

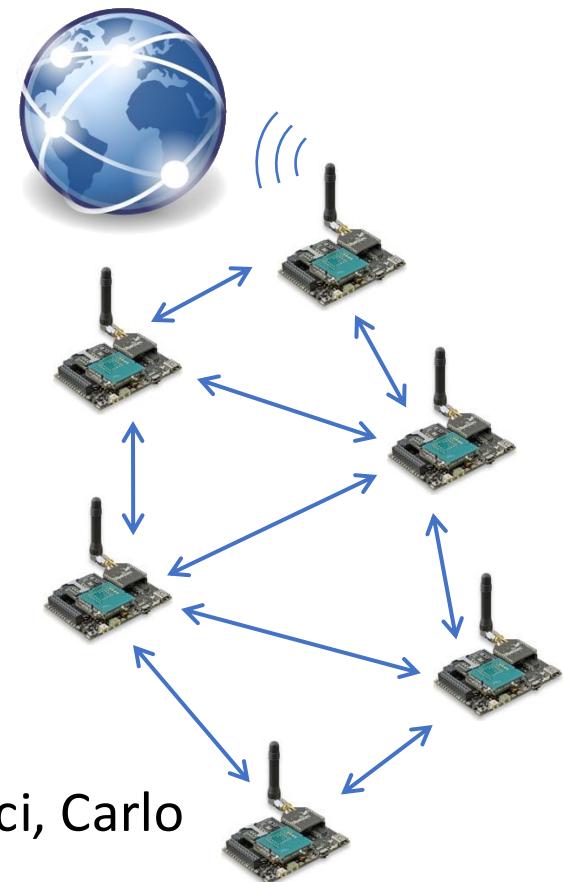
Low-power Wireless Networking for the Internet of Things

Lab3: The Rime network stack

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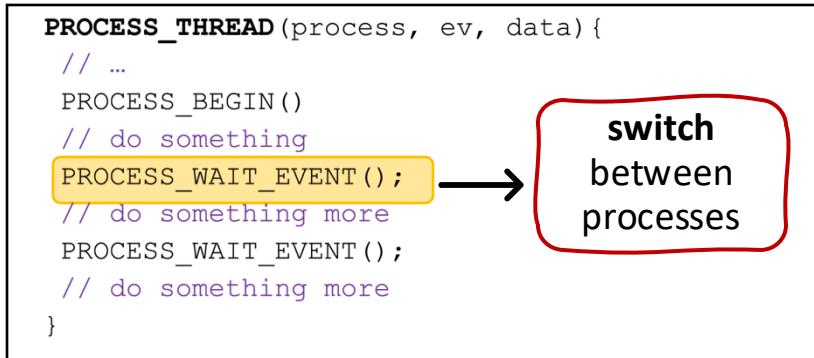
Credits for some slides to:

Timofei Istomin, Pablo Corbalán, Ramona Marfievici, Carlo Alberto Boano



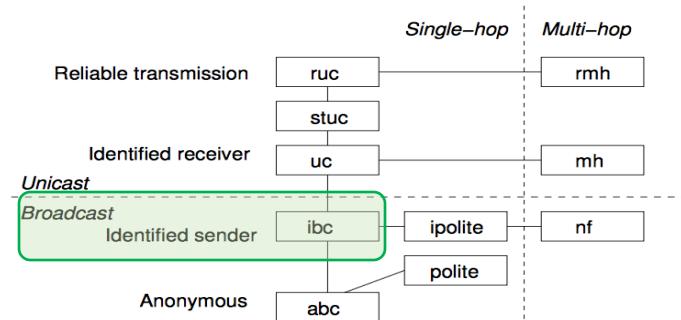
Lab 2 – Recap

- Events, processes, and protothreads



- Processes are **cooperative**
- Events govern the execution of processes

- The Rime network stack: layered architecture based on simple communication primitives



- Broadcast primitive
 - Open a connection: `broadcast_open(&connection, channel, &callbacks)`
 - Implement the SENT and RECEIVED callbacks

Function Pointers in C

```
#include <stdio.h>

void sum(int a, int b) {
    printf("Sum: %d\n", a+b);
}

void diff(int a, int b) {
    printf("Diff: %d\n", a-b);
}

/* Function pointer declaration*/
void (*fp)(int, int);

int main() {
    fp = sum;
    fp(5, 3);
    return 0;
}
```

```
struct broadcast_callbacks my_cb = {
    .recv = my_recv,
    .sent = my_sent
};

/* The callbacks structure (broadcast.h) */

struct broadcast_callbacks {
    void (*recv)(struct broadcast_conn *conn,
                 const linkaddr_t *sender);
    void (*sent)(struct broadcast_conn *conn,
                 int status, int num_tx);
}
```



Function pointer: a variable that stores the memory address of a function. It allows to call a function indirectly through the variable

OUTPUT:
Sum: 8

Function Pointers in C

```
#include <stdio.h>

void sum(int a, int b) {
    printf("Sum: %d\n", a+b);
}

void diff(int a, int b) {
    printf("Diff: %d\n", a-b);
}

/* Function pointer declaration*/
void (*fp)(int, int);

int main() {
    fp = diff;
    fp(5, 3);
    return 0;
}
```

```
struct broadcast_callbacks my_cb = {
    .recv = my_recv,
    .sent = my_sent
};

/* The callbacks structure (broadcast.h) */

struct broadcast_callbacks {
    void (*recv)(struct broadcast_conn *conn,
                 const linkaddr_t *sender);
    void (*sent)(struct broadcast_conn *conn,
                 int status, int num_tx);
}
```

Function pointer: a variable that stores the memory address of a function. It allows to call a function indirectly through the variable

OUTPUT:
Diff: 2

Function Pointers in C

```
#include <stdio.h>

void sum(int a, int b) {
    printf("Sum: %d\n", a+b);
}

void diff(int a, int b) {
    printf("Diff: %d\n", a-b);
}
```

```
struct broadcast_callbacks my_cb = {
    .recv = my_recv,
    .sent = my_sent
};

/* The callbacks structure (broadcast.h) */

struct broadcast_callbacks {
    void (*recv)(struct broadcast_conn *conn,
                 const linkaddr_t *sender);
    void (*sent)(struct broadcast_conn *conn,
                 int status, int num_tx);
}
```

```
void math_operation(int a, int b, void (*fp)(int, int)) {
    fp(a, b);
}
```

```
int main() {
    math_operation(5, 3, sum); → Sum: 8
    math_operation(5, 3, diff); → Diff: 2
    return 0;
}
```

Callback Timer (ctimer): API

```
/* Start the callback timer */

void ctimer_set(
    struct ctimer *c,
    clock_time_t t,
    void(*f)(void *), /* The CALLBACK FUNCTION */
    void *ptr); /* Data Pointer */
```

Callback Timer (ctimer)

Declaration:

- static struct ctimer ct;

How does it work?

- Calls a function when the timer expires (defined “callback”)
- Built on top of etimer

Usage in Contiki:

- Rime Stack: many primitives (e.g., stubborn unicast, collect, etc.)
- uIPv6: RPL, neighbor discovery and maintenance, etc.

Programming style: callback-based

- Different from etimers (protothread-based) --- recall LAB1

Callback Timer (ctimer): API

```
/* Start the callback timer */
void ctimer_set(
    struct ctimer *c,
    clock_time_t t,
    void(*f)(void *), /* The CALLBACK FUNCTION */
    void *ptr); /* Data Pointer */

/* Restart timer from the previous expiration time */
void ctimer_reset(struct ctimer *t);

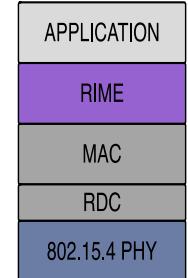
/* Restart the timer from current time */
void ctimer_restart(struct ctimer *t);

/* Stop the timer */
void ctimer_stop(struct ctimer *t);

/* Check if the timer has expired */
int ctimer_expired(struct ctimer *t);
```

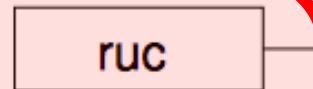
The Rime Stack

Network layer →

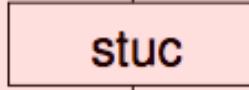


In this lab!

Reliable transmission



Identified receiver

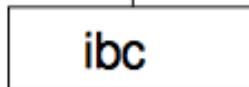


Unicast



Broadcast

Identified sender

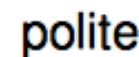
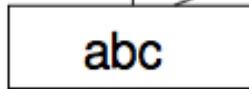


Single-hop

Multi-hop

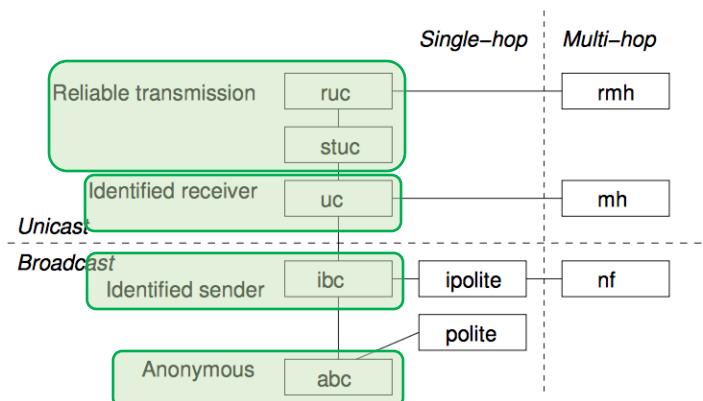
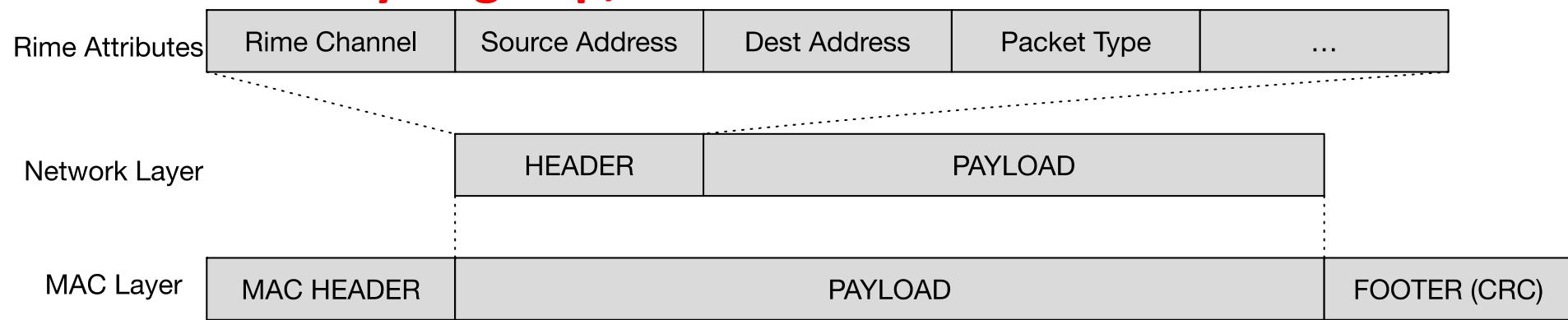


Anonymous



The Rime Stack: Protocol Headers

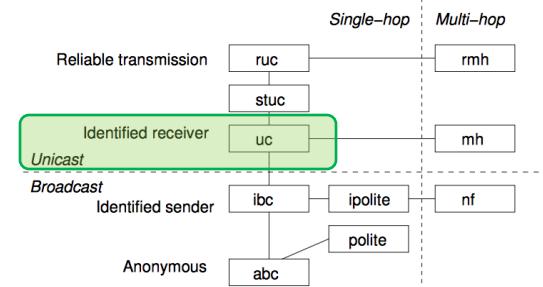
Rime Attributes change depending on the primitive!
The more you go up, the more attributes will be added!



The Unicast Primitive

How does it work?

- Built on top of broadcast primitive by adding the **destination address**
- No network-layer reliability: *one message sent, no retransmissions*



Added Rime attributes:

- Receiver address attribute: PACKETBUF_ADDR_RECEIVER

Unicast Connection:

```
static struct unicast_conn uc;
```

Callbacks:

```
static const struct unicast_callbacks uc_callbacks = {
    .recv = recv_unicast,
    .sent = sent_unicast
};
```

The Unicast Primitive: Callbacks

```
struct unicast_callbacks {
    /* RECV called when a packet has been received */
    void (* recv) (
        struct unicast_conn *c,
        const linkaddr_t *from); /* Sender ADDRESS */

    /* SENT called after transmitting a packet */
    void (* sent) (
        struct unicast_conn *c,
        int status, /* From MAC Layer: TX_OK, COLLISION */
        int num_tx); /* From MAC Layer: number of TX */
};
```

The Unicast Primitive: API

```
/* Open a Unicast connection */
void unicast_open(  
    struct unicast_conn *c,  
    uint16_t channel, /* Similar to TCP port */  
    const struct unicast_callbacks *u);  
  
/* Close a Unicast connection */
void unicast_close(struct unicast_conn *c)  
  
/* Send a Unicast packet */
int unicast_send(  
    struct unicast_conn *c,  
    const linkaddr_t *receiver);
```

You need to specify
the receiver address!

The Unicast Primitive: Example

```
static struct unicast_conn uc;

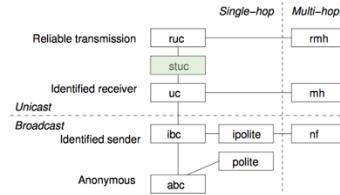
void my_recv(struct unicast_conn *conn, const linkaddr_t *from) {
    /* Your code here... */
}

struct unicast_callbacks my_cb = { .recv = my_recv, .sent = NULL };

PROCESS_THREAD(my_process, ev, data)
{
    PROCESS_BEGIN();
    unicast_open(&uc, 146, &my_cb);

    while(1) {
        /* Do something or wait for events */
        unicast_send(&uc, &dest); /* Send packet to dest */
    }
    PROCESS_END();
}
```

NULL = not interested



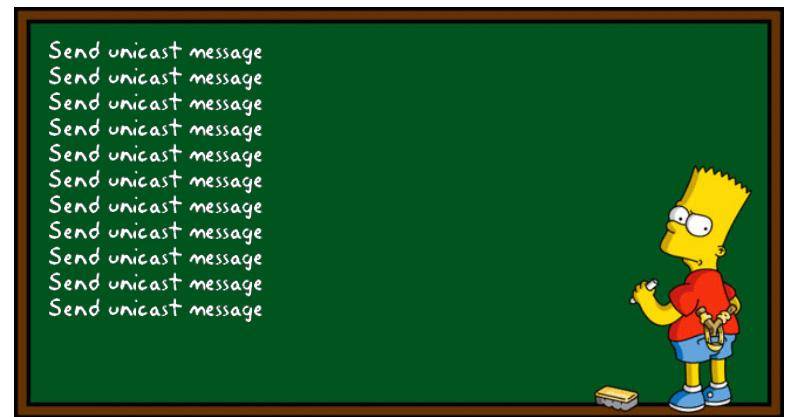
Stunicast: The Stubborn Unicast Primitive

Why stubborn?

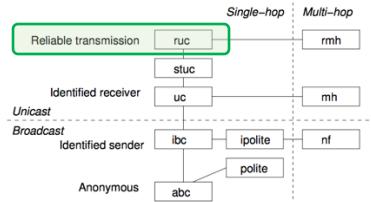
- **Repeatedly** send a packet until an upper layer (e.g., **runicast**) cancels the transmission

In a nutshell:

- Built on top of unicast
- Rime attributes: same as unicast
- Stunicast uses:
 - **queuebuf** to store the packet and its attributes
 - **ctimers** to schedule packet transmissions
- Behavior: when the **ctimer expires**, stunicast copies the data from the **queuebuf** to the **packetbuf** and re-sends the packet



Adding Reliability: the Runicast Primitive



How does it work?

- Built on top of stunicast by adding ACKs and a stop
- **Reliable**: it sends a message until it receives an ACK or reaches the maximum number of retransmissions (configurable)

Added Rime attributes:

- Packet type: data or ACK
- Packet ID: seqno to match packets with ACKs

Declaration:

```
static struct runicast_conn runicast;
```

Callbacks:

```
static const struct runicast_callbacks ruc_callbacks = {  
    recv_runicast, sent_runicast, timedout_runicast};
```

The Runicast Primitive: Callbacks

```
struct runicast_callbacks {

    /* RECV called when a packet has been received */
    void (*recv)(
        struct runicast_conn *c,
        const linkaddr_t *from,
        uint8_t seqno); /* Runicast SEQNO for ACKs */

    /* SENT called after successful packet TX */
    void (*sent)(
        struct runicast_conn *c,
        const linkaddr_t *to,
        uint8_t retransmissions);

    /* TIMEDOUT --- packet not received or properly ACK*/
    void (*timedout)(
        struct runicast_conn *c,
        const linkaddr_t *to,
        uint8_t retransmissions);

};
```

The Reliable Unicast Primitive: API

```
/* Open a Runicast connection */
void runicast_open(
    struct runicast_conn *c,
    uint16_t channel, /* Similar to TCP port */
    const struct runicast_callbacks *u);

/* Close a Unicast connection */
void runicast_close(struct runicast_conn *c);

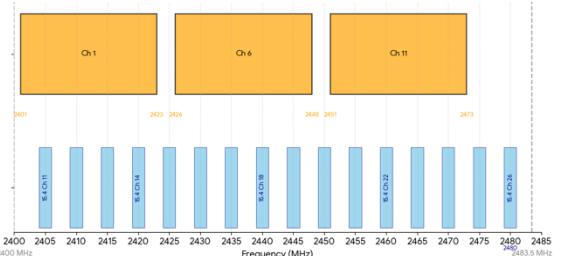
/* Send a Runicast packet */
int runicast_send(
    struct runicast_conn *c,
    const linkaddr_t *receiver,
    uint8_t max_retransmissions);

/* Is Runicast transmitting a packet? */
uint8_t runicast_is_transmitting(struct runicast_conn *c);
```

Specify the **maximum** number of TXs, e.g., 4 or 8

RF Configuration

Wi-Fi



IEEE 802.15.4 (2.4 GHz):

- RF Channel: For narrowband devices, 16 channels available (from channel 11 to 26). So far channel 26 has been exploited (`project-conf.h`).
- TX power: E.g., you can TX at 0dBm (1mW)
- CSMA Clear Channel Assessment (CCA) Threshold

RF Configuration Parameters:

 (`contiki-uwb/contiki/core/dev/radio.h`)

- RF Channel: `RADIO_PARAM_CHANNEL`
- TX power: `RADIO_PARAM_TXPOWER`
- CCA Threshold: `RADIO_PARAM_CCA_THRESHOLD`

To read a value:

```
radio_value_t rfval;  
NETSTACK_RADIO.get_value(RADIO_PARAM_CHANNEL, &rfval)
```

To set a value:

```
radio_value_t rfval = 26;  
NETSTACK_RADIO.set_value(RADIO_PARAM_CHANNEL, &rfval)
```

Noise floor and RSSI

Noise floor: RADIO_PARAM_RSSI

```
radio_value_t rfval;  
NETSTACK_RADIO.get_value(RADIO_PARAM_RSSI, &rfval);
```

[Last Packet] Received Signal Strength Indicator (RSSI): RADIO_PARAM_LAST_RSSI

```
radio_value_t rfval;  
NETSTACK_RADIO.get_value(RADIO_PARAM_LAST_RSSI, &rfval);
```

→ E.g., to get a rough estimate of the link quality

Code Templates

Download and unzip the provided code

- Unzip Lab3-exercise.zip

Go to the code directory

- \$ cd Lab3-exercise/ping-pong-exercise

The file you should edit is **uc-ctimer.c**

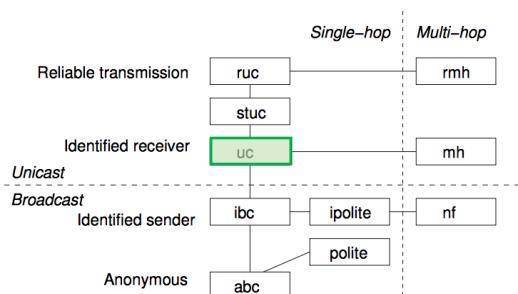
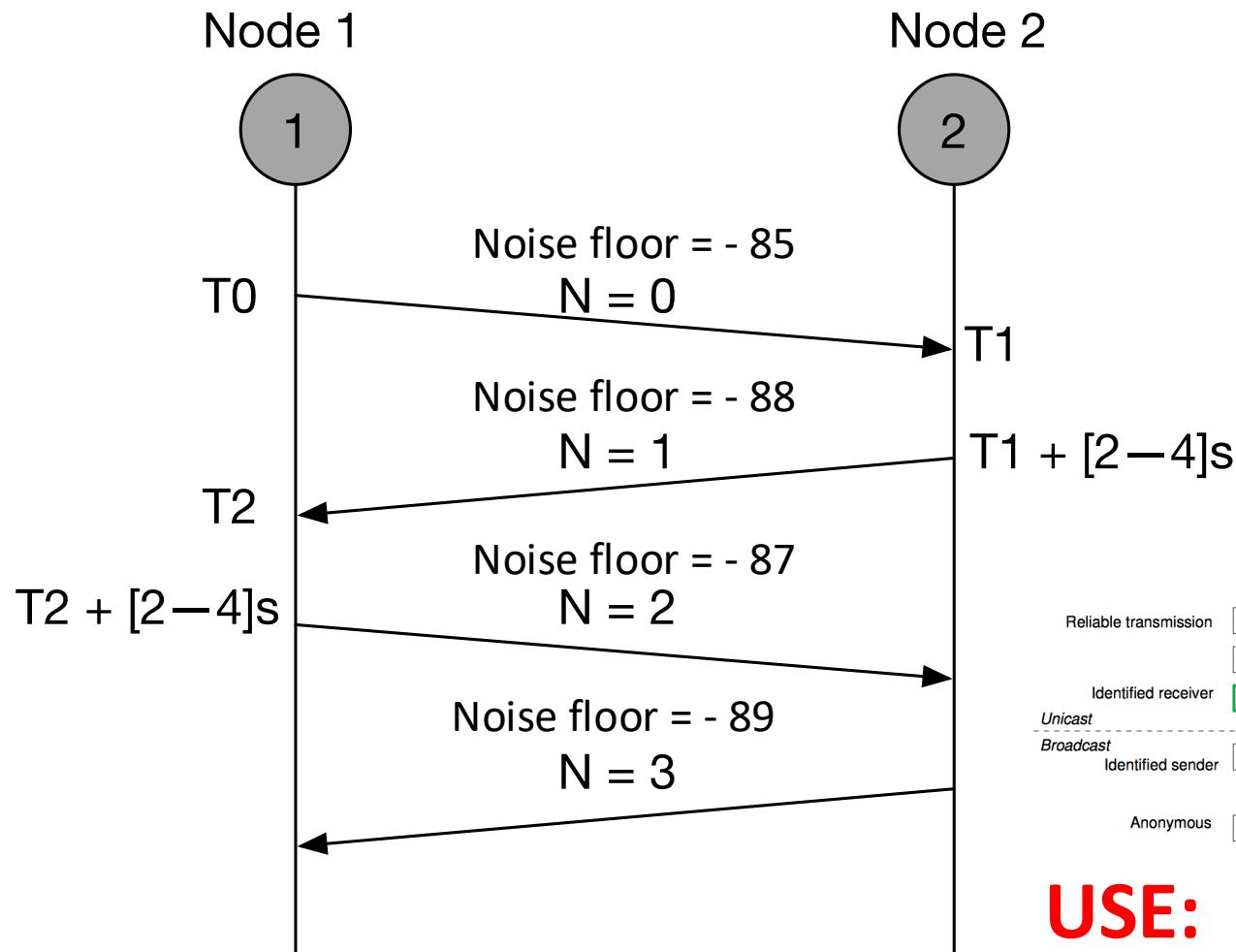
To compile:

- \$ make or make TARGET=SKY

When everything seems to work, test it in Cooja:

- \$ cooja **lab3-ctimer.csc** &

Exercise: Ping-Pong Application



**USE:
UNICAST and CTIMERS**

Credit for the exercise idea to:
Ramona Marfievici

Exercise – packet structure

```
typedef struct ping_pong_msg {  
    uint16_t sequence_number;  
    int16_t noise_floor;  
} ping_pong_msg_t;
```

Already provided in **uc-ctimer.c**,
alongside other template code and
several TODOs.
Check them all before start coding!!!

What to do?

- For the first message, set the `ctimer`, when it expires (i) fill in the packet with the `noise_floor` and the `ping_pong_number`, and (ii) send the packet
- Next, consider how (and where) you can use the `ctimer` to let the receiver react to the packet reception, allowing the ping-pong exchange to continue.

Hint:

- Initially set `noise_floor` to 0 and focus only on making the ping-pong application work
- Once it works, add the real noise floor to the message structure

Optional Exercise

If you don't remember something, check the Lab 2 slides!

Same application but with **Etimers + Process Events**

Instructions:

- Template code in **uc_etimer.c**
- Cooja simulation: **\$ cooja lab3-etimer.csc &**

Hints: **(check them ONLY if you are lost)**

- Upon receiving a message: post a custom process event (**app_event**) to the main process
- Handling **app_event**: set an etimer with 2–4s timeout
- Timer expiration: send the ping-pong message

Finished? Try with **runicast**!

Recap: Packet Buffer (packetbuf.h)

To send a packet:

1. Clear packetbuf: **packetbuf_clear()** ;
2. Copy your message to packetbuf:
packetbuf_copyfrom(
 const void ***from**, /* Message to copy */
 uint16_t **len**); /* Message length */
3. Send message: **unicast_send**(&uc, &dest) ;

OPTIONAL!

packetbuf_copyfrom
clears the buffer anyway ☺

To read a received packet:

1. Received data length: **packetbuf_datalen()** ;
2. Pointer to the received data in packetbuf:
void* packetbuf_dataptr() ;
3. Use **memcpy**(void ***to**, void ***from**, int **length**) to
retrieve data from the packetbuf

Suggested reading

1. A. Dunkels. **Rime — A Lightweight Layered Communication Stack for Sensor Networks.** In *Proceedings of the European Conference on Wireless Sensor Networks (EWSN)*, 2007. [PDF](#)
2. A. Dunkels, F. Österlind, and Z. He. **An Adaptive Communication Architecture for Wireless Sensor Networks.** In *Proceedings of the 5th ACM Int. Conference on Embedded Networked Sensor Systems (SenSys)*, 2007. [PDF](#)
3. **Contiki Wiki: Timers**
<https://github.com/contiki-os/contiki/wiki/Timers>
4. **Contiki Wiki: Processes**
<https://github.com/contiki-os/contiki/wiki/Processes>