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## **Command used to run the program:**

python3 main.py

The simulation will run without intervention and display a total time until the algorithm reaches a stable state.

## Notes:

- Time is measured in steps, categorized as a "Hop"
- Each Node # has two columns that represent the DV table
  - The first column represents the destination node linked
  - The second column represents the cost of the link
  - Destination nodes not listed are not linked, same as the ones listed in the Lab 2 example with a "-"
- The state of stability is listed after the last node in each run

## Adjusting a link cost:

When the cost of a link is set to infinity (16), the cost of the DV from 1 to 3 increased drastically. When the cost of a link from node 1 to node 2 is set to 16, as well as the cost of the link from node 2 to node 3 is set to 16, the cost of node 1 to node 3 becomes 32. Node 1 has no alternative means of travelling to node 3 before the programs finds stability because the nodes are generally not very interconnected.

When the cost is set back to what is was originally, the cost of node 1 to node 3 by the end of the program becomes 8.

## **DVs for each step:**

Hop: #0
Node 1
10
2 7
5 1
Node 2
20
3 1
5 8
Node 3

```
3 0
Node 4
40
5 2
3 2
Node 5
50
Node 6
60
____ Hop: #1 ____
Node 1
10
27
38
5 1
Node 2
20
3 1
58
Node 3
30
Node 4
40
5 2
3 2
Node 5
50
Node 6
60
### not stable ###
____ Hop: #2 ____
Node 1
10
27
38
51
Node 2
20
3 1
58
Node 3
3 0
```

Node 4

40

5 2

3 2

Node 5

50

Node 6

60

### stable ###