

| | dia | Clases | transparencias | Teoría | Problemas | |
|----|---------------------|--|----------------|-----------|---------------|---|
| 1 | 09 08 | General/Introduction 1 | Lecture 1 | Salvatore | | |
| 2 | 09 09 | Introduction 2 | Lecture 1 | Salvatore | | |
| 3 | 09 09 | Introduction 3 | Lecture 1 | Salvatore | | |
| 4 | 09 15 | <i>P Introduction</i> | Lecture 1 | | Salvatore | |
| 5 | 09 16 | Orbital Mechanics 1 | Lecture 2 | Salvatore | | |
| 6 | 09 16 | Orbital Mechanics 2 | Lecture 2 | Salvatore | | |
| 7 | 09 22 | <i>P Orbital Mechanics</i> | Lecture 2 | | Salvatore | |
| 8 | 09 23 | Perturbations 1 | Lecture 3 | Salvatore | | |
| 9 | 09 23 | Perturbations 2 | Lecture 3 | Salvatore | | |
| 10 | 09 29 | <i>P Perturbations</i> | Lecture 3 | | Salvatore | |
| 11 | 09 30 | Attitude Concepts 1 | Lecture 4 | Salvatore | | |
| 12 | 09 30 | Attitude Concepts 2 | Lecture 4 | Salvatore | | |
| 13 | 10 06 | Attitude Concepts 3 | Lecture 4 | Salvatore | | |
| 14 | 10 07 | Space Project | Lecture 5 | Salvatore | | |
| 15 | 10 07 | Space Project | Lecture 5 | Salvatore | | |
| 16 | 10 13 | Modelo satélite Simulink | Lecture 5 | | Javier | |
| 17 | 10 14 | Attitude Kinematics | Lecture 6 | Salvatore | | |
| 18 | 10 14 | Attitude Kinematics | Lecture 6 | Salvatore | | |
| 19 | 10 20 | <i>P Attitude Kinematics</i> | Lecture 6 | | Salvatore | * |
| 20 | 10 21 | Attitude Determination | Lecture 7 | Salvatore | | |
| 21 | 10 21 | Attitude Determination | Lecture 7 | Salvatore | | |
| 22 | 10 27 | <i>P Attitude Determination</i> | Lecture 7 | | Salvatore | * |
| 23 | 10 28 | Rigid Body Dynamics | Lecture 8 | Salvatore | | |
| 24 | 10 28 | Rigid Body Dynamics | Lecture 8 | Salvatore | | |
| 25 | 11 03 | <i>P Rigid Body Dynamic</i> | Lecture 8 | | Salvatore | * |
| 26 | 11 04 | Attitude Dynamics | Lecture 9A | Salvatore | | |
| 27 | 11 04 | Attitude Dynamics | Lecture 9A | Salvatore | | |
| 28 | 11 10 | Modelos de instrumentos y estimación de parámetros | | | Javier | |
| 29 | 11 11 | Attitude Dynamics | Lecture 9A/B | Salvatore | | |
| 30 | 11 11 | Attitude Dynamics | Lecture 9B | Salvatore | | |
| 31 | 11 17 | Dinámica y Cinemática | | | Javier | |
| 32 | 11 18 | Attitude Control | Lecture 10 | Salvatore | | |
| 33 | 11 18 | Attitude Control | Lecture 10 | Salvatore | | |
| 34 | 11 24 | Filtro Kalman | | | Javier | |
| 35 | 11 25 | Attitude Control | Lecture 10 | Salvatore | | |
| 36 | 11 25 | Attitude Control | Lecture 10 | Salvatore | | |
| 37 | 12 01 | Control lineal Simulink | | | Javier | |
| 38 | 12 02 | Control lineal Simulink | | | Javier | |
| 39 | 12 02 | Control lineal Simulink | | | Javier | |
| 40 | 12 15 | Problemas | | Salvatore | | |
| 41 | 12 16 | Control no lineal | | | Javier | |
| 42 | 12 16 | Control no lineal | | | Javier | |
| 43 | 12 22 | Presentación trabajos | | | Javier | |
| | Total clases | 33 h Salvatore 10 h Javier | | | | |

Miércoles 17:00-17:45

Jueves 17:00-18:45