

Multiparameter (iterated) sums

J. **Diehl** (University of Greifswald)
work in progress with L. **Schmitz** (University of Greifswald)

SRA '22

Iterated sums (or integrals) have proven very beneficial in time series analysis.

- Graham '13 “Sparse arrays of signatures for ...”.
- [Lyons, Ni, Oberhauser '14 “A feature set for streams ...”](#)
- various works by L Jin et al '15 on Chinese character recognition.
- [Kiraly, Oberhauser '16 “Kernels for sequentially ordered data”.](#)
- [Lyons, Oberhauser '17 “Sketching the order of events”.](#)
- D '13, D, Reizenstein '19 on invariant features.
- D, Ebrahimi-Fard, Tapia '19 “Time warping invariants”.
- [Kidger, Bonnier, Arribas, Salvi, Lyons '19 “Deep Signature Transforms”. - NeurIPS '19](#)
- [Kidger, Morrill, Foster, Lyons - Neural Controlled Differential Equations for Irregular Time Series - NeurIPS '20](#)
- [Toth, Bonnier, Oberhauser '20 “Seq2Tens”.](#)

A key property is their invariance to the parametrization of the data.

For iterated sums this is their **time-warping invariance**: for example for any iterated sum F ,

$$\begin{aligned}
 F \left(\begin{array}{c} \text{Bar chart 1} \\ \text{X-axis: 0, 1, 2, 3} \end{array} \right) &= F \left(\begin{array}{c} \text{Bar chart 2} \\ \text{X-axis: 0, 1, 2, 3, 4} \end{array} \right) \\
 &= F \left(\begin{array}{c} \text{Bar chart 3} \\ \text{X-axis: 0, 1, 2, 3, 4} \end{array} \right) \\
 &= F \left(\begin{array}{c} \text{Bar chart 4} \\ \text{X-axis: 0, 1, 2, 3, 4, 5, 6, 7} \end{array} \right).
 \end{aligned}$$

We are now concerned with two-dimensional data, e.g. images.
 We would like to have functionals Φ that are **warping invariant**,
 for example

$$\Phi \left(\begin{array}{c} \text{Dachshund} \end{array} \right) = \Phi \left(\begin{array}{c} \text{Small Dachshund} \end{array} \right)$$

$$= \Phi \left(\begin{array}{c} \text{Stretched Dachshund} \end{array} \right)$$

It is easier to think about invariants to zero-insertion .

$$\begin{aligned}\Phi\left(\begin{pmatrix} 0.41 & 0.22 & 0.03 & 0.72 \\ 0.32 & 0.72 & 0.48 & 0.84 \\ 0.60 & 0.64 & 0.25 & 0.93 \end{pmatrix}\right) &= \Phi\left(\begin{pmatrix} 0.41 & 0.22 & 0 & 0.03 & 0.72 \\ 0.32 & 0.72 & 0 & 0.48 & 0.84 \\ 0.60 & 0.64 & 0 & 0.25 & 0.93 \end{pmatrix}\right) \\ &= \Phi\left(\begin{pmatrix} 0.41 & 0.22 & 0 & 0.03 & 0.72 \\ 0.32 & 0.72 & 0 & 0.48 & 0.84 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0.60 & 0.64 & 0 & 0.25 & 0.93 \end{pmatrix}\right)\end{aligned}$$

(One can afterwards obtain stretching invariants, by plugging in – for example – the discrete second derivative.)

First examples

$$\sum_{i,j} Z_{ij}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j}} Z_{i_1 j} Z_{i_2 j}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} Z_{i_1 j_1} Z_{i_2 j_2}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} Z_{i_1 j_1} Z_{i_1 j_2} Z_{i_2 j_1} Z_{i_2 j_2}$$

Visualization

First examples

$$\sum_{i,j} z_{ij}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j}} z_{i_1 j} z_{i_2 j}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1} z_{i_2 j_2}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1} z_{i_1 j_2} z_{i_2 j_1} z_{i_2 j_2}$$

Visualization

First examples

$$\sum_{i,j} z_{ij}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j}} z_{i_1 j} z_{i_2 j}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1} z_{i_2 j_2}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1} z_{i_1 j_2} z_{i_2 j_1} z_{i_2 j_2}$$

Visualization

First examples

$$\sum_{i,j} z_{ij}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j}} z_{i_1 j} z_{i_2 j}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1} z_{i_2 j_2}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1} z_{i_1 j_2} z_{i_2 j_1} z_{i_2 j_2}$$

Visualization

First examples

$$\sum_{i,j} Z_{ij}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j}} Z_{i_1 j} Z_{i_2 j}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} Z_{i_1 j_1} Z_{i_2 j_2}$$

Visualization

$$\sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} Z_{i_1 j_1}^3 Z_{i_1 j_2}^2 Z_{i_2 j_1} Z_{i_2 j_2}^4$$

Visualization

Theorem (D-Schmitz '22)

All polynomial invariants to zero-insertion are given by expressions of the form

$$\langle \text{SS}(Z), A \rangle := \sum_{\substack{1 \leq \iota_1 < \dots < \iota_m \\ 1 \leq \kappa_1 < \dots < \kappa_n}} \prod_{s=1}^m \prod_{t=1}^n z_{\iota_s \kappa_t}^{A_{s t}},$$

for **matrix compositions** A , that is $A \in \mathbb{N}_0^{m \times n}$ containing no zero rows and no zero columns.

Example

$$\langle \text{SS}(Z), [3] \rangle = \sum_{i,j} x_{ij}^3 \quad \langle \text{SS}(z), \begin{bmatrix} 1 \\ 3 \end{bmatrix} \rangle = \sum_{\substack{i_1 < i_2 \\ j}} z_{i_1 j} z_{i_2 j}^3$$

$$\langle \text{SS}(z), \begin{bmatrix} 3 & 2 \\ 1 & 4 \end{bmatrix} \rangle = \sum_{\substack{i_1 < i_2 \\ j_1 < j_2}} z_{i_1 j_1}^3 z_{i_1 j_2}^2 z_{i_2 j_1} z_{i_2 j_2}^4.$$

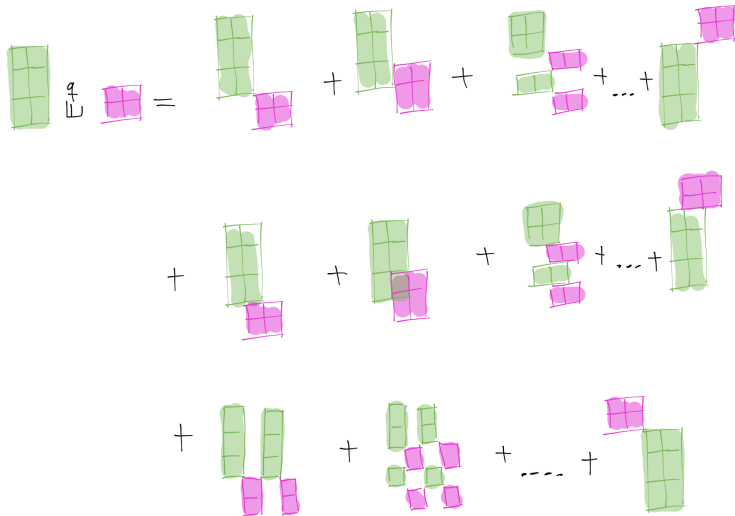
The linear span of matrix compositions becomes an associative, commutative algebra with the **quasi-shuffle product** \sqcup^q .

Example

$$\begin{aligned} \begin{bmatrix} 1 \\ 1 \end{bmatrix} \sqcup^q \begin{bmatrix} 5 \\ 5 \end{bmatrix} &= \begin{bmatrix} 1 & 0 \\ 0 & 5 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 5 & 0 \end{bmatrix} + \begin{bmatrix} 5 & 0 \\ 0 & 1 \end{bmatrix} + \begin{bmatrix} 0 & 5 \\ 1 & 0 \end{bmatrix} \\ &\quad + \begin{bmatrix} 1 \\ 5 \end{bmatrix} + \begin{bmatrix} 5 \\ 1 \end{bmatrix} + \begin{bmatrix} 1 & 5 \\ 5 & 1 \end{bmatrix} + \begin{bmatrix} 6 \end{bmatrix} \end{aligned}$$

$$\begin{aligned} \begin{bmatrix} 1 \\ 2 \end{bmatrix} \sqcup^q \begin{bmatrix} 3 \\ 3 \end{bmatrix} &= \begin{bmatrix} 1 & 0 \\ 2 & 0 \\ 0 & 3 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 0 & 2 \\ 3 & 0 \end{bmatrix} + \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 0 & 3 \\ 2 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 3 & 0 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \\ &\quad + \begin{bmatrix} 0 & 3 \\ 1 & 0 \\ 2 & 0 \end{bmatrix} + \begin{bmatrix} 3 & 0 \\ 0 & 1 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} \\ &\quad + \begin{bmatrix} 1 & 3 \\ 2 & 0 \end{bmatrix} + \begin{bmatrix} 1 & 0 \\ 2 & 3 \end{bmatrix} + \begin{bmatrix} 3 & 1 \\ 0 & 2 \end{bmatrix} + \begin{bmatrix} 0 & 1 \\ 3 & 2 \end{bmatrix} + \begin{bmatrix} 4 \\ 2 \end{bmatrix} + \begin{bmatrix} 1 \\ 5 \end{bmatrix} \end{aligned}$$

Quasi-shuffle pictorally



Theorem (Quasi-shuffle identity; D-Schmitz '22)

$$\langle SS(Z), A \rangle \cdot_{\mathbb{R}} \langle SS(Z), B \rangle = \langle SS(Z), A \overset{q}{\sqcup} B \rangle$$

A coproduct would be nice to have for a least two reasons:

- 1 freeness of the quasi-shuffle algebra,
- 2 some form of Chen's identity

Currently we have one which gives us point 1) and a weak incarnation of Chen's identity. It is obtained by considering matrix compositions as diagonal 'words' of 'connected' compositions.

Lemma

*Every matrix composition can be written as 'diagonal' block matrix of **connected** matrix compositions which cannot be further decomposed.*

Example

$$\begin{pmatrix} 3 & 0 & 0 \\ 0 & 5 & 1 \end{pmatrix} = \text{diag}\left(\begin{pmatrix} 3 \end{pmatrix}, \begin{pmatrix} 5 & 1 \end{pmatrix}\right)$$

Example

$$\begin{pmatrix} 3 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 2 \end{pmatrix} = \text{diag}\left(\begin{pmatrix} 3 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 2 \end{pmatrix}\right)$$

For such a decomposition

$$A = \text{diag}(A_1, \dots, A_n),$$

we define

$$\Delta A := \sum_{i=0}^n \text{diag}(A_1, \dots, A_i) \otimes \text{diag}(A_{i+1}, \dots, A_n).$$

Example

$$\Delta \begin{pmatrix} 3 & 0 & 0 \\ 0 & 5 & 1 \end{pmatrix} = \begin{pmatrix} 3 & 0 & 0 \\ 0 & 5 & 1 \end{pmatrix} \otimes e + (3) \otimes \begin{pmatrix} 5 & 1 \end{pmatrix} + e \otimes \begin{pmatrix} 3 & 0 & 0 \\ 0 & 5 & 1 \end{pmatrix}$$

Theorem (D-Schmitz '22)

The linear span of matrix compositions with the quasi-shuffle product $\overset{q}{\sqcup}$ and the 'deconcatenation' coproduct Δ is a connected, graded bialgebra (and hence a Hopf algebra).

SS is a character on it. It stores all invariants to zero-insertion. The following form of Chen's identity holds:

$$\left\langle \text{SS} \left(\begin{array}{c} \text{🐶} \\ \text{🐧} \end{array} \right), A \right\rangle = \left\langle \text{SS} \left(\text{🐶} \right) \otimes \text{SS} \left(\text{🐧} \right), \Delta A \right\rangle.$$

Remark

This is quite a weak form of Chen's identity. It does not help in splitting the calculation of either

$$\left\langle \text{SS} \left(\begin{array}{c} \text{Dachshund} \\ \text{Puffin} \end{array} \right), A \right\rangle$$

or

$$\left\langle \text{SS} \left(\text{Dachshund} \mid \text{Puffin} \right), A \right\rangle$$

This is related to the fact that most of the sums we define are not some kind of iterated sum.

Related work

- Chad Giusti, Darrick Lee, Vidit Nanda, and Harald Oberhauser. A topological approach to mapping space signatures, 2022.
- Sheng Zhang, Guang Lin, and Samy Tindel. 2-d signature of images and texture classification, 2022.
- Mohamed R Ibrahim and Terry Lyons. Imagesig: A signature transform for ultra-lightweight image recognition. In Proceedings of the IEEE/CVF Conference on Computer Vision and Pattern Recognition, pages 3649-3659, 2022.

Summary / Outlook

- Characterization of all zero-insertion invariants, which then lead to (some) warping invariants. ✓
- Stored as a character on a Hopf algebra. ✓
- (Weak) form of Chen's identity. ✓
- By Cartier-Milnor-Moore, the quasi-shuffle algebra is free. Is there a generating set akin to **Lynon words** ?
- Better Chen's identity / Efficient calculation ?

Question / Comments ?

Summary / Outlook

- Characterization of all zero-insertion invariants, which then lead to (some) warping invariants. ✓
- Stored as a character on a Hopf algebra. ✓
- (Weak) form of Chen's identity. ✓
- By Cartier-Milnor-Moore, the quasi-shuffle algebra is free. Is there a generating set akin to **Lynon words** ?
- Better Chen's identity / Efficient calculation ?

Question / Comments ?

Complexity

Certain elements, like $\begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix}$ are cheap ($= \mathcal{O}(T^2)$) to calculate

But most are not. For example,

$$\left\langle \text{SS}(z), \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \right\rangle$$

seems to be truly of cost $\mathcal{O}(T^3)$.

(Over the Boolean semiring it is $\mathcal{O}(T^\omega)$..)