Chapter 7: Sparse Arrays, Cell Arrays, and Structures

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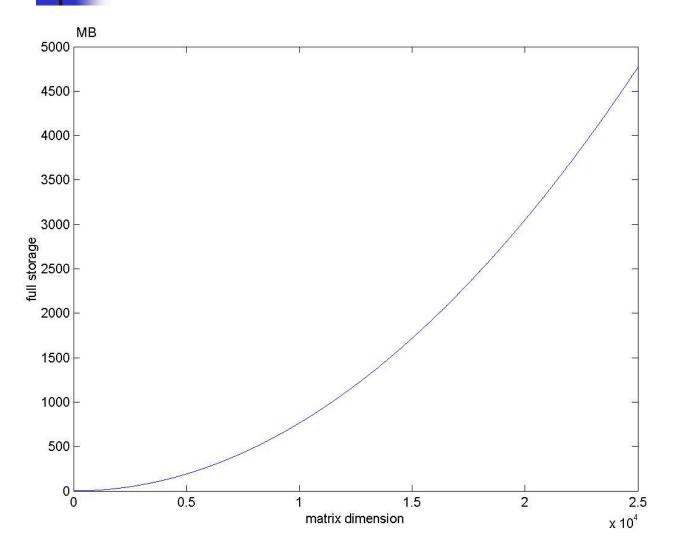
•

Why introduce Sparse Arrays?

```
>> x=1:10:25000;
>> y=((x.^2*8)/1024)/1024;\% mb
>> plot(x,y)
>> text(0,5000,'MB')
>> ylabel('full storage')
>> xlabel('matrix dimension')
>> y(end) \rightarrow ans = 4764.9
>> y(end)/1024 \rightarrow ans = 4.6533
```



Full matrix storage



memory: 25000*25000 *8 bytes =4765MB

=4.65GB

Matrix / Array Storage

- In standard matrix implementations,
- the computational complexity is O(N^3) operations,
- the storage complexity is O(N^2) operations.

923.2

618.0

Table 1: Memory requirement of a matrix in double precision versus its dimension N

Dimension N	1000	3000	5000	7000
Storage (MB)	7.7	68.7	190.8	373.9
9000 1100	00 13	000	15000	17000

1289.4

1716.6



Matrix / Array Storage (Cont.)

1) What happens if we don't have enough memory storage?

2) Virtual memory?

3) What could we do?

Sparse Arrays

10*10=100 elements

value 1: 14 elements value 0: 86 elements

Sparse data type:
three values for each nonzero
element are saved:
value of the element;
the row and column numbers
where the element is located

Sparse Arrays (Cont.)

```
>> a=eye(10)
a =
```

1	0	0	0	0	0	0	0	0	0
0	1	0	0	0	0	0	0	0	0
0	0	1	0	0	0	0	0	0	0
0	0	0	1	0	0	0	0	0	0
0	0	0	0	1	0	0	0	0	0
0	0	0	0	0	1	0	0	0	0
0	0	0	0	0	0	1	0	0	0
0	0	0	0	0	0	0	1	0	0
0	0	0	0	0	0	0	0	1	0
0	0	0	0	0	0	0	0	0	1

Sparse Arrays (Cont.)

>> as=sparse(a)

as =

(1,1)	1
(2,2)	1
(3,3)	1
(4,4)	1

(5,5)

(6,6)	1
(7,7)	1
(8,8)	1
(9,9)	1
(10,10)	1

Workspace			
=) Stac	#C Base ▼
Name	Size	Bytes	Class
⊞ a	10×10	800	double array
<u> as</u>	10x10	164	double array (sparse)

压缩了5倍:原空间的20%就够了



Generating Sparse Matrices

£. .11/_ \

>> a=speye(5)	>> b=	=full(a	a)		
a =	b =				
(1,1) 1 (2,2) 1 (3,3) 1 (4,4) 1 (5,5) 1	1 0 0 0 0	0 1 0 0	0 0 1 0	0 0 0 1 0	0 0 0 0 1



Working with Sparse Matrices

$$b =$$



>> a(2,1)=	=2
a =	
(1,1) (2,1) (2,2) (3,3) (4,4) (5,5)	1 2 1 1 1

```
>> c=a+2*b
```

full matrix

Cell Arrays

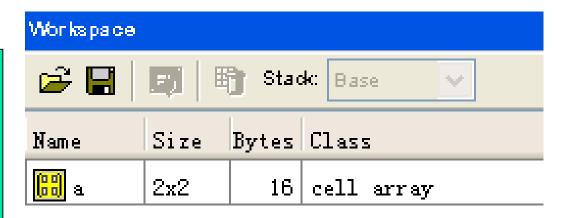
Each element of a cell array is a <u>pointer</u> to another data structure, and those data structures can be of different types.

cell 1,1	cell 1,2
'project name:	'PI: Lisa'
Computer networks'	
cell 2,1	cell 2,2
['J.F.Mends';	[2000;
'A. L. Albert'	3000;
]]



Creating Cell Arrays

a=cell(2,2)



$$a =$$

Creating Cell Arrays (Cont.)

```
>> a{1,1}=[1 2 3; 4 5 6; 7 8 9];
>> a{1,2}='Matlab Programming';
>> a{2,1}=[3+4i 5; 4+6i 7];
>> a{2,2}=[];
```

```
a{m,n}: set/display the values of cell a at location (m,n)
```

a(m,n): set/display the data structure of cell a at location (m,n)

Parentheses (), Brackets [], Braces {}

>> help .

Operators and special characters.

Arithmetic operators.

	plus	- Plus	+	
	uplus	- Unary plus	+	
	minus	- Minus	-	
	uminus	- Unary minus		-
	mtimes	- Matrix multiply	k	<
	times	- Array multiply	.*	
	mpower	- Matrix power		^
	power	- Array power	.′	\
	mldivide	- Backslash or left matrix	divide	\
	mrdivide	e - Slash or right matrix divi	ide	/
	ldivide	- Left array divide	.\	
	rdivide	- Right array divide	./	
	kron	- Kronecker tensor product		kron
ř	احجم الحجام (an aunhaun		

Relational operators.

	and the second second	
eq	- Equal	==
ne	- Not equal	~=
lt	- Less than	<
gt	- Greater than	>
le	- Less than or equal	<=
ge	- Greater than or equal	>=

Logical operators.

and	- Logical AND	&
or	- Logical OR	I
not	- Logical NOT	~
xor	- Logical EXCLUSIVE OR	
any	- True if any element of	ector is nonzero
all	- True if all elements of ve	ctor are nonzero

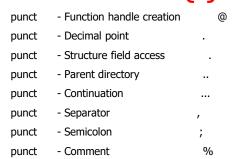
Special characters.

colon - Colon

Parentheses ()

Brackets

Braces



punct	- Invoke operating system of	ommand !		
punct	- Assignment	=		
punct	- Quote	1		
transpos	e - Transpose	.'		
ctranspose - Complex conjugate transpose '				
horzcat	- Horizontal concatenation	[,]		
vertcat	- Vertical concatenation	[;]		
subsasgı	n - Subscripted assignment	(),{ },.		
subsref	- Subscripted reference	(),{ },.		
Ritwica one	arators			

Bitwise operators.

bitand - Bit-wise AND.
bitcmp - Complement bits.
bitor - Bit-wise OR.
bitmax - Maximum floating point integer.

bitxor - Bit-wise XOR.

bitset - Set bit. bitget - Get bit.

bitshift - Bit-wise shift.

Set operators.

union - Set union.
unique - Set unique.
intersect - Set intersection.
setdiff - Set difference.
setxor - Set exclusive-or.
ismember - True for set member.



Viewing the Cell Arrays

4

Viewing the Cell Arrays(Cont.)

```
>> a
```

a =

```
[3x3 double] 'Matlab Programming' [2x2 double] []
```

Displays the data structures in each element of a cell array in a <u>condensed</u> form that limits each data structure to a single line.



condensed phase	
condensed phosphate	
condensed profile	
condensed section	
condensed spark	
condensed specifications	
condensed steam	
condensed tannin extracts	
condensed type	
condensed water outlet	
condensed water removal	
condensed whey	
condenser	
condenser armature	
condenser auxiliary	
condenser bank	
condenser block	
condenser bolometer	
condenser box	
condenser bracket	3
	-

condenser capacity 简明英汉词典 condenser capacity 电容器电容量 冷凝器容量 condenser coil condenser component condenser coupling condenser current condenser current compens condenser damping condenser discharge condenser divider condenser duty condenser excitation condenser expansion joint condenser flange condenser foil condenser gasket

Viewing the Cell Arrays(Cont.)

>> celldisp(a)

$$a{2,1} =$$

$$a{1,2} =$$

Matlab Programming

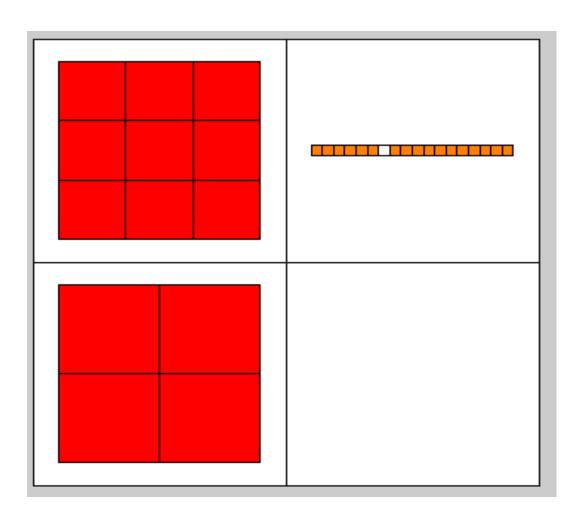
$$a{2,2} =$$

[]



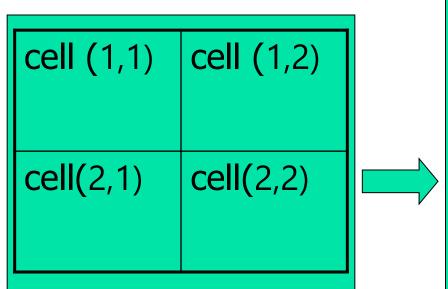
Viewing the Cell Arrays(Cont.)

>> cellplot(a)





Extending Cell Arrays



cell(1,1)	cell(1,2)	
		[]
coll(2.1)	coll(2, 2)	
cell(2,1)	Cell(2,2)	
		LJ
		cell(3,3)
[]	[]	1

cell(3,3)=1



Extending Cell Arrays (Cont.)

```
a=cell(3,3);
for i=1:3
    for j=1:3
        a{i,j}=[i,j];
    end
end
```

```
for i=1:3
    for j=1:3
        a{i,j}=[i,j];
    end
end
```

(a) (b)

Extending Cell Arrays (Cont.)

Recall the learned knowledge!

```
CASE 1:
square=zeros(1,100);
for i=1:100
    square(i)=i^2;
end
```

```
for i=1:100
    square(i)=i^2;
end
```

In CASE 2, the vector square has different size at different time. At each time, Matlab has to

- 1) create a new vector;
- 2) copy the contents of the old array to the new longer array;
- 3) add the new value to the array;
- 4) delete the old array.

Using Data in Cell Arrays

cell(1,1) [1 2 3; 4 5 6; 7 8 9]	cell(1,2) 'Matlab Programming'
cell(2,1) [3 + 4i 5 4 + 6i 7]	cell(2,2) []

```
>> a\{1,1\}
ans =
   1 2 3
4 5 6
7 8 9
>> a\{1,1\}(2,3)
ans =
    6
```

Significance of Cell Arrays Application example:

```
x=0:pi/100:2*pi;
y=sin(2*x);

plot(x,y);

plot(x,y,'-ro');

plot(x,y,'-ro','LineWidth',3.0,'MarkerSize',
8,'MarkerEdgeColor','b','MarkerFaceColor','g');
```

- A variable number of input arguments
- Arguments may have different data types

```
plot(x,y);
cell a \leq = x y
plot(x,y,'-ro');
cell a \leq = x y 'String'
plot(x,y,'-ro','LineWidth',3.0,'MarkerSize',
8,'MarkerEdgeColor','b','MarkerFaceColor','g');
cell a \leq = x y 'string 1' 'string2' value 1
```

varargin

This argument returns a cell array with any number of actual arguments.

varargout

cf. nargin
nargout
nargchk
error
warning
inputname

```
>> help varargin
VARARGIN Variable length input argument list.
   Allows any number of arguments to a function.
                                                 The variable
   VARARGIN is a cell array containing the optional arguments to the
   function. VARARGIN must be declared as the last input argument
   and collects all the inputs from that point onwards. In the
   declaration, VARARGIN must be lowercase (i.e., varargin).
For example, the function,
                  function myplot (x, varargin)
                  plot(x, varargin{:})
  collects all the inputs starting with the second input into the
  variable "varargin". MYPLOT uses the comma-separated list syntax
  varargin{:} to pass the optional parameters to plot. The call,
        myplot(sin(0:.1:1), 'color', [.5 .7 .3], 'linestyle', ':')
```

results in varargin being a 1-by-4 cell array containing the

values 'color', [.5 .7 .3], 'linestyle', and ':'.



```
plot(x,y);
plot(x,y,'-ro');
```

function plotline(varargin)



function plotline(varargin)

```
msg=nargchk(2,inf,nargin);
error(msg);

j=0;
string=";
```



```
for i=1:nargin
   if ischar(varargin{i})
      string=varargin{i};
   else
     j=j+1;
      x(j)=varargin{i}{(1)};
      y(j)=varargin{i}{2};
   end
end
```

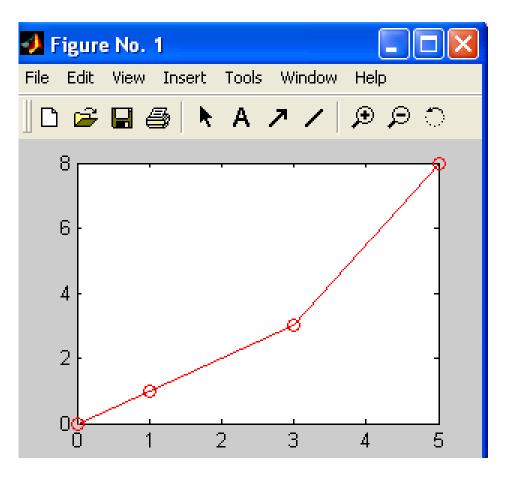


```
if isempty(string)
    plot(x,y);
else
    plot(x,y,string);
end
```

1

Significance of Cell Arrays (Cont.)

>> plotline([0 0], [1 1], [3 3], [5 8], '-ro');



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About varargout

>> help varargout VARARGOUT Variable length output argument list.

Allows any number of output arguments from a function. The variable VARARGOUT is a cell array containing the optional output arguments from the function. VARARGOUT must be declared as the last output argument and must contain all the outputs after that point onwards. In the declaration, VARARGOUT must be lowercase (i.e., varargout).

VARARGOUT is not initialized when the function is invoked. You must create it before your function returns. Use NARGOUT to determine the number of outputs to produce.

```
For example, the function,
  function [s,varargout] = mysize(x)
  nout = max(nargout,1)-1;
  s = size(x);
  for i=1:nout, varargout(i) = {s(i)}; % varargout{i} = s(i), in some new version end
  returns the size vector and optionally individual sizes. So,
    [s,rows,cols] = mysize(rand(4,5));
  returns s = [4 5], rows = 4, cols = 5.
```

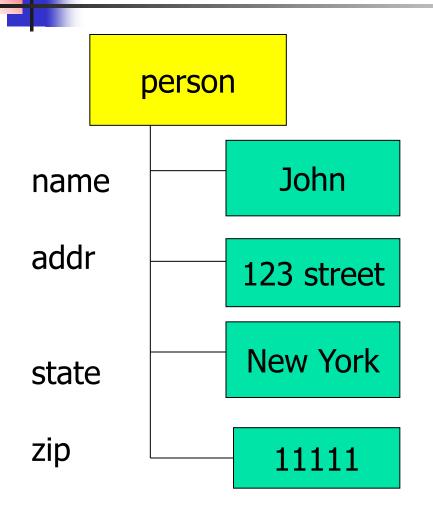


Structure Arrays

elephant trunk tusk长牙 ear body tail

读老子感言: 道不可口, 可口者乃其似也。

Structure Arrays (Cont.)



```
person.name='John';
person.addr='123 street';
person.state='New York';
person.zip=11111;
```

A **structure** is a data type in which each individual property is given a name

field: an individual property of a structure

cf. the situation in C_{35}



Creating Structures

var=struct(fields)

a=struct('name','addr','state','zip');

```
a(1).name='John';
a(1).addr='123 street';
a(1).state='New York';
a(1).zip=111111;
```

```
a(2).name='...';
a(2).addr='...';
a(2).state='...';
a(2).zip=...;
a(3).name=...
```

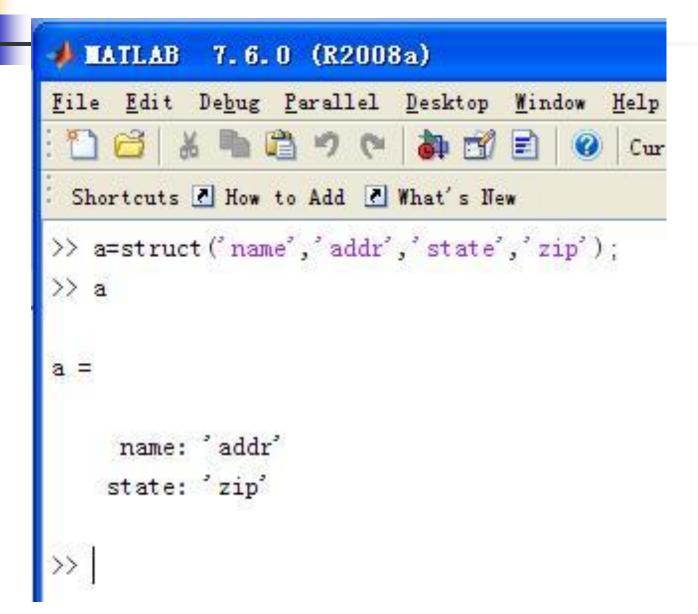
Be careful: Different Versions!!

```
>> help struct ____STRUCT Create or convert to structure array.
    S = STRUCT('field1', VALUES1, 'field2', VALUES2,...) creates a
structure array with the specified fields and values. The value
arrays VALUES1, VALUES2, etc. must be cell arrays of the same size, scalar cells or single values. Corresponding elements of the value
arrays are placed into corresponding structure array elements.
The size of the resulting structure is the same size as the
value cell arrays or 1-by-1 if none of the values is a cell.
    STRUCT(OBJ) converts the object OBJ into its equivalent
structure. The class information is lost.
    STRUCT([]) creates an empty structure.
    To create fields that contain cell arrays, place the cell
arrays within a VALUE cell array. For instance,
       s = struct('strings', {{'hello', 'yes'}}, 'lengths', [5 3])
    creates the 1-by-1 structure
        s = strings: { 'hello' 'yes' }
           lengths: [5 3]
     Example
        s = struct('type',{'big','little'},'color','red','x',{3 4})
```

Be careful: Different Versions!!

```
>> a=struct('name','addr','state','zip')
 = name: 'addr'
    state: 'zip'
>> a(1)
ans = name: 'addr'
      state: 'zip'
??? Index exceeds matrix dimensions.
  a(2)=a(1);
 = 1x2 struct array with fields:
    name
    state
ans = name: 'addr'
      state: 'zip'
                           证实 > 勿轻言否定 > 证伪
```

MATLAB 7.6 version:





Adding Fields to Structures

 By adding a new field to any element in a structure array, this field is automatically added to all of the elements in the array

```
a(1).grade=[2 3];
```

```
a(1).name='John';
a(1).addr='123 street';
a(1).state='New York';
a(1).zip=111111;
a(1).grade=[2 3];
```



Removing Fields from Structures

new_struc=rmfield(old_array,'field')

b=rmfield(a,'zip');



getfield and setfield functions

- var=getfield(array,{array_idx},'field',{field_idx})
- var=array(array_index).field(field_index)

```
a(1).name='John';
a(1).addr='123 street';
a(1).state='New York';
a(1).zip=111111;
a(1).grade=[2 3];
```

```
b=getfield(a,{1},'grade',{2});
b=a(1).grade(2);
```

getfield and setfield functions (Cont.)

- f=setfield(array,{array_idx},'field',{field_idx},val)
- array(array_index).field(field_index)=value

```
a(1).name='John';
a(1).addr='123 street';
a(1).state='New York';
a(1).zip=1111111;
a(1).grade=[2 3];
```

f=setfield(a,{1},'grade',{1},4);

```
a(1).name='John';
a(1).addr='123 street';
a(1).state='New York';
a(1).zip=111111;
a(1).grade=[4 3];
```



- Using this group of PPTs, please read
- [1] Yunong Zhang, Weimu Ma, Xiao-Dong Li, Hong-Zhou Tan, Ke Chen, MATLAB Simulink modeling and simulation of LVI-based primal-dual neural network for solving linear and quadratic programs, Neurocomputing 72 (2009) 1679-1687
- [2] Yunong Zhang, Chenfu Yi, Weimu Ma, Simulation and verification of Zhang neural network for online timevarying matrix inversion, Simulation Modelling Practice and Theory 17 (2009) 1603-1617