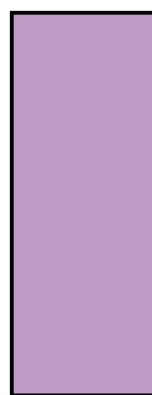


$\mathbf{Ez}_{x_{yp}}$

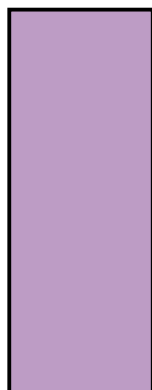


$=$

$\mathbf{Cezx}_{e_{yp}}$



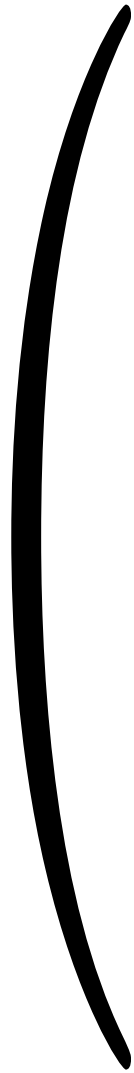
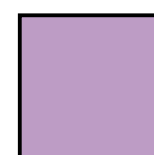
$\mathbf{Ez}_{x_{yp}}$



\dots

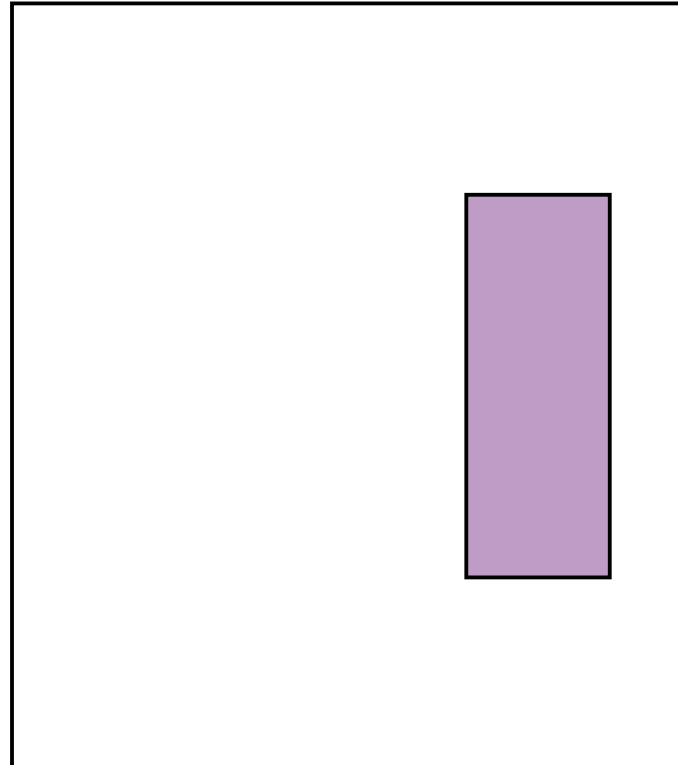
$+$

$\mathbf{Cezx}_{hy_{yp}}$



$\text{pie} - 1$

$\text{pis} + 1$

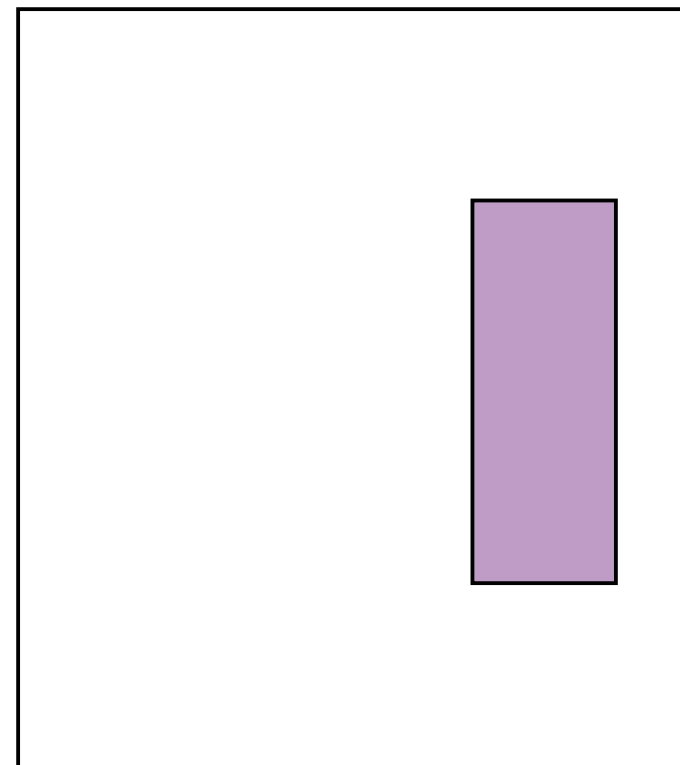


\mathbf{H}_y

$-$

$\text{pie} - 2$

pis



\mathbf{H}_y



pje

ny

pje

ny