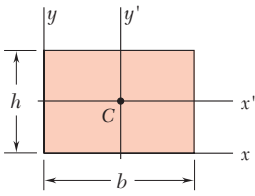
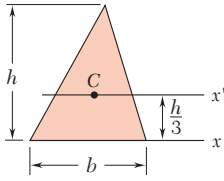
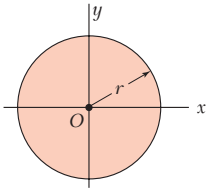
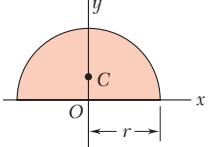
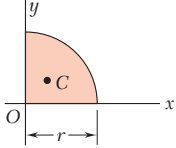
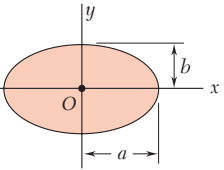
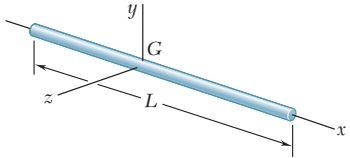
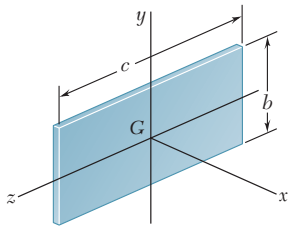
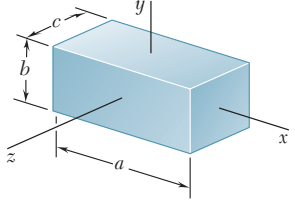
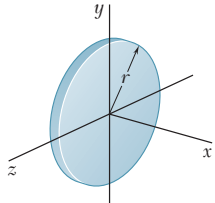
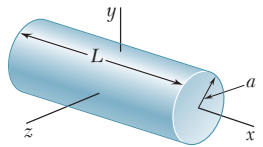
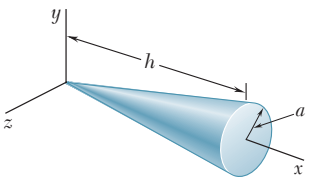


Moments of Inertia of Common Geometric Shapes

<p>Rectangle</p> $\bar{I}_{x'} = \frac{1}{12}bh^3$ $\bar{I}_{y'} = \frac{1}{12}b^3h$ $I_x = \frac{1}{3}bh^3$ $I_y = \frac{1}{3}b^3h$ $J_C = \frac{1}{12}bh(b^2 + h^2)$	
<p>Triangle</p> $\bar{I}_{x'} = \frac{1}{36}bh^3$ $I_x = \frac{1}{12}bh^3$	
<p>Circle</p> $\bar{I}_x = \bar{I}_y = \frac{1}{4}\pi r^4$ $J_O = \frac{1}{2}\pi r^4$	
<p>Semicircle</p> $I_x = I_y = \frac{1}{8}\pi r^4$ $J_O = \frac{1}{4}\pi r^4$	
<p>Quarter circle</p> $I_x = I_y = \frac{1}{16}\pi r^4$ $J_O = \frac{1}{8}\pi r^4$	
<p>Ellipse</p> $\bar{I}_x = \frac{1}{4}\pi ab^3$ $\bar{I}_y = \frac{1}{4}\pi a^3b$ $J_O = \frac{1}{4}\pi ab(a^2 + b^2)$	

Mass Moments of Inertia of Common Geometric Shapes

<p>Slender rod</p> $I_y = I_z = \frac{1}{12}mL^2$	
<p>Thin rectangular plate</p> $I_x = \frac{1}{12}m(b^2 + c^2)$ $I_y = \frac{1}{12}mc^2$ $I_z = \frac{1}{12}mb^2$	
<p>Rectangular prism</p> $I_x = \frac{1}{12}m(b^2 + c^2)$ $I_y = \frac{1}{12}m(c^2 + a^2)$ $I_z = \frac{1}{12}m(a^2 + b^2)$	
<p>Thin disk</p> $I_x = \frac{1}{2}mr^2$ $I_y = I_z = \frac{1}{4}mr^2$	
<p>Circular cylinder</p> $I_x = \frac{1}{2}ma^2$ $I_y = I_z = \frac{1}{12}m(3a^2 + L^2)$	
<p>Circular cone</p> $I_x = \frac{3}{10}ma^2$ $I_y = I_z = \frac{3}{5}m(\frac{1}{4}a^2 + h^2)$	
<p>Sphere</p> $I_x = I_y = I_z = \frac{2}{5}ma^2$	