

**SSIE 660: Applied Stochastic Processes**  
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**Note 8**  
**Chapter 4. Discrete Markov Chains**

Unconditional Probabilities

Example: What is the probability that the inventory at the beginning of the 3rd day is 3?  
That is  $P[X_2 = 3]$ ?

Beginning step is '0', not '1'

$$P^2 = \begin{bmatrix} 0.23 & 0.28 & 0.49 \\ 0.3 & 0.21 & 0.49 \\ 0.30 & 0.28 & 0.42 \end{bmatrix}$$

We cannot find the unconditional probability  $P[X_2 = 3]$ , unless we know

$$P[X_2 = 3] = \sum_{i=1}^3 P[X_2 = 3 | x_0 = i] P[X_0 = i]$$

Let  $\alpha_1 = 0.3, \alpha_2 = 0.6, \alpha_3 = 0.1$ . Then,  $P[X_2 = 3] = \begin{pmatrix} .49 \\ .49 \\ .42 \end{pmatrix}^T \begin{pmatrix} .3 \\ .6 \\ .1 \end{pmatrix} = .483$ .

In general,

$$P[X_n = j] = \sum_i P[X_j = j | X_0 = i] P[X_0 = i]$$

### Other Probabilities

$$P[X_5 = 3, X_4 = 1, X_3 = 2, X_1 = 1 | X_0 = 2] =$$

$$= P_{21} * P_{12}^{(2)} * P_{21} * P_{13} = .4 * .28 * .4 * .7 = .0314$$

$$P[X_4 = 3, X_3 = 1, X_2 = 1] =$$

Recall:  $(\alpha_1 = 0.3, \alpha_2 = 0.6, \alpha_3 = 0.1)$

Classification of States:

(A) Transition probability matrix in our inventory example.

$$P = \begin{bmatrix} 0.3 & 0 & 0.7 \\ 0.4 & 0.3 & 0.3 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}, P^4 = \begin{bmatrix} 0.284 & 0.26 & 0.456 \\ 0.279 & 0.265 & 0.456 \\ 0.279 & 0.260 & 0.461 \end{bmatrix}$$

$$P^8 = \begin{bmatrix} 0.280 & 0.262 & 0.458 \\ 0.280 & 0.262 & 0.458 \\ 0.280 & 0.262 & 0.458 \end{bmatrix}, P^{12} = \begin{bmatrix} 0.280 & 0.262 & 0.458 \\ 0.280 & 0.262 & 0.458 \\ 0.280 & 0.262 & 0.458 \end{bmatrix}$$

(B)

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, P^2 = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}, P^{12} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P^{13} = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}, P^{14} = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

(C)

$$P = \begin{bmatrix} 0.3 & 0.3 & 0.4 \\ 0.4 & 0.2 & 0.4 \\ 0 & 0 & 1 \end{bmatrix}, P^2 = \begin{bmatrix} 0.21 & 0.15 & 0.64 \\ 0.20 & 0.16 & 0.64 \\ 0 & 0 & 1 \end{bmatrix}$$

$$P^{12} = \begin{bmatrix} 0.001 & 0.0009 & 0.998 \\ 0.001 & 0.0009 & 0.998 \\ 0 & 0 & 1 \end{bmatrix}, P^{16} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 1 \\ 0 & 0 & 1 \end{bmatrix}$$

(D)

$$P = \begin{bmatrix} 0.2 & 0.8 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 \\ 0 & 0 & 0.3 & 0.7 \\ 0 & 0 & 0.5 & 0.5 \end{bmatrix}, P^2 = \begin{bmatrix} 0.36 & 0.64 & 0 & 0 \\ 0.32 & 0.68 & 0 & 0 \\ 0 & 0 & 0.44 & 0.56 \\ 0 & 0 & 0.40 & 0.60 \end{bmatrix}$$

$$P^{16} = \begin{bmatrix} 0.333 & 0.667 & 0 & 0 \\ 0.333 & 0.667 & 0 & 0 \\ 0 & 0 & 0.417 & 0.583 \\ 0 & 0 & 0.417 & 0.583 \end{bmatrix}, P^{17} = \begin{bmatrix} 0.333 & 0.667 & 0 & 0 \\ 0.333 & 0.667 & 0 & 0 \\ 0 & 0 & 0.417 & 0.583 \\ 0 & 0 & 0.417 & 0.583 \end{bmatrix}$$

- It can be seen that in some Markov Chains, multiplying  $P$  by itself a large number of times will result in identical rows (A and C) - independent of starting states.

- This means that n-step transition probability does not depend on starting state.
- These probabilities are called steady state or stationary probabilities.
- In B and D, the rows are not identical; this means that only certain type of Markov Chains have steady state probabilities. This depends upon the types of states a Markov Chain has, which we will study next.

Classification of States:

1. State  $j$  is "accessible" from state  $i$ , if

$$P_{ij}^n > 0, \text{ for some } n \geq 0.$$

That is, process or system will enter state  $j$ , at some time in the future (some  $n$ ), starting in state  $i$  now.

2. Two states,  $i$  and  $j$ , that are accessible to each other are said to "communicate each other"
  - (a) If  $i \leftrightarrow j$ , then  $j \leftrightarrow i$ .
  - (b) If  $i \leftrightarrow j$ , and  $j \leftrightarrow k$ , then  $i \leftrightarrow k$ .
  - (c) A state communicates with itself if  $i \leftrightarrow i$ .
3. If  $i \leftrightarrow j$ , then  $i, j$  belong to the same class.
4. A Markov Chain could have more than one class of states.
5. If a Markov Chain has only one class, then it is said to be irreducible.

**Example 1.**

$$P = \begin{bmatrix} 0.3 & 0 & 0.7 \\ 0.4 & 0.3 & 0.3 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$$

**Example 2.**

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

**Example 3.**

$$P = \begin{bmatrix} 0.3 & 0.3 & 0.4 \\ 0.4 & 0.2 & 0.4 \\ 0 & 0 & 1 \end{bmatrix}$$

**Example 4.**

$$P = \begin{bmatrix} 0.2 & 0.8 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 \\ 0 & 0 & 0.3 & 0.7 \\ 0 & 0 & 0.5 & 0.5 \end{bmatrix}$$

Closed Sets:

1. No state outside the set can be reached from it.
2. If only one state forms a closed set, then it is called an *absorbing state*. That is if  $j$  is an absorbing state, then  $P_{jj} =$

Definition:

Probability [ the system will *ever* revisit state  $i$ , after it leaves it] =  $f_i$

- A state is said to be *recurrent* if  $f_i = 1$ .
- A state is said to be *transient* if  $f_i < 1$ .

**Example 5.**

$$P = \begin{bmatrix} 0.3 & 0 & 0.7 \\ 0.4 & 0.3 & 0.3 \\ 0.2 & 0.4 & 0.4 \end{bmatrix}$$

**Example 6.**

$$P = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{bmatrix}$$

**Example 7.**

$$P = \begin{bmatrix} 0.3 & 0.3 & 0.4 \\ 0.4 & 0.2 & 0.4 \\ 0 & 0 & 1 \end{bmatrix}$$



**Example 8.**

$$P = \begin{bmatrix} 0.2 & 0.8 & 0 & 0 \\ 0.4 & 0.6 & 0 & 0 \\ 0 & 0 & 0.3 & 0.7 \\ 0 & 0 & 0.5 & 0.5 \end{bmatrix}$$

- If state  $i$  is recurrent, then the number of times the process/system visits state  $i$  is
  - If state  $i$  is transient, then the number of times the process/system visits state  $i$  is
  - Let us consider a transient state  $i$  and derive the mean number of times the system visits  $i$ , before it leaves state  $i$  forever.
  - After each visit to state  $i$ , there are two outcomes.
    1. It will come back with probability
    2. It will not come back with probability
  - The number of times the system visits  $i$ , before it leaves  $i$  forever
- 
- Mean number of times the system visits  $i$ , before it leaves  $i$  forever

- We can also derive an alternative expression for the expected (mean) number of visits to state  $i$ , before the system leaves  $i$  forever.
- Let us define an indicator (0-1 variable)  $I_n$  as follows.

$$I_n = \begin{cases} 1, \\ 0, \end{cases}$$

- Total number of visits to  $i$  after leaving  $i$

$$\sum_{n=0}^{\infty} I_n | X_0 = i$$

- Expected number of visits to  $i$ , after leaving  $i$

$$E \left[ \sum_{n=0}^{\infty} I_n | X_0 = i \right] =$$

- State  $i$  is recurrent if

- State  $i$  is transient if

In summary: State  $i$  is

- recurrent if

- transient if

Also,

- If  $i$  is recurrent and if  $i \leftrightarrow j$ , then  $j$  is
- If  $i$  is transient and if  $i \leftrightarrow j$ , then  $j$  is
- Recurrence and Transience are Class properties.