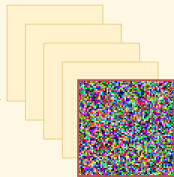


**Flickered Sequence  
(5 frames)**



**Reference ROI**

**Input Data**



$X_t$

**Forward Diffusion**

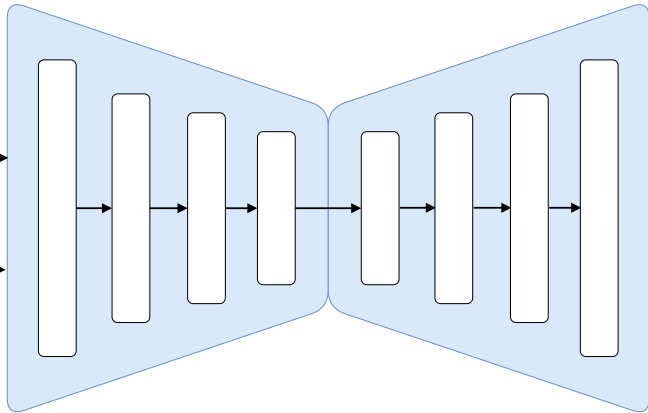
**Combined Condition**

**Time  
Embed**

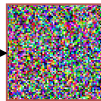
**Class  
Embed**



**Class-Conditioned 3D UNet**



**Predicted Noise  
 $\hat{\epsilon}$**



$T$  steps

