

6. en el caso 3D sea $\{e_i\}$ define un sistema de coordenadas dextrógiro
no necesariamente ortogonal
Demuestre que

(a)

$$e^i = \frac{e_j \times e_k}{e_i \cdot (e_j \times e_k)}, \quad i, j, k = 1, 2, 3 \text{ y las permutaciones cíclicas}$$

$\begin{matrix} 2, 3, 1 \\ 3, 1, 2 \end{matrix}$

intentamos generar de la base dual la base covariante

sea entonces

$$e^1 = \frac{e_2 \times e_3}{e_1 \cdot (e_2 \times e_3)}, \quad e^2 = \frac{e_3 \times e_1}{e_2 \cdot (e_3 \times e_1)}, \quad e^3 = \frac{e_1 \times e_2}{e_3 \cdot (e_1 \times e_2)}$$

esto sera cierto si $e^i \cdot e_i = 1$ y $e^i \cdot e_j = 0$

$$e^1 \cdot e_1 = \frac{e_2 \times e_3}{e_1 \cdot (e_2 \times e_3)} \cdot e_1 \Rightarrow \frac{e_1 \cdot (e_2 \times e_3)}{e_1 \cdot (e_2 \times e_3)} = 1$$

$$e^2 \cdot e_2 = \frac{e_3 \times e_1}{e_2 \cdot (e_3 \times e_1)} \cdot e_2 \Rightarrow \frac{e_2 \cdot (e_3 \times e_1)}{e_2 \cdot (e_3 \times e_1)} = 1$$

tomando la propiedad del producto triple
 las permutaciones cíclicas tenemos

$$e^3 \cdot e_3 = \frac{e_1 \times e_2}{e_3 \cdot (e_1 \times e_2)} \cdot e_3 \Rightarrow \frac{e_3 \cdot (e_1 \times e_2)}{e_3 \cdot (e_1 \times e_2)} = 1$$

tenemos que

$$e^i \cdot e_i = 1$$

$$e^1 \cdot e_2 = \frac{e_2 \times e_3}{e_1 \cdot (e_2 \times e_3)} \cdot e_2 = \frac{e_2 \cdot (e_2 \times e_3)}{e_1 \cdot (e_2 \times e_3)} = 0$$

Por propiedades $(e_2 \times e_3) \perp e_2$
 y su producto punto sera cero

$$e^1 \cdot e_3 = \frac{e_2 \times e_3}{e_1 \cdot (e_2 \times e_3)} \cdot e_3 = \frac{e_3 \cdot (e_2 \times e_3)}{e_1 \cdot (e_2 \times e_3)} = 0 \quad \dots \text{ y así para todos}$$

Siendo entonces $e^i \cdot e_j = 0$ Q.E.D

(b) Si los volúmenes: $V = e_1 \cdot (e_2 \times e_3)$ y $\tilde{V} = e^1 \cdot (e^2 \times e^3)$
entonces $V\tilde{V} = 1$

sea $e^1 = \frac{(e_2 \times e_3)}{e_1 \cdot (e_2 \times e_3)}$, $e^2 = \frac{(e_3 \times e_1)}{e_1 \cdot (e_2 \times e_3)}$, $e^3 = \frac{(e_1 \times e_2)}{e_1 \cdot (e_2 \times e_3)}$

$$\tilde{V} = \frac{e_2 \times e_3}{e_1 \cdot (e_2 \times e_3)} \cdot \left(\frac{(e_3 \times e_1)}{e_1 \cdot (e_2 \times e_3)} \times \frac{(e_1 \times e_2)}{e_1 \cdot (e_2 \times e_3)} \right)$$

$$V\tilde{V} = e_1 \cdot (e_2 \times e_3) \cdot \left(\frac{e_2 \times e_3}{e_1 \cdot (e_2 \times e_3)} \cdot \left(\frac{e_3 \times e_1}{e_1 \cdot (e_2 \times e_3)} \times \frac{e_1 \times e_2}{e_1 \cdot (e_2 \times e_3)} \right) \right)$$

$$V\tilde{V} = e_2 \times e_3 \cdot (e_2 \times e_3)$$

$$V\tilde{V} = e_1 \cdot e_1 = 1 \quad QED$$

(c) ¿Que vector satisface $a \cdot e^i = 1$, Demuestre que es unico

sea $e^i = \frac{e_j \times e_k}{e_i \cdot (e_j \times e_k)}$ y $a = (a_1, a_2, a_3)$

$$a \cdot (e_j \times e_k) = e_i \cdot (e_j \times e_k)$$

$$a = \frac{e_i \cdot (e_j \times e_k)}{(e_j \times e_k)}$$

$$a = e_i \quad \checkmark \quad \text{entonces} \quad e_i \cdot e^i = 1 \quad \checkmark$$

d) Encuentre el producto vectorial de los vectores a y b que están en el sistema

$$w_1 = 4\hat{i} + 2\hat{j} + \hat{k}$$

$$w_2 = 3\hat{i} + 3\hat{j}$$

$$w_3 = 2\hat{k}$$

Expresados en esta base son tal que

$$a = (a_1, a_2, a_3)$$

$$b = (b_1, b_2, b_3)$$

$$a = a_1 w_1 + a_2 w_2 + a_3 w_3$$

$$b = b_1 w_1 + b_2 w_2 + b_3 w_3$$

$$a \times b = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ a_1 w_1 & a_2 w_2 & a_3 w_3 \\ b_1 w_1 & b_2 w_2 & b_3 w_3 \end{vmatrix} = \epsilon_{ijk} a_j b_k$$

I Las bases reciprocas $\{e^i\}$

$$e^1 = \frac{(w_2 \times w_3)}{w_1 \cdot (w_2 \times w_3)} = \frac{6\hat{i} - 6\hat{j}}{-36}$$

$$e^2 = \frac{(w_3 \times w_1)}{w_2 \cdot (w_3 \times w_1)} = \frac{-12\hat{i}}{-36}$$

$$e^3 = \frac{(w_1 \times w_2)}{w_3 \cdot (w_1 \times w_2)} = \frac{-3\hat{i} + 3\hat{j} - 18\hat{k}}{-36}$$

II Las componentes covariantes y contravariantes de $a = \hat{i} + 2\hat{j} + 3\hat{k}$

Covariantes

$$a|w_1\rangle = 15$$

$$a|w_2\rangle = 9$$

$$a|w_3\rangle = 6$$

Contravariantes

$$\langle e^1 | a \rangle = \frac{1}{6}$$

$$\langle e^2 | a \rangle = \frac{1}{3}$$

$$\langle e^3 | a \rangle = \frac{17}{12}$$