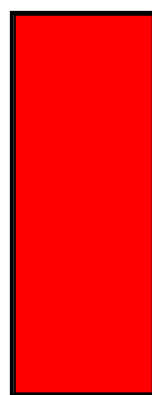
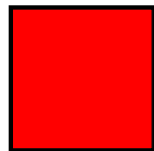


$Ez_{x_{yp}}$

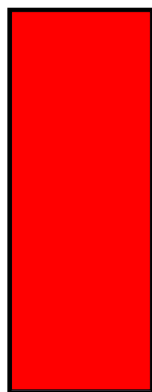


$=$

$Cezx_{e_{yp}}$



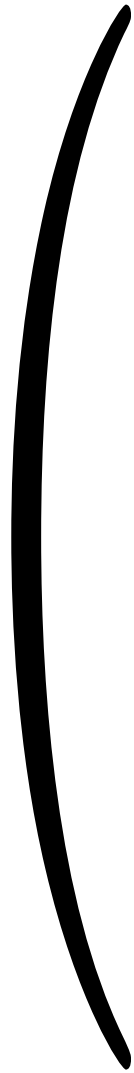
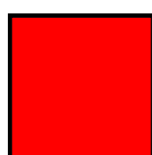
$Ez_{x_{yp}}$



\dots

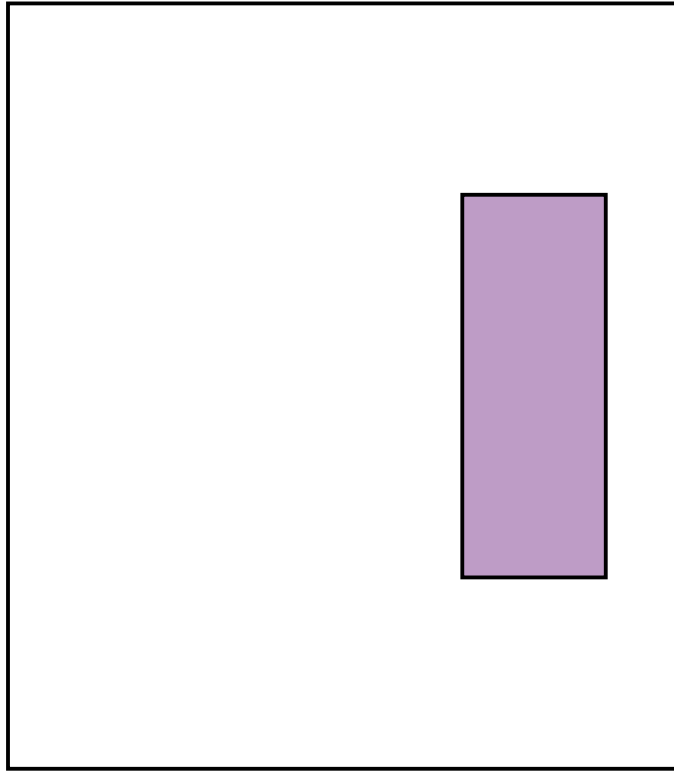
$+$

$Cezx_{hy_{yp}}$



$pie - 1$

$pis + 1$

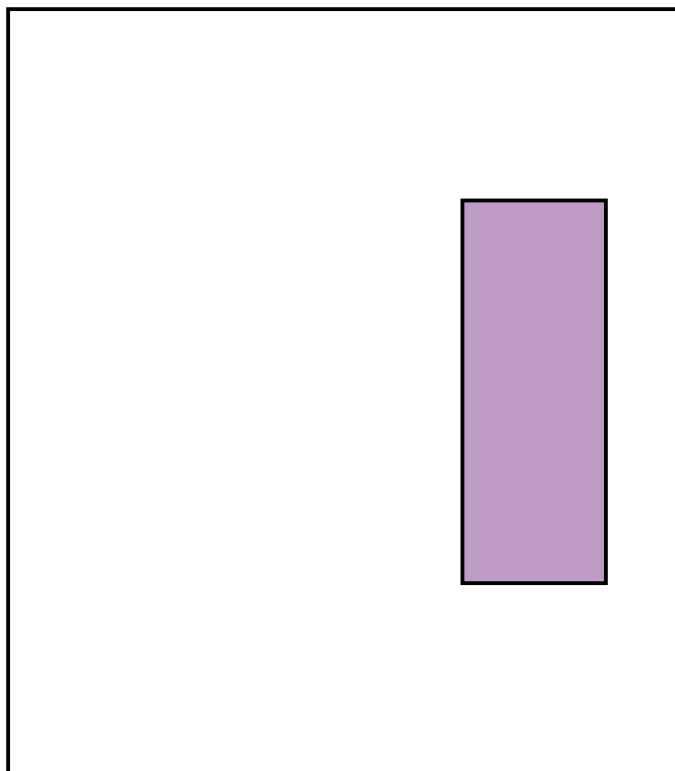


H_y

$-$

$pie - 2$

pis



H_y

