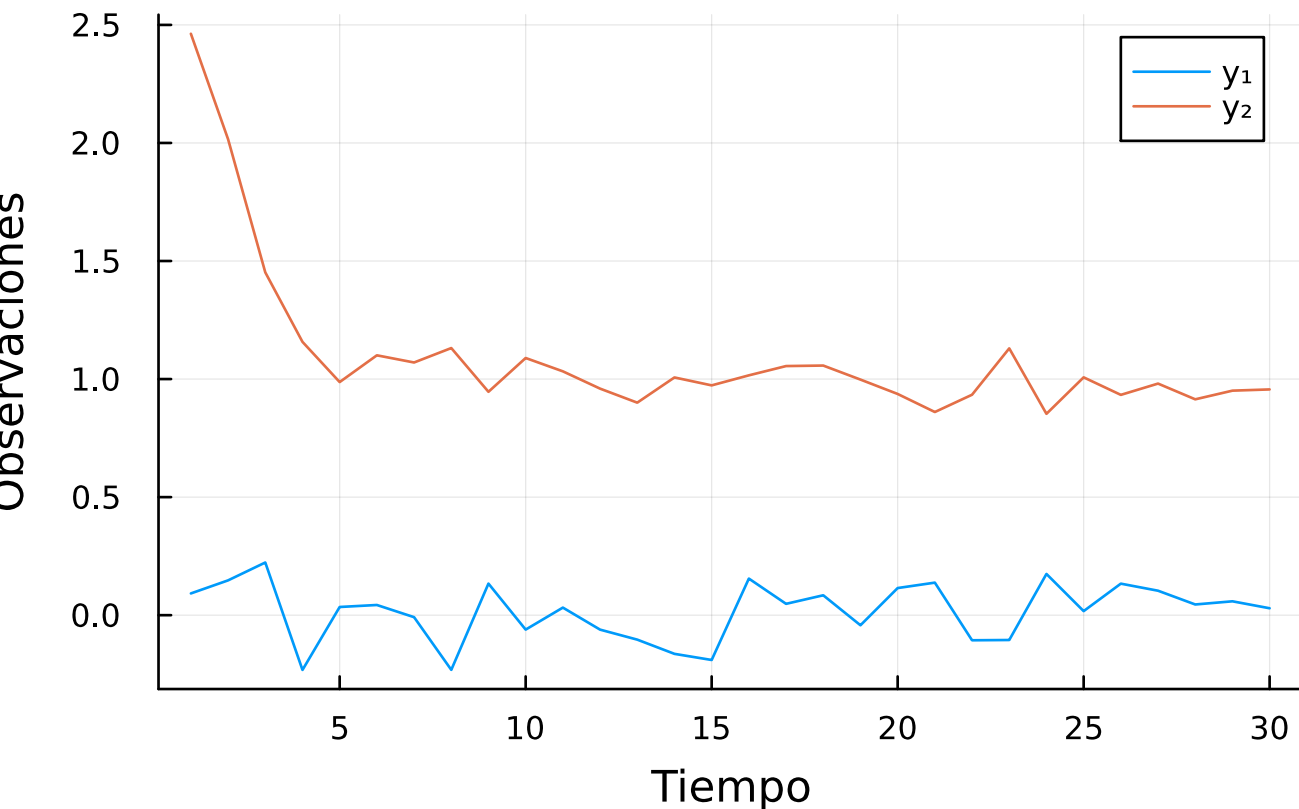
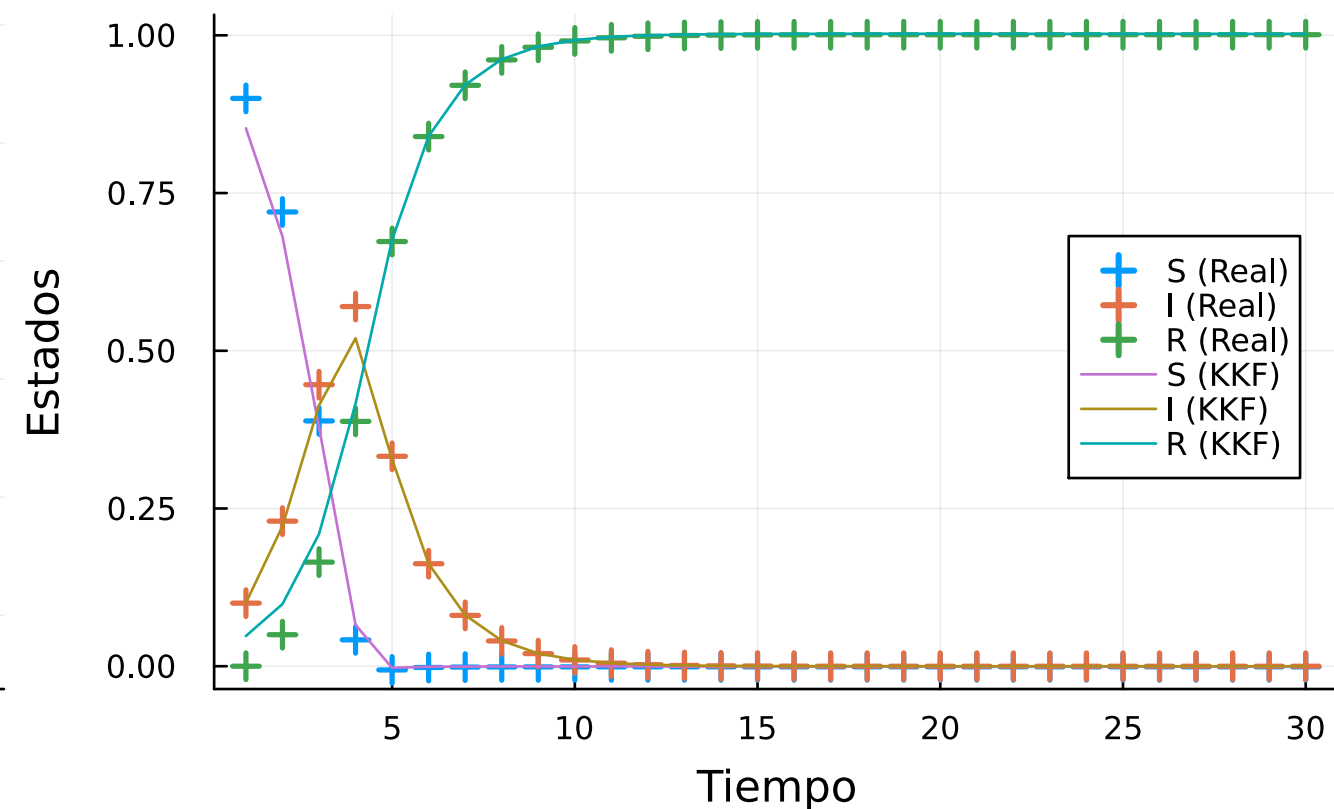


Ruido de dinámica con $\sigma = 0.001$

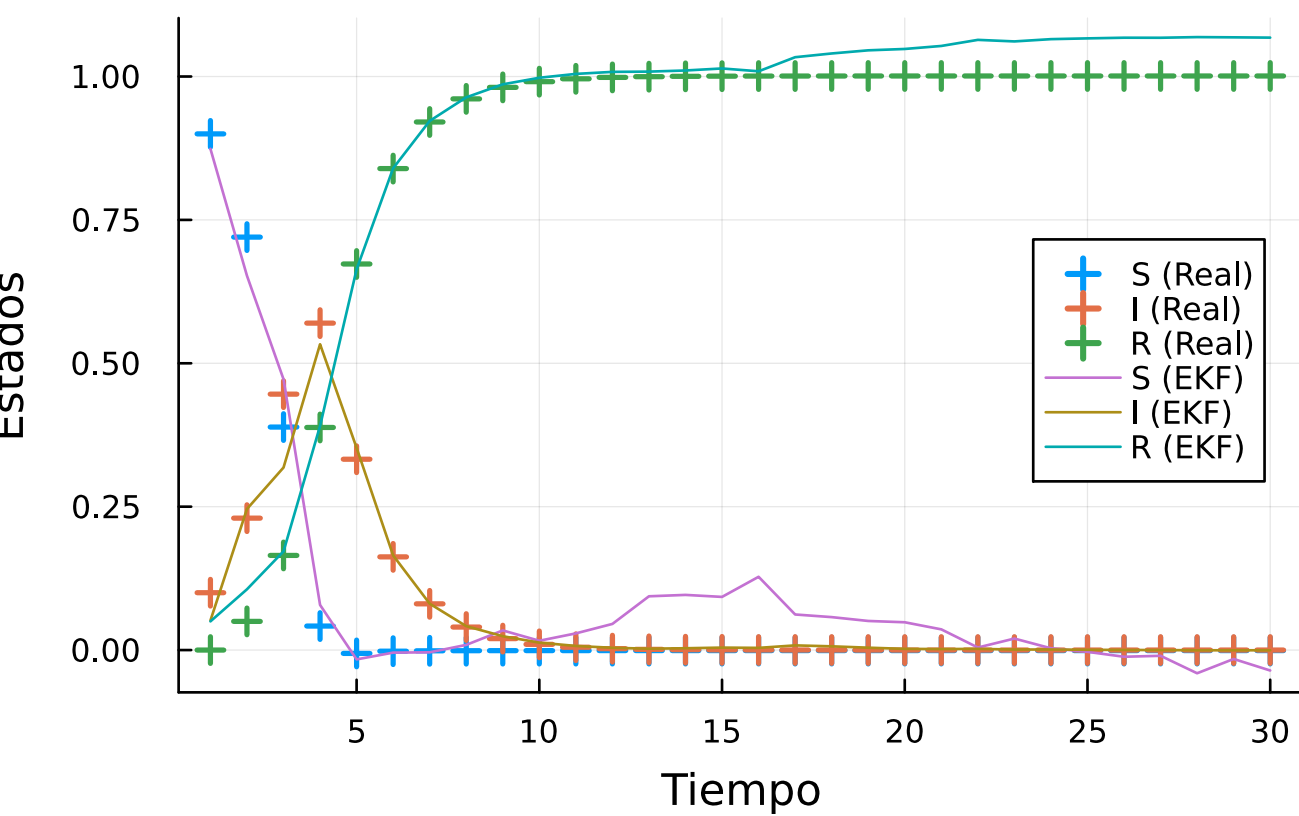
Observaciones no lineales ruidosas



KKF



EKF



UKF

