

Given the joint, which is proportional (to a constant) to the posterior, each conditional posterior can be found by regarding all other variables as constant.

P(2; |...): Probability terms for N_i , r_j , q_j , and z_j are all functions of z.

SEE BELOW

$$\begin{array}{c}
(T) \\
j \in A_1 \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_2
\end{array}$$

$$\begin{array}{c}
(T) \\
j \in A_1
\end{array}$$

$$\begin{array}{c}
(T) \\
($$

P(T*1...): Only the Tj and T* probability distributions contain T*.

$$P(\Lambda^{*}|...) \propto \prod_{j=1}^{N} \left[\delta(z_{j}=1) \cdot \Pi^{*} q_{j} + \delta(z_{j}=0) \cdot (1-\Pi^{*}) \cdot r_{j} \right] \cdot (\Pi^{*})^{a^{k-1}} (1-\Pi^{*})^{b^{k-1}}$$

$$\propto \left[\prod_{j \in A_{1}} \Pi^{*} q_{i} \right] \cdot \left[\prod_{j \in A_{0}} (1-\Pi^{*}) \cdot r_{j} \right] \cdot (\Pi^{*})^{a^{k-1}} (1-\Pi^{*})^{b^{k-1}}$$

Recall |AI = M, |Ao| = Mo

· Beta (Mith, Mott)

*
$$P(z_1 \mid ...) \propto I(z_{i=1}) \left[q_{ij}^{\alpha_i} \cdot \hat{\gamma}^* \cdot \rho \right] + I(z_{i=0}) \cdot \left[r_i^{\alpha_0} \cdot (1-\hat{\gamma}^*)(1-\hat{\rho}) \right]$$

$$P(q|...) \propto \left[\frac{T}{JeA_1} q_j \right] \cdot \left[\frac{T}{JeA_1} \frac{q_j^{\alpha_1-1}}{B(\alpha_1)} \right]$$

$$P(r_1,...) \propto \begin{bmatrix} TT & r_j & \frac{r_j a_0-1}{B(a_0)} \end{bmatrix}$$

$$\alpha TT$$
 $j \in A_0$
 $f_j \cdot f_j^{a_0-1} = TT \quad f_j^{a_0} \sim Dir\left(M_0; a_0+1,...,a_0+1\right)$