	MD		Enum:	
					0x0: no more data	
					0x1: more data will follow after T	2+
5	3	MsgId	MI	Message Id; 0x05	Enum:	
	· ·				5: Message Id	
8		Not Used (= 0)	ı			
9	7	Set Point Range		Limit of Set Point Range,	Enum:	
		Limit		absolute value:	0x00: Set Point disabled	
				REMARK:	0,1° 12,7°	
				Set Point Range shall be	0x010x7F: [0,1°] 0),112,7 °
				symmetrical to 0°		
16		Not Used (= 0)			†	
17	7	Set PointSteps	SPS	Number of Set Point Steps:	Enum:	
		`		REMARK:	0x00: Set Point disabled	
				Specifies the number of	0x010x7F: 1 127	107
				equidistant steps between 0	1	l127
				and Set Point Range Limit		
24	4	Temperature	TT (LSB)	Time between two	Enum:	
		Measurement Timing	\	subsequent Temperature measurements	0x00: Temperature	
		Tilling	`	medsurements	measurement disabled	
				LSB (Bit 3 0)	10 600s [10s]	
					0x010x3C:	10600 s
28	4	Not Used (= 0)				
32	3	` '	PR	Number of Presence Levels	Enum:	
				available to user	0x0: Presence disabled	
					0x10x7: 1 7	
					1	.7
35	3	Fan	F		Enum:	
				available to user:	0x0: Fan Speed disabled	
					0x10x7: 1 7	
					1.	7
38	2	Temperature		Time between two		
		Measurement Timing		subsequent Temperature measurements		
		Tilling		ineasurements		
				MSB (Bit 5 4)		
40	4	Significant	ST	Difference between two	0x00xF 0.03.0	0
		Temperature		subsequent temperature		
		Difference		measurements to trigger a Message Type D [0.2°]		
44	1	Not Used (= 0)		Message Type D [0.2-]		
45		` ,	KA	Number of measurements	Enum:	
13		Timing		(without trigger of a message		
		, and the second		Type D) between two	measurement result wit	h
				subsequent "Keep Alive	each Temperature	
				messages":	measurement	
					10 70 measurements	
					0x10x7: [step-size 10]	1070

D2-01: Electronic switches and dimmers with Energy Measurement and Local Control

This EEP family shall be used for bidirectional actuators that control electric loads, e.g. for lightning purposes. Switching and dimming is controlled and high-resolution energy measurement is supported. Local Control, either thru a user interface or thru other measures shall be supported on the actuator. This may include other EnOcean enabled devices taught-in to a device belonging to the EEP family, e.g. a simple rocker switch or more sophisticated devices like occupancy sensors with timing control. The proposed EEP family serves up to 30 output channels and allows controlling them either individually or as a bulk. Extension of this EEP family is possible in different ways:

1. A new device with a different feature mix creates a new TYPE within this EEP family

- -> new column in following table
- 2. An additional feature is added and a new device with a new TYPE is created
- -> new column and new line in following table
- 3. Like 2, but EnOcean communication of the EEP family needs to be extended
- -> new column and new line in following table
- -> one or more additional messages need to be defined

For teach-in and teach-out UTE (Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication) shall be used.

Supported function	Type 0x00	Type 0x01	Type 0x02	Type 0x03	Type 0x04	Type 0x05	Type 0x06	Type 0x07	Type 0x08	Type 0x09	Type 0x0A	Type 0x0B	Type 0x10	Type 0x11
No. of output	1	1	1	1	1	1	1	1	1	1	1	1	2	2
channels				_	_	_	_	_	_	_	_	_	_	_
	Х	Х	X	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	X
Dimming	-		X	Х	Х	Х	-	=	=	Х	-	=	=	-
Dimming	-		-	-	Х	Х	-	_	_	Х	-	_	_	-
configurable														
Local control	X	X	X	X	X	X	-	_	X	X	X	X	X	X
Local control enable/disable	-	-	-		Х	Х	-	-	Х	-	Х	Х	-	-
Taught-in devices enable/disable 2)	-	-	-		X	Х	-	-	Х	Х	X	Х	-	-
User interface day/night mode	-	-	-			Х	-	-	X	-	Х	Х	-	-
Over current reporting	=	=	=		X	X	=	=	Х	Х	-	=	=	=
Over current configurable	-	-	-	-	X	X	-	-	Х	-	-	-	-	-
Energy measurement	Х	-	Х	-	X	X	X	-	Х	Х	-	Х	Х	-
Power measurement	-	-	-	-	Х	X		-	Х	Х	-	Х	-	-
Measurement Roll Over 1)	Х	-	Х	-	-		X	-	-	-	-	Х	Х	-
Measurement Auto Scaling 1)	-	-	-	-	Х	X		-	Х	Х	-	-	-	-
Measurement configurable	-	-	-	-	-	Х	-	-	Х	Х	-	Х	-	-
Measurement report on query	Х	-	Х	-	Х	Х	X		X	Х	-	Х	Х	-
Measurement auto reporting	-	-	-	-	Х	Х	-		X	Х	-	Х	-	-
Default state configurable	-	-	-	-	-	Х	-		X	X	Х	Х	-	-
Error level reporting	-	-	-	-	-	Х	-	-	X	X	-	-	-	-
Power Failure Detection	-	-	-	-	-	-	-	-		1	X	Х	-	-
Power Failure Detection enable/disable	-	-	-	_	-	_	_	-	-	-	X	Х	-	-

- 1) A device may either support Measurement Roll Over or Measurement Auto Scaling.
- 2) Enable / disable only effects devices that are taught-in to a device belonging to this EEP family; it does not effect communication between a device belonging to this EEP family and any other entity where this device has been taught-in by itself.

RORG	D2	VLD Telegram		
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local	Contr	ol
TYPE	00	Type 0x00		

Submitter: Team

CMD 0x1 - Actuator Set Output

This message is sent to an actuator. It controls switching / dimming of one or all channels of an actuator.

REMARK:

In case an Actuator Set Output message specifies a parameter that is not supported by the device being addresses, such device shall react as following:

- channel not supported by device -> ignore message
- dimming command to switching device -> no change of status
- dimming command with non supported speed -> dim with regular speed

RECOMMENDATION:

Dimmers should take things like phase shifting into account to provide dimming based on power consumption (results in brightness for lamps) rather than interpreting percentage values as phase angle only.

Offset	Size	Data	ShortCut	Description	Val	id Range	Scale	Unit
0	4	Not Used (=	0)					
4	4	Command ID	CMD	command identifier	Enum: 0x01: ID 01			
8	3	Dim value	DV		Enum: 0x00: 0x01: 0x02: 0x03: 0x04: 0x050x07	Switch to new out Dim to new output Dim to new output Dim to new output Stop dimming 7: not used	t value – dim tim t value – dim tim	er 2
11	5	I/O channel	I/O		0x000x1D: 0x1E: 0x1F:	Output channel (to All output channel device Input channel (fro	s supported by t	
16	1	Not Used (=	0)	•				
17	7	Output value	OV		Enum: 0x00: 0x010x64 0x650x7E 0x7F:	Output value 0% of the control of th	to 100% or ON	able

CMD 0x2 - Actuator Set Local

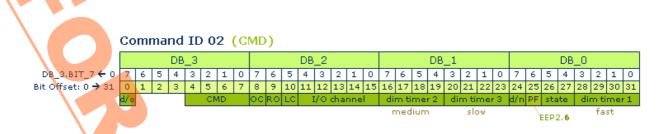
This message is sent to an actuator. It configures one or all channels of an actuator.

Response Timing: None

RECOMMENDATION:

In case the device implements an internal order for dim timers, this order should be from "dim timer 1" (fast) to "dim

timer 3" (slow). The configured time shall always be interpreted for a full range (0 to 100%) dimming.



Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	1	Taught-in devices	d/e		Enum:
					Disable taught-in devices (with different 0b0: EEP)
					Enable taught-in devices (with different 0b1: EEP)
1		Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum: 0x02: ID 02
8	1	Over current shut down	oc		Enum:
					Over current shut down: static off 0b0:
					Over current shut down: automatic 0b1: restart
9		reset over current shut	RO		Enum:
		down			Reset over current shut down: not active 0b0:
					Reset over current shut down: trigger 0b1: signal
10	1	Local control	LC		Enum:
					0b0: Disable local control
4.4	_	7/0	7.10		0b1: Enable local control
11	5	I/O channel	I/O	· ·	Enum:
					Output channel (to load) 0x000x1D:
					0x1E: All output channels supported by the device
					0x1F: Input channel (from mains supply)
16	4	Dim timer 2	DT2		Enum:
					0x00: Not used
					Dim timer 2 [0,5 7,5s / steps 0x010x0F: 0,5s]
20	4	Dim timer 3	DT3		Enum:
					0x00: Not used
					Dim timer 3 [0,5 7,5s / steps 0x010x0F: 0,5s]
24			d/n		Enum:
		indication			0b0: User interface indication: day operation
					0b1: User interface indication: night operation
25	1	Power Failure	PF		Enum:
					0b0: Disable Power Failure Detection
					0b1: Enable Power Failure Detection
26	2	Default state	DS		Enum:
					0b00: Default state: 0% or OFF
					0b01: Default state: 100% or ON
					0b10: Default state: remember previous state
					0b11: Not used

28	4	Dim timer 1	DT1	En	num:	
1					0x00:	Not used
				0x	x010x0F:	Dim timer 1 [0,5 7,5s / steps 0,5s]

CMD 0x3 - Actuator Status Query

This message is sent to an actuator. It requests the status of one or all channels of an actuator.

Response Timing:

An Actuator Status Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (=	0)				
4	-	Command ID	CMD	Command identifier	Enum: 0x03: ID 03		
8	3	Not Used (=	0)	1			
11	5	I/O channel	I/O		Ox16: Ox1F: Output channel (in	els supported by	

CMD 0x4 - Actuator Status Response

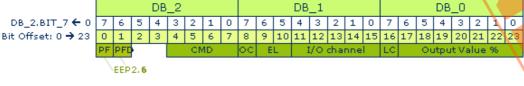
This message is sent by an actuator if one of the following events occurs:

- Status of one channel has been changed locally
- Message Actuator Status Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Status Query message.

Command ID 04 (CMD)



EEP 2.6.3 Specification © EnOcean Alliance

REMARK 1:

In case an Actuator Status Query message specifies a parameter that is not supported by the device being addresses, such device shall ignore the message and shall not answer using the Actuator Status Response message.

REMARK 2:

In case an Actuator Status Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Power Failure	PF		Enum:		
					Power Failure Detectio	n disabled/not	
					0b0: supported		
					Power Failure Detectio	n enabled	
					0b1:		
1	1	Power Failure Detection	PFD		Enum:		
		Detection			Power Failure not dete 0b0: supported/disabled	cted/not	
					Power Failure Detected		
					Ob1:	4	
2	2	Not Used (= 0)			100-1		
4	4	Command ID	CMD	Command	Enum:		
				identifier	0x04: ID 04		
8	1	Over current switch	ОС		Enum:		
		off			Over current switch of	f: ready / not	
					0b0: supported		
					Over current switch of	f: executed	
_					0b1:		
9	2	Error level	EL		Enum:		
					0b00: Error level 0: hardwa		
					0b01: Error level 1: hardwa		
					0b10: Error level 2: hardwa		
11	5	I/O shannal	1/0		0b11: Error level not suppor	rtea	
11	Э	I/O channel	I/O		Enum:	-1 (+- 11)	
					0x000x1D: Output channe 0x1E: Not applicable		
						(from mains s	upply)
16	1	Local control	LC			(ITOTTI TITALITS 5	ирріу)
10	_	Local control	LC		Ob0: Local control disabled	/ not supported	
				\	0b1: Local control enabled	not supported	<u> </u>
17	7	Output value	OV		Enum:		
_,		Surput value			0x00: Output value ()% or OFF	
					0x010x64: Output value 1		· ON
					0x650x7E: Not used	2 200 70 01	
					0x7F: output value n	ot valid / not s	et
						,	

CMD 0x5 - Actuator Set Measurement

The command defines values at offset 32 and at offset 40 which are the limits for the transmission periodicity of messages. MIT must not be set to 0, MAT >= MIT.

Response Timing: None



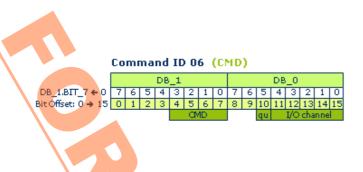
Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x05: ID 05		
8	1	Report measurement	RM		Enum:		
					Report measons ob0: only	urement: quei	ry
					Report measi 0b1: auto reportin	urement: quei g	ry /
9	1	Reset measurement	RE		Enum:		
					Reset measu 0b0:	rement: not a	ctive
					Reset measu 0b1: signal	rement: trigge	er
10	1	Measurement mode	e/p		Enum:		
					0b0: Energy meas	urement	
					0b1: Power measu	rement	
11	5	I/O channel	I/O		Enum:		
					Outpu 0x000x1D: load)	it channel (to	
						tput channels orted by the de	
						channel (fron supply)	n
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN		Enum:		
					0x00: Ener	gy [Ws]	
						gy [Wh]	
			\			gy [KWh]	
			\			er [W]	
						er [KW]	
					0x050x07: Not u		1
24		Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32			MAT	Measurement	Enum:		_
		subsequent actuator messages		Response messages [10s]	1255:	S	
		coougeo		[100]	0 0	102550	_
40	0	NAT . T	NATT	M	0: Reserved		
40		Minimum time between two subsequent actuator	MIT	Measurement Response messages	Enum:		
		messages		[s]	1255:	s 1255	
					0: Reserved	1233	
					0: Reserved		

CMD 0x6 - Actuator Measurement Query

This message is sent to an actuator. The actuator replies with an Actuator Measurement Response message.

Response Timing:

An Actuator Message Response message shall be received within a maximum of 300ms from the time of transmission of this message. In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (=	0)				
4		Command ID	CMD	Command identifier	Enum: 0x06: ID 06		
8	2	Not Used (=	0)				
10	1	Query	qu		Enum: Ob0: Query energy Ob1: Query power		
11	5	I/O channel	I/O		device	(to load) els supported by t	

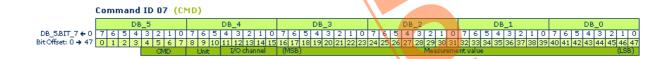
CMD 0x7 - Actuator Measurement Response

This message is sent by an actuator if one of the following events occurs:

- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing:

This message shall be sent within a maximum of 50ms from the time of reception of the Actuator Measurement Query message.



REMARK 1:

In case an Actuator Measurement Query message specifies a parameter that is not supported by the device addressed, such device shall ignore the message and shall not answer using the Actuator Measurement Response message.

REMARK 2:

In case an Actuator Measurement Query message queries all output channels supported by a device being addresses, such device shall answer per each output channel by using an individual Actuator Measurement Response message.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x07: ID 07		
8	3	Unit	UN		Enum: 0x00: Energy [W 0x01: Energy [W 0x02: Energy [K 0x03: Power [W]	/h] Wh]	

					0x04: 0x050x07	Power [KW] : Not used		
11	5	I/O channel	I/O		Enum:			
					0x000x1D:	Output chan	nel (to load	l)
· ·	\setminus				0x1E:	Not applicab	le, do not ι	ıse
					0x1F:	Input channe supply)	el (from ma	ains
16	32	Measurement value (4 bytes)	MV	DB3 = MSB / DB0 = LSB	0429496729	5		N/A

RORG	D2			VLD Telegram
FUNC	01	1	Electronic	switches and dimmers with Energy Measurement and Local Control
TYPE	01			Type 0x01 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	02	Type 0x02 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	03	Type 0x03 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	04	Type 0x04 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram			
FUNC	01	Electronic switches and dimmers with Energy Measurement a	and	Local Co	ontrol
TYPE	05	Type 0x05 (description: see table)	_/		

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	06	Type 0x06 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	07	Type 0x07 (description: see table)

See profile: D2-01-00

RORG	D2		VLD Telegram	
FUNC	01	Electron	ic switches and dimmers with Energy Measurement and Local Co	ntrol
TYPE	08		Type 0x08 (description: see table)	

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	09	Type 0x09 (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0A	Type 0x0A (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control
TYPE	0B	Type 0x0B (description: see table)

See profile: D2-01-00

RORG	D2	VLD Telegram		
FUNC	01	Electronic switches and dimmers with Energy Measurement an	d Local	Control
TYPE	10	Type 0x10 (description: see table)	1	

See profile: D2-01-00

			A
RORG	D2	VLD Telegram	1
FUNC	01	Electronic switches and dimmers with Energy Measurement and Local Control	lc

TYPE 11 Type 0x11 (description: see table)
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See profile: D2-01-00

D2-02: Sensors for Temperature, Illumination, Occupancy And Smoke

This EEP family shall be used for bidirectional sensors that measure temperature, illumination, and detect room occupancy and smoke presence.

The EEP may be used in conjunction with the Smart Acknowledge protocol.

For teach-in and teach-out the "Universal Uni- and Bidirectional Teach-In Procedure for EEP based Communication" shall be used. Alternatively the Smart Acknowledge Teach-In Procedure is used for those sensors supporting Smart Acknowledge.

Supported function	Type	0>	00	Type	Ox	01	Type 0x02
Temperature Sensor	Χ	7		X			X
Illumination Sensor	Χ		\	Χ	4		=
Occupancy Detector	Χ		//	-			-
Smoke Detector	Χ			X			X

RORG	D2	VLD Telegram
FUNC	02	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE	00	Type 0x00

Submitter: MSR-Office

CMD 0x1 - Sensor Measurement

This message is sent by a sensor if one of the following events occurs:

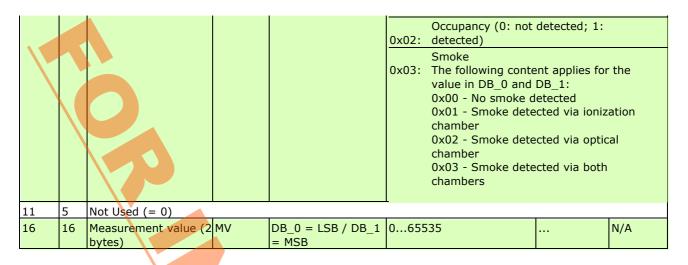
- Measurement results trigger an automated transmission (see Actuator Set Measurement message)
- Message Actuator Measurement Query has been received

Response Timing: None

Command ID 01 (CMD)

DB_3.BIT_7 ← 0 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 7 6 5 4 3 2 1 0 8 3 2 1 0 7 6 5 4 3 2 1 0 8 3 2 1 0 7 6 5 4 3 2 1 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 8 3 2 1 0 0 0 8 3 2 1 0 0 0 8 3 2 1 0 0 0 8 3 2 1 0 0 0 0 8 3 2 1 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0						DΒ	_3							DB	_2							DΒ	_1							DΒ	_0			
	DB_3.BIT_7 ← 0	7	7 6	5 [5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
CMD tune MCD recognition LCD	Bit Offset: 0 → 31	0	1	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
CMD Cype MOB Measurement value Lob								a	MD			type							MS	B.				me	ası	ire n	nent	: val	ue				L	SB.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	4	Not Used (= 0)				
4	4	Command ID	CMD	command identifier	Enum: 0x01: ID 01	
8	3	Measurement type	type		Enum: Temperature (065 0x00: +120°C) Illumination (0655 0x01:	



CMD 0x2 - Sensor Test/Trigger

This message is sent to a sensor. It causes the sensor to enter self-test mode or trigger an alarm (if supported).

Response Timing: None

Command ID 02 (CMD)

				DΒ	_1							DB	_0			
$DB_1.BIT_7 \leftarrow 0$		6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 → 15	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
,						a	ИD		ST	TΑ	V					

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0))				
4	4	Command ID	CMD	Command identifier	Enum: 0x02:ID 02		
8	1	Self-test	ST		Enum: 0b0: Self-test 0b1: Normal	_	on
9	1	Trigger alarm	ТА		Enum: 0b0: Trigger 0b1: Normal	_	on
10	6	Not Used (= 0))			//	

CMD 0x3 - Actuator Set Measurement

This message is sent to a sensor. It configures the measurement behaviour of the sensor

Response Timing: None



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum:		
					0x03: ID 03		
8	1	Report measurement	RM		Enum:		
					Report mea 0b0: only	surement: que	ery
					Report mea 0b1: auto report	surement: que ing	ery /
9	7	Not Used (= 0)					
16	4	Measurement delta to be reported (LSB)	MD_LSB		04095	04095	N/A
20	1	Not Used (= 0)					
21	3	Unit	UN		Enum:		
					0x00: Ter	mperature (°C))
					0x01: Illu	mination (lx)	
					0x020x07: No		
24	8	Measurement delta to be reported (MSB)	MD_MSB		04095	04095	N/A
32	8	Maximum time between two subsequent Actuator		Measurement Response messages [10s]	0255	102550	S
40	8	Minimum time between two subsequent Actuator	MIT	Measurement Response messages [s]	0255	0255	S

CMD 0x4 - Sensor Measurement Query

This message is sent to a sensor. The sensor replies with an Sensor Measurement message.

Response Timing:

A Sensor Measurement message shall be received within a maximum of 300ms from the time of transmission of this message.

In case no such response is received within this time frame the action shall be treated as completed without result.



Offset	Size	Data	ShortCut	Description	Valid Rar	nge	Scale	Unit
0	4	Not Used (= (0)					
4	4	Command ID	CMD	Command identifier	Enum:			
					0x04: ID 0	4		
8	3	Query	qu		Enum:			
					0x0:	Query	temperat	ure
					0x1:	Query	illuminati	on
					0x2:	Query	occupanc	У

		0x3: Qu	ery smoke
		0x40x7: Not	used
11 5 Not Used (= 0))		

			/	
RORG		D	2	VLD Telegram
FUNC		0:	2	Sensors for Temperature, Illumination, Occupancy And Smoke
TYPE		0	1	Type 0x01 (description: see table)
	_			

See profile: D2-02-00

RORG	D2			VLD Telegram
FUNC	02	Sei	nsors fo	r Temperature, Illumination, Occupancy And Smoke
TYPE	02			Type 0x02 (description: see table)

See profile: D2-02-00

D2-03: Light, Switching + Blind Control

The EEP family D2-03-xx provides different telegram types for switches, light and blind control. The purpose is to support secure communication and other functional aspects of applications extending the possibilities given by existing profiles (1BS, RPS, 4BS). Transmitting information in the status field of a telegram is not necessary with this EEP family.

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Contro
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

EEP Properties: DATA EXCHANGE Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: N/A Tx delay: N/A Rx timeout: N/A

Teach-in method: Universal teach-in (UTE) + Secure Teach-in (for secure communication)

SECURITY

Encryption supported: yes

EEP Family Table:

Supported function	Type 00
2 Rocker Switch	X

The encrypted telegram has the R-ORG 0x30. The payload (4 bits) is encrypted. That telegram can be repeated. After decryption and the authentication of the CMAC, the telegram turns into a non-encrypted EnOcean telegram with the R-ORG 0x32. The payload will be expanded to 8 bits (4 MSB set to zero) and can then be interpreted as described in the telegram definition table.

The decrypted telegram may not be repeated as the information is not secure anymore. The following table provides information about the conversion between the profiles D2-03-00 and F6-02-01:

F6-02-01 DATA	F6-02-01 STATUS
-	-
0x17	0x30
0x70	0x20
0x37	0x30
0×10	0x20
0x15	0x30
0x35	0x30
0x50	0x30
0x70	0x30
0x10	0x30
0x30	0x30
bxxx0xxxx	0x20
	0x17 0x70 0x37 0x10 0x15 0x35 0x50 0x70 0x10 0x30

0 4 Not Used (= 0) 4 Rocker Information RI2 Information about pressed rockers (similar to RPS profiles) Enum: Reserved 04: 5: Button A1 + B0 pressed, energy bow pressed 6: 3 or 4 buttons pressed, energy bow pressed 7: Button A0 + B0 pressed, energy bow pressed 8: No buttons pressed, energy bow pressed 8: No buttons pressed, energy bow pressed 9: Button A1 + B1 pressed, energy bow pressed 10: Button A0 + B1 pressed, energy bow pressed 11: Button B1 pressed, energy bow pressed 12: Button B0 pressed, energy bow pressed 13: Button A1 pressed, energy	Offset	Size	Data	ShortCut	Description	Va	lid Range	Scale	Unit
Information (similar to RPS profiles) Reserved 04: 5: Button A1 + B0 pressed, energy bow pressed 6: 3 or 4 buttons pressed, energy bow pressed 7: Button A0 + B0 pressed, energy bow pressed 8: No buttons pressed, energy bow pressed 9: Button A1 + B1 pressed, energy bow pressed 10: Button A0 + B1 pressed, energy bow pressed 11: Button B1 pressed, energy bow pressed 12: Button B0 pressed, energy bow pressed 13: Button A1 pressed, energy bow pressed 13: Button A1 pressed, energy	0	4	Not Used (= 0)						
bow pressed 14: Button A0 pressed, energy bow pressed 15: Energy bow released	_		Rocker	RI2		04: 5: 6: 7: 8: 9: 10: 11: 12: 13:	Reserved Button A1 + energy bow 3 or 4 buttor energy bow Button A0 + energy bow No buttons p bow pressed Button A1 + energy bow Button A0 + energy bow Button B1 pr bow pressed Button B0 pr bow pressed Button A1 pr bow pressed Button A1 pr bow pressed Button A0 pr bow pressed	bressed Bo pressed Bo pressed ressed, energy B1 pressed bressed B1 pressed bressed essed, energy essed, energy essed, energy essed, energy	rgy , , rgy

RORG	D2	VLD Telegram
FUNC	03	Light, Switching + Blind Control
TYPE	10	Mechanical Handle

Submitter: Eltako

This document contains the description of <u>decrypted</u> mechanical handle data. The mechanical handle profile must be redefined because there is no status field in EnOcean security available.

EEP Properties:

DATA EXCHANGE Direction: unidirectional Addressing: broadcast

Communication trigger: event-triggered

Communication interval: N/A

Trigger event: rotate mechanical handle

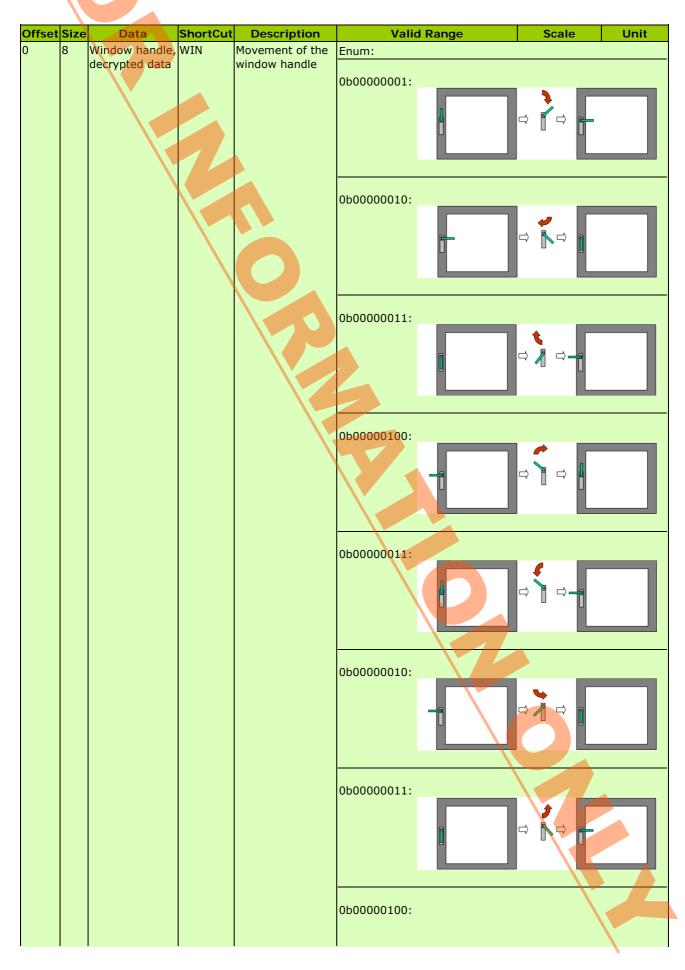
Tx delay: N/A Rx timeout: N/A

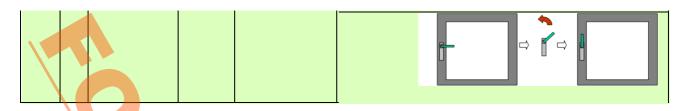
TEACH-IN

Teach-in method: Secure Teach-in, followed by special RPS teach-in sequence: Mechanical handle (closed => opened => closed within 2s)

SECURITY

Encryption supported: yes Security level format:





D2-04: CO2, Humidity, Temperature, Day/Night and Autonomy

CO2 sensor with 8 bits resolution (0 - 2000ppm or 0-5000ppm range) 8 bits temperature and relative humidity with Day / Night and battery autonomy.

Day / Night is based on illumination not on clock

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered

Communication interval: According to remaining autonomy and day or night

Trigger event: heartbeat, ...

Teach-in method: Universal teach-in, Smart Ack

Encryption required: no Security level format: 0

EEP Family Table

Each TYPE has to support every parameter that is marked in its column!

TYPE	0x00	0x01	0x02	0x03	0x04	0x05	0x06	0x07	0x08	0x09	0x10	0x1A	0x1B	0x1C	0x1D	0x1E
CO2 Sensor 0-2000	Χ	Χ	Χ	X	X	X	X	Χ	-	-	-	-	-	-	-	-
ppm range																
CO2 Sensor 0-5000	-	-	-	-	-	-	-	-	Χ	Χ	Χ	Χ	Χ	Χ	Χ	Χ
ppm range																
Humidity Sensor	Χ	Χ	-	-	-		-		Χ	Χ	-	-	-	-	-	-
Temperature Sensor	Χ	-	Χ	Χ	Χ	X	-	-	Χ	-	Χ	Χ	Χ	Χ	-	-
Day/Night Sensor	Χ	Χ	Χ	-	-	Х	X	X	X	X	Χ	-	-	Χ	Χ	Χ
Battery Autonomy	Χ	Χ	Χ	Χ	-	-	-	X	Χ	Χ	Χ	Χ	-	-	-	Χ

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Nig	ht and Autonomy
TYPE	00	Type 0x00	

Submitter: NanoSense

The manufacturer will indicate emission rates versus battery autonomy and day night status.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	8	CO2		Concentration (linear), 1 LSB = 7.84 ppm Or Concentration (linear), 1 LSB = 19.6 ppm	0255	02000 (or 5000)	ppm
8	8	Humidity	HUM	Rel. Humidity (linear), 1 LSB = 0.5 %	0200	0100	%
16	8	Temperature	TMP	Temperature (linear), 1 LSB = 0.2 °C	0255	0+51	°C
24	1	Day/Night	DN		Enum: 0: Day 1: Night		
25		Battery autonomy	ВА	Battery autonomy	1: 87.5 - 6 2: 75 - 6 3: 62.5 -	87.5 % - 75 % 52.5 % - 50 % 37.5 %	<u>}</u>

	5: 37.5 - 25 %
	6: 25 - 12.5 %
	7: 12.5 - 0 %
28 4 Not Used (= 0)	

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	01	Type 0x01 (description: see table)
TYPE	01	7

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	02	Type 0x02 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	03	Type 0x03 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	04	Type 0x04 (description: see table)

See profile: D2-04-00

				٨
RORG	D2	VLD Telegram		,
FUNC	04	CO2, Humidity, Temperature, Day/Night and Au	ıtonomy	
TYPE	05	Type 0x05 (description: see table)		

See profile: D2-04-00

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonom	
TYPE	06	Type 0x06 (description: see table)	

See profile: D2-04-00

RORG	D2	VLD Telegram	
FUNC _	04	CO2, Humidity, Temperature, Day/Night and Autonomy	
TYPĖ	07	Type 0x07 (description: see table)	

See profile: D2-04-00

RORG	D2	VLD Telegram	
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy	
TYPE	08	Type 0x08 (description: see table)	

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	09	Type 0x09 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	10	Type 0x10 (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1A	Type 0x1A (description: see table)

See profile: D2-04-00

RORG D2 VLD Telegram			
FUNC 04 CO2, Humidity, Temperature, Day/Night and Auto		CO2, Humidity, Temperature, Day/Night and Autonom	
TYPE	1B	Type 0x1B (description: see table)	

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1C	Type 0x1C (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1D	Type 0x1D (description: see table)

See profile: D2-04-00

RORG	D2	VLD Telegram
FUNC	04	CO2, Humidity, Temperature, Day/Night and Autonomy
TYPE	1E	Type 0x1E (description: see table)

See profile: D2-04-00

D2-05: Blinds Control for Position and Angle

Submitter: AWAG Elektrotechnik AG

Description

The protocol is intended for commissioning as well as for operation of a single channel blind actuator that supports control of the vertical position as well as the rotation angle of the slats.

Data exchange

Direction: bidirectional

Addressing: unicast (ADT) & broadcast

Communication trigger: event-triggered or upon query Communication interval: heartbeat (off or 30 s or 3 min)

Trigger event:

a) status change (alarm, blockage, deblockage)

b) position change > 10 % of range c) end position reached (0% or 100%)

d) heartbeat

Tx delay: n/a Rx timeout: n/a

Teach-in

Teach-in method: Universal teach-in

Security

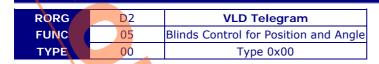
Encryption supported: no Security level format: n/a

EEP Family Table

Each TYPE has to support all telegrams and parameters marked in its column.

Telegram	Type 0x00
No. of output channels	1
Go to Position and Angle	X
Stop	X
Query Position and Angle	X
Reply Position and Angle	Χ
Set parameters	X

Parameter	Type 0x00
Vertical position	X
Rotation angle	Х
Repositioning	Х
Blockage mode	Х
Alarm mode	Х
Set vertical, 5 sec 5 min	Х
Set rotation, 0 2.54 sec	Х
Set Alarm Action	Х



Submitter: AWAG Elektrotechnik AG

CMD 1 - Go to Position and Angle

Once the actuator is configured either by the "Set Parameters" command or through manual configuration (using local buttons) the position of the blinds can be controlled with this command.

When the actuator is set to "blockage" mode, neither local nor central positioning and configuration commands will be executed. This mode is intended for putting the device temporarily out of service, e.g. for a maintenance operation. When the actuator is set to the "alarm" mode neither local nor central positioning and configuration commands will be executed. Before entering the "alarm" mode, the actuator will execute the "alarm action" as configured by the "Set parameter" command.

When this command is sent with the "deblockage" option, the actuator terminates the "alarm" or "blockage" mode and enters the normal mode.

Exemplary illustration of data bytes 0 ... 3:

Command ID 01 (CMD)

	DB_3			DB_3					1		DE	_2							DB	_1							DB	_0				
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🗲 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
·					POS	5							ANG					R	(EP	С		L	oc	K		CH	HN.			CM	1D	

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0)				
1	7	Position	POS	Vertical position	Enum:		
					0. 100.	0 1	00.0/
					0100:	01	00 %
					127: Do not change		
8	1	Not Used (= 0)				
9	7	Angle	ANG	Rotation angle	Enum:		
					0100:	01	00 %
					127: Do not change		
16	1	Not Used (= 0)		analige		
17		Repositioning		How to adjust the internal positioning	Enum:		
				tracker before going to the new position	0: Go directly	to POS/AN	IG
					1: Go up (0%) POS/ANG	, then to	
					2: Go down (1 POS/ANG	00%), the	en to
					3 Reserved 7:		
20	1	Not Used (= 0)				
21		Locking	LOCK	Set/reset locking modes	Enum:		
		modes			0: Do not cha	nge	
					1: Set blocka	ge mode	
					2: Set alarm	mode	

					3 6: Reserved
•					7: Deblockage
24	4	Channel	CHN	Channel address	Enum:
					0: Channel 1
28	4	Command ID	CMD	Command identifier	Enum:
					1: Goto command

CMD 2 - Stop

This command immediately stops a running blind motor. It has no effect when the actuator is in "blockage" or "alarm" mode, i.e. it will not stop an eventual "go up" or "go down" alarm action.

Offset	Size	Data	Sho	rtCut	Description	Valid Range	Scale Unit
0	4	Channel	CHN		Channel address	Enum:	
						0: Channe	el 1
4	4	Command ID	CMD		Command identifier	Enum:	
			1			2: Stop co	ommand

CMD 3 - Query Position and Angle

This command requests the actuator to return a "reply" command.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Channel	CHN	Channel address	Enum:
					0: Channel 1
4	4	Command ID	CMD	Command identifier	Enum:
					3: Query command

CMD 4 - Reply Position and Angle

Either upon request ("Query" command) or after an internal trigger (see EEP Properties) the actuator sends this command to inform about its current state.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0))				
1	7	Position	POS	Current vertical position	0100: 127: Position unknown, known after the next goto	will be	0100 %
8	1	Not Used (= 0))				
9	7	Angle	ANG	Current rotation angle	Enum: 0100: 127: Angle unknown, wil after the next goto	I be known	.100
16	5	Not Used (= 0))				
21		Locking modes	LOCK	Current locking mode	Enum: 0: Normal (no lock) 1: Blockage mode 2: Alarm mode 3 7: Reserved		
24	4	Channel	CHN	Channel address	Enum: 0: Channel 1		

28	4 Command ID	CMD	Command identifier	Enum:
				4: Reply command

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CMD 5 - Set parameters

This command sets one or multiple configuration parameters of the actuator. When a parameter value is set to "-> no change" this parameter will not be modified. The VERT and ROT parameters describe the duration needed by the motor for a full run of the blind, or for a complete turn of the slats, respectively. They have to be measured on site and assigned to the actuator.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (=	0)				
1	15	Set vertical	VERT	Measured duration of a vertical run	Enum: 50030000: 0 499: Reserved 32767 -> No (0x7FFF): change	500030	00000 ms
16		Set rotation		Measured duration of rotation	Enum: 1254: 0: No rotation 255: -> No change	102540	ms
24	5	Not Used (=	0)				
29	_	Set alarm action	AA	Besides locking all other commands entering the alarm mode results in	Enum: 0: No action 1: Immediate stop 2: Go up (0%) 3: Go down (100%) 4 6: Reserved 7: -> No change)	
32	4	Channel	CHN	Channel address	Enum: 0: Channel 1		
36		Command ID	CMD	Command identifier	Enum: 5: Set parameters con	mmand	

D2-10: Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program

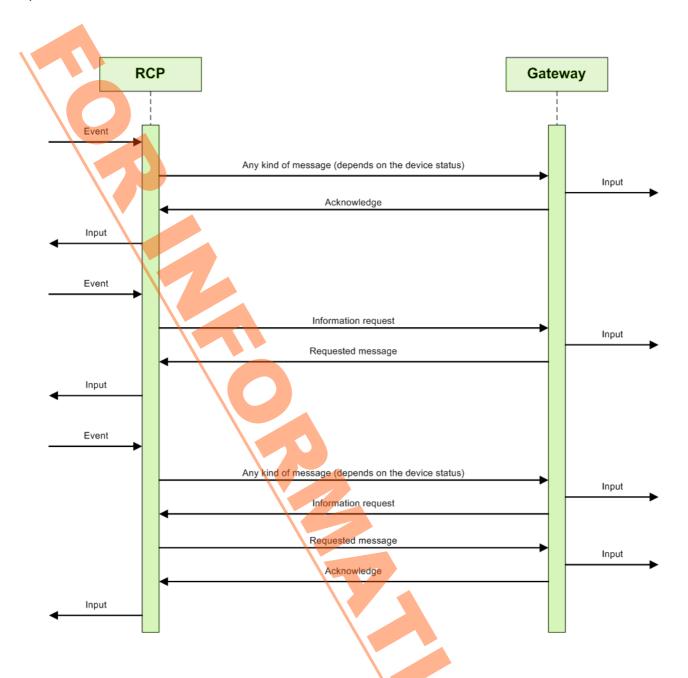
Submitter: Kieback&Peter GmbH & CO KG

Description

This VLD family consists of several profiles for a group of different room control panels with various functions and measurements (see following table of parameters for a feature list).

The profiles are designed to establish a communication between a battery-powered room control panel and a line-powered (and therefor always receiving) gateway. It also allows a gateway-to-gateway communication.

Due to the high energy consumption while powering the receiver, the room control panel will always be the initiator of a data exchange. It cannot be triggered by the gateway as it is not in a receiving mode most of the time.



Data exchange

Direction: bidirectional

Addressing: unicast (ADT) & broadcast

Communication trigger: event- & time-triggered Communication interval: can be defined during runtime

Trigger event: device status change

Tx delay: 1 s Rx timeout: N/A

Teach-in

Teach-in method: UTE

 $\frac{\underline{\mathsf{Security}}}{\mathsf{Encryption}} \ \mathsf{required:} \ \mathsf{no}$ Security level format: -

EEP Family Table:

Type 00	Type 01	Type 02
Χ	Χ	Χ
Χ	Χ	Χ
Χ	Χ	Χ
Χ	Χ	Χ
Χ	Χ	-
	X X	Type 00 Type 01 X X X X X X X X X X X X

Type 00 Type 01 Type 02 **Parameter**

Managa Idantifian	V	lv	lv
Message Identifier	X	X	X
Message Continuation Flag	X	X	X
Information Request Classifier	X	X	X
Feedback Classifier			
General Message Type	X	X	X
Humidity	X	-	-
Humidity Validity Flag	X	_	-
Fan Speed Control	X	-	-
Fan Speed Validity Flag	X	-	-
Fan Speed Mode	X	-	-
Custom Warning 2	X	X	X
Custom Warning 1	X	X	X
Mold Warning	X	-	-
Window Open Detection	X	X	X
Battery Status	X	Х	X
Solar-power Status	X	-	X
PIR Status	X	-	X
Occupancy Button Status	X	Х	Х
Cooling Operation Status	X	-	-
Heating Operation Status	X	-	-
Room Control Mode	Х	Х	Х
Temperature Set Point Validity	X	Х	Х
Temperature Validity	Х	X	X
Temperature Set Point	X	X	X
Room Temperature	X	X	X
PIR Status Lock	X	-	X
Temperature Scale Lock	X	X	-
Display Content Lock	X	X	X
Date / Time Lock	X	X	Χ
Time Program Lock	X	X	X
Occupancy Button Lock	X	X	X
Temperature Set Point Lock	X	X	-
Fan Speed Lock	X	-	-
Radio Communication Interval	Х	X	Χ
Key Lock	Х	X	
Display Content	X	X	X
Temperature Scale	X	X	X
Daylight Saving Time Flag	Х	X	Х
Time Notation	Х	X	X
Day	Х	X	X
Month	Х	X	X
Year	Х	X	X
Minute	Х	X	X
Hour	Х	X	X
Date / Time Update Flag	Х	X	X
Temperature Set Point Building Protection Mode	Х	X	-
Temperature Set Point Pre-comfort Mode	Х	-	-
Temperature Set Point Economy Mode	Х	Χ	X
Temperature Set Point Comfort Mode	Χ	X	Χ
Temperature Set Point Flag Building Protection Mode		X	-
Temperature Set Point Flag Pre-comfort Mode	X	-	-
Temperature Set Point Flag Economy Mode	Х	Χ	Χ
Temperature Set Point Flag Comfort Mode	Χ	Χ	Х
End Time: Minute	Χ	Χ	-
End Time: Hour	Χ	Χ	-
Start Time: Minute	Χ	Χ	-
Start Time: Hour	Χ	Χ	-
Period	Χ	Χ	-
Time Program Deletion	Χ	X	-

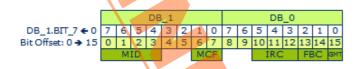
RORG D2 VLD Telegram

FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	00	Type 0x00

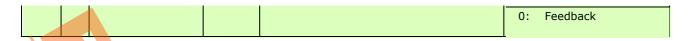
Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Size	Data	ShortCut	Description	Valid	Range Scale Unit	
0	3		MID	Defines the type of message	Enum		
					0:	General Message	
3	3	Not Used (= 0)					
6	2		MCF	Indicates if another telegram has to be	Enum	:	
		continuation flag		expected or if the message is complete	3:	Reserved	
					2:	Automatic message control	
					1:	Incomplete	
					0:	Complete	
8	2	Not Used (= 0)					
10	3	Information request	IRC	Defines the type of information request	Enum		
		classifier			7:	Reserved	
					6:	Reserved	
					5:	Reserved	
					4:	Time program request	
					3:	Room control setup request	
					2:	Configuration request	
					1:	Data request	
					0:	Acknowledge request	
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum		
				,,	_	Reserved	
					2:	Message repetition request	
						1:	Telegram repetition request
					0:	Acknowledge / heartbeat	
15	1	General message	GMT	Indicates if the general message is a	Enum		
		type		feedback or an information request	1:	Information request	



Data Message

Offse	t Size		ShortCut	Description	Valid Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum:
					1: Data Message
3	3	Not Used (= 0)			
6	2	Message	MCF	Indicates if another telegram has to be	Enum:
		continuation flag		expected or if the message is complete	3: Reserved
					2: Automatic message
					control
					1: Incomplete
					0: Complete
					o. Complete
8	8	Humidity	HUM	Measured humidity	0255 0100 %
16	1	Humidity validity	HVF	Indicates if the value for humidity is valid	Enum:
10	1	flag	1101	indicates if the value for fluminity is valid	1: Valid value
					0: No change
17	7	Fan speed control	FS	Fan speed	0100 0100 %
1 <i>7</i> 24	1	Fan speed control	FSV	Indicates if the fan speed value is valid	l l
24	1	flag	130	Thurcates if the fall speed value is valid	Enum: 1: Valid value
		nag			
2.5	1	F	ECM	Define the mode the Constitution	0: No change
25	1	Fan speed mode	FSM	Defines the mode the fan runs in	Enum:
					1: Individual fan speed control
					0: Central fan speed
					control
26	1	Not Used (= 0)			Control
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum:
_,	_		02	riag for an application operation training	1: True
					0: False
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum:
	_		0.1.2	riag for an application operation and in	1: True
					0: False
29	1	Mold warning	MW	Flag for an application depending mold	Enum:
23	1	Piola Warning	1.144	warning	1: True
					0: False
20	2	Window onen	WOD	Indicates if an open window is detected	
30	2	Window open detection	WOD	Indicates if an open window is detected	Enum:
		d CCCCCIOII			3: Reserved
					2: Open
					1: Closed
22	1	Not Head (O)			0: No change
32	1	Not Used (= 0)	DC.	Dotton, status	I - Land
33	2	Battery status	BS	Battery status	Enum:
					3: Critical
					2: Low
					1: Good
25			CDC	To Book of the character of the characte	0: No change
35	1	Solar-powered status	SPS	Indicates if the device is powered by its solar cell	Enum:
		Status		Solut Cell	1: Not solar-powered
					0: Solar-powered
36	2	PIR status	PIR	Indicates if the PIR detected a movement	Enum:
					3: Locked
					2 11
					2: Movement detected

		•						
					1:	No mo	vement ed	
					0:	No cha	nge	
38	2	Occupancy button	OBS	Indicates if the occupancy button was	Enum:			
30		status	OBS	pressed and its occupancy status	3:	Reserv	od	
				process and its secupation status	3.	Reserv	eu	
	- / / 7				2:	Button	pressed a	and
	1					unoccu		
					1:	Button	pressed a	and
						occupie	ed	
					0:	No cha	nge	
40	2	Cooling	coo	Recent cooling operation status	Enum:			
					3:	Autom	atic	
					2:	Off		
					1:	On		
					0:	No cha	nge	
42	2	Heating	HEA	Recent heating operation status	Enum:			
					3:	Autom	atic	
		\			2:	Off		
					1:	On		
					0:	No cha	nge	
44	2	Room control mode	RCM	Recent room control mode	Enum:			
					3:	Buildin	g protecti	on
			\		2:	Pre-coi	mfort	
			•		1:	Econor	ny	
					0:	Comfo	rt	
46	1		SPV	Indicates if the temperature set point	Enum:			
		point validity		value is valid	1:	Valid v		
					0:	No cha	nge	
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum:			
					1:	Valid v	alue	
					0:	No cha		
48	8	Temperature set point	TSP	Recent temperature set point	0255		0+40	°C
56	8	Temperature	TMP	Recent room temperature	0255	5	0+40	°C

Configuration Message

Offset	Size	Data	ShortCut	Description	Valid Range Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum: 2: Configuration Message	
3	3	Not Used (= 0)				
6		Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Reserved 2: Automatic mess control 1: Incomplete 0: Complete	sage
8	1	PIR status lock	PSL	Indicates if the PIR status is transmitted or kept inside the room control panel	Enum: 1: Unlocked 0: Locked	
9	1	Temperature scale lock	TSL	Indicates if the temperature scale can be changed at the room control panel	Enum: 1: Unlocked	

10		B' de control les	D.C.I	To disclose if the alice by a second color of the	0: Locked
10	1	Display content lock	DCL	Indicates if the display content can be changed at the room control panel	Enum:
				Changed at the room control panel	1: Unlocked
					0: Locked
11	1	Date / time lock	DTL	Indicates if date and time can be changed	Enum:
				at the room control panel	1: Unlocked
					0: Locked
12	1	Time program lock	TPL	Indicates if the time program can be	Enum:
				changed at the room control panel	1: Unlocked
					0: Locked
13	1	Occupancy button	OBL	Indicates if the occupancy status can be	Enum:
		lock		changed at the room control panel	1: Unlocked
					0: Locked
14	1	Temperature set	SPL	Indicates if the temperature set point can	Enum:
		point lock		be changed at the room control panel	1: Unlocked
					0: Locked
15	1	Fan speed lock	FSL	Indicates if the fan speed can be changed	Enum:
				at the room control panel	1: Unlocked
					0: Locked
16	6	Radio	RCI	Defines the longest time between two	Enum:
		communication		consecutive telegrams (clock-based	63: 24 hours
		interval		communication)	03. 24 Hours
			1		62: 12 hours
			\		61: 3 hours
			`		
					160 min
					160:
					0: No communication
					interval
22	1	Key lock	KL	Indicates if all buttons on the device are locked	Enum:
				locked	1: Unlocked
					0: Locked
23	1	Not Used (= 0)			
24	3	II lichlay contont			_
		Display content	DC	Defines the main display content	Enum:
		Display content	DC	Defines the main display content	Enum: 7: Humidity
		Display Content	DC	Defines the main display content	7: Humidity
		Display Content	DC	Defines the main display content	
		Display Concent	DC	Defines the main display content	7: Humidity 6: Display off
		Display Concent	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set
		Display Content	DC	Defines the main display content	7: Humidity 6: Display off
		Display Concent	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point
		Display Concent	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature
		Display Concent	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external)
		Display Concent	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature
		Display Content	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time
		Display Content	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal)
		Display Content	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default
		Display Content	DC	Defines the main display content	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time
27					7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change
27	2	Temperature scale	TS	Defines the main display content Defines the used temperature scale for the room control panel display and menus	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change
27				Defines the used temperature scale for the	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit
27				Defines the used temperature scale for the	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius
27				Defines the used temperature scale for the	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default
	2	Temperature scale	TS	Defines the used temperature scale for the room control panel display and menus	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change
27		Temperature scale Daylight saving		Defines the used temperature scale for the room control panel display and menus Indicates if daylight saving time is	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum:
	2	Temperature scale	TS	Defines the used temperature scale for the room control panel display and menus	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported
29	2	Temperature scale Daylight saving time flag	TS DST	Defines the used temperature scale for the room control panel display and menus Indicates if daylight saving time is supported	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported
	2	Temperature scale Daylight saving	TS	Defines the used temperature scale for the room control panel display and menus Indicates if daylight saving time is	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum:
29	2	Temperature scale Daylight saving time flag	TS DST	Defines the used temperature scale for the room control panel display and menus Indicates if daylight saving time is supported	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h
29	2	Temperature scale Daylight saving time flag	TS DST	Defines the used temperature scale for the room control panel display and menus Indicates if daylight saving time is supported	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 3: ° Fahrenheit 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h 2: 24 h
29	2	Temperature scale Daylight saving time flag	TS DST	Defines the used temperature scale for the room control panel display and menus Indicates if daylight saving time is supported	7: Humidity 6: Display off 5: Temperature set point 4: Room temperature (external) 3: Room temperature (internal) 2: Time 1: Default 0: No change Enum: 2: ° Celsius 1: Default 0: No change Enum: 1: Not supported 0: Supported Enum: 3: 12 h

					0: No	change	
32	5	Day	DAY	Date format: YYYY/MM/DD	131	131	day
37	4	Month	MON	Date format: YYYY/MM/DD	112	112	mon
41	7	Year		Date format: YYYY/MM/DD year = 2000 + x	0127	20002127	year
48	6	Minute	MIN	Time format: hh:mm	059	059	min
54	2	Not Used (= 0)	•				
56	5	Hour	HR	Time format: hh:mm	023	023	h
61	2	Not Used (= 0)					
63	1	Date / time update flag	DTU	Indicates if an update of date or time is provided	Enum: 1: Upo 0: No	late update	

Room Control Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum: 3: Roon Setu	n Control	
6	2	Not Used (= 0) Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	mess	matic sage contr	rol
8	8	Temperature set point building protection mode	SPB	Temperature set point building protection mode	0255	0+40	°C
16	8	Temperature set point pre-comfort mode	SPP	Temperature set point pre-comfort mode	0255	0+40	°C
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C
40	4	Not Used (= 0)	•		•		
44	1	Temperature set point flag building protection mode	SFB	Indicates if a temperature set point for the building protection mode is provided	1: Valid	value nange	
45	1	Temperature set point flag pre-comfort mode	SFP	Indicates if a temperature set point for the pre-comfort mode is provided	1: Valid	value nange	
46	1	Temperature set point flag economy mode	SFE	Indicates if a temperature set point for the economy mode is provided	1: Valid	value nange	-
47	1	Temperature set point flag comfort mode	SFC	Indicates if a temperature set point for the comfort mode is provided	1: Valid	value nange	

Time Program Setup

Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit

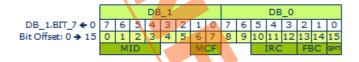
0	3	Message identifier	MID	Defines the type of message	Enum	
U	3	Message identifier	MID	Defines the type of message	Enum: 4: Time Program	
1					Setup	
3	3	Not Used (= 0)				
6	2	Message	MCF	Indicates if another telegram has to be	Enum:	
	V	contin <mark>uat</mark> ion flag		expected or if the message is complete	3: Reserved	
	/				2: Automatic message control	
					1: Incomplete	
					0: Complete	
8	2	Not Used (= 0)				
10	6	End time: Minute	ETM	Time format: hh:mm	059 059 1	
16	3	Not Used (= 0)				
19	5	End time: Hour	ETH	Time format: hh:mm	023 023 1	
24	2	Not Used (= 0)				
26	6	Start time: Minute	STM	Time format: hh:mm	059 059 1	
32	3	Not Used (= 0)				
35	5	Start time: Hour	STH	Time format: hh:mm	023 023 1	
40	4	Period	PER	Assigned period of time (weekdays) for the	Enum:	
		provided schedule time	15: Friday - Monday			
					14: Friday - Sunday	
		·		13: Thursday - Friday		
					12: Wednesday - Friday	
					11: Tuesday - Thursday	
					10: Monday - Wednesday	
					9: Sunday	
					8: Saturday	
					7: Friday	
					6: Thursday	
					5: Wednesday	
					4: Tuesday	
					3: Monday	
					2: Saturday - Sunday	
					1: Monday - Friday	
					0: Monday - Sunday	
44	2	Room control	RCM	Assigned room control mode for the provided	Enum:	
		mode		schedule time	3: Building protection	
					2: Pre-comfort	
					1: Economy	
					0: Comfort	
46	1	Not Used (= 0)				
47	1	Time program	TPD	Deletes the stored time program	Enum:	
		deletion		. 3	1: Deletion	
					0: No deletion	

RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	01	Type 0x01

Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Size	Data	ShortCut	Description	Valid	Range Scale Unit
0	3		MID	Defines the type of message	Enum	
			\		0:	General Message
3	3	Not Used (= 0)				
6	2		MCF	Indicates if another telegram has to be	Enum	:
		continuation flag		expected or if the message is complete	3:	Reserved
					2:	Automatic message control
					1:	Incomplete
					0:	Complete
8		Not Used (= 0)				
10	3	Information request	IRC	Defines the type of information request	Enum	:
		classifier			7:	Reserved
					6:	Reserved
					5:	Reserved
					4:	Time program request
					3:	Room control setup request
					2:	Configuration request
					1:	Data request
					0:	Acknowledge request
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum	
					3:	Reserved
					2:	Message repetition request
					1:	Telegram repetition request
					0:	Acknowledge / heartbeat

1. Information	15	1	1 General message (GMT Indicates if the general message is a	Enum:
0: Feedback			type	feedback or an information request	request

Data Message

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
		Message identifier	MID	Defines the type of message	Enum:
					1: Data Message
3	3	Not Used (= 0)			
6		Message	MCF	Indicates if another telegram has to be	Enum:
		continuation flag		expected or if the message is complete	3: Reserved
					2: Automatic message control
					1: Incomplete
					0: Complete
8	8	Not Used (= 0)			
16	1	Not Used (= 0)			
	7	Not Used (= 0)			
		Not Used (= 0)			
		Not Used (= 0)			
		Not Used (= 0)			
27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum:
					1: True
					0: False
28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum:
					1: True
					0: False
		Not Used (= 0)		,	
30		Window open	WOD	Indicates if an open window is detected	Enum:
		detection			3: Reserved
					2: Open
					1: Closed
					0: No change
		Not Used (= 0)			In .
33	2	Battery status	BS	Battery status	Enum:
					3: Critical
					2: Low
					1: Good
					0: No change
		Not Used (= 0)			
		Not Used (= 0)	OBC	To disease if the	
38		Occupancy button status	OBS	Indicates if the occupancy button was pressed and its occupancy status	Enum:
		status		pressed and its occupancy status	3: Reserved
					2: Button pressed and unoccupied
					1: Button pressed and
					occupied 0: No change
40		Not Used (= 0)			
42	2	Not Used $(= 0)$			

44	2	Room control mode	RCM	Recent room control mode	Enum:			
	1				3: Building protection 2: Pre-comfort 1: Economy		on	
					0: Comfo	rt		
46	1	Temperature set	SPV	Indicates if the temperature set point	Enum:			
	point validity value is valid		value is valid	1: Valid value				
					0: No change			
47	1	Temperature validity	TPV	Indicates if the temperature value is valid	Enum:			
					1: Valid v	alue		
					0: No change			
48	8	Temperature set	TSP	Recent temperature set point	0255	0+40	°C	
		point						
56	8	Temperature	TMP	Recent room temperature	0255	0+40	°C	

Configuration Message

					Valid		
Offset	Size	Data	ShortCut	Description	Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum:		
					2: Con	figuration	
					Mes	sage	
3	3	Not Used (= 0)			ı		
6			MCF	Indicates if another telegram has to be	Enum:		
		continuation flag		expected or if the message is complete	3: Res	erved	
					2: Auto	omatic messa trol	ige
					1: Inco	omplete	
					0: Con	nplete	
8	1	Not Used (= 0)					
9		Temperature scale	TSL	Indicates if the temperature scale can be	Enum:		
		lock		changed at the room control panel	1: Unlo	ocked	
					0: Lock	ked	
10	1	Display content lock	DCL	Indicates if the display content can be	Enum:		
				changed at the room control panel	1: Unlo	ocked	
					0: Lock	ked	
11	1	Date / time lock	DTL	Indicates if date and time can be changed	Enum:		
				at the room control panel	1: Unlo	ocked	
					0: Lock	ked	
12	1	Time program lock	TPL	Indicates if the time program can be	Enum:		
				changed at the room control panel	1: Unio	ocked	
					0: Locl	ked	
13		Occupancy button	OBL	Indicates if the occupancy status can be	Enum:		
		lock		changed at the room control panel		ocked	
					0: Lock	ked	
14		·	SPL	Indicates if the temperature set point can	Enum:		
		point lock		be changed at the room control panel	1: Unlo	ocked	
					0: Locl	ked	
15		Not Used (= 0)					
16	_		RCI	Defines the longest time between two	Enum:		
		communication interval		consecutive telegrams (clock-based communication)	63: 24	hours	
					62: 12	hours	
					61: 3 h	nours	

					160:				
					0:	No commu	nicatio	n	
22	1	Key lock	KL	Indicates if all buttons on the device are	Enum:				
				locked	1:	Unlocked	_		
					0:	Locked			
23	1	Not Used (= 0)	1						
24	3	Display content	DC	Defines the main display content	Enum:				
						Humidity			
					6: Display off				
						Temperature point			
						Room tempe (external)			
						Room tempe (internal)	eratur	е	
						Time			
					1:	Default			
					0:	No change			
27	2	Temperature scale	TS	Defines the used temperature scale for the	Enum:				
			\	room control panel display and menus	3: ° Fahrenheit				
					2: ° Celsius 1: Default				
					-	No change			
29	1	Daylight saving	DST	Indicates if daylight saving time is	Enum:	ivo change	<u></u>		
		time flag		supported	1: Not supported				
					0: Supported				
30	2	Time notation	TN	Defines the used time notation	Enum:				
					3:	12 h			
					-	24 h			
						Default	_		
22	_	1	D 4) /	D 1 6 1 2000/04/1/DD		No change			
32 37	5	Day Month	DAY MON	Date format: YYYY/MM/DD	131	131 112		day	
41	7	Year	YR	Date format: YYYY/MM/DD Date format: YYYY/MM/DD	0127		2127	mon year	
71		- Cui		year = 2000 + x	J12/	20002	.12/	year	
48	6	Minute	MIN	Time format: hh:mm	059	059		min	
54	2	Not Used (= 0)	l						
56	5	Hour	HR	Time format: hh:mm	023	023		h	
61	2	Not Used (= 0)							
63	1	Date / time update	DTU	Indicates if an update of date or time is	Enum:				
		flag		provided		1: Update			
					0:	No update			

Room Control Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum: 3: Room Setur	Control	
3	3	Not Used (= 0)					
6	2	Message continuation flag		Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Reser	rved	

					1: Inco	matic sage conti mplete plete	rol
8	8	Temperature set point building protection mode	SPB	Temperature set point building protection mode	0255	0+40	°C
16	8	Not Used (= 0)					
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C
40	4	Not Used (= 0)					
44	1	Temperature set point flag building protection mode	SFB	Indicates if a temperature set point for the building protection mode is provided	1: Valid	l value hange	-
45	1	Not Used (= 0)					
46	1	Temperature set point flag economy mode	SFE	Indicates if a temperature set point for the economy mode is provided	1: Valid	l value hange	-
47	1	Temperature set point flag comfort mode	SFC	Indicates if a temperature set point for the comfort mode is provided	1: Valid	l value hange	-

Time Program Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit		
0	3	Message identifier	MID	Defines the type of message	Enum:			
					4: Time Pr	rogram		
					Setup			
3		Not Used (= 0)						
6		Message	MCF	Indicates if another telegram has to be	Enum:			
		continuation flag		expected or if the message is complete	3: Reserve	ed		
					2: Automatic message control			
					1: Incomp	lete		
					0: Comple	te		
8	2	Not Used (= 0)						
10	6	End time: Minute	ETM	Time format: hh:mm	059	059 1		
16	3	Not Used (= 0)						
19	5	End time: Hour	ETH	Time format: hh:mm	023	023 1		
24	2	Not Used (= 0)						
26	6	Start time: Minute	STM	Time format: hh:mm	059	059 1		
32	3	Not Used (= 0)						
35	5	Start time: Hour	STH	Time format: hh:mm	023	023 1		
40	4	Period	PER	Assigned period of time (weekdays) for the	Enum:			
				provided schedule time	15: Friday -	- Monday		
					14: Friday -	- Sunday		
					13: Thursda	ay - Friday		
					12: Wednes Friday	sday -		
					11: Tuesda Thursda			

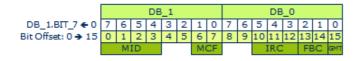
	_					
					10:	Monday - Wednesday
					9:	Sunday
					8:	Saturday
	//				7:	Friday
	\				6:	Thursday
					5:	Wednesday
					4:	Tuesday
					3:	Monday
					2:	Saturday - Sunday
					1:	Monday - Friday
					0:	Monday - Sunday
44	2	Room control	RCM	Assigned room control mode for the provided	Enum	
		mode		schedule time	3:	Building protection
					2:	Pre-comfort
					1:	Economy
					0:	Comfort
46	1	Not Used (= 0)				
47	1	Time program			Enum	
		deletion				Deletion
				0:	No deletion	

RORG	D2	VLD Telegram
FUNC	10	Room Control Panels with Temperature & Fan Speed Control, Room Status Information and Time Program
TYPE	02	Type 0x02

Submitter: Kieback&Peter GmbH & CO KG

General Message

exemplary illustration of data bytes 0/1:



Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	3	Message identifier	MID	Defines the type of message	Enum:	Massaga	
					0: General	Message	<u>:</u>
3	3	Not Used (= 0)					
6		Message continuation flag		Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Reserved	1	
					J. Reserved		

1						
					2:	Automatic message control
	1				1:	Incomplete
					0:	Complete
8	2	Not Used (= 0)			•	
10	3	Information request	IRC	Defines the type of information request	Enum	:
	classifier	classifier			7:	Reserved
						Reserved
					5:	Reserved
					4:	Time program request
					3:	Room control setup request
					2:	Configuration request
			1:	Data request		
					0:	Acknowledge request
13	2	Feedback classifier	FBC	Defines the type of feedback	Enum	
					3:	Reserved
					2:	Message repetition request
					1:	Telegram repetition request
					0:	Acknowledge / heartbeat
15	1	General message		Indicates if the general message is a	Enum	
		type		feedback or an information request	1:	Information request
						Feedback

Data Message

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	3	Message identifier	MID	Defines the type of message	Enum:
					1: Data Message
3	3	Not Used (= 0)			
6	2	Message	MCF	Indicates if another telegram has to be	Enum:
		continuation flag		expected or if the message is complete	3: Reserved
					2: Automatic message
					control
					1: Incomplete
					0: Complete
					0: Complete
8	8	Not Used (= 0)			
16	1	Not Used (= 0)			
17	7	Not Used (= 0)			
24	1	Not Used (= 0)			
25	1	Not Used (= 0)			
26	1	Not Used (= 0)			
		-			

True Custom warning 1 CW1 Flag for an application specific warning Enum: 1: True O: False	27	1	Custom warning 2	CW2	Flag for an application specific warning	Enum: 1: True 0: False
Solar-powered SPS Indicates if the device is powered by its status Solar-powered	28	1	Custom warning 1	CW1	Flag for an application specific warning	Enum: 1: True
Seserved 2: Open 1: Closed 0: No change	29	1	Not Used (= 0)			
22 Open 12 Closed 13 Critical 22 Low 13 Critical 22 Low 14 Closed 15 Closed 15 Closed 16 Closed 16 Closed 17 Closed 17 Closed 18 Closed 19	30	2		WOD	Indicates if an open window is detected	Enum:
1: Closed 0: No change			detection			3: Reserved
32						2: Open
32 1 Not Used (= 0)						1: Closed
Battery status BS Battery status Enum: 3: Critical 2: Low 1: Good 0: No change Enum: 1: Not solar-powered SPS Indicates if the device is powered by its solar cell 1: Not solar-powered 1: Not solar-powered 1: Not solar-powered 2: Movement detected 2: Button pressed and its occupancy status 3: Reserved 2: Button pressed and its occupancy status 3: Reserved 3: Reserved 3: Reserved 3: Button pressed and its occupancy status 3: Reserved 3: Button pressed and occupied 3: Button pressed and occu			V			0: No change
3: Critical 2: Low 1: Good 0: No change	32	1	Not Used (= 0)			
SPS Indicates if the device is powered by its solar-powered status SPS Indicates if the device is powered by its solar-powered SPS Indicates if the PIR detected a movement Solar-powered Sola	33	2	Battery status	BS	Battery status	Enum:
1: Good 0: No change						3: Critical
Solar-powered status SPS Indicates if the device is powered by its solar cell SPS Indicates if the device is powered by its solar cell SPS Solar cell						2: Low
Solar-powered status SPS Indicates if the device is powered by its solar cell 1: Not solar-powered 0: Solar-powered 0: Solar-powered 1: Not solar-						1: Good
Status Solar cell						0: No change
Solar cell 1: Not solar-powered 0: No change	35	1	Solar-powered	SPS	Indicates if the device is powered by its	Enum:
O: Solar-powered			status		solar cell	1: Not solar-powered
PIR status PIR Indicates if the PIR detected a movement Enum: 3: Locked						
3: Locked 2: Movement detected 1: No movement detected 0: No change 38	36	2	PIR status	PIR	Indicates if the PIR detected a movement	
1: No movement detected 0: No change		_				
According to the control mode Company Company						2: Movement detected
38 2 Occupancy button status Description Description						
status pressed and its occupancy status 3: Reserved						0: No change
2: Button pressed an unoccupied 1: Button pressed an occupied 0: No change 40 2 Not Used (= 0) 42 2 Not Used (= 0) 44 2 Room control mode RCM Recent room control mode Enum: 3: Building protection 2: Pre-comfort 1: Economy 0: Comfort 46 1 Temperature set point validity Value is valid T: Valid value 0: No change	38	2		OBS		
Unoccupied 1: Button pressed an occupied 0: No change 0: N			status		pressed and its occupancy status	
Occupied O: No change						unoccupied
40 2 Not Used (= 0) 42 2 Not Used (= 0) 44 2 Room control mode RCM Recent room control mode Building protection 2: Pre-comfort 1: Economy 0: Comfort 46 1 Temperature set point validity SPV Indicates if the temperature set point value is valid 1: Valid value 0: No change						occupied
2 Not Used (= 0) RCM Recent room control mode Enum: 3: Building protection 2: Pre-comfort 1: Economy 0: Comfort						0: No change
2 Not Used (= 0) RCM Recent room control mode Enum: 3: Building protection 2: Pre-comfort 1: Economy 0: Comfort	40	2	Not Used (= 0)			
Room control mode RCM Recent room control mode Enum: 3: Building protection 2: Pre-comfort 1: Economy 0: Comfort			` '			
3: Building protection 2: Pre-comfort 1: Economy 0: Comfort 46 1 Temperature set point validity SPV Indicates if the temperature set point value is valid 1: Valid value 0: No change				RCM	Recent room control mode	Enum:
2: Pre-comfort 1: Economy 0: Comfort 46					The state of the s	
1: Economy 0: Comfort 46 1 Temperature set point validity SPV Indicates if the temperature set point value is valid 1: Valid value 0: No change						
46 1 Temperature set point validity SPV Indicates if the temperature set point value is valid 0: Comfort Comfort Enum: 1: Valid value						
1 Temperature set point validity SPV Indicates if the temperature set point value is valid Enum: 1: Valid value 0: No change						I —
point validity value is valid 1: Valid value 0: No change	46	1	Temperature set	SPV	Indicates if the temperature set point	_
0: No change	70	_		J1 V		
			, , , , , , , , , , , , , , , , , , , ,			
147 1 reinperature validity iPV Indicates if the temperature value is valid Enum:	47	1	Tomporative	TD\/	Indicates if the temperature value is a list	
	4/	1	Temperature validity	TPV	indicates if the temperature value is valid	
1: Valid value						
0: No change			_			
point			point			
56 8 Temperature TMP Recent room temperature 0255 0+40	56	8	Temperature	IMP	Recent room temperature	0255 0+40 °C

Configuration Message

Offset Siz	ze Data	ShortCut	Description	Valid Range	Scale	Uni	it
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0	3	Message identifier	MID	Defines the type of message	Enum:
		go lacitation			2: Configuration
					Message
3	3	Not Used (= 0)			_
6	2	Message continuation flag	MCF	Indicates if another telegram has to be expected or if the message is complete	Enum: 3: Reserved
					2: Automatic message control
					1: Incomplete
					0: Complete
8	1	PIR status lock	PSL	Indicates if the PIR status is transmitted or	Enum:
				kept inside the room control panel	1: Unlocked
					0: Locked
9	1	Not Used (= 0)			
10	1	Display content lock	DCL	Indicates if the display content can be	Enum:
				changed at the room control panel	1: Unlocked
					0: Locked
11	1	Date / time lock	DTL	Indicates if date and time can be changed	Enum:
				at the room control panel	1: Unlocked
					0: Locked
12	1	Timo program lock	TDI	Indicator if the time program can be	-
12	1	Time program lock	TPL	Indicates if the time program can be changed at the room control panel	Enum:
			\	enanged at the room control punct	1: Unlocked
					0: Locked
13	1	Occupancy button	OBL	Indicates if the occupancy status can be	Enum:
		lock		changed at the room control panel	1: Unlocked
					0: Locked
14	1	Not Used (= 0)			
15	1	Not Used (= 0)			
16	6	Radio	RCI	Defines the longest time between two	Enum:
		communication interval		consecutive telegrams (clock-based communication)	63: 24 hours
					62: 12 hours
					61: 3 hours
					160 min 160:
					0: No communication interval
22	1	Not Used (= 0)			
23	1	Not Used (= 0)			
24	3	Display content	DC	Defines the main display content	Enum: 7: Humidity
					6: Display off
					5: Temperature set point
					4: Room temperature (external)
					3: Room temperature (internal)
					2: Time
					1: Default
2=		-	T0		0: No change
27	2	Temperature scale	TS	Defines the used temperature scale for the room control panel display and menus	Enum: 3: ° Fahrenheit
					2: ° Celsius

					1: D	efault	
					0: N	o change	
29	1	Daylight saving	DST	Indicates if daylight saving time is	Enum:		
		time flag		supported	1: N	ot supported	
					0: S	upported	
30	2	Time notation	TN	Defines the used time notation	Enum:		
	1/4				3: 1	2 h	
	\				2: 2	1 h	
					1: Default		
					0: N	o change	
32	5	Day	DAY	Date format: YYYY/MM/DD	131	131	day
37	4	Month	MON	Date format: YYYY/MM/DD	112	112	mon
41	7	Year	YR	Date format: YYYY/MM/DD year = 2000 + x	0127	20002127	year
48	6	Minute	MIN	Time format: hh:mm	059	059	min
54	2	Not Used (= 0)					
56	5	Hour	HR	Time format: hh:mm	023	023	h
61	2	Not Used (= 0)					
63			DTU	Indicates if an update of date or time is	Enum:		
		flag		provided	1: Update		
			0: N	o update			

Room Control Setup

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit	
0	3	Message identifier	MID	Defines the type of message	Enum:			
					3: Room Setup	Control		
3	3	Not Used (= 0)						
6		Message continuation	MCF	Indicates if another telegram has to be	Enum:			
		flag		expected or if the message is complete	3: Reser	rved		
					2: Autor mess	natic age contr	ol	
					1: Incon	nplete		
					0: Comp	olete		
8	8	Not Used (= 0)						
16	8	Not Used (= 0)						
24	8	Temperature set point economy mode	SPE	Temperature set point economy mode	0255	0+40	°C	
32	8	Temperature set point comfort mode	SPC	Temperature set point comfort mode	0255	0+40	°C	
40	4	Not Used (= 0)						
44	1	Not Used (= 0)						
45	1	Not Used (= 0)						
46	1	Temperature set point	SFE	Indicates if a temperature set point for	Enum:			
		flag economy mode		the economy mode is provided	1: Valid	value	•	
				`	0: No ch	nange	•	
47	1	Temperature set point	SFC	Indicates if a temperature set point for	Enum:			
		flag comfort mode		the comfort mode is provided		value		
					0: No ch	nange		

D2-20: Fan Control

The EEP family D2-20-xx provides different telegram types for fan control and fan supervision messages using various parameters and variables.

Devices using this EEP family may include a master-slave function (for further description see subheading 'Master-slave function').

EEP Properties:

DATA EXCHANGE
Direction: bidirectional

Addressing: unicast (ADT) + broadcast Communication trigger: event-triggered

Communication interval: N/A Trigger event: query / polling

Tx delay: N/A Rx timeout : N/A

TEACH-IN

Teach-in method: Universal teach-in (UTE)

SECURITY

Encryption supported: no Security level: none

EEP Family Table:

Supported function	Type 00	Type 01	Type 02
Fan Speed	Х	X	X
Fan Speed Status	X	X	X
Humidity	X	-	-
Humidity Control	Χ	-\	
Humidity Control Status	Χ	-	Χ
Humidity Threshold	Χ	- \\	-/
Message Type	Χ	X	X
Operating Mode	Χ	-	-
Operating Mode Status	X	X	-
Room Size	Χ	Χ	X
Room Size Reference	Χ	Χ	X
Room Size Reference Status	X	Χ	X
Room Size Status	Χ	Χ	X
Service Information	Χ	-	-
Temperature Level	X	-	-

Each TYPE has to support every parameter that is marked in its column!

Master-slave function:

A device using this EEP may be able to work as a master or a slave fan. Master fans control slave fans. Slave fans are controlled by master fans. These roles are defined during the teach-in process. A slave fan will always be taught-in to a master. A master fan will accept teach-in requests from slave fans. A fan that is taught-in to another device will from now on work as a slave. A fan that accepted the teach-in of another device will go on working as a master. Combining master fans is not possible. Not every device is able to work as a master and a slave. Certain fans might only be able to be used as slaves.

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	00	Type 0x00

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset Size Data ShortCut Description Valid Range Scale Unit

0	4	Operating Mode	ОМ	Sets the operating mode	Enum: 0: Disabled
					1: Standard compliant Reserved
					214: 15: No change
4	1	Not Used (= 0)			
5	2	Temperature Level	TL	Status of the temperature supervision	Enum:
					0: Too low
		\'			1: Normal
					2: Too high
					3: No change
7	1	Message Type	MT	Defines the message type	Enum:
					0: Fan control
8	2	Humidity Control	НС	Activates the humidity control	Enum:
		\			0: Disabled
					1: Enabled
					2: Default
					3: No change
10	2	Room Size	RSR	Defines if the provided room size has to be	Enum:
		Reference		considered	0: Used
					1: Not used
			`		2: Default
					3: No change
12	4	Room Size	RS	Defines the room size	Enum:
					0: < 25 m ²
					1: 2550 m ²
					2: 5075 m²
					3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
1.6		Library 20	LIT	Cata the house it is the	15: No change
16	8	Humidity Threshold	HT	Sets the humidity threshold	Enum:
		Triconolu			0100: 0100%
					101252: Reserved
					253: Auto 254: Default
					255: No change
24	8	Fan Speed *	FS	Sets the fan speed	
- 	0	an Speed		Sets the fair speed	Enum: 0100: 0100%
					101252: Reserved
					253: Auto
					254: Default
					255: No change
					233. Ho change
ГеІед	ram	Definition : 'Far	Status I	Message'	

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Operating Mode	OMS	Provides the recent operating mode	Enum:
		Status			0: Disabled
					1: Standard
					compliant Reserved
	1/4				214:
	\				15: Not supported
4	3	Service Information	SI	Service information	Enum:
					0: Nothing to report
					1: Air filter error
					2: Hardware error
					36: Reserved
					7: Not supported
7	1	Message Type	MT	Defines the message type	Enum:
					1: Fan status
8	2	Humidity Control	HCS	States if the humidity control is active	Enum:
		Status			0: Disabled
					1: Enabled
					2: Reserved 3: Not supported
10	2	Room Size	RSR	States if the provided room size has to be	• • • • • • • • • • • • • • • • • • • •
10	2	Reference	KSK	considered	Enum: 0: Used
		. 10.0.0.0.00			1: Not used
			\		2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum:
		. Koom oleo olalaa			0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
					4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
					10: 250275 m ²
					11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ² 14: > 350 m ²
					15: Not supported
16	8	Humidity	HUM	Humidity measurement	Enum:
				The state of the s	0100: 0100%
					Reserved
					101254: 255: Not
2.1		5 0 10	500		supported
24	8	Fan Speed Status	FSS	Fan speed	Enum:
					0100: 0100%
					Reserved
					101254:
					255: Not
					supported

					Reserved 101254: 255: Not supported	
	RORG	D2	VLD Telegram			
2	015			TTG Interoperability	156	

FUNC	20	Fan Control
TYPE	01	Type 0x01

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

				vels to the next lower fan speed level.		
Offset	Size	Data	ShortCut	Description	Valid Rang	je Scale Unit
0	7	Not Used (= 0)	4			
7	1	Message Type	MT	Defines the message type	Enum:	
					0: Fan d	control
8	2	Not Used (= 0)				
10	2	Room Size	RSR	Defines if the provided room size has to be	Enum:	
		Reference		considered	0: Used	
			\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		1: Not u	ısed
					2: Defa	ult
					3: No ch	nange
12	4	Room Size	RS	Defines the room size	Enum:	
					0: < 25	m²
			\			50 m ²
						75 m²
						100 m ²
						.125 m²
						.150 m²
						.175 m²
					7: 175	.200 m²
						.225 m²
					9: 225	.250 m²
					10: 250	.275 m²
					11: 275	.300 m²
					12: 300	.325 m²
					13: 325	350 m²
					14: > 35	0 m²
					15: No ch	nange
16	8	Not Used (= 0)				
24	8	Fan Speed *	FS	Sets the fan speed	Enum:	
					0100:	0100%
					101 252	Reserved
					101252:	Auto
					253:	Auto
					254:	Default
					255:	No
					255.	change

Telegram Definition: 'Fan Status Message'

Off	set Si	ize	Data	ShortCut	Description	Valid I	Range	Scale	Unit
0	4		Operating Mode	OMS	Provides the recent operating mode	Enum:			
			Status			0:	Disable		
						1:	Standar complia		

		A			1
					Reserved
					214:
					15: Not supported
		1 (2)			
4	3	Not Used (= 0)		I	
7	1	Message Type	MT	Defines the message type	Enum:
					1: Fan status
8	2	Not Used (= 0)			
10	2	Room Size	RSR	States if the provided room size has to be	Enum:
		Reference		considered	0: Used
					1: Not used
					2: Reserved
					3: Not supported
12	4	Room Size Status	RSS	Room size status	Enum:
					0: < 25 m ²
					1: 2550 m ²
					2: 5075 m ²
					3: 75100 m ²
		\			4: 100125 m ²
					5: 125150 m ²
					6: 150175 m ²
					7: 175200 m ²
					8: 200225 m ²
					9: 225250 m ²
			\		10: 250275 m ²
			\		11: 275300 m ²
					12: 300325 m ²
					13: 325350 m ²
					14: > 350 m ²
					15: Not supported
16	8	Not Used (= 0)			
24	8	Fan Speed Status	FSS	Fan speed	Enum:
		,			0100: 0100%
					Reserved
					101254:
				V	255: Not
					supported

RORG	D2	VLD Telegram
FUNC	20	Fan Control
TYPE	02	Type 0x02

Submitter: Maico Elektroapparate-Fabrik GmbH

Telegram Definition: 'Fan Control Message'

* Devices with discrete fan speed levels instead of a continuous fan speed range should divide the full range linearly and match values beside those discrete levels to the next lower fan speed level.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	7	Not Used (= 0)			
7	1	Message Type	MT	Defines the message type	Enum: 0: Fan control
8	2	Not Used (= 0)			
10		Room Size Reference		Defines if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Default

					3. No.c	hange
12	4	Room Size	RS	Defines the room size	Enum: 0: < 25 1: 25 2: 50 3: 75 4: 100. 5: 125. 6: 150. 7: 175. 8: 200.	50 m ² 75 m ² 100 m ² 125 m ² 150 m ² 175 m ² 200 m ² 225 m ² 250 m ² 275 m ² 300 m ² 325 m ²
					14: > 35	i0 m²
					15: No c	hange
	8	Not Used (= 0)				
24	8	Fan Speed *	FS	Sets the fan speed	Enum: 0100:	0100%
					101252:	Reserved
				253:	Auto	
					254:	Default
					255:	No change

Telegram Definition: 'Fan Status Message'

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	7	Not Used (= 0)					
7	1	Message Type	MT	Defines the message type	Enum: 1: Fan stat	us	
8	2	Humidity Control Status	HCS	States if the humidity control is active	Enum: 0: Disabled 1: Enabled 2: Reserve 3: Not supplements of the	d	- - - -
10	2	Room Size Reference	RSR	States if the provided room size has to be considered	Enum: 0: Used 1: Not used 2: Reserve 3: Not supplementarials	b	_ _ _ _
12	4	Room Size Status	RSS	Room size status	Enum: 0: < 25 m ² 1: 2550 2: 5075 3: 75100 4: 10012 5: 12515 6: 15017 7: 17520 8: 20022 9: 22525 10: 25027 11: 27530	m ² m ² 5 m ² 0 m ² 5 m ² 0 m ² 5 m ² 0 m ² 5 m ² 5 m ² 0 m ² 5 m ²	-

16	8 Not Used (= 0)			12: 300325 m ² 13: 325350 m ² 14: > 350 m ² 15: Not supported
24	8 Not Used (= 0) 8 Fan Speed Status	FSS	Fan speed	Enum: 0100: 0100%
				Reserved 101254: 255: Not supported

D2-30: Floor Heating Controls and Automated Meter Reading

Floor heating controls and automated meter reading gateway may appear combined in one device, but the metering functionality can also be absent.

The floor heating control unit controls a number of valves for separate heating circuits (e.g. for separate heating of single rooms). It measures the common hot water supply temperature as well as the return water temperatures of each single circuit.

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered

Communication interval: minimum 1-1000 s, maximum 1000 s

Trigger event: heartbeat 1000 s, value change in "Position", "Return Temperature", "Status/Error", "Supply

Temperature", "Meter Reading" while respecting the minimum reporting interval

Tx delay: 500 ms (maximum response time, first telegram)

Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: Universal teach-in (outbound)

Encryption required : no Security level format : 0

EEP Family Table

Туре	0x00	0x01	0x02	0x03	0x04	0x05	0x06
Number of heating channels/valves	4	8	8	8	8	6	12
Channel return temperature	Χ	Χ	Χ	Χ	Χ	ĭ	1
Global return temperature	Χ	Χ	Χ	Χ	Χ	-	-
Global supply temperature	Χ	Χ	Χ	Χ	Χ	-	-
Number of supported MBUS meters	0	0	8	10	10	0	0
Number of supported S0 meters	0	0	0	0	1	0	0
Number of supported D0 meters	0	0	0	0	0	0	0

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

D0-Interface:

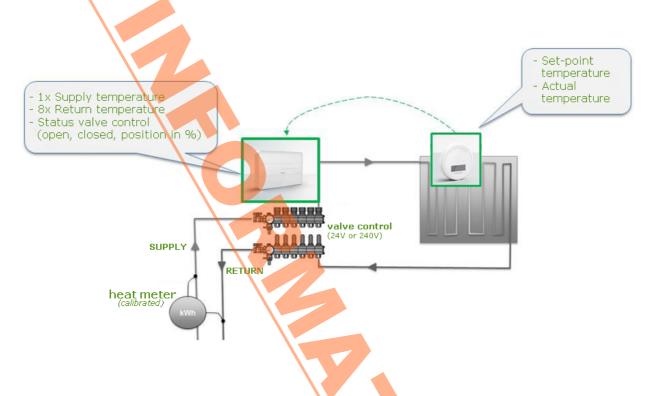
The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and

type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

Application example for floor heating controls



References:

M-Bus documentation: www.m-bus.com

SML specification: www.vde.com/de/fnn/arbeitsgebiete/messwesen/Sym2/Seiten/default.aspx

DLMS User Association: www.dlms.com

RORG	D2	VLD Telegram	
FUNC	30	Floor Heating Controls and Automated Meter R	eading
TYPE	TYPE 00 Type 0x00		

Submitter: MSR-Solutions

CMD 0x1 - Set heating controls output

This message is sent to a floor heating actuator. It controls the valve position of one channel or of all channels of the floor heating controls.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0		Valve control period / PWM signal interval		Total on-off time for two-position valve controller (T valve open + T valve closed)		default / i	no
					1: 1 s		

					2: 2 s 3: 5 s 4: 10 s 5: 20 s 6: 50 s 7: 100 s 8: 200 s 9: 500 s 10: 1000 s Reserved 1115:
4	4	Command ID	CMD	Command identifier	Enum: 0x01:ID 01
8	2	Not Used (= 0)			
10	1	Valve type	VTYP	Type of connected valve	Enum: 0: Valve normally closed (N.C.) 1: Valve normally open (N.O.)
11	5	Heating channel	HCH	The heating channel that should be set	Enum: 015: A valid channel number Reserved 1630: 31: All valid channels
16	1	Run init sequence	RIN	Measure and store the valve zero point	Enum: 0: No action 1: Run init sequence
17	7	Valve position set point	POS	Valve set point 0100% (0=closed, 100=open)	0100 0100 %

CMD 0x2 - Heating controls status query

This message is sent to a floor heating actuator. It requests the status of one channel or the status of the global control unit of an actuator.

Sender: controller; send type: broadcast or addressed; expected response: CMD 0x3

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)				
4	4	Command ID	CMD	Command identifier	Enum: 0x02: ID 02		
8	3	Not Used (= 0)				
11		Heating channel		The heating channel that should be reported	device statu	nnels	pal

CMD 0x3 - Heating controls status response / CH = 0...15

This message is sent by a floor heating controls if one of the following events occurs:

- Message 'status query' has been received (CMD 0x2).
 Status of one channel or temperature has changed.

Sender: actuator; send type: broadcast; maximum send delay 1 s.

If the response is for single channel data (CH = 0...15):

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit		
0	4	Not Used $(= 0)$							
4	4	Command ID	CMD	Command identifier	Enum:				
					0x03: ID 03				
8	3	Status / Error	STATUS	Status / Error indication of given	Enum:				
				channel	0: No fault				
					1: General error				
			1, 1		1: General err	or			
					2: Init sequen	ce running			
			//		3: Channel not available				
			`		4: Temperature sensor error				
					4: Temperatur	e sensor en	101		
					5: Valve error				
					6: Temperature sensor and				
					valve error 7: Reserved				
					7. Reserved				
11	5	Heating channel	НСН	The heating channel that is reported	Enum:				
					015: A valid	channel nun	nber		
					1631: Reserve	ed			
16		Not Used (= 0)							
17	7	Valve position	POS		0100	0100	%		
24	8	Dotum	TEMPOET	(0=closed, 100=open)	0 100	0 00	°C		
24	_	Return temperature	TEMPRET	The current return temperature of the channel	0180	090	٠,		
		po. ata. o		a					

CMD 0x3 - Heating controls status response / CH = 31

If the response is for global floor heating controls unit data (CH = 31):

Offse	t Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					
4	4	Command ID	CMD	Command identifier	Enum: 0x03: ID 03		
8	3	Status / Error	STATUS	Global unit status	3: Return error	temperatur temperatur n both sens	е

11		5	Heating channe	I HCH	The heating channel that is reported	Enum:			
					(=global unit)	31: Unit status only			
16		8	Supply temperature	TSUP	The current supply temperature of the unit	0180	090	°C	
24	1	8	Return temperature	TRET	The current common return temperature	0180	090	°C	

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Ur	nit
0			RM	Minimum auto reporting	Enum:	Journ Of	-
· ·	·	measurement		interval	0: No auto repo	rting	
		\\			1: Min. 1 s inter		
		\			2: Min. 3 s inter		
					3: Min. 10 s inte		
					4: Min. 30 s inte		
					5: Min. 100 s in		
					6: Min. 300 s in		
			//		7: Min. 1000 s i		
			\		815: Reserved	incervar	
4	4	Command ID	CMD	Command identifier	Enum:		
_	_	Command 15	CIND	Command Identine	0x06: ID 06		
0	1	Not Used (= 0)			0X00.1D 00		
8		Not Used (= 0)	BUS	The motor bus that should be	Enum		
9	2	Meter bus type	BU3	The meter bus that should be configured	Enum:		
				S gai ca	0: Reserved		
					1: MBUS		
					2: S0		
	_		14611		3: D0		
11	5	Meter channel index	MCH	The meter bus that should be configured	030	030 1	
16	2	Not Used (= 0)		comigured			
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum		
10	3	Meter 1 units	ONTI	quantity		aanfiaad)	
				(imported value)	0: No reading (un	comigured)	
					1: Current value V	V accumulated	
					value kWh	v, accamalated	
					2: Current value V	V, accumulated	
					3: Accumulated va	alue kWh only	
						n3/h, accumulated	d
					value m3	l 2 //-	
					5: Current value d		
					6: Accumulated va		
					7: Digital counter		
					7: Digital counter		
21	3	Meter 2 units	UNIT2	Physical units of second	Enum:		
21	3	ricter 2 units	ONTIZ	measured quantity (exported value)	0: No reading (un	configured)	
				(C.Forton Forde)	1: Current value V	V, accumulated	
						V, accumulated	
					value Wh		
					3: Accumulated va	alue kWh only	
						n3/h, accumulated	d
					value m3		
		· · · · · · · · · · · · · · · · · · ·					

						Current value of accumulated value of Accumulated value of Digital counter	alue dm3	
24	8	Primary Address	ADDR	The primary MBUS address of the meter	125	0	1250	1
32	40	Not Used (= 0)						

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:		
		measurement			0: No auto rep	orting	
		\			1: Min. 1 s inte		
		\			2: Min. 3 s inte	erval	
		· ·			3: Min. 10 s in		
					4: Min. 30 s in		
					5: Min. 100 s i		
					6: Min. 300 s i		
					7: Min. 1000 s		
			\		815: Reserved		
4	4	Command ID	CMD	Command identifier	Enum:		
					0x06: ID 06		
8	1	Not Used (= 0)					
9	_	Meter bus type	BUS	The meter bus that should be	Enum:		
		,,,,,		configured	0: Reserved		
					1: MBUS		
					2: S0		
					3: D0		
11	5	Meter channel	МСН	The meter number of given bus	030	030 1	
	3	index	PICH	that should be configured	050	050	
16	2	Not Used (= 0)					
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:		
				quantity	0: No reading (ur	nconfigured)	
				(imported value)	, , , , , , , , , , , , , , , , , , , ,	,	
					1: Current value	W, accumula	ted
					value kWh 2: Current value	W. accumula	ted
					value Wh		
					3: Accumulated v	value kWh on	ly
					4: Current value		
					accumulated v		
					5: Current value accumulated v		
					6: Accumulated v		,
					7: Digital counter	-	
24		M	LINITTO	District the Control			
21	3	Meter 2 units	UNIT2	Physical units of second measured quantity	Enum:	(1)	
				(exported value)	0: No reading (ur	nconfigured)	
					1: Current value value kWh	W, accumula	ted
					2: Current value value Wh	W, accumula	ted
					3: Accumulated v	value kWh on	ly
					4: Current value		
					accumulated v	alue m3	

					5: Current value dm3/h, accumulated value dm3 6: Accumulated value m3 only 7: Digital counter
24	2	Factor of number of pulses	FACP	The factor for the number of pulses per value in UNIT1	Enum: 0: 1 1: 0.1 2: 0.01 3: 0.001
26	14	Number of pulses	NOP	The number of pulses per value in UNIT1* FACP	Enum: 0: Do not change the current setting of NOP Number of pulses per 165535: unit
40	32	Preset value	RST	Preset the accumulated value to this value	Enum: New preset value 04294967294: 0xFFFFFFFF: Do not change the current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

Minimum auto reporting interval	Enum: 0: No auto reporting
	0: No auto reporting
	1: Min. 1 s interval
	2: Min. 3 s interval
	3: Min. 10 s interval
	4: Min. 30 s interval
	5: Min. 100 s interval
	6: Min. 300 s interval
	7: Min. 1000 s interval
	815: Reserved
Command identifier	Enum:
	0x06: ID 06
The meter bus that should be	Enum:
configured	0: Reserved
	1: MBUS
`	2: 50
	3: D0
The meter number of given bus	030 030 1
that should be configured	
1	
	Enum:
(imported value)	0: No reading (unconfigured)
	1: Current value W, accumulated value kWh
	2: Current value W, accumulated value Wh
	3: Accumulated value kWh only
	4: Current value m3/h,
	accumulated value m3
	5: Current value dm3/h, accumulated value dm3
	6: Accumulated value m3 only
	o. Accommisced value in Solly
	The meter bus that should be configured The meter number of given bus that should be configured Physical units of first measured quantity

					7:	Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum	:
				quantity (exported value)	0:	No reading (unconfigured)
					1:	Current value W, accumulated value kWh
	/				2:	Current value W, accumulated value Wh
					3:	Accumulated value kWh only
					4:	Current value m3/h,
		· V				accumulated value m3
					5:	Current value dm3/h, accumulated value dm3
					6:	Accumulated value m3 only
					7:	Digital counter
24	8	D0 Protocol	PROT	The D0 protocol that should be	Enum	:
				used for that meter	0:	Auto detect
					1:	SML (Smart Message Language)
					2:	DLMS (Device Language Message Specification)
					325	Reserved 5:
32	40	Not Used (= 0)				

CMD 0x7 - Meter Status Query

This message is sent to a metering device gateway to query the status of a meter. Sender: controller; send type: broadcast or addressed; expected response: CMD 0x8.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Not Used (= 0)			
4	4	Command ID	CMD	Command identifier	Enum:
					0x07: ID 07
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus type that is queried	Enum:
					0: Reserved
					1: MBUS
					2: S0
					3: D0
11	5	Meter channel	MCH	The meter channel of given bus that status is	Enum:
		index		queried	Meter channel
					030:
					31: All valid
					channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:

- Message 'meter status query' has been received (CMD 0x7)
- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay $1\ \mathrm{s}.$

Offset Size	Data	ShortCut	Description	Valid Range	Scale	Unit

0	1	Not Used (= 0))		
1	3	Meter status / error	MSTAT	Meter channel status	Enum: 0: No fault 1: General error 2: Bus unconfigured 3: Bus unconnected 4: Bus shortcut 5: Communication timeout 6: Unknown protocol or configuration mismatch 7: Bus initialization running
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08
8	1	Not Used $(= 0)$			
9	2	Meter bus type	BUS	The used bus of the meter status response	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11	5	Meter channel index	МСН	The meter number of given bus that status is reported	030 030 1
16	3	Not Used (= 0))		
19	2	Value selection	VSEL	The selection of the reported value	Enum: 0: Meter 1 Current value 1: Meter 1 Accumulated value 2: Meter 2 Current value 3: Meter 2 Accumulated value
21	3	Value unit	VUNIT	The unit of the reported value	Enum: 0: W 1: Wh 2: kWh 3: m3/h 4: dm3/h 5: m3 6: dm3 7: 1 (digital counter)
24	32	Meter reading value	VAL	The reported value	04294967295 04294967295 According to VUNIT

RORG	D2	VLD Telegram	
FUNC	30	Floor Heating Controls and Automated Meter Rea	ding
TYPE	01	Type 0x01 (description: see table)	

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	02	Type 0x02 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	03	Type 0x03 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	04	Type 0x04 (description: see table)

See profile: D2-30-00

RORG	D2	1				VLD Telegram
FUNC	30	I	Floor	r He	eating	Controls and Automated Meter Reading
TYPE	05		//		Тур	e 0x05 (description: see table)

See profile: D2-30-00

RORG	D2	VLD Telegram
FUNC	30	Floor Heating Controls and Automated Meter Reading
TYPE	06	Type 0x06 (description: see table)

See profile: D2-30-00

D2-31: Automated Meter Reading Gateway

The automated meter reading gateway is a device that connects to various counters such as heating, water, gas or electrical energy meters. The meters may be connected to the gateway by one or several of these interface types: M-Bus, D0, S0 (see appendix). The gateway reports the continuous energy or flow volume meter reading of each of the connected metering devices. Typically the measured variables consist of a momentary value and an accumulated value. The transmission of separated consumption import and export values is supported, too.

Data exchange

Direction: bidirectional

Addressing: ADT inbound, broadcast outbound Communication trigger: event- & time-triggered

Communication interval: minimum 1-1000 s (configuration item), maximum 1000 s

Trigger event: heartbeat 1000 s, value change in "Status/Error", "Meter Reading" while respecting the minimum

reporting interval

Tx delay: 500 ms (maximum response time, first telegram)
Rx timeout: 0 ms (minimum time between two received messages)

Teach-in method: Universal teach-in (outbound)

Encryption required : no Security level format : 0

Telegram Definition

The telegram definition is inherited from profile D2-30-xx and thus identical to the definition there.

EEP Family Table

Supported function	Type 0x00	Type 0x01
Number of supported MBUS meters	10	16
Number of supported S0 meters	2	0
Number of supported D0 meters	2	0

Description of the meter interfaces

S0-Interface:

The S0-Interface is a two-wire connection designed for the transmission of monotonously rising measurement data. The standard is defined in EN 62053-31. The meter device transmits a fixed number of pulses per physical meter unit. The number of pulses per unit is defined by the meter manufacturer and depends on the necessary precision of the meter system. The pulses are output as currency variations, where a value lower than 3 mA corresponds to a logical 0. The sender output is mostly realized by a transistor or an opto-coupler, which needs to be supplied by a voltage of 27-30 V. Polarity must be respected.

D0-Interface:

The D0-interface is an optical metering interface defined in EN62056-61. It allows the unidirectional readout of metering data at a rate of 9600 Baud, using telegrams with start bit, 7 data bits, parity and a stop bit. One of the protocols SML (Smart Message Language) or DLMS (Device Language Message Specification, EN62056-21) can be used for coding the data. A D0-Meter can deliver consumption data as well as various system data. The source and type of a data point is indicated by the standardized OBIS-codes.

MBUS-Interface:

The M-Bus (Meter-Bus) is a bidirectional field bus for the communication with consumption meters. It is described in standard EN13757. Typically there can be connected up to 250 devices in one M-Bus network. There is a common master in the network, who periodically collects the meter data from its slaves. The network may be implemented either as two-wire cable network allowing remote powering of the slaves or as wireless network. The protocol operates at 300 to 9600 Baud and codes the data bytes with start bit, 8 data bits, parity and a stop bit. The data records sent by a metering slave deliver in their header field the coding information of the following data field (value size, measurement medium, unit, multiplier). The master can address a single slave by its primary address (1...250), which must be assigned during network configuration, or by its secondary address, which is a unique device identification number assigned by the device manufacturer.

References:

M-Bus documentation: www.m-bus.com

SML specification: www.vde.com/de/fnn/arbeitsgebiete/messwesen/Sym2/Seiten/default.aspx

DLMS User Association: www.dlms.com

RORG	D2	VLD Telegram
FUNC	31	Automated Meter Reading Gateway
TYPE	00	Type 0x00

Submitter: MSR-Solutions

CMD 0x6 - Set meter configuration / MBUS (BUS = 1)

This message is sent to a metering device gateway to configure the meter settings for one channel.

Sender: controller; send type: broadcast or addressed.

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	4	Report measurement	RM	Minimum auto reporting interval	Enum: 0: No auto reporting 1: Min. 1 s interval 2: Min. 3 s interval 3: Min. 10 s interval 4: Min. 30 s interval 5: Min. 100 s interval 6: Min. 300 s interval 7: Min. 1000 s interval
4	4	Command ID	CMD	Command identifier	815: Reserved Enum: 0x06: ID 06
8	1	Not Used (= 0)			0x06: ID 06
9		Meter bus type	BUS	The meter bus that should be configured	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11	5	Meter channel index	MCH	The meter number of given bus that should be configured	030 030 1
16	2	Not Used (= 0)			

18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:
				quantity (imported value)	0: No reading (unconfigured)
					1: Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
	/				3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum:
				quantity (exported value)	0: No reading (unconfigured)
					1: Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
					3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h,
					accumulated value dm3 6: Accumulated value m3 only
					6: Accumulated value m3 only
					7: Digital counter
24	8	Primary Address	ADDR	The primary MBUS address of the meter	1250 1250 1
32	40	Not Used (= 0)			•

CMD 0x6 - Set meter configuration / S0 (BUS = 2)

Offset	Size	Data	ShortCut	Description	Valid Range Scale	Unit
0		Report	RM	Minimum auto reporting interval	Enum:	
		measurement			0: No auto reporting	
					1: Min. 1 s interval	
					2: Min. 3 s interval	
					3: Min. 10 s interval	
					4: Min. 30 s interval	
					5: Min. 100 s interval	
					6: Min. 300 s interval	
					7: Min. 1000 s interval	
					815: Reserved	
4	4	Command ID	CMD	Command identifier	Enum:	
					0x06: ID 06	
8	1	Not Used (= 0)				
9	2	Meter bus type	BUS	The meter bus that should be	Enum:	
				configured	0: Reserved	
					1: MBUS	
					2: S0	
					3: D0	
11	5	Meter channel	MCH	The meter number of given bus	030 030 1	
		index		that should be configured		
16	2	Not Used (= 0)				
			·	<u> </u>		

18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:
				quantity (imported value)	0: No reading (unconfigured)
					Current value W, accumulated value kWh
	V				2: Current value W, accumulated value Wh
	/				3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second	Enum:
				measured quantity (exported value)	0: No reading (unconfigured)
					1: Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
					3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
24	2	Factor of number	FACP	The factor for the number of	Enum:
		of pulses		pulses	0: 1
				per value in UNIT1	1: 0.1
					2: 0.01
					3: 0.001
26	14	Number of pulses	NOP	The number of pulses per value in UNIT1* FACP	Enum: 0: Do not change the current
					setting of NOP
					Number of pulses per 165535: unit
40	32	Preset value	RST	Preset the accumulated value to	Enum:
				this value	New preset value 04294967294:
					OxFFFFFFFF: Do not change the current value

CMD 0x6 - Set meter configuration / D0 (BUS = 3)

Offset	Size	Data	ShortCut	Description	Val	id Range	Scale	Unit
0	4	Report	RM	Minimum auto reporting interval	Enum:			
		measurement			0:	No auto repor	ting	
					1:	Min. 1 s inter	/al	
					2:	Min. 3 s interv	/al	
					3:	Min. 10 s inte	rval	
					4:	Min. 30 s inte	rval	
					5:	Min. 100 s int	erval	
					6:	Min. 300 s int	erval	
					7:	Min. 1000 s ir	iterval	

					815: Reserved
4	4	Command ID	CMD	Command identifier	Enum:
					0x06: ID 06
8	1	Not Used (= 0)			
9	2	Meter bus type	BUS	The meter bus that should be	Enum:
				configured	0: Reserved
	1/4				1: MBUS
	1				2: S0
					3: D0
11	5	Meter channel index	MCH	The meter number of given bus that should be configured	030 030 1
16	2	Not Used (= 0)	4		
18	3	Meter 1 units	UNIT1	Physical units of first measured	Enum:
				quantity (imported value)	0: No reading (unconfigured)
					1: Current value W, accumulated value kWh
		\			2: Current value W, accumulated value Wh
					3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
21	3	Meter 2 units	UNIT2	Physical units of second measured	Enum:
				quantity (exported value)	0: No reading (unconfigured)
					1: Current value W, accumulated value kWh
					2: Current value W, accumulated value Wh
					3: Accumulated value kWh only
					4: Current value m3/h, accumulated value m3
					5: Current value dm3/h, accumulated value dm3
					6: Accumulated value m3 only
					7: Digital counter
24	8	D0 Protocol	PROT	The D0 protocol that should be	Enum:
				used for that meter	0: Auto detect
					1: SML (Smart Message Language)
					2: DLMS (Device Language Message Specification)
					Reserved 3255:
32	40	Not Used (= 0)			15255
	٠.٠_				

CMD 0x7 - Meter Status Query

This message is sent to a metering device gateway to query the status of a meter. Sender: controller; send type: broadcast or addressed; expected response: CMD 0x8.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	4	Not Used (= 0)					

4	4 Command	ID CMD	Command identifier	Enum: 0x07: ID 07
8	1 Not Used ((= 0)		
9	2 Meter bus	type BUS	The meter bus type that is queried	Enum: 0: Reserved 1: MBUS 2: S0 3: D0
11	5 Meter chai	nnel MCH	The meter channel of given bus that status is queried	Enum: Meter channel 030: 31: All valid channels

CMD 0x8 - Meter reading report / status response

This message is sent by a metering device gateway to report the meter values for each configured channel. It is sent if one of the following events occurs:
- Message 'meter status query' has been received (CMD 0x7)

- Status or meter reading of one channel has changed and auto reporting was configured by signal RM.

Sender: sensor; send type: broadcast; maximum send delay 1 s.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale	Unit
0	1	Not Used (= 0))				•
1	3	Meter status / error		Meter channel status	6: Unknown configura	nfigured nnected	
4	4	Command ID	CMD	Command identifier	Enum: 0x08: ID 08	_	
8	1	Not Used (= 0))				
9	2	Meter bus type	BUS	The used bus of the meter status response	0: Reserved 1: MBUS 2: S0 3: D0		
11	5	Meter channel index	МСН	The meter number of given bus that status is reported	030	030	1
16	3	Not Used (= 0))				•
19	2	Value selection	VSEL	The selection of the reported value	1: Meter 1 A 2: Meter 2 C	Current value accumulated value Current value accumulated value	
21	3	Value unit	VUNIT	The unit of the reported value	Enum: 0: W 1: Wh 2: kWh 3: m3/h 4: dm3/h 5: m3 6: dm3 7: 1 (digital	counter)	

24	32	Meter reading	VAL	The reported value	04294967295 0429496729	5 According to
		value				VUNIT

RORG	D2	VLD Telegram					
FUNC	31	Automated Meter Reading Gateway					
TYPE	01	Type 0x01 (description: see table)					

See profile: D2-31-00

D2-32: A.C. Current Clamp

Description

A family of EEP's based on a central unit where up to three a.c. Current Clamps can be connected. Each one capable of energy harvesting sufficiently to enable readings of current values to be taken in amps and transmitted every 30 seconds.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: time-triggered Communication interval: 30 seconds

Trigger event: Threshold Voltage for Power Fail transmission bit

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table:

Supported function	Type 00	Type 01	Type 02
Channel 1	Х	Χ	Χ
Channel 2	-	Χ	Χ
Channel 3	-	-	Χ

Each TYPE has to support every parameter that is marked in its column!

The list of parameters could be structured following the features that always include a certain group of parameters.

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	00	Type 0x00

Submitter: Pressac Communications Ltd

Type 00

			DB_2							DB_1						DR_0								
DB_2.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 -> 23	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23
	PF	DIV												CH	11									

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
	1/4				0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
					1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	4	Not Used	(=0)			

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	01	Type 0x01

Submitter: Pressac Communications Ltd

Type 01

				DB	_3							DB	_2							DB	_1							DB	_0_			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 -> 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	PF	PF DIV												Cl	11											CH	12					

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
					1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	12	Channel 2	CH2	Current value	00xFFF	04095 (409,5) A

RORG	D2	VLD Telegram
FUNC	32	A.C. Current Clamp
TYPE	02	Type 0x02

Submitter: Pressac Communications Ltd



		DB_5						DB	_4						D	B_ 3							DB_	2					D	B_1							DB.	_0				
DB_5.BIT_7 ← 0	7	6 5	4	3	2	1	0 7	7 6	5	4	3	2	1	0	7	6 5	5 4	3	2	1	0	7	6	5	4 3	2	1	0	7	6 :	5 4	3	2	1	0	7	6	5	4	3	2 :	0
Bit Offset: 0 -> 47	0	1 2	3	4	5	6	7 8	3 9	10	11	12	13	14	15	16	17 1	8 1	9 20	21	22	23	24	25	26	27 2	3 29	30	31	32	33 3	4 3	5 36	37	38	39	40	41	42	43	44 4	15 4	6 47
	PF 0	IV							CH1												СН	2									CI	13										

Notes

- 1) If Power Fail bit is set, all channel readings will be set to zero when this final telegram is sent.
- 2) Scale/divisor is set to 0 or 1 for all channels only, not individually.

Offset	Size	Data	ShortCut	Description	Valid Range	Scale Unit
0	1	Power Fail	PF	See Note 1	Enum:	
					0: False	
					1: True	
1	1	Divisor	DIV	Divisor for all channels	Enum:	
					0: x/1	
			\		1: x/10	
2	6	Not Used ((= 0)			
8	12	Channel 1	CH1	Current value	00xFFF	04095 (409,5) A
20	12	Channel 2	CH2	Current value	00xFFF	04095 (409,5) A
32	12	Channel 3	CH3	Current value	00xFFF	04095 (409,5) A
44	4	Not Used ((= 0)		·	

D2-40: LED Controller Status

Description

This family of EEP's is used for sending handling a LED controller device. The status is send periodically, or after product specific event occurred e.g. when one of the parameters from the status message has changed. It allows other devices to monitor LED controller and react to its actions.

Data exchange

Direction: unidirectional Addressing: broadcast

Communication trigger: event- & time-triggered

Communication interval: configurable

Trigger event: heartbeat, change of one of the parameters from the status message

Tx delay: -Rx timeout: -

Teach-in

Teach-in method: Universal teach-in (UTE)

Security

Encryption supported: no Security level format: -

EEP Family Table:

Supported function	Type 00	Type 01
MsgId	Χ	Χ
LED output enabled	Χ	Χ
"Demand Response" mode Active	Χ	Χ
Daylight Harvesting	Χ	Χ
Occupancy state	Χ	Χ
Status Tx reason	Χ	Χ
Current Dim Level	Χ	ĺ
Current Dim Level LED R	i	X
Current Dim Level LED G	-	Χ
Current Dim Level LED B	1	Χ

Each TYPE has to support every parameter that is marked in its column!

"LED output enabled" parameter is correlated with dimming level – it is set to ENABLE if dimming level is above 0%. 0% dimming level means that the light is completely OFF.

LED controller has a "Demand Response" feature. When DR mode is triggered by external device, "Demand Response" mode Active will be set to TRUE.

Daylight Harvesting feature of the LED controller is also triggered by the external sensor.

Occupancy state is change by occupancy sensor taught in to the LED controller.

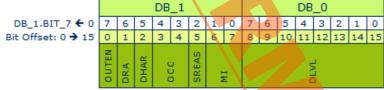
DR, Daylight Harvesting, and Occupancy will influence dimming levels, with an algorithm specific to the device that sends the status message.

RORG	D2	VLD Telegram
FUNC	40	LED Controller Status
TYPE	00	Type 0x00

Submitter: EnOcean GmbH

Msgld 0x00:Status of monocolor LED controller

MsgId 0x00



monocolor LED

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	1	LED output enabled	OUTEN	Driving LED enabled	Enum: 0: Disabled 1: Enabled
1	1	"Demand Response" mode Active		Controller is in the DR mode. It had received a DR command from DR controller, and it is executing it.	Enum: 0: False 1: True
2	1	Daylight Harvesting Active		Daylight harvesting feature is turned on. Readings from photo sensor are influencing the dimming level.	Enum: 0: False 1: True
3	2	Occupancy State		Room which controller is in charge of is considered occupied.	Enum: 0: Not occupied 1: Occupied 2: Unknown
5	1	Status Tx reason	SREAS	Reason for sending this status message	Enum: 0: Other 1: Heartbeat
6	2	MsgId	MI	Message Id; 0x00	0: LED Status monocolor
8	8	Current Dim Level	DLVL	Current dim level for the monocolor LED	0200: 0100 % OXFF: If not used

RORG	D2	VLD Telegram
FUNC	40	LED Controller Status
TYPE	01	Type 0x01

Submitter: EnOcean GmbH

Msgld 0x01:Status of RGB LED controller

MsgId 0x01

\				DB	_3							DB	_2							DB	_1							DB	_0			
DB_3.BIT_7 ← 0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
Bit Offset: 0 🗲 31	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
	OUTEN	DRA	DHAR	000	1	SREAS	I M	111				5	טרערא							2	3							2	DLVLB			
			7.1						red LED									q	reer	1 LE	D					ь	olue	LED)			

Offset	Size	Data	ShortCut	Description	Valid Range Scale Unit
0	1	LED output	OUTEN	Driving LED enabled	Enum:
		enabled	`		0: Disabled
					1: Enabled
1	1	"Demand	DRA	Controller is in the DR mode. It had received	Enum:
		Response" mode Active		a DR command from DR controller, and it is executing it.	0: False
		Active			1: True
2		Daylight	DHAR	Daylight harvesting feature is turned on.	Enum:
		Harvesting Active		Readings from photo sensor are influencing the dimming level.	0: False
					1: True
3	2	Occupancy State	occ	Room which controller is in charge of is	Enum:
				considered occupied.	0: Not occupied
					1: Occupied
		-			2: Unknown
5	1	Status Tx reason	SREAS	Reason for sending this status message	Enum:
					0: Other
_	_				1: Heartbeat
6	2	MsgId	MI	Message Id; 0x01	Enum:
_	_				1: LED Status RGB
8	8	Current Dim Level LED R	DLVLR	Current dim level for the red LED	Enum:
		LLD K			0200: 0100 %
					0xFF: If not
					used
16	8	Current Dim Level	DLVLG	Current dim level for the green LED	Enum:
		LED G			
					0200: 0100 %
					0xFF: If not
					used
24	8	Current Dim Level LED B	DLVLB	Current dim level for the blue LED	Enum:
		LED R			200
					0200: 0100 %
					0xFF: If not used
					useu

D2-A0: Standard Valve

RORG	D2	VLD Telegram			
FUNC	A0	Standard Valve Valve Control (BI-DIR)			
TYPE	01				

Submitter: Afriso / EnOcean

Description:

Radio operated valve control with feedback message. Valve is controlled through the air interface to be opened or closed. The valve reports the actual status after finishing the determined operation.

Data exchange

Direction: bidirectional

Addressing: addressed (inbound) and broadcast (outbound)

Communication trigger: event- & time-triggered Trigger event: position of valve has changed

Teach-in method: UTE

DIRECTION-1 = Outbound (water valve to the controller)

Description: Valve reports its status. Report is sent after operation was executed or as a heartbeat.

DIRECTION-2 = Inbound (controller to the water valve)

Description: Operational command to the valve. After this request a feedback response will be transmitted, once the

operation is finished.

A "no change"-command will also be followed by a feedback response. Therefore, it can be used as a status request.

DIRECTION-1

Offset	Size	Data	ShortCut	Descrip	tion	Valid	Range	Scale	Unit
0	6	Not Used	(= 0)						
6	2	Feedback	FDB	Return		0b0 0b1	0: Not 1: Clos 0: Oper	_	

DIRECTION-2

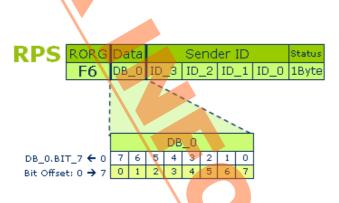
Offset	Size	Data	ShortCut	Description		Valid Range	Scale	Unit
0	6	Not Use	d (= 0)					
6	2	Request	REQ	Request to operate the valv	'e	Ob00: No change (required) Ob01: Request to close Ob10: Request to oper Ob11: Request to close	e valve valve	back)

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3) Appendix

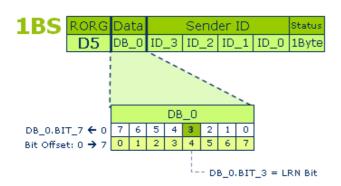
3.1) RPS Teach-in



The RPS telegram can only send data and has no special telegram modification to teach-in the device. Therefore, the teach-in procedure takes place manually on the actuator/controller through a normal data telegram. The EEP profile must be manually supplied to the controller per sender ID.

In learn mode, the receiving actuator reduces the input sensitivity in order to fade out weakly received data telegrams. This helps avoid inadvertently teaching-in sensors.

3.2) 1BS Teach-in



The 1BS telegram has its own teach-in telegram, which can signal the teach-in command through the DB_0.BIT_3 data bit.

Offset Size Bitrange Data Valid Range Scale Unit

4	1	DB0.3	LRN Bit	Enum:	
				0:	Teach-in telegram
				1:	Data telegram

Here, an EEP profile must also be manually allocated per sender ID.





The 4BS telegram also has its own teach-in telegram, however with more teach-in variations:

Variation 1

The profile-less unidirectional teach-in procedure functions according to the same principle as the 1BS telegram: if the data bit is $DB_0.BIT_3 = 0$, then a teach-in telegram is sent. This includes the 'LRN TYPE' $DB_0.BIT_7 = 0$ data bit. Then no EEP profile identifier and no manufacturer ID are transferred.

Offset	Size	Bitrange	Data		Valid Range	Scale		Unit
24	1	DB0.7	LRN Type	Enum:		/	17	
				0:	telegram without EEP	and Manu	fact	urer ID
28	1	DB0.3	LRN Bit	Enum:			//	
				0:	Teach-in telegram			
				1:	Data telegram		<u> </u>	

Variation 2

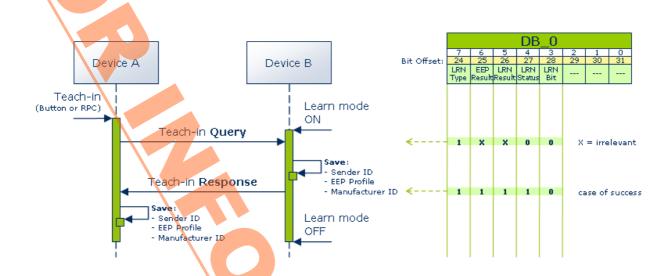
For the unidirectional profile teach-in procedure, it is preferred in opposite to variation 1), as the teach-in telegram contains both the complete EEP number and the manufacturer ID. The device is therefore clearly identifiable as ready-to-use and can be securely executed in a complex system environment or by foreign systems. In this case, the 1 LRN TYPE' data bit is DB_0.BIT_7 = 1.

Offset	Size	Bitrange	Data		Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum	:		
				1:	telegram with EEP num	ber and Manufac	cturer ID
28	1	DB0.3	LRN Bit	Enum	:		
				0:	Teach-in telegram		
				1:	Data telegram		

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Variation 3

During the bidirectional teach-in procedure, further bits are required from the DB_0, in order to develop the mutual teach-in between two communication partners. For this, the procedure is made up of 2 teach-in telegrams, which are exchanged on both sides. The following UML diagram is used to illustrate this:

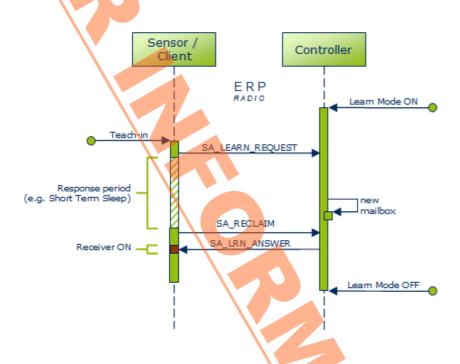


Offset	Size	Bitrange	Data	Valid Range	Scale	Unit
24	1	DB0.7	LRN Type	Enum:		
				0: telegram without EEP and	d Manufacturer	ID
				1: telegram with EEP numb	er and Manufac	turer ID
25	1	DB0.6	EEP Result	Enum:		
				0: EEP not supported		
				1: EEP supported		
26	1	DB0.5	LRN Result			
				0: Sender ID deleted/not st	cored	
				1: Sender ID stored		
27	1	DB0.4	LRN Status	Enum:		
				0: Query		
				1: Response		
28	1	DB0.3	LRN Bit	Enum:		
				0: Teach-in telegram		
				1: Data telegram		

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3.4) Smart Ack Teach-in (without repeater)

Under Smart Ack (SA), the teach-in procedure is more complex as, alongside the SA client and SA controller, a Postmaster must also be established to prepare a mailbox for each taught-in SA client. The Postmaster is normally found in the controller. If a repeater is installed, then a postmaster is set up there.



After the learn mode is activated on the controller, the teach-in procedure can be started on the client. The client sends an SA_LEARN_REQUEST telegram:

	RORG	Req.	Manuf.ID	EE	EEP (3 byte)			Repeater ID					Send	Status	СНСК		
	C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
Ī	1	Request	t														

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0x00	0 = Without repeater
Repeater ID	0x00000000	0 = Without repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

During the 'response period' in the SA client, which is always 550 ms during the teach-in, the controller creates a new mailbox in its postmaster and leaves its first message there with an OK receipt. This entry is requested from the postmaster by the SA client with an SA_RECLAIM 'Learn' telegram:

1									_	
	Choice	RCLI	M_ID		Send	er ID		Status		
\	A7			ID_3	ID_2	ID_1	ID_0	1Byte		
)						Data Reclaim) n / 1 Data Recla	im

Data	Value	Description
Message Index	0b0	Bit 7: 0 = Learn Reclaim
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating desired
CHCK	0xnn	Checksum

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

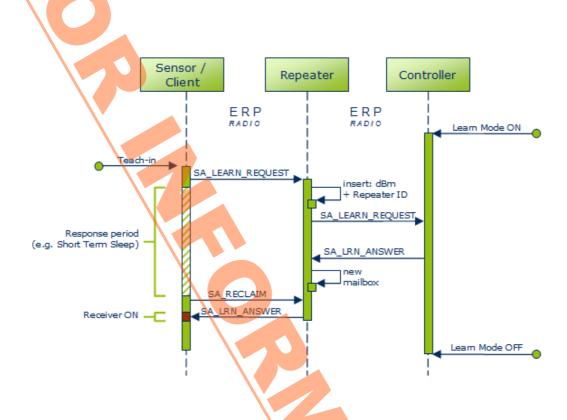
RORG	RORG-EN	Index	Respor	nse time	Acl	k C.	Mailbox		not used	d t		Postma	ster ID			Contro	oller ID		Status	CHCK
0	1	2	3	4		5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
A6	C7	02						/ -	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description
RORG	0xA6	A6 = ADR Telegram
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER
Index	0x02	Message Index; 02 = Learn Acknowledge
Response time		Response time for Smart Ack Client in ms in which the controller can prepare the data and send it to the postmaster (max. value 550 ms = 0x0226)
Acknowledge code	0x00	First Learn In successful
Mailbox index	0xnn	Index no. of the assigned mailbox
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate
Controller ID	0xnnnnnnn	Device ID of the assigned controller
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

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3.5) Smart Ack Teach-in (with repeater)



If a repeater comes into operation, the SA_LEARN_REQUEST telegram sent by the SA client (with an EEP No., Manufacturer ID, Sender ID) is completed on the repeater with the RSSI value (in dBm) and the Repeater ID, and sent to the controller.

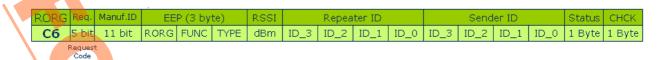
RORG	Req.	Manuf.ID	EEP (3 byte)			RSSI	SSI Repeater ID					Sender ID				Status	СНСК
C6	5 bit	11 bit	RORG	FUNC	TYPE	dBm	ID_3	ID_2	I	0_1	ID_0	ID_3	ID_2	ID_1	ID_0	1 Byte	1 Byte
	Reques	t							_/								

Data	Value	Description
Request Code	0b11111	Default value – send by sensor
Manufacturer ID	0bnnnnnnnnnn	Corresponding to the teach-in sensor
EEP No.	0xnnnnn	RORG, FUNC, TYPE
RSSI	0xnn	Value added from repeater
Repeater ID	0xnnnnnnn	Device ID repeater
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in
Status	0x0F	0F = no repeating permitted
CHCK	0xnn	Checksum

From the reception strength of the RSSI, the controller can recognise which repeater is best for the task of postmaster. In the meantime, the SA client will be in its 'response period'.

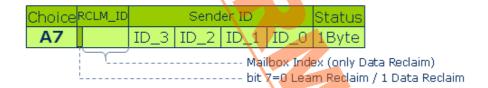
The sent addressed telegram **SA_LRN_ANSWER** with the message 'Learn Reply' by the controller to the repeater ensures that the postmaster is activated and a mailbox is created.

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Data	Value	Description						
RORG	0xA6	6 = ADR Telegram						
RORG-EN	0xC7	ORG encapsulated / C7 = SA_LRN_ANSWER						
Index	0×01	Message Index; 01 = Learn Reply						
Response time		esponse time for Smart Ack Client in ms in which the controller can prepare the data send it to the postmaster (max. value 550 ms = 0x0226)						
Acknowledge code	0x00	irst Learn In successful						
Sender ID	0xnnnnnnn	Chip ID of sensor to be teach-in						
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate						
Controller ID	0xnnnnnnn	Device ID of the assigned controller						
Status	0x0F	OF = no repeating permitted						
CHCK	0xnn	Checksum						

Also, a mailbox is created for the SA client, where an initial entry with an OK message is left. This information is requested by the SA client from the repeater's postmaster with the SA_RECLAIM 'Learn' telegram.



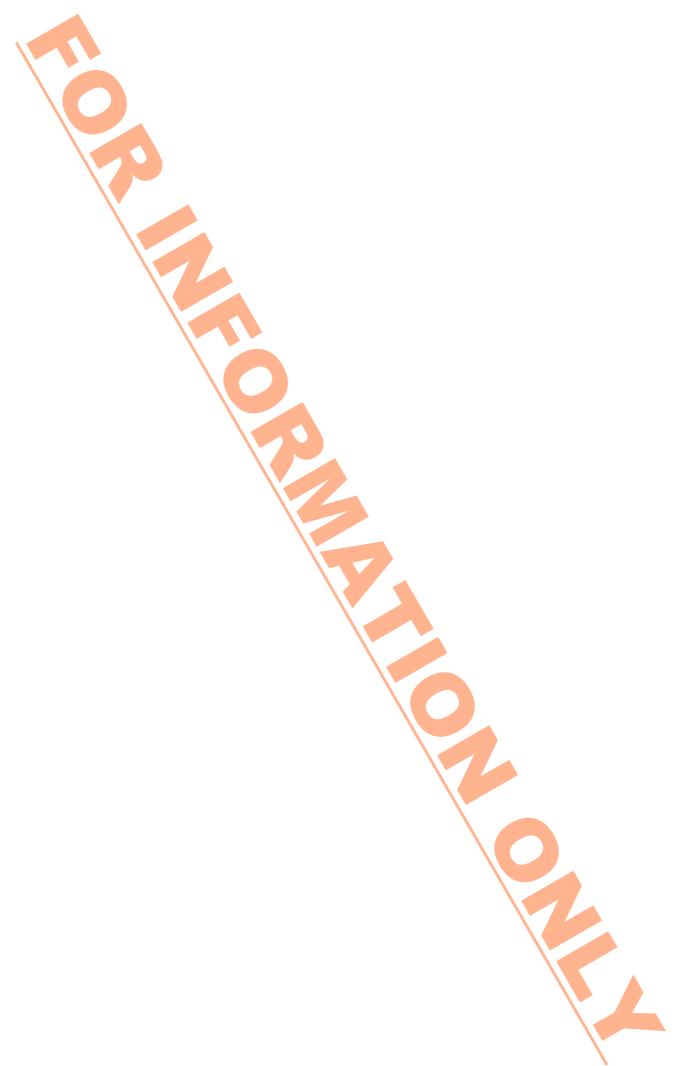
Data	Value	Description						
Message Index	0b0	Bit 7: 0 = Learn Reclaim						
Sender ID	0xnnnnnnn	Chip ID of sensor for teach-in						
Status	0x0F	0F = no repeating desired						
CHCK	0xnn	Checksum						

The final telegram sent to the SA client, SA_LRN_ANSWER, contains the 'Learn Acknowledge' message from the mailbox that the teach-in procedure has been carried out successfully:

Smart Ack Learn Answer (Learn Acknowledge)

RC	RG	RORG-EN	Index	Respor	nse time	Ack C.	Mailbox		not used	i		Postma	ster ID			Contro	ller ID		Status	CHCK
	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
Α	6	C7	02					-	-	-	ID_3	ID_2	ID_1	ID_0	ID_3	ID_2	ID_1	ID_0		

Data	Value	Description					
RORG	0xA6	A6 = ADR Telegram					
RORG-EN	0xC7	RORG encapsulated / C7 = SA_LRN_ANSWER					
Index	0x02	Message Index; 02 = Learn Acknowledge					
Response time	0xnnnn	sponse time for Smart Ack Client in ms in which the controller can prepare the data d send it to the postmaster (max. value 550 ms = 0x0226)					
Acknowledge code	0x00	First Learn In successful					
Mailbox index	0xnn	Index no. of the assigned mailbox					
Postmaster ID	0xnnnnnnn	Device ID of the Post master candidate					
Controller ID	0xnnnnnnn	Device ID of the assigned controller					
Status	0x0F	0F = no repeating permitted					
CHCK	0xnn	Checksum					



3.6) UTE - Universal Uni- and Bidirectional Teach-in

General

Up to now there are teach-in procedures available for:

- RPS communication (EnOcean ID + rocker/channel information, unidirectional)
- 1BS communication (LRN telegram, w/o EEP and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, unidirectional)
- 4BS communication (LRN telegram, w FUNC+TYPE and MID, bidirectional)
- SmartACK communication (self powered devices, bidirectional)

For uni- and bidirectional EEP communication that does not fit into SmartACK communication principles but is based on e.g. MSC and VLD messages no teach-in procedure is defined so far.

Therefore, this document proposes a universal teach-in procedure that allows handling of teach-in and teach-out requirements for EEP based communication of all different RORG. This proposal shall be understood as an alternative to SmartACK teach-in for devices where SmartACK is not applicable.

RORG to be used: 0xD4 Universal Teach-in, EEP based (UTE)

FUNC and TYPE shall be represented as 8bit parameters, both with a value range from 0x00 ... 0xFF. This aligns UTE with the EEP representation defined for SmartACK teach-in.

REMARK 1:

Even though the proposed Universal Tech-In Procedure is able to cover EEPs based on RPS, 1BS and 4BS messages as well, it is not intended to replace the existing RPS, 1BS and 4BS teach-in / teach-out procedures for unidirectional and the existing 4BS teach-in / teach-out procedures for bidirectional communication.

However, it is recommended that with the acceptance of the proposed Universal Tech-In Procedure all new bidirectional 4BS applications shall use it for teach-in and teach-out as well.

REMARK 2:

The proposed Universal Tech-In Procedure is dedicated to EEP based EnOcean communication. It does neither compete with nor shall it interfere with the tech-in process of the Generic EnOcean Communication.

Communication – Principles and Definitions

BIDIRECTIONAL EEP-BASED COMMUNICATION

Bidirectional EnOcean communication means a point-to-point communication relationship between two enabled EnOcean devices. It requires all parties involved to know the unique EnOcean ID of their partners. Such point-to-point communication relationship is established with the completion of a successful teach-in process and it is deleted with the completion of a successful teach-out process.

To get a maximum reliable teach-in process with a minimum consumption of energy and resources, a simple query response mechanism is used: the device that is intended to be taught-in broadcasts a query message and gets back an addresses response message, containing its own EnOcean ID as the transmission target address.

In case there is more than one device ready to accept teach-in query messages at the same time and within the same radio range, the device with the quickest response time will be accepted by the device to be taught-in. Second and further devices will respond as well but they will not be accepted by the device to be taught-in. This will result in a configuration situation that is common to today's EEP based unidirectional teach-in processes.

UNIDIRECTIONAL EEP-BASED COMMUNICATION

Unidirectional EnOcean communication means a point-to-multipoint communication relationship between enabled EnOcean devices. In this case of broadcasting the device to be taught-in to other devices does not know the unique EnOcean ID of those communication partners.

The proposed Universal Teach-In Procedure supports unidirectional EnOcean communication thru related configuration bits in the query message.

However, for specific applications – e.g. configuration feedback - it is also possible to combine a bidirectional teach-in process with a unidirectional EEP based communication during the regular operation of a device.

EEP Teach-In Query - UTE Message (Broadcast / CMD: 0x0)

This message is sent by the EEP based EnOcean device that is intended to be taught-in to another device (which has been set into LRN-mode before either manually or thru a ReMan command).

Response Timing:

If a response is expected it shall be received within a maximum of 700ms from the time of transmission of this message. In case no such response is received within this time frame the query action shall be treated as completed with negative result. If no response is expected, each query action has to be treated as completed with positive result.



TABLE OF 7 BYTE PAYLOAD:

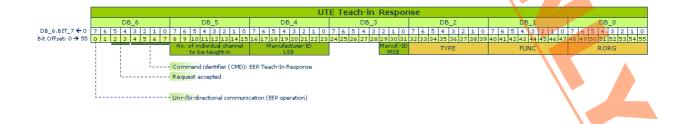
Offset	Size	Bitrange	Value	Description
0	1	DB6.7	0b0	Unidirectional communication (EEP operation)
" "	=	" "	0b1	Bidirectional communication (EEP operation)
1	1	DB6.6	0b0	EEP Teach-In-Response message expected
11 11	=	==	0b1	No EEP Teach-In-Response message expected
2	2	DB6.5 DB6.4	0b00	Teach-in request
" "	=	==	0b01	Teach-in deletion request
" "	" "	" "	0b10	Teach-in or deletion of teach-in, not specified
" "	" "	" "	0b11	Not used
4	4	DB6.3 DB6.0	0x0	Command identifier (CMD) / 0x0: EEP Teach-In Query
8	8	DB5.7 DB5.0	0x00 0xFE	Number of individual channel to be taught in
" "	=	" "	0xFF	Teach-in of all channels supported by the device
16	8	DB4.7 DB4.0	MID (8LSB)	Manufacturer-ID (8LSB)
24	5	DB3.7 DB3.3	-	Do not use
29	3	DB3.2 DB3.0	MID (3MSB)	Manufacturer-ID (3MSB)
32	8	DB2.7 DB2.0	TYPE	TYPE of EEP [0x00 0xFF]
40	8	DB1.7 DB1.0	FUNC	FUNC of EEP [0x00 0xFF]
48	8	DB0.7 DB0.0	RORG	RORG of EEP [0x00 0xFF]

EEP Teach-In Response - UTE Message (Addressed / CMD: 0x1)

This message is the reply to an EEP Teach-In Query message. It is sent by the EEP based EnOcean device that has been set into LRN-mode before (either manually by HMI or thru a ReMan command).

Response Timing:

If a response is requested this message shall be sent within a maximum of 500ms from the time of reception of the EEP Teach-In Query message. This limit shall give sufficient time to decide on the teach-in request and answer accordingly (e.g. when requests need to be processes by data base systems connected asynchronously).

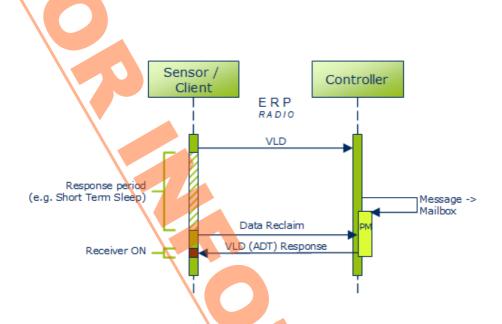


EEP 2.6.3 Specification

TABLE OF 7 BYTE PAYLOAD:

Offset	Size	Bitrange	Value	Description
0	1	DB6.7	0b0	Unidirectional communication (EEP operation)
" "	1	" "	0b1	Bidirectional communication (EEP operation)
1	1	DB6.6	-	Not used
2	2	DB6.5 DB6.4	0b00	Request not accepted, general reason
11 11	" "	The state of the s	0b01	Request accepted, teach-in successful
" "	" "	" "	0b10	Request accepted, deletion of teach-in successful
11 11	п п	" "	0b11	Request not accepted, EEP not supported
4	4	DB6.3 DB6.0	0x1	Command identifier (CMD) / 0x1: EEP Teach-In Response
8	48	DB5.7 DB0.0		Same structure as Teach-In Query message (EEP, MID and channel of requesting device is echoed back)

3.7) Smart Ack: functional principle (without repeater)



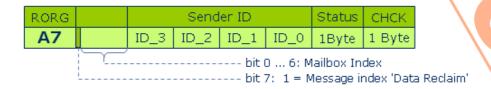
Smart Ack is a bidirectional communication protocol between a self-powered device and a line-powered controller. Data transmission in both directions is controlled by the sensor/client, as the limited energy budget requires an exact synchronization of the sent and the received messages. This pre-defined time interval allows a very short activation of the energy-intensive receiver electronics on the client.

If the teach-in procedure has already taken place as in Chapter 'Smart Ack Teach-in procedure' and the two devices already 'know each other', communication always takes place as following under Smart Ack:

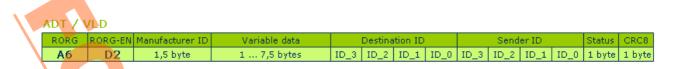
The client sends its message over a VLD telegram to the controller (Manufacturer ID = optional).

VLD										
RO	RG	Manufacturer ID	Variable data			Send	er ID		Status	CRC8
D:	2	1,5 byte	1 12,5 bytes		ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

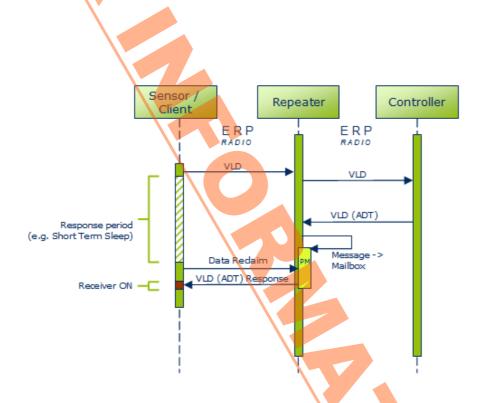
Finally, the message is processed in the controller, or forwarded to an external micro-controller over the serial interface for each use case. During the intervening period, the client is in the 'response period', which is frequently connected to an energy saving measure (like 'Short Term Sleep'). The length of this time period is agreed during the teach-in procedure between the devices as 'response time'. The feedback defined for the client is deposited in the mailbox of the postmaster (PM). When the client is active again, it requests this message containing the Smart Ack telegram DATA_RECLAIM from the responsible postmaster.



Finally, the receiver part of the client is activated and the message sent by the postmaster is accepted. In this case the VLD telegram is sent encapsulated as ADT telegram (= addressed).



3.8) Smart Ack: functional principle (with repeater)



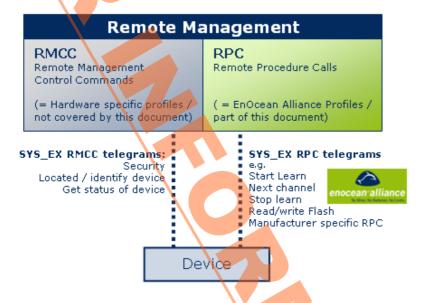
If a repeater is used, it takes over the task of the postmaster after the teach-in procedure. Hence, the client cannot view under operating conditions whether it is communicating directly with a controller or with a repeater.

The VLD telegram of the client is forwarded by the repeater 1:1 in the direction of the controller. The feedback is transferred in the form of an addressed telegram (containing Repeater ID) to the postmaster of the repeater and stored in the mailbox.

The client then turns to the repeater with its 'Data Reclaim', instead of turning to the controller, and requests the response message from the postmaster.

3.9) Remote Management / RPC

Remote Management allows EnOcean devices to be configured and maintained over the air or via a serial interface. For instance sensor or switch IDs can be stored or deleted from already installed actuators or gateways that are hard to access. There is a remote management library available for Dolphin based products.



Remote management is divided into two function groups:

RMCCs are mandatory features; they are permanently defined and they have overlapping tasks. They cannot be modified devicespecifically and are therefore, not an integral part of this description.

RPCs cover optional and manufacturer-specific features, and they have a flexible number of functionalities that can be used for numerous devices. If new device properties are mapped, RPCs can be extended correspondingly. To keep the RPCs interoperable, it is in the interest of the EnOcean Alliance to standardize these procedures.

The RPCs available today with their SYS_EX structures do not have any data-technical commonalities with EEP, but are to be handled the same way in future within the framework of coordination measures.

Structure of SYS_EX for RPC

SYS_EX telegrams for RPCs are generally encapsulated in an ADT telegram (RORG = A6) and are sent addressed as such.

ADT / SYS_EX / RPC

RORG	RORG-EN	SYS-EX data		Destina	ition ID				Send	ler ID			Status	CRC8
A6	C5	x bytes	ID_3	ID_2	ID_1	ID_0	ID.	3	ID_2	ID_	1	ID_0	1 byte	1 byte

In the following section the SYS_EX data is described in detail. Note that Remote Management RPC commands are composed of several telegrams. That means SYS_EX data is than merged in one data block. The next section describes this datablock in detail.

For further details refer to the specification Remote Management, V1.7, Dec 16, 2010, released by EnOcean GmbH www.enocean.com/fileadmin/redaktion/pdf/tec_docs/RemoteManagement.pdf , please.



Manufacturerid	0x7FF
Datalength	0x04
Broadcast	YES
Addressable	YES
Answer	NO

Offset	Size	Data	Description	Valid F	Range	Scale	Unit
0	24	EEP (ORG-FUNC-TYPE)	Determines the device type to learn in, all other devices learn telegrams are ignored. To ignore EEP controll the mask bits has to be set to 0)				
24	8	Flag	learn flag, determines different behaviour of the learn procedure	0x00:	RESERV Start lea		
		\		Next channel 0x02: Stop learn 0x03:			
			0x04: s 0x05: a	simple I SmartA	CK - Sta earn mo CK - Sta ed learn	de	
				0x06: I		CK - Sto	р

Title	RPC - Remote flash write
Function code	0x203
Manufacturerid	0x7FF
Datalength	0x04 + N
Broadcast	YES
Addressable	YES
Answer	NO

Using this command the flash of a device can be written.

Offset	Size	Data	Description
0	16	Flash Memory Address	Destination where the data should be stored
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash
32	N*8	Data	data to be transfered and written to the flash

Title	RPC - Remote flash read
Function code	0x204
Manufacturerid	0x7FF
Datalength	0x04
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the flash can be read from the application. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description
16	16	Number of Bytes	Number of bytes to be transfered and written to the flash

RPC - Remote flash read answer
0x804
0x7FF
N
NO
YES
NO

Offset	Size	Data		Desc	riptio	n
0	N*8	Data	dat	a reac	l from	flash

Title	RPC - SmartACK read settings
Function code	0x205
Manufacturerid	0×7FF
Datalength	1
Broadcast	NO
Addressable	YES
Answer	YES

Using this command the SmartACK settings and learn tables can be read from the device. The Setting type filled determines what type of data is requested. The data requested data area transmitted in RPC telegrams.

Offset	Size	Data	Description		✓ Valid Range	Scale	Unit
0		_	type of settings to read	0x00: 0x01:	RESERVED Mailbox settings Learned sensor - read the ID Controller	table of sensors i	in the

Title	RPC - SmartACK read settings - Mailbox settings	ngs answer
Function code	0x805	
Manufacturerid	0x7FF	
Datalength	4	
Broadcast	NO	
Addressable	YES	
Answer	NO	

Offset	Size	Data	Description	
0	16	SmartACK flash address	Address where the SmartACK settings are st	red
16	16	SmartACK mailbox count	number of mailboxes stored in flash	

Title RPC - SmartACK read settings - Learned sensor answer Function code 0x806 Manufacturerid 0x7FF Datalength N*9 Broadcast NO Addressable YES Answer NO		
Manufacturerid 0x7FF Datalength N*9 Broadcast NO Addressable YES	Title	RPC - SmartACK read settings - Learned sensor answer
Datalength N*9 Broadcast NO Addressable YES	Function code	0x806
Broadcast NO Addressable YES	Manufacturerid	0x7FF
Addressable YES	Datalength	N*9
	Broadcast	NO
Answer NO	Addressable	YES
	Answer	NO

 $\ensuremath{\mathsf{N}}$ - is the number of entries: SensorID, ControllerID, LearnCount

Offset	Size	Data
N*0	32	SensorID
N*32	32	ControllerID
N*64	8	Learned Count

Title	RPC - SmartACK write settings
Function code	0x206
Manufacturerid	0x7FF
Datalength	10
Broadcast	NO
Addressable	YES
Answer	YES

Using this command different type of data can be transmitted to the SmartACK devices. This command is useful when the SmartACK device has to be configured remotely. The structure of the data transmitted is depends on the Operation Type field.

Operation Type = 0x01: Add mailbox (only controller)

Offset	Size	Data	Value	Descriptio	n
0	8	Operatian Type	0x01	Add mailbox (only o	controller)
8	8	Mailbox Index			
16	32	SensorID			
48	32	PostmasterID			

Operation Type = 0x02: Delete mailbox

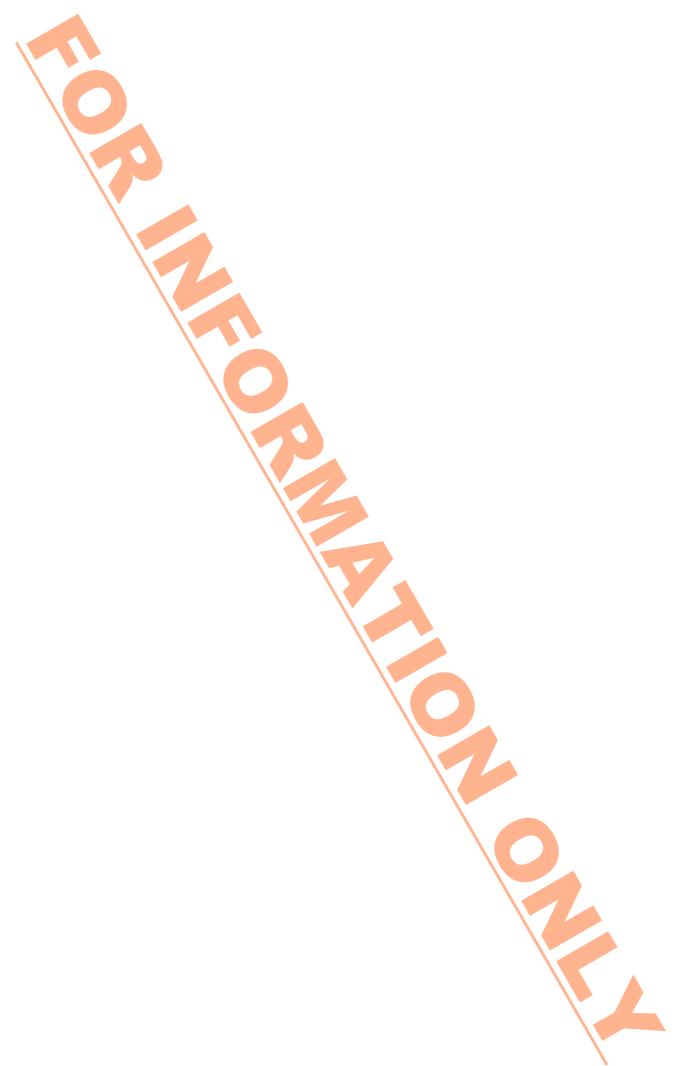
Offset	Size	Data	Value	Description
0	8	Operation Type	0x02	Delete mailbox
8	8	Mailbox Index		
16	64	Not Used (= 0)		

Operation Type = 0x03: LearnIn - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x03	LearnIn - only controller
8	8	Learn Count		
16	32	SensorID		
48	32	ControllerID		

Operation Type = 0x04: LearnOut - only controller

Offset	Size	Data	Value	Description
0	8	Operation Type	0x04	LearnOut - only controller
8	8	Learn Count		
16	32	SensorID		
48	32	ControllerID		



EEP 2.6.3 Specification

3,10) Interoperability with Security of EnOcean Networks

The Specification "Security of EnOcean Networks" defines two new telegram types for secure EnOcean telegrams in operational mode:

- R-ORG = 0x30 = SEC <u>Secure telegram</u>
- R-ORG = 0x31 = SEC_ENCAPS Secure telegram with R-ORG encapsulation

To make sure that interoperability is warranted, both telegrams may used for telegram transmission with existing EEP's. Because the profile of the device is known, the data of the SEC or SEC_ENCAPS telegram contains the same information as described in the profile, but it may be encrypted defined by the SLF (Security level format) of the device. When the device uses more than one R-ORG's in operational mode, the SEC_ENCAPS telegram has to be applied to ensure the correct original R-ORG after converting from secure to unsecure telegram. At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

Example for converting a telegram from unsecure to secure and back:

Unsecure:	4BS		Data of	profile		TX-I	D Sta	itus Chk		
Secure:	SEC	Encr	ypted D	ata of p	profile	RLC	CMAC	TX-ID	Status (Chk
Unsecure:	NON SEC		Data of	profile		TX-I	D Sta	atus Chk		

The data of the known profile will be applied in the unsecure telegram after the conversion from secure to unsecure telegram.

Example for converting a telegram from unsecure to secure and back with encapsulated R-ORG:

Unsecure:	4BS	Data	of profile	T	(-ID	Status	Chk			
Secure:	SEC ENCAPS	4BS	Encrypted Da	ata of	profile	e RLC	CMAC	TX-ID	Status	Chk
Unsecure:	4BS	Data	of profile	T	(-ID	Status	Chk			
	•									

After conversion from secure to unsecure telegram, the encapsulated R-ORG will be applied in the telegram. The data of the profile of the encapsulated R-ORG will be applied.

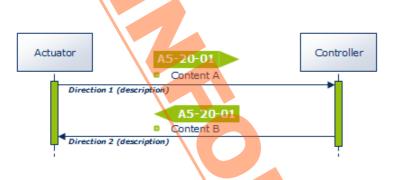
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3.11) Existing 'bidirectional' profile structures

At present, 3 different communication variants having the existing XML structure can be mapped, which approximate the principles of a bi-directional data transfer. The teach-in procedure required for this is described in the same chapter.

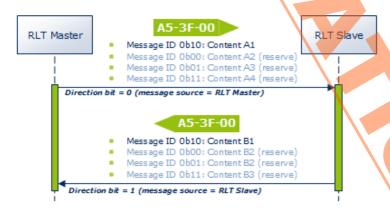
The original terminology 'transmit mode / receive mode' was not taken over, as no unique assignment to device type and hence to transmission direction can be derived there from. A neutral number (Direction 1 / 2) or the state of a bit should allow the required free space to the individual application.

Variant 1:



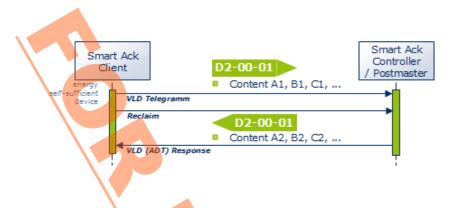
In Variant 1, there is no data-technical differentiation option in the 4BS telegram between Direction 1 and Direction 2, but only a documentation-related direction specification. No transmission direction can be detected if the telegrams are monitored on the radio stretch.

Variant 2:



In Variant 2, 3 bits are provided in the 4BS telegram, which allow up to 8 different data interpretations of the same EEP Profile No. through bit combination. 1 bit is used for direction (with the instruction text 'message source') and 2 bits for the Message ID.

Variant 3:



In Variant 3, the Smart Ack technology normally offers multiple use options of bidirectional data transmission. Smart Ack clients can therefore be energy self-sufficient devices. The used VLD telegrams allow a payload of up to 14 bytes (12.5 bytes with Manufacturer ID). Contents can thus be structured more individually.



3,12) MSC telegram - Manufacturer Specific Communication

Communication over MSC telegrams can always be used when bigger data volumes are to be transmitted, and at the same time, a closed system structure is to be created. This can be the case if e.g., the controller system backbone is expanded to include radio components, or if safety-related controls require proprietary data structures.

Such communication must not affect any interoperable EEP-based communication and should be identifiable as MSC by any Dolphin-based hardware.

Interoperability Conditions:

A device using MSC in addition to other EEPs may be marked with the EnOcean ingredient logo, as long as it complies with the rules defined by the EnOcean alliance for such markings. A device using MSC may be marked with the EnOcean ingredient logo even though the manufacturer does not disclose any or all information regarding the MSC payload. However, all other functionality of such a device shall comply with the latest EEP specification and such a device shall support at least one additional EEP. The manufacturer must clearly state which EEP(s) the device complies with. To safeguard interoperability, if there is sufficient justified doubt within the EnOcean Alliance TWG, a specific unit using MSC can be assessed by the TWG and if found to breach the interoperability intentions, the TWG may then decide (majority vote) to adapt the rules for the usage of the interoperability logo.

The MSC telegram has the same structure as a VLD telegram. The only difference is that the RORG Number is different and the payload specification is missing.

MSC									
RORG	Manufacturer ID	Variable	e data		Send	er ID		Status	CRC8
D1	1,5 byte	1 12,5	5 bytes	ID_3	ID_2	ID_1	ID_0	1 byte	1 byte

The following points are to be noted:

- 1. The usage of the Multi User Manufacturer ID (0x7FF) shall not be allowed.
- 2. Each user may send MSC telegrams under his own Manufacturer ID. The Manufacturer ID should not be left out.

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3.13) Manufacturer ID's

This chapter was transferred into a separate document entitled **EnOcean Manufacturer Identification (ManID)**. This document will be updated as soon as a new ManID will be allocated to a member of the EnOcean Alliance. The document **EnOcean Manufacturer Identification (ManID)** is stored in the webspace of the TWG on http://portal.enocean-alliance.org/MyWorkGroups/Documents.aspx (access only for registered members of the TWG).

3.14) XML + DOC Maintenance process

3.14.1) General

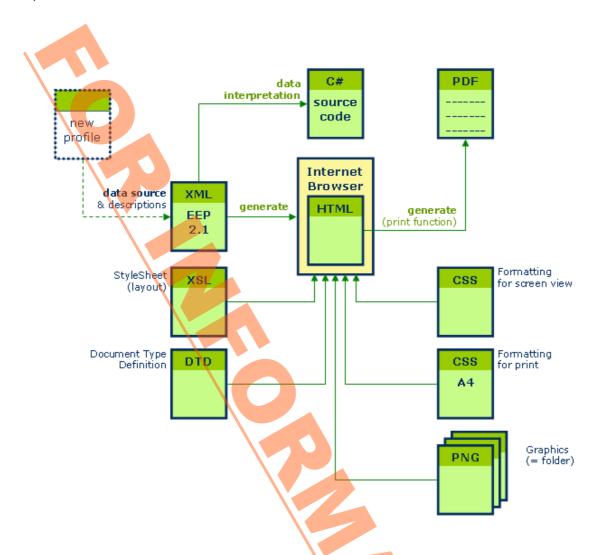
The maintenance process is descripted separately in the document: EEP2x_Maintenance_Process.pdf.

3.14.2) XML file

With EEP 2.1, a new type of documentation is introduced, which can also display logical structures next to the described contents. These can be adapted by developers into their programming environment.

XML is fully compatible with applications like C# or JAVA, and it can be combined with any application which is capable of processing XML irrespective of the platform it is being used on. If the application can work alongside XML, then XML can work on any platform and has no boundaries. It is also vendor independent and system independent.

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Only the XML data is edited and released in defined time intervals as a total release under a new version. A styles sheet file (XSL) and formatting specifications (CSS) ensure that an attractive HTML representation is possible in an internet browser. The author of the new version also creates a final PDF file.

This method ensures that the document view, as well as the software environment, remain synchronized. Errors are strongly reduced and data maintenance is optimized.

3.15) Revision

Dov	Date	Editor	Major Changes
Rev . 0.10	Date	GT	Major Changes Initial EnOcean Alliance Version created, based on the EnOcean GmbH document
0.10		GT	Standardization EnOcean Communication Profiles v1.04'
0.90		TR	EEP for ORG = 0x05 added
			EEP for ORG = $0x06$ added
			Headlines and Text formatted
0.91		TR	FUNC = 11 "Controller Status" added
			Proposals added: EEP 07-11-01 "Lightning Controller" (EchoFlex)
			EEP 07-02-0C "Temp.Sensor, Window Contact" (EchoFlex)
			EEP 07-10-0A "Temp. Sensor, Set-Point Adj., Window Contact" (EchoFlex)
			EEP 07-30-02 "Window Contact, Single Input" (EchoFlex)
0.92		TR	Manufacturer ID: Guidelines added. Definitions updated
			Revision History moved to a separate document chapter INPUT document for Berlin Meeting April 2009
2.0R		TR	EEP 07-02-0C shifted to Room Operating Panels -> EEP 07-10-0B
			EEP 06-00-00 renamed to 06-00-01
			EEP 05-xx-xx (PRS telegram / PTM200) updated with results of latest discussions
			EEP 05-04-01 (Key Card Activated Switch) updated Proposals Added:
			EEP 07-10-0C "Temp. Sensor, Occupancy Control" (Termokon)
			EEP 07-10-0D "Temp. Sensor, Day/Night Control" (Termokon)
			Ratification info and period added
2.0	July 2009		Creation of final Version V2.0 EEP 05-03-02 added
	2009		EEP 05-04-01 corrected
			EEP 06-00-01 renamed Single Input Contact
			EEP 07-10-0A and EEP 07-10-0B updated Single Input Contact
			EEP 07-30-01 and EEP 07-30-02 updated Single Input Contact 4BS teach in Telegram updated FUNC /TYPE
			Editorial corrections
2.1	Nov	Ор	The EEP 2.0 document as well as all 2.1 single documents were transferred to an XML data
R1	12,		structure and standardized. The following chapters were re-written: Introduction, Teach-in,
	2010		Bi-directional profiles, Smart Ack, RPC and MSC. Profiles that are still being coordinated were also accepted. These are characterized as 'Not approved' in the document. Bidirectional profiles
			are labeled with 'BI-DIR'. RPS ORG 05 = RORG F6; 1BS ORG 06 = RORG D5; 4BS ORG 07 =
			RORG A5
2.1	Dec	Ор	2th review
R2	31, 2010		
2.1	Jan 20,	Ор	Final version V2.1
	2011	- 1	
2.5	May	Ор	Review version 1
R1	20, 2012		Added profiles: - 1 RPS: F6-02-03
	2012		- 1 KFS. F0-02-03 - 16 4BS: A5-07-02, A5-09-02, A5-09-05, A5-09-06, A5-09-07, A5-10-1F, A5-11-03,
			A5-11-04, A5-14-01, A5-14-02, A5-14-03, A5-14-04, A5-14 <mark>-05, A5-</mark> 14-06, A5-38-08 CMD
			0x07, A5-38-09
			- 15 VLD: D2-01-0011, D2-01-0002 Updated profiles: A5-07-01, A5-09-01, A5-09-04
			Further:
			- Description: UTE – Universal Uni- and Bidirectional Teach-in
			- RPC function no. added - Manufacturer ID's added
2.5	Nov	Ор	Review version 2
R2	08,		Significant changes:
	2012		- Chapter 1.3
			- Add new profiles: A5-06-03, A5-07-03, A5-13-07 - Update of profiles: A5-10-15, A5-10-16, A5-10-17, A5-13-01, A5-13-05
2.5	Feb 03,	Op	Significant changes:
R3	2013		- Add new profiles: D2-03-00, D2-20-00, D2-20-01, D2-20-02
			- Update of profiles: A5-07-02, A5-13-02, D2-01-00
			- Deleted Chapter 'Manufacturer ID's'

2.5	March 04, 2013	Ор	FINAL version V2.5
	Nov 26, 2013	Op	Review version
2.6	Dec 17, 2013	Op	FINAL version 2.6
	Apr 15, 2014	Op	Review version
	Apr 27, 2014	Ор	2nd review version / contains EnOcean checking
2.6.1	Jun 04, 2014	Ор	FINAL version 2.6.1
	Oct 15, 2014	Ор	Review version
2.6.2	Nov 19, 2014	Ор	FINAL version 2.6.2
	May 03, 2015	Ор	Review version
2.6.3 R2	May 19, 2015	Ор	2nd Review version: - New: A5-09-0A, A5-09-0B - Modified: A5-30-06 (previous A5-0B-01) submitter, encryption, security, graphic of case 2 - Modified: D2-32-xx Enum structur
2.6.3	Jun 08, 2015	Ор	FINAL version 2.6.3 - Removed: A5-30-06 (withdrawn profile)