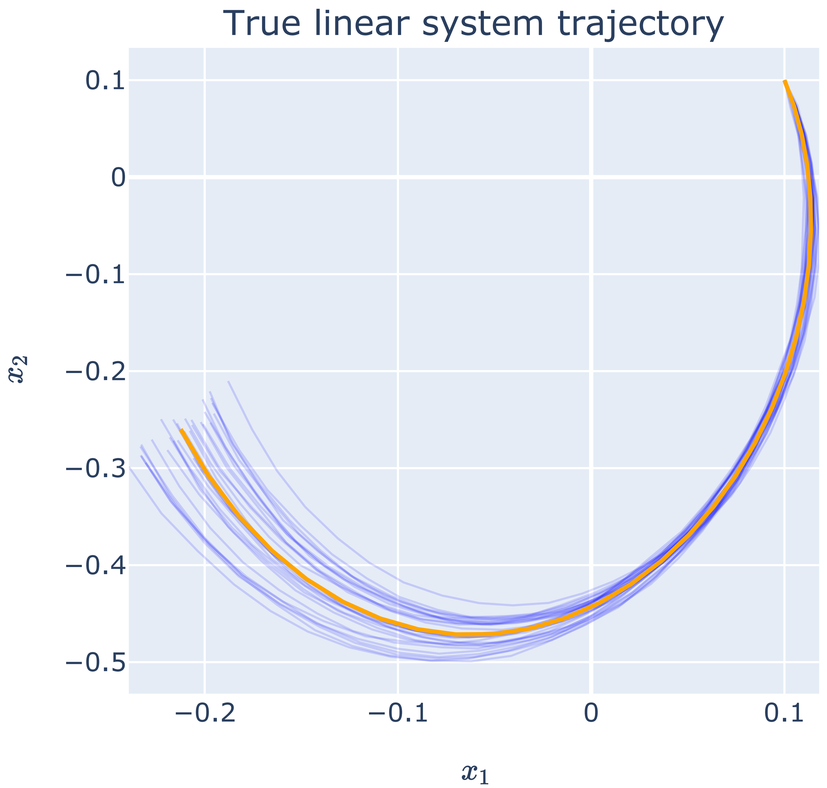
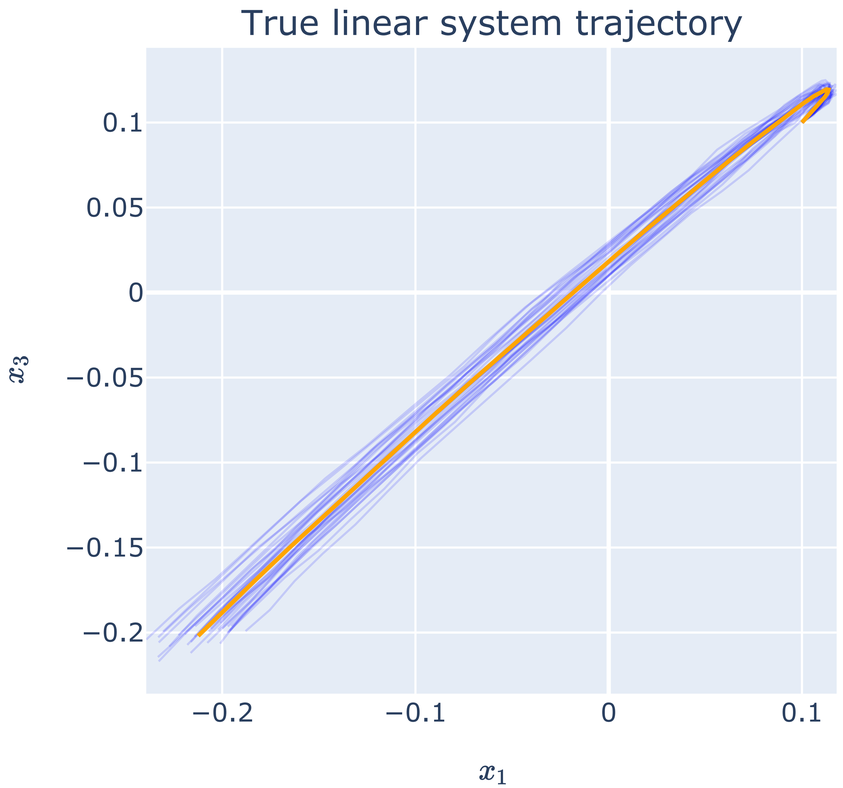
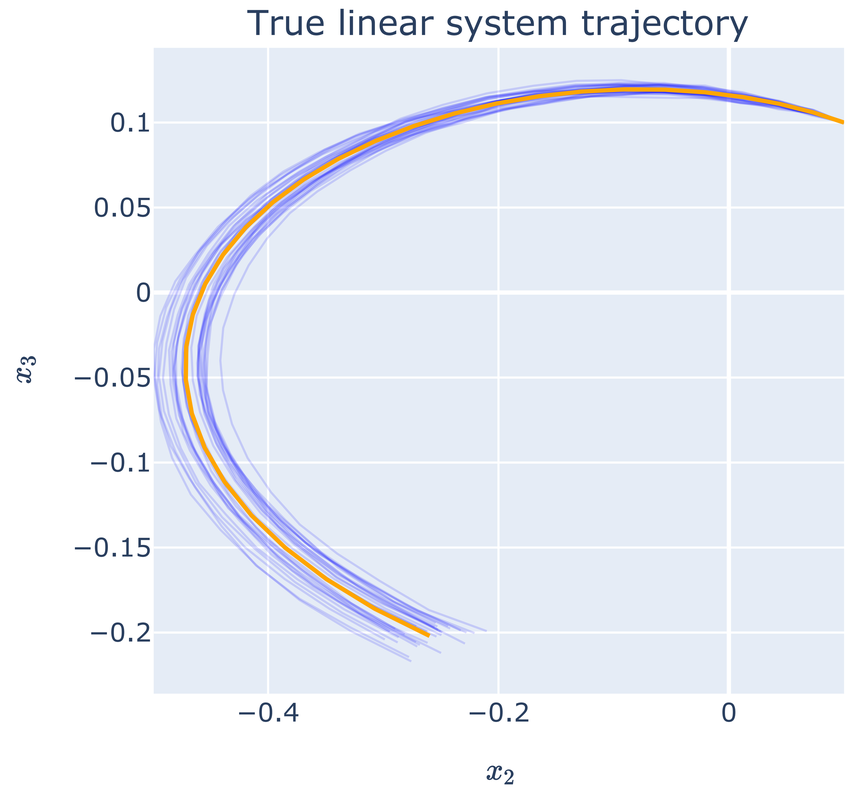
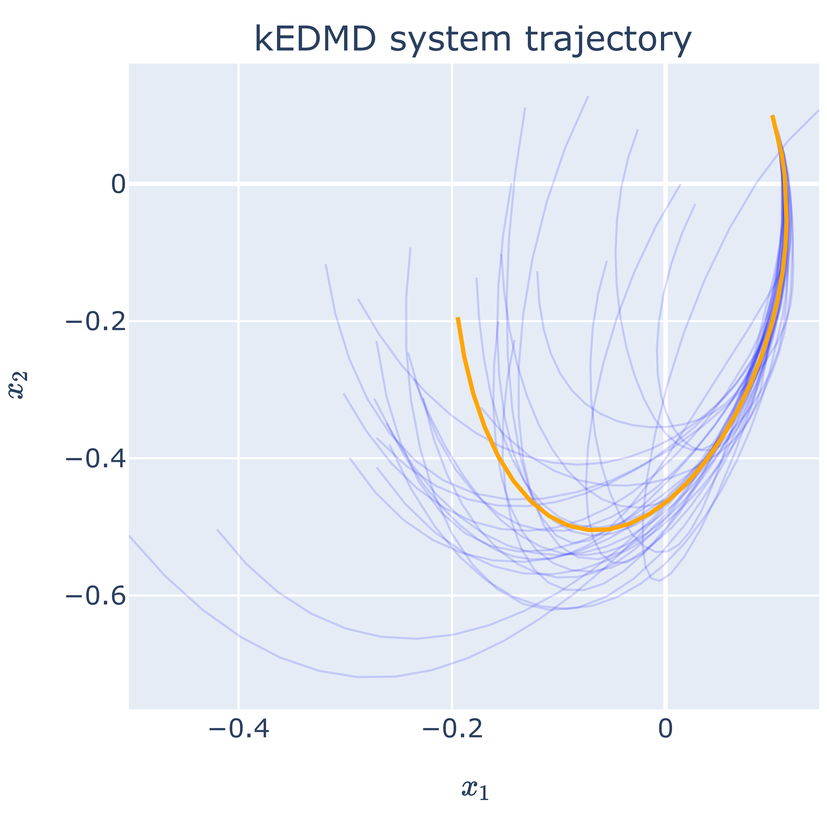
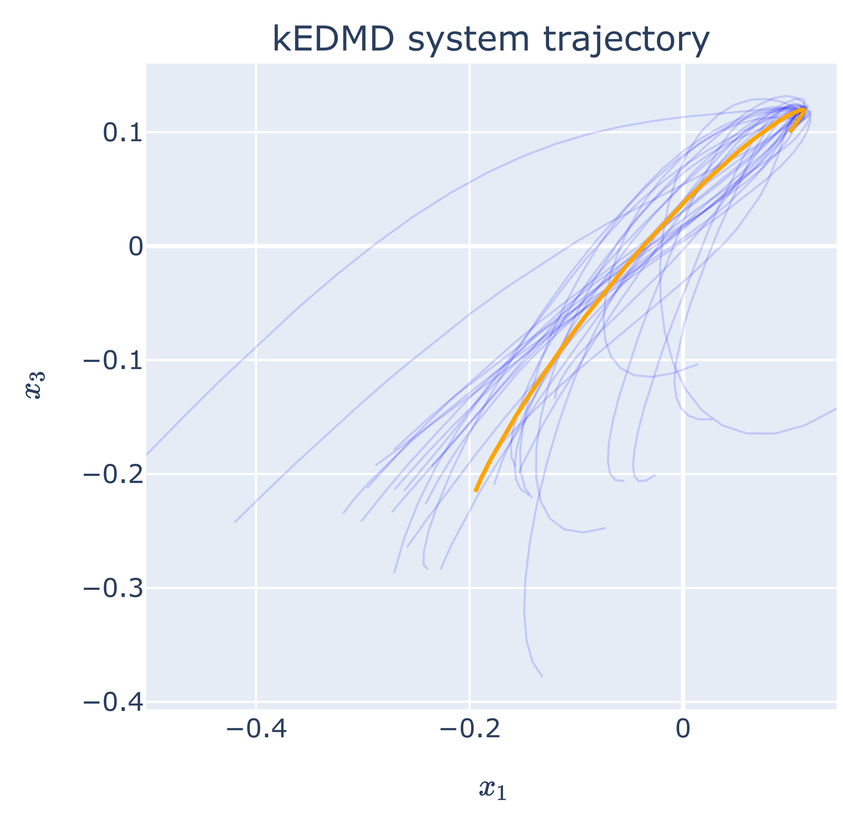
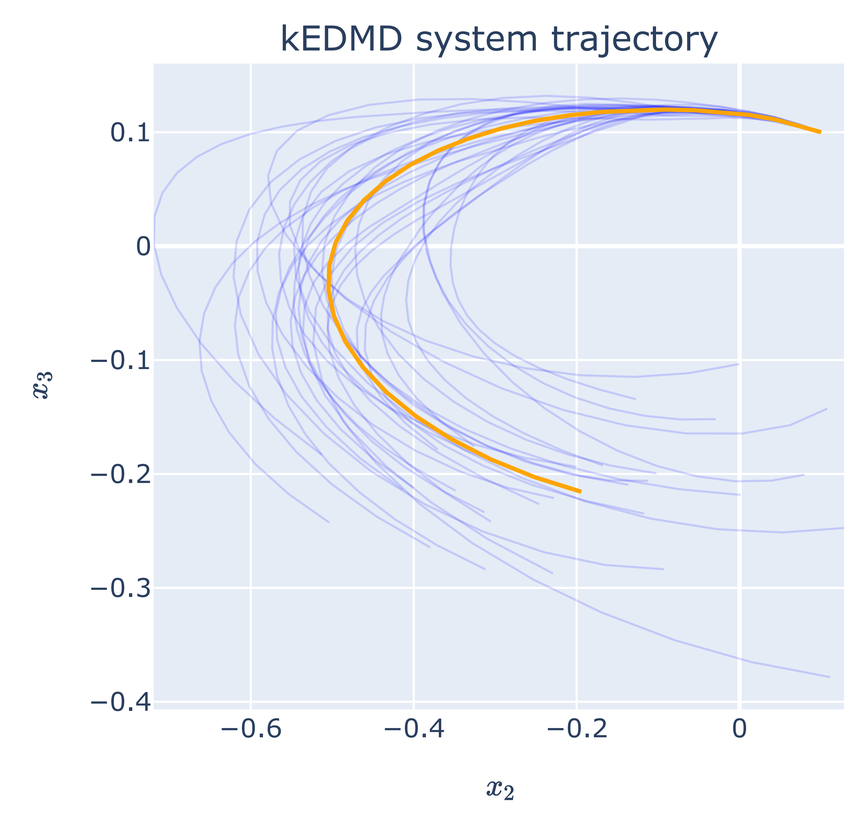

True linear system trajectory
0.1
0
−0.1
−0.2
−0.3
−0.4
−0.5
−0.2
−0.1
0
0.1
x_2
x_1


True linear system trajectory
0.1
0.05
0
−0.05
−0.1
−0.15
−0.2
−0.2
−0.1
0
0.1
x_3
x_1


True linear system trajectory
0.1
0.05
0
−0.05
−0.1
−0.15
−0.2
−0.4
−0.2
0
x_3
x_2


kEDMD system trajectory
0
−0.2
−0.4
−0.6
−0.4
−0.2
0
x_2
x_1


kEDMD system trajectory
0.1
0
−0.1
−0.2
−0.3
−0.4
−0.4
−0.2
0
x_3
x_1


kEDMD system trajectory
0.1
0
−0.1
−0.2
−0.3
−0.4
−0.6
−0.4
−0.2
0
x_3
x_2