

AERO 422 Homework #2

Instructor: Vedang Deshpande

Due: September 22, 2021 at 12:40p.m.

Fall 2021

(25 Points)

1. Consider the function $f(t) = te^{2t} \sin 3t$

- (a) (2 points) Find the Laplace transform using the table. Mention which entries from the table are being used.

Use the following properties from the Laplace table

$$\mathcal{L}\{t^n f(t)\} = (-1)^n \frac{d^n F(s)}{ds^n} \quad (7), \quad \mathcal{L}\{e^{at} \sin kt\} = \frac{k}{(s-a)^2 + k^2} \quad (22)$$

Let $f(t) = e^{2t} \sin 3t$. Apply (7) to get

$$\begin{aligned} \mathcal{L}\{te^{2t} \sin 3t\} &= \mathcal{L}\{tf(t)\} \\ &= (-1) \frac{dF(s)}{ds} \\ &= (-1) \frac{d[\mathcal{L}\{e^{2t} \sin 3t\}]}{ds} \end{aligned}$$

Apply (22) and simplify using the quotient rule.

$$\begin{aligned} \mathcal{L}\{te^{2t} \sin 3t\} &= (-1) \frac{d}{ds} \left\{ \frac{3}{(s-2)^2 + 3^2} \right\} \\ &= (-1) \frac{-3 \cdot 2(s-2)}{((s-2)^2 + 9)^2} \\ &= \frac{6s-12}{((s-2)^2 + 9)^2} \end{aligned}$$

- (b) (1 point) Can we use the F.V.T. to determine $f(\infty)$? Why or why not?

2. Find the inverse Laplace transform using the table and partial fraction expansion. Show your work.

- (a) (2 points)

$$F(s) = \frac{s+10}{s^2+2s+10}$$

- (b) (3 points)

$$F(s) = \frac{s^2+1}{s(s-1)^3}$$

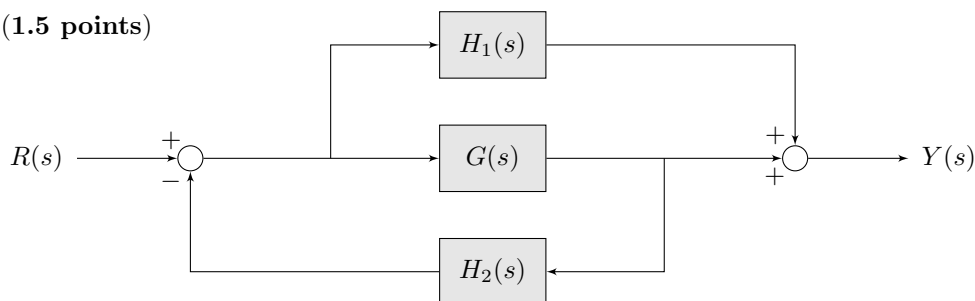
3. A given system is found to have a transfer function that is

$$\frac{Y(s)}{R(s)} = \frac{10(s+2)}{s^2+8s+15}$$

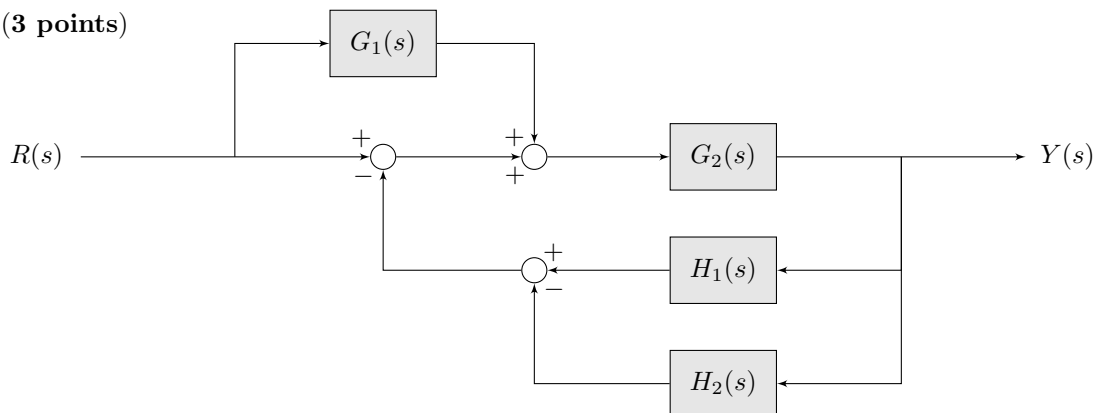
- (a) (3 points) Using partial fractions, determine $y(t)$ when $r(t)$ is a unit step input. Show your work.

- (b) **(1 point)** Can we use F.V.T. to find $y(\infty)$? If the answer is yes, apply F.V.T. If not, explain why.
4. (a) **(3 points)** Using the convolution integral, find the step response of the system whose impulse response is given below
- $$h(t) = \begin{cases} te^{-t} & t \geq 0 \\ 0 & t < 0 \end{cases}$$
- (b) **(2 points)** Now use the Laplace transform table and partial fraction expansion to find $y(t)$.
- (c) **(2 points)** Apply I.V.T. and F.V.T. (if applicable) to find $y(0)$ and $y(\infty)$.
5. For each of the following block diagrams, reduce the block diagram to find $T(s)$, where $T(s)$ is defined by $Y(s) = T(s)R(s)$.

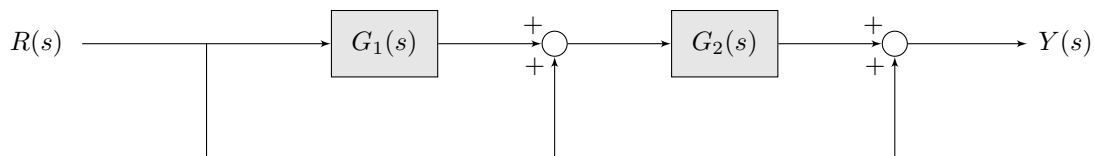
(a) **(1.5 points)**



(b) **(3 points)**



(c) **(1.5 points)**



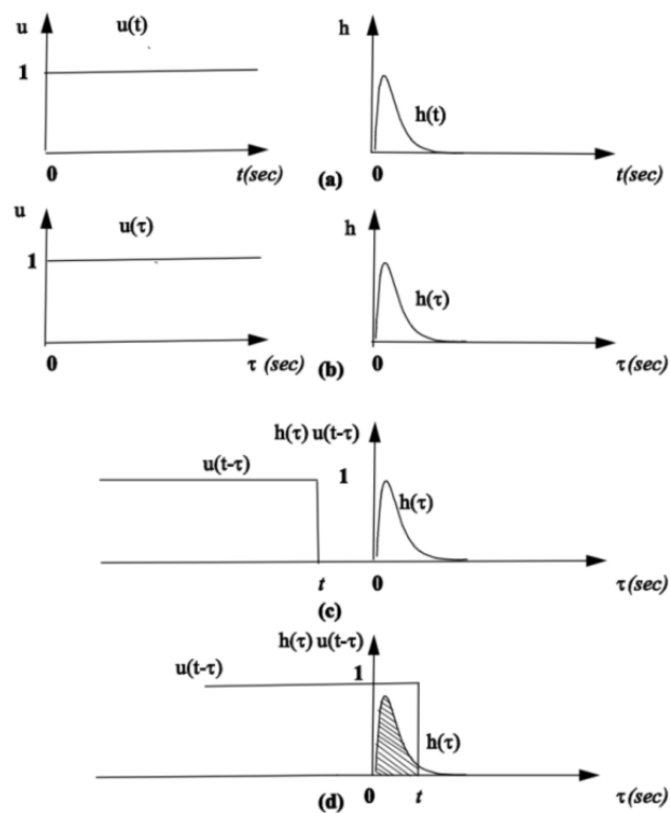


Illustration of convolution.

Figure 1: Convolution integral (reference for problem 4)