

Manual Trace of the Daltonization Algorithm

Input RGB Image / Video Feed Frame

Converting RGB image to LMS image

Simulate color blindness on 'LMS Image' -> 'Simulated LMS Image'

Compensate 'Simulated LMS Image' -> 'Simulated RGB Image'

Convert 'Simulated RGB Image' to 'Compensated/Daltonized RGB Image'

Output Daltonized RGB Image

Converting RGB image to LMS image					
	RGB2LMS = [[17.8824,43.5161,4.11935],	Line	i	j	
	[3.45565,27.1554,3.86714],	1	0		1st row
	[0.0299566,0.184309,1.46709]]	3		0	
		5-15			LMS multiplication
1	i = 0	16		1	
2	WHILE i < height DO	5-15			LMS multiplication
3	j = 0	16		2	
4	WHILE j < width DO #(j, i) refer to pixel position			
5	R = RGB_image[j, i, 0]	16		width	
6	G = RGB_image[j, i, 1]	18	1		2nd row
7	B = RGB_image[j, i, 2]	3		0	
8		5-15			LMS multiplication
9	L = RGB2LMS[0][0] * R + RGB2LMS[0][1] * G + RGB2LMS[0][2] * B	16		1	
10	M = RGB2LMS[1][0] * R + RGB2LMS[1][1] * G + RGB2LMS[1][2] * B			
11	S = RGB2LMS[2][0] * R + RGB2LMS[2][1] * G + RGB2LMS[2][2] * B	16		width	
12		18	2		3rd row
13	LMS_image[j, i, 0] = L	3		0	
14	LMS_image[j, i, 1] = M	5-15			LMS multiplication
15	LMS_image[j, i, 2] = S	16		1	
16	j = j + 1			
17	END WHILE	16		width	
18	i = i + 1			
19	END WHILE	18	height		End
		Time complexity = O(height x width) = O(n)			

Simulate color blindness on 'LMS Image' -> 'Simulated LMS Image'					
colorblind_type = 0 # For example; 0 is for Protanope, 1 is for Deutanope, and 2 is for Tritanope	Line	i	j		
L, M, and S values from previous process	1	0			1st Row
1 i = 0	3		0		
2 WHILE i < height DO	9-34			LMS multiplication	Row loop
3 j = 0	34		1		
4 WHILE j < width DO	9-34			LMS multiplication	
5 L = LMS_image[j, i, 0]	34		2		
6 M = LMS_image[j, i, 1]	...				
7 S = LMS_image[j, i, 2]	34		width		
8	36	1			2nd Row
9 IF colorblind_type == 0 THEN	3		0		
10 simulated_L = protanope_matrix[0][0] * L + protanope_matrix[0][1] * M + protanope_matrix[0][2] * S	9-34			LMS multiplication	Row loop
11 simulated_M = protanope_matrix[1][0] * L + protanope_matrix[1][1] * M + protanope_matrix[1][2] * S	34		1		
12 simulated_S = protanope_matrix[2][0] * L + protanope_matrix[2][1] * M + protanope_matrix[2][2] * S	...				
13	34		width		
14 ELSE IF colorblind_type == 1 THEN	...				
15 simulated_L = deutanope_matrix[0][0] * L + deutanope_matrix[0][1] * M + deutanope_matrix[0][2] * S	36	height			End
16 simulated_M = deutanope_matrix[1][0] * L + deutanope_matrix[1][1] * M + deutanope_matrix[1][2] * S	Time complexity = O(height x width) = O(n)				
17 simulated_S = deutanope_matrix[2][0] * L + deutanope_matrix[2][1] * M + deutanope_matrix[2][2] * S					
18					
19 ELSE IF colorblind_type == 2 THEN					
20 simulated_L = tritanope_matrix[0][0] * L + tritanope_matrix[0][1] * M + tritanope_matrix[0][2] * S					
21 simulated_M = tritanope_matrix[1][0] * L + tritanope_matrix[1][1] * M + tritanope_matrix[1][2] * S					
22 simulated_S = tritanope_matrix[2][0] * L + tritanope_matrix[2][1] * M + tritanope_matrix[2][2] * S					
23					
24 ELSE # original LMS values					
25 simulated_L = L					
26 simulated_M = M					
27 simulated_S = S					
28 END IF					
29					
30 simulated_image[j, i, 0] = simulated_L					
31 simulated_image[j, i, 1] = simulated_M					
32 simulated_image[j, i, 2] = simulated_S					
33					
34 j = j + 1					
35 END WHILE					
36 i = i + 1					
37 END WHILE					

Compensate 'Simulated LMS Image' -> 'Simulated RGB Image'					
	LMS2RGB = [[0.0809444479, -0.130504409, 0.116721066],	Line	i	j	
	[-0.0102485335, 0.0540193266, -0.113614708],	1	0		1st row
	[-0.000365296938, -0.00412161469, 0.693511405]]	3		0	
		5-15			RGB multiplication
1	i = 0	16		1	Row loop
2	WHILE i < height DO	5-15			RGB multiplication
3	j = 0	16		2	
4	WHILE j < width DO #(j, i) refer to pixel position			
5	L = LMS_image[j, i, 0]	16		width	
6	M = LMS_image[j, i, 1]	18	1		2nd row
7	S = LMS_image[j, i, 2]	3		0	
8		5-15			RGB multiplication
9	R = LMS2RGB[0][0] * L + LMS2RGB[0][1] * M + LMS2RGB[0][2] * S	16		1	Row loop
10	G = LMS2RGB[1][0] * L + LMS2RGB[1][1] * M + LMS2RGB[1][2] * S			
11	B = LMS2RGB[2][0] * L + LMS2RGB[2][1] * M + LMS2RGB[2][2] * S	16		width	
12		18	2		3rd row
13	RGB_image[j, i, 0] = R	3		0	
14	RGB_image[j, i, 1] = G	5-15			RGB multiplication
15	RGB_image[j, i, 2] = B	16		1	Row loop
16	j = j + 1			
17	END WHILE	16		width	
18	i = i + 1			
19	END WHILE	18	height		End
					Time complexity = O(height x width) = O(n)

Convert 'Simulated RGB Image' to 'Compensated/Daltonized RGB Image'					
1	i = 0	Line	i	j	
2	WHILE i < height DO	1	0		1st row
3	j = 0	3		0	
4	WHILE j < width DO	5-19			Conversion process
5	simulated_R = simulated_RGB_image[j, i, 0]	21		1	
6	simulated_G = simulated_RGB_image[j, i, 1]	5-19			Conversion process
7	simulated_B = simulated_RGB_image[j, i, 2]	21		2	
8	# Isolate "invisible colors" (colors that people with a CVD can't see)			
9	error_R = R - simulated_R	21		width	
10	error_G = G - simulated_G	23	1		2nd row
11	error_B = B - simulated_B	3		0	
12	# Shift the colors towards the visible spectrum	5-19			Conversion process
13	compensated_R = (0.0 * error_R) + (0.0 * error_G) + (0.0 * error_B)	21		1	
14	compensated_G = (0.7 * error_R) + (1.0 * error_G) + (0.0 * error_B)			
15	compensated_B = (0.7 * error_R) + (0.0 * error_G) + (1.0 * error_B)	21		width	
16	# Add compensation	23	2		3rd row
17	compensated_R = compensated_R + R	3		0	
18	compensated_G = compensated_G + G	5-19			Conversion process
19	compensated_B = compensated_B + B	21		1	
20				
21	j = j + 1	21		width	
22	END WHILE			
23	i = i + 1	23	height		End
24	END WHILE				