AERO-222: Introduction to Aerospace Computation Fall 2021. Homework #4. **Due date: November 15, 2021**

Show all work and justify your answers!

Instructions

- This homework contains both handwritten and coding problems and shall be submitted according to the following guidelines.
- *Hardcopy:*
 - Due on CANVAS at 11:59 PM on the day of the deadline.
 - Shall include screenshots of any hand-written work.
 - For coding problems, the hardcopy shall include any relevant derivations and emphasize the final results (i.e. boxed, highlighted, etc.). INCLUDE ALL CODING RESULTS (including plots, final values) IN THE HARDCOPY.
 - Shall be submitted as a single file according to the provided template with the following naming scheme: "LastnameHW#.pdf"
- Coding Submission:
 - Due on CANVAS at 11:59 PM on the day of the deadline.
 - Shall be submitted as a single file according to the provided template with the following naming scheme: "LastnameHW#.py"
 - The script shall print out all outputs asked for in the problem.
- Late submissions will be accepted with a 10 point deduction per day late.
- 1. Numerical Differentiation (20 pts) Code. The derivative of the function,

$$f(x) = 5\cos(10x) + x^3 - 2x^2 - 6x + 10$$

is the function, $f'(x) = -50 \sin(10 x) + 3 x^2 - 4 x - 6$. Discretize the function f(x) using N = 100 points, $[x_k, f_k]$, that are uniformly distributed in $x \in [0, 4]$. Evaluate the first numerical derivative using the 5-point difference formula. Plot the absolute error between true and numerical derivatives. Pay attention to the two extremes: you cannot always use the 5-point **central** difference formula.

Solution:

The plots should look very similar to this.

2. Richardson Extrapolation (20 pts) By hand. Using the function given in problem #1, compute the accuracy gain using Richardson extrapolation to compute the first derivative using the central seven points formula at x = 2, using $h_1 = 0.02$ and $h_2 = 0.03$. Compute also the absolute error with respect to the true solution.

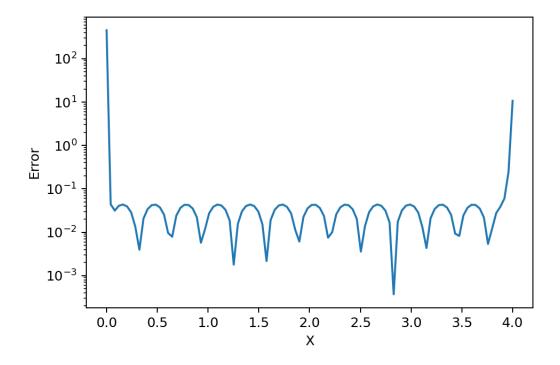


Figure 1: Caption

Solution:

The central seven point first derivative has the expression,

$$f_i' \approx \frac{-f_{i-3} + 9f_{i-2} - 45f_{i-1} + 45f_{i+1} - 9f_{i+2} + f_{i+3}}{60 h} + \mathcal{O}(h^6)$$

The points are in the table,

h	f_{i-3}	f_{i-2}	f_{i-1}	f_{i+1}	f_{i+2}	f_{i+3}
$h_1 = 0.02$	2.3956	1.7433	0.9482	-0.9455	-1.9718	-2.9988
$h_2 = 0.03$	3.0557	2.3956	1.3618	-1.4561	-2.9988	-4.4542

Using the central seven point first derivative for h_1 and h_2 we obtain,

$$f'(h_1) \approx -47.6472$$
 and $f'(h_2) \approx -47.6470$

Richardson extrapolation gives

$$f'_{\text{true}} \approx f'_{\text{RE}} = f'(h_1) + c h_1^6 = f'(h_2) + c h_2^6$$
 $\rightarrow c = \frac{f'(h_1) - f'(h_2)}{h_2^6 - h_1^6} \approx -3.2009 \cdot 10^5$

and the absolute errors are

$$|f'_{\rm true} - f'(h_1)| \approx 2.0705 \cdot 10^{-5}, \quad |f'_{\rm true} - f'(h_2)| \approx 2.3357 \cdot 10^{-4}, \quad |f'_{\rm true} - f'_{\rm RE}| \approx 2.1966 \cdot 10^{-7}$$

3. Numerical Differentiation (20 pts) By hand Show all steps to derive the second derivative, f_i'' , using using all of the following points

$$f_{i-4}, \qquad f_{i-3}, \qquad f_{i-2}, \qquad f_{i-1}, \qquad f_{i+1},$$

via matrix inversion.

Solution:

$$f_{i-4} = f_i - 4hf'_i + 16\frac{h^2f''_i}{2!} - 64\frac{h^3f'''_i}{3!} + 256\frac{h^4f_i^{(4)}}{4!} - 1024\frac{h^5f_i^{(5)}}{5!} + \mathcal{O}(h^6)$$

$$f_{i-3} = f_i - 3hf'_i + 9\frac{h^2f''_i}{2!} - 27\frac{h^3f'''_i}{3!} + 81\frac{h^4f_i^{(4)}}{4!} - 243\frac{h^5f_i^{(5)}}{5!} + \mathcal{O}(h^6)$$

$$f_{i-2} = f_i - 2hf'_i + 4\frac{h^2f''_i}{2!} - 8\frac{h^3f'''_i}{3!} + 16\frac{h^4f_i^{(4)}}{4!} - 32\frac{h^5f_i^{(5)}}{5!} + \mathcal{O}(h^6)$$

$$f_{i-1} = f_i - hf'_i + \frac{h^2f''_i}{2!} - \frac{h^3f'''_i}{3!} + \frac{h^4f_i^{(4)}}{4!} - \frac{h^5f_i^{(5)}}{5!} + \mathcal{O}(h^6)$$

$$f_{i+1} = f_i + hf'_i + \frac{h^2f''_i}{2!} + \frac{h^3f'''_i}{3!} + \frac{h^4f_i^{(4)}}{4!} + \frac{h^5f_i^{(5)}}{5!} + \mathcal{O}(h^6)$$

$$\begin{bmatrix} -4 & -3 & -2 & -1 & 1 \\ 16 & 9 & 4 & 1 & 1 \\ -64 & -27 & -8 & -1 & 1 \\ 256 & 81 & 16 & 1 & 1 \\ -1024 & -243 & -32 & -1 & 1 \end{bmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \\ c_4 \\ c_5 \end{pmatrix} = \begin{cases} 0 \\ 1 \\ 0 \\ 0 \\ 0 \end{cases}$$

whose exact rational solutions are,

$$c_1 = \frac{1}{24}$$
, $c_2 = -\frac{1}{4}$, $c_3 = \frac{7}{12}$, $c_4 = -\frac{1}{6}$, $c_5 = \frac{5}{12}$

or, approximated,

$$c_1 \approx 0.0417$$
, $c_2 = -0.25$, $c_3 \approx 0.5833$, $c_4 \approx -0.1667$, $c_5 \approx 0.4167$

- **4. Numerical Differentiation (20 pts) Code.** Consider the function $f(x) = x + \sin x$ and a step size $h = \pi/8$.
 - (a) Compare the three-point forward, backward, and central finite-difference approximations of the second derivative of f(x) with respect to the exact solution at x = 1. Provide a table of values.

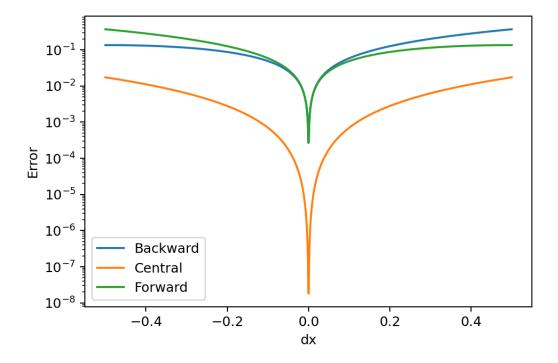


Figure 2: Central Finite Differences should have the best accuracy, as should smaller magnitudes of dx

(b) Compute the absolute error of the 3-point forward, backward, and central approximations for a step size range $\Delta x \in [-0.5, +0.5]$ broken into 1,000 values. Provide a single semi-logarithmic plot of the absolute errors versus the given x-range. Include proper axes labels and a reference legend.

Solution:

Backward	Central	Forward
0.278	0.0108	0.130

5. An Aerospace Application (20 pts) Code. An airfoil is placed in a wind tunnel and heated to 80°C before lowering the surface temperature to 20.7°C using convective cooling. A thermocouple is placed on the surface of the airfoil and measures the surface temperature at discrete time steps. The following temperatures are recorded,

Use numerical differentiation to compute the first derivative $T'(t_k)$ at each time step given in the table above. Specifically, apply the three-point forward, backward or

central finite-difference method wherever appropriate in order to estimate the airfoil's temperature gradient, $T'(t_k)$. Provide a table of values.

Solution:

$t ext{ (sec)}$	0	5	10	15	20	25
T (°C)	80	44.5	30	24.1	21.7	20.7
T' (°C)	-9.2	-5.0	-2.04	-0.83	-0.34	-0.06

```
import numpy as np
 import matplotlib.pyplot as plt
 from tabulate import tabulate
### Problem 1
def f1(x): return 5*np.cos(10*x)+x**3-2*x**2-6*x+10
def df1(x): return -50*np.sin(10*x) + 3*x**2 - 4*x - 6
def forw1(x,f,i,h=np.pi/8): return (1*f[i+0]-2*f[i+1]+1*f[i+2])/(1*1.0*i)
def forw2(x,f,i,h=np.pi/8): return (-3*f[i-1]-10*f[i+0]+18*f[i+1]-6*f[i+1]
def cent1(x,f,i,h=np.pi/8): return (1*f[i-2]-8*f[i-1]+0*f[i+0]+8*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+1]+0*f[i+
def back1(x,f,i,h=np.pi/8): return (-1*f[i-3]+6*f[i-2]-18*f[i-1]+10*f[i
def back2(x,f,i,h=np.pi/8): return (3*f[i-4]-16*f[i-3]+36*f[i-2]-48*f[i-4]-16*f[i-3]+36*f[i-2]-48*f[i-4]-16*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[i-3]+36*f[
xList1 = np.linspace(0,4,100)
 fx = [f1(val) for val in xList1]
dfx = [df1(val) for val in xList1]
df1 = []
xList = xList1
 for i in range(len(xList)):
                                  if i < 1:
                                                                  val = forw1(xList[i], fx, i, h=xList[1]-xList[0])
                                  elif i < 2:
                                                                  val = forw2(xList[i],fx,i,h=xList[1]-xList[0])
                                  elif i < len(xList)-3:
                                                                  val = cent1(xList[i],fx,i,h=xList[1]-xList[0])
                                  elif i < len(xList)-2:
                                                                  val = back1(xList[i],fx,i,h=xList[1]-xList[0])
                                  elif i < len(xList)-1:
                                                                  val = back2(xList[i],fx,i,h=xList[1]-xList[0])
                                  df1.append(val)
 error1 = [abs(df1[i]-dfx[i]) for i in range(len(df1))]
plt.semilogy(xList,error1)
plt.xlabel('X')
plt.ylabel('Error')
plt.show()
plt.close()
### Problem 4
def f(x): return x+np.sin(x)
def df(x): return 1+np.cos(x)
def ddf(x): return -np.sin(x)
```

```
xList = np.linspace(0,4,100)
hList = np.linspace(-.5, .5, 1000)
ddfx = [ddf(val) for val in xList]
def back4(x,f,h=np.pi/8): return (f(x-2*h)-2*f(x-h)+f(x))/h**2
def forw4(x,f,h=np.pi/8): return (f(x-0*h)-2*f(x+1*h)+f(x+2*h))/h**2
def cent4(x,f,h=np.pi/8): return (f(x-1*h)-2*f(x-0*h)+f(x+1*h))/h**2
ddf1 = ddf(1.0)
b4 = back4(1.0, f)
f4 = forw4(1.0, f)
c4 = cent4(1.0, f)
table = [["Backwards", "Central", "Forwards"],
                  [abs(b4-ddf1), abs(c4-ddf1), abs(f4-ddf1)]]
print(tabulate(table))
backddf = [back4(1.0,f,h=i) for i in hList]
centddf = [cent4(1.0,f,h=i) for i in hList]
forwddf = [forw4(1.0, f, h=i) for i in hList]
errorB = abs(backddf-ddf1)
errorC = abs(centddf-ddf1)
errorF = abs(forwddf-ddf1)
plt.semilogy(hList,errorB,label='Backward')
plt.semilogy(hList,errorC,label='Central')
plt.semilogy(hList,errorF,label='Forward')
plt.xlabel('dx')
plt.ylabel('Error')
plt.legend()
plt.show()
plt.close()
### Problem 5
T = [80,44.5, 30, 24.1, 21.7, 20.7]
t = [0,5,10,15,20,25]
h = 5
der = []
for i in range(len(T)):
        if i <1:
                f_x = (-3*T[i+0]+4*T[i+1]-1*T[i+2])/(2*1.0*h**1)
        if 0 < i and i < 5:
                f_x = (-1*T[i-1]+0*T[i+0]+1*T[i+1])/(2*1.0*h**1)
        if i > 4:
                f_x = (1*T[i-2]-4*T[i-1]+3*T[i+0])/(2*1.0*h**1)
        der.append(f_x)
table = [["t",t],["T",T],["T'",der]]
print(tabulate(table))
```