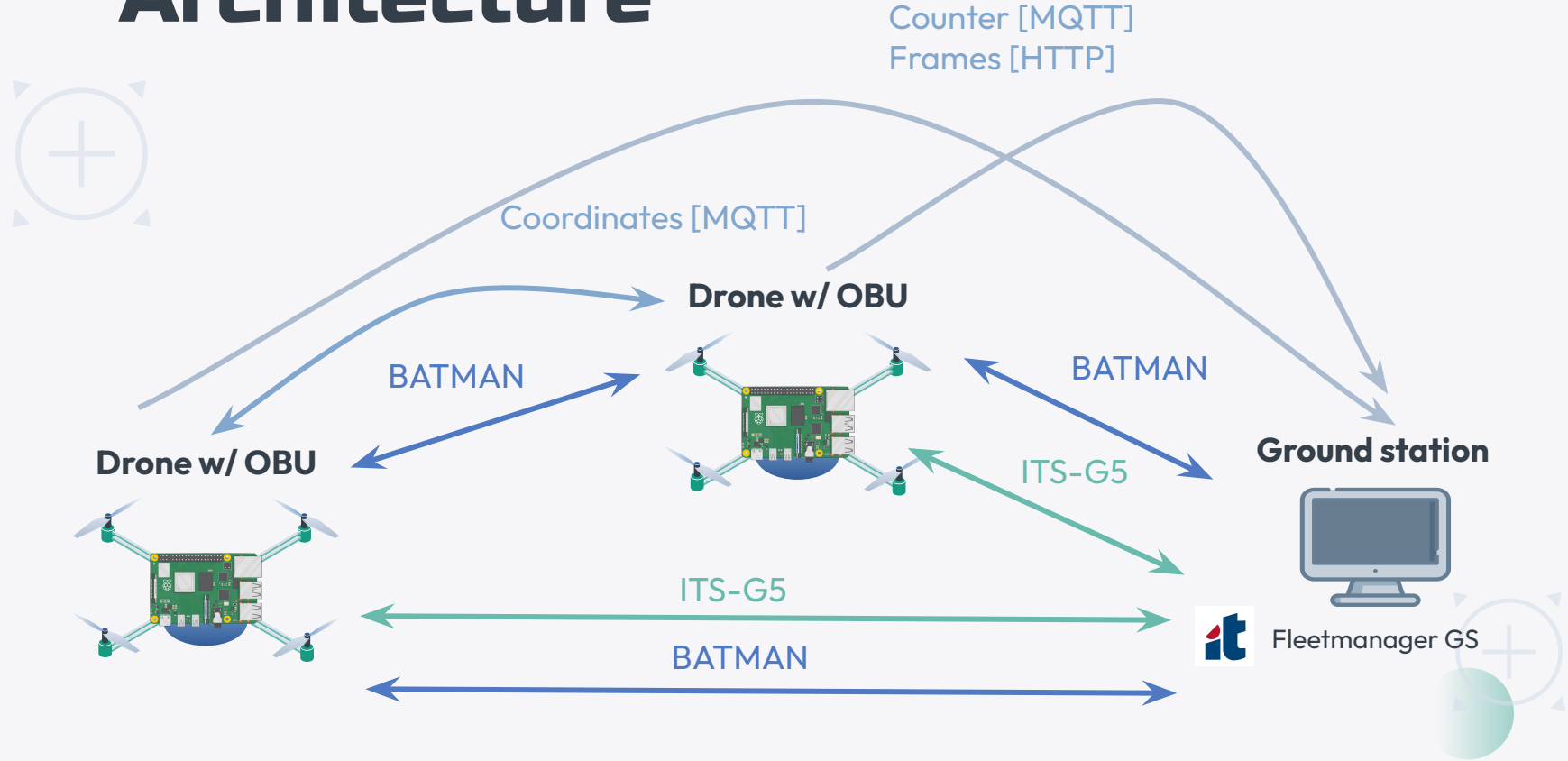


# DRONE MESH FOR CROWD DENSITY MONITORING

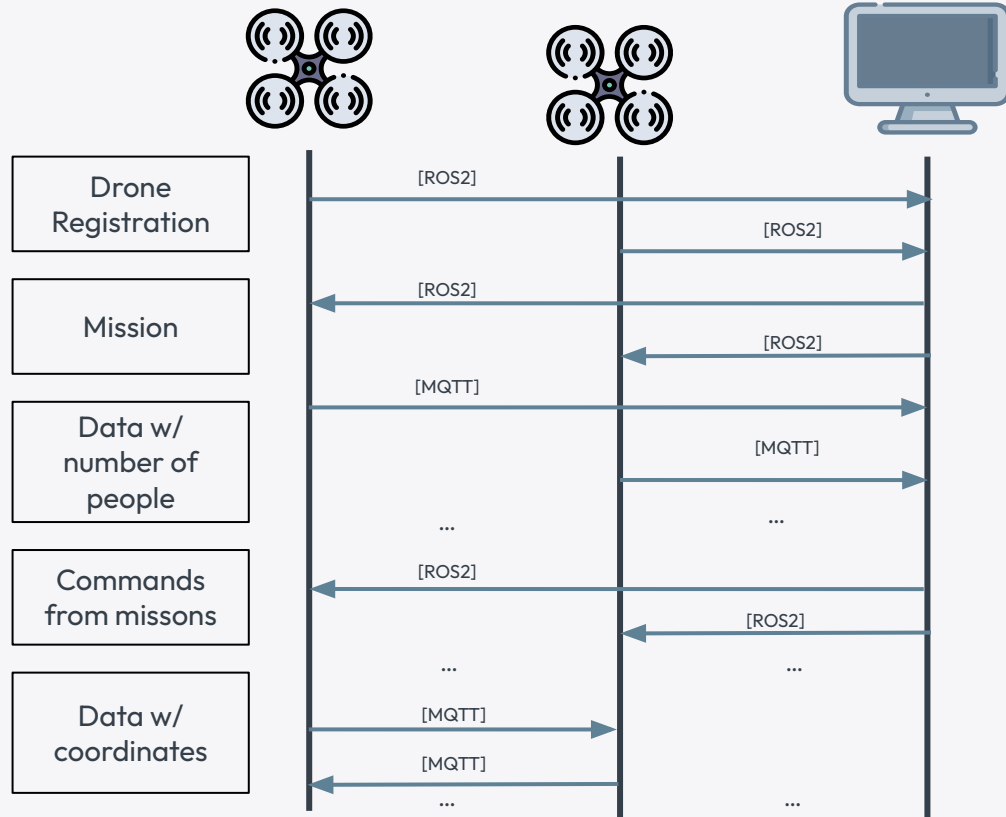


Diogo Correia 90327  
Tiago Rodrigues 93413

# Architecture



# Event sequence



# What was done on the 1st iteration

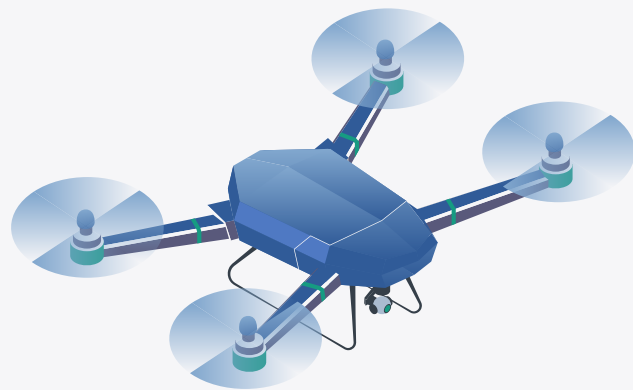
- Person detection algorithm implementation using ultralytics, an efficient way of implementing YOLO.
- Drones connection to Fleetmanager Ground station (NAP@IT-Aveiro)

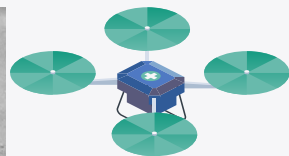


[illegible]

# Person detection

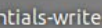
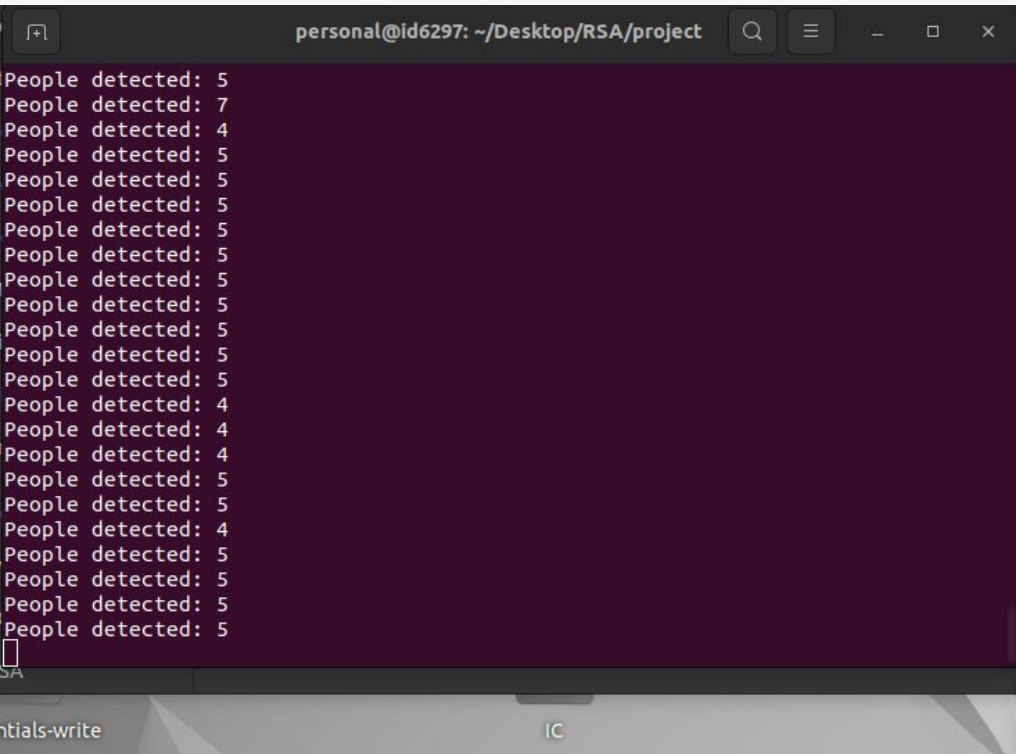
Output examples





Test using Demo Picutre



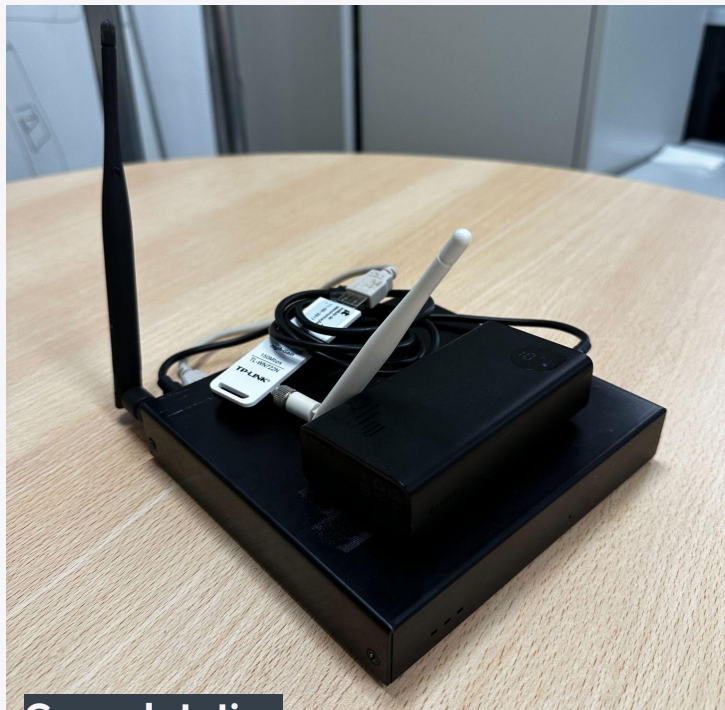




# What we have (and don't) so far



# Components



**Ground station**



**Drone w/ OBU**

# Ground station



ITS-G5

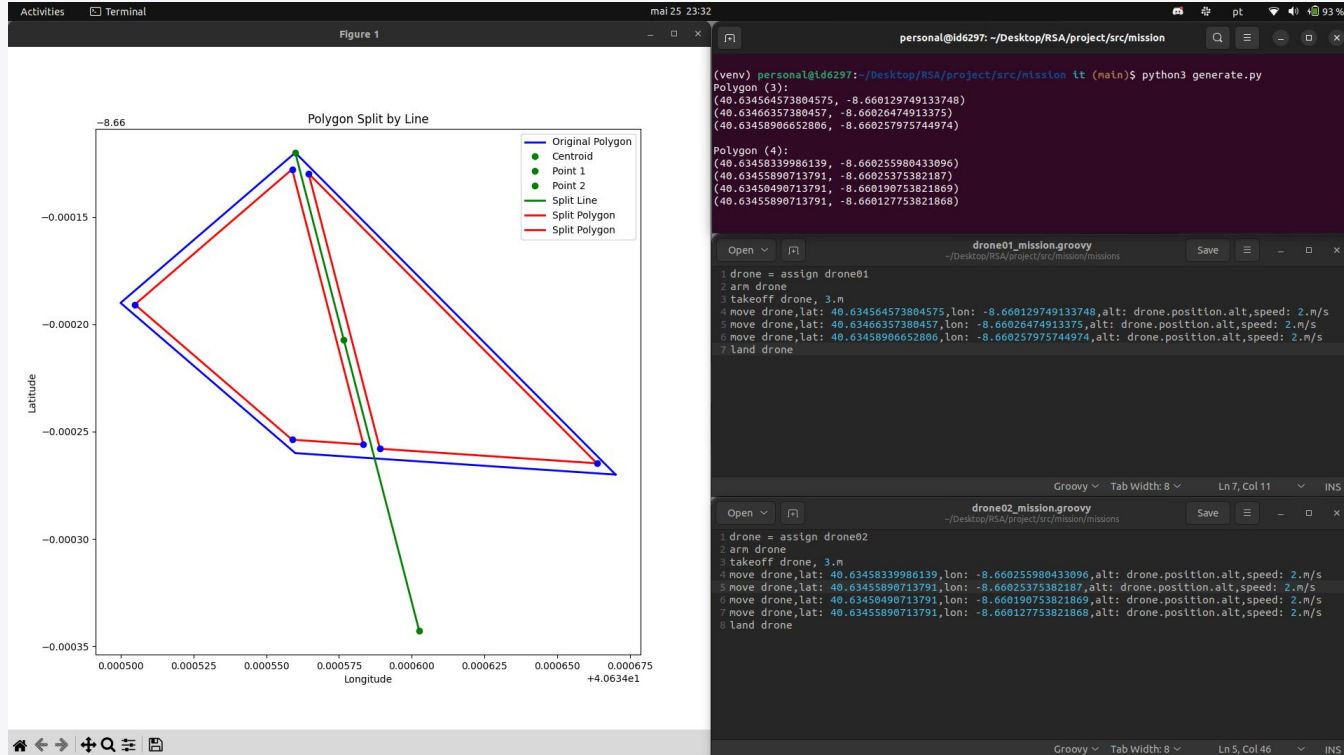
Wi-Fi

APU

The Ground station has:

- A WLAN interface with **ITS-G5**, used to communicate with the drones and **send commands**.
- A WLAN interface with **Wi-Fi**, used to integrate a **BATMAN** ad-hoc network and **receive the video frames** from each drone
- A CPU running the **Fleetmanager Groundstation** module, and this project's **Dashboard** with the video streaming, the person counter and the mission generator.

# Mission Generator



# Drone



ITS-G5

Raspberry Pi

APU

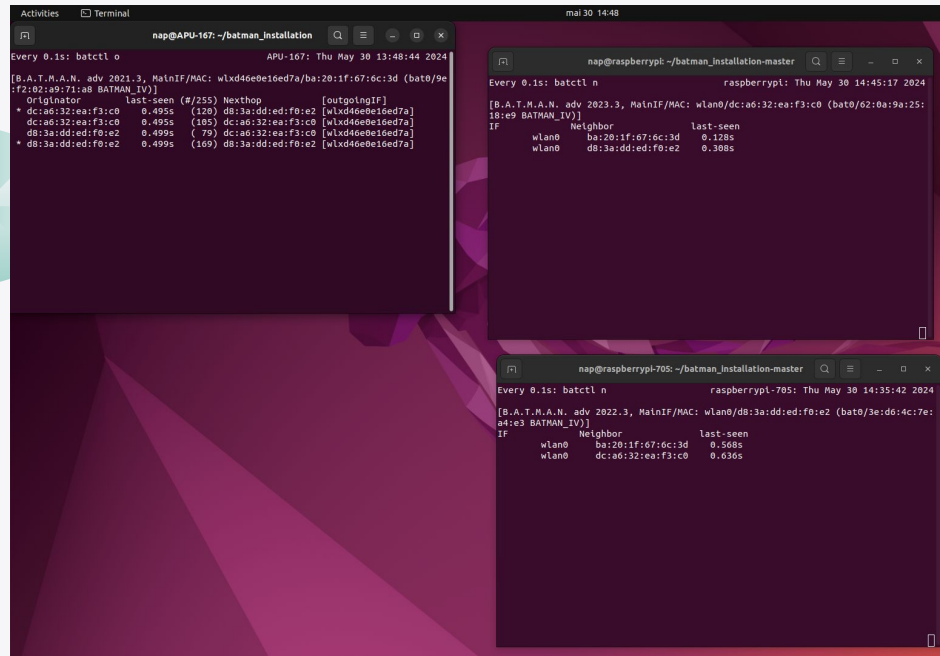
The drone has:

- A WLAN interface with **ITS-G5**, used to communicate with the ground station and **receive commands**.
- A WLAN interface with **Wi-Fi** on the Raspberry Pi, used to integrate a **BATMAN** ad-hoc network and **send the video frames** through HTTP and the **Counter** and **Coordinates** through MQTT
- A CPU running the **Fleetmanager Drone** module and a Raspberry Pi running the **Detection** module and the **Telemetry** module



```
Activities Terminal m91 2024/05/01 10:00 100%
[nap@APU-167: ~] uavs [root@raspberrypi-705: /home]
nap@APU-167: ~$ uavs
[30-05-2024 18:02:57.400] WARN - drones - Stopped receiving messages from drone
[30-05-2024 18:05:10.502] INFO - drones - Start manual mode
[30-05-2024 18:05:10.875] INFO - drones - Established connection with ground station
* Starting NTP server ntpd
..done
18:07:32.436 [main] DEBUG org.ros2.rcljava.common.JNIUtils - Loading implementation: o
rg.ros2.rcljava_rcl_java_jni
18:07:32.437 [main] DEBUG org.ros2.rcljava.common.JNIUtils - Loading implementation: o
rg.ros2.rcljava_context_impl_jni
18:07:32.599 [main] INFO org.ros2.rcljava.RCLJava - Using RMW implementation: rmw_fast
rtcps_cpp
[30-05-2024 18:07:38.376] INFO - Starting FleetmanServerApplication using Java 10.0.2
2 on APU-167 with PID 86 (/usr/install/server/share/server/java/server-1.10-SNAPSHOT.jar started by root i
n /usr)
[30-05-2024 18:07:38.389] DEBUG - Running with Spring Boot v2.4.5, Spring v5.3.6
[30-05-2024 18:07:38.396] INFO - No active profile set, falling back to default profi
les: default
[30-05-2024 19:08:00.362] DEBUG - Filter 'requestLoggingFilter' configured for use
[30-05-2024 19:08:18.082] WARN - Could not detect network interface within the '10.1
1.0/24' subnet
[30-05-2024 19:08:23.621] INFO - Loaded person_location sensor configuration from fl
e 'person_location.yml'
[30-05-2024 19:08:23.646] INFO - Loaded temperature sensor configuration from file 't
emperature.yml'
[30-05-2024 19:08:23.742] INFO - Loaded locator sensor configuration from file 'locat
or.yml'
[30-05-2024 19:08:23.764] INFO - Loaded network sensor configuration from file 'netwo
rk.yml'
WARNING: An illegal reflective access operation has occurred
WARNING: Illegal reflective access by org.eclipse.paho.client.mqttv3.internal.FileLock
(file:/opt/jardep/org.eclipse.paho.client.mqttv3-1.2.5.jar) to method sun.nio.ch.FileLockImpl.release()
WARNING: Please consider reporting this to the maintainers of org.eclipse.paho.client
.mqttv3.internal.FileLock
WARNING: Use --illegal-access=warn to enable warnings of further illegal reflective ac
cess operations
WARNING: All illegal access operations will be denied in a future release
[30-05-2024 19:08:24.842] INFO - Connected to mqtt server at tcp://localhost:1883
[30-05-2024 19:08:32.330] INFO - Started FleetmanServerApplication in 58.463 seconds
(JVM running for 62.366)
[30-05-2024 19:08:48.954] INFO - drones - Registered
[30-05-2024 19:08:49.964] INFO - drones - Flight controller system connected
[30-05-2024 19:08:52.973] ERROR - Critical battery level
[30-05-2024 19:08:59.087] INFO - drones - Established connection with ground station
Received coordinates: (40.6346664, -8.6606765)
Received coordinates: (40.634684, -8.6606767)
Received coordinates: (40.6346802, -8.6606769)
Received coordinates: (40.6346861, -8.6606775)
Received coordinates: (40.6346857, -8.6606783)
Received coordinates: (40.6346852, -8.6606791)
Received coordinates: (40.6346847, -8.6606801)
Received coordinates: (40.634684, -8.6606812)
Received coordinates: (40.6346834, -8.6606825)
Received coordinates: (40.6346827, -8.6606836)
Received coordinates: (40.6346821, -8.6606845)
Received coordinates: (40.6346815, -8.6606858)
Received coordinates: (40.634681, -8.660687)
Received coordinates: (40.6346806, -8.6606878)
Received coordinates: (40.6346804, -8.6606883)
Received coordinates: (40.6346803, -8.6606885)
Received coordinates: (40.6346803, -8.6606886)
Received coordinates: (40.6346804, -8.6606887)
Received coordinates: (40.6346804, -8.6606889)
Received coordinates: (40.6346805, -8.660689)
Received coordinates: (40.6346805, -8.6606891)
Received coordinates: (40.6346806, -8.6606892)
Received coordinates: (40.6346807, -8.6606893)
Received coordinates: (40.6346808, -8.6606894)
Received coordinates: (40.6346809, -8.6606894)
Received coordinates: (40.634681, -8.6606894)
Received coordinates: (40.6346812, -8.6606895)
Received coordinates: (40.6346816, -8.6606898)
Received coordinates: (40.634682, -8.6606884)
Received coordinates: (40.6346826, -8.6606879)
Received coordinates: (40.6346833, -8.6606872)
Received coordinates: (40.6346841, -8.6606862)
Received coordinates: (40.634685, -8.6606851)
Received coordinates: (40.6346859, -8.6606837)
Received coordinates: (40.6346869, -8.6606824)
Received coordinates: (40.6346877, -8.6606812)
Received coordinates: (40.6346881, -8.6606802)
Received coordinates: (40.6346885, -8.6606794)
Received coordinates: (40.6346886, -8.660679)
Received coordinates: (40.6346887, -8.6606788)
Received coordinates: (40.6346888, -8.6606786)
Received coordinates: (40.6346889, -8.6606785)
Received coordinates: (40.634689, -8.6606786)
Received coordinates: (40.6346891, -8.6606786)
Received coordinates: (40.6346891, -8.6606787)
Received coordinates: (40.6346892, -8.6606788)
Received coordinates: (40.6346893, -8.6606789)
Received coordinates: (40.6346894, -8.6606791)
Received coordinates: (40.6346896, -8.6606792)
Received coordinates: (40.6346898, -8.6606793)
Received coordinates: (40.63469, -8.6606794)
Received coordinates: (40.6346902, -8.6606795)
Received coordinates: (40.6346904, -8.6606797)
Received coordinates: (40.6346905, -8.6606797)
```

# B.A.T.M.A.N.



The image displays three terminal windows from the B.A.T.M.A.N. project, showing configuration and status information on different Raspberry Pi devices.

**Terminal 1 (Left):** nap@APU-167: ~/batman\_installation

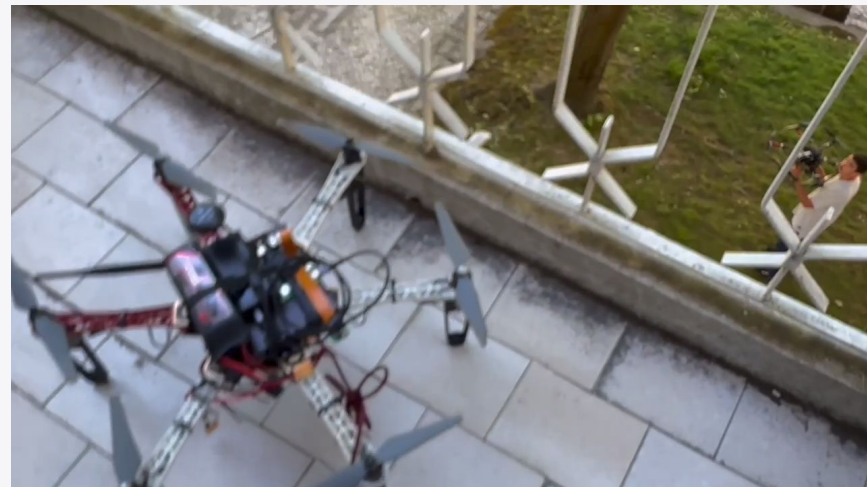
```
Every 0.1s: batctl o APU-167: Thu May 30 13:48:44 2024
[B.A.T.M.A.N. adv 2021.3, MainIF/MAC: wlx46e0e1e0d7a/ba:20:1f:67:6c:3d (bat0/9e:f2:02:a9:71:a8 BATMAN_IV)]
Originator Last-seen (#/255) Next-hop [outgoingIF]
* dc:a6:32:ea:f3:c0 0.495s (120) d8:3a:dd:ed:f0:e2 [wix46e0e1e0d7a]
dc:a6:32:ea:f3:c0 0.495s (185) dc:a6:32:ea:f3:c0 [wix46e0e1e0d7a]
d8:3a:dd:ed:f0:e2 0.499s ( 79) dc:a6:32:ea:f3:c0 [wix46e0e1e0d7a]
* d8:3a:dd:ed:f0:e2 0.499s (100) d8:3a:dd:ed:f0:e2 [wix46e0e1e0d7a]
```

**Terminal 2 (Top Right):** nap@raspberrypi: ~/batman\_installation-master

```
Every 0.1s: batctl n raspberrypi: Thu May 30 14:45:17 2024
[B.A.T.M.A.N. adv 2023.3, MainIF/MAC: wlan0/dc:a6:32:ea:f3:c0 (bat0/62:0a:9a:25:18:e9 BATMAN_IV)]
IF Neighbor Last-seen
wlan0 ba:20:1f:67:6c:3d 0.128s
wlan0 d8:3a:dd:ed:f0:e2 0.308s
```

**Terminal 3 (Bottom Right):** nap@raspberrypi-705: ~/batman\_installation-master

```
Every 0.1s: batctl n raspberrypi-705: Thu May 30 14:35:42 2024
[B.A.T.M.A.N. adv 2022.3, MainIF/MAC: wlan0/d8:3a:dd:ed:f0:e2 (bat0/3e:d6:4c:7e:a4:e3 BATMAN_IV)]
IF Neighbor Last-seen
wlan0 ba:20:1f:67:6c:3d 0.568s
wlan0 dc:a6:32:ea:f3:c0 0.630s
```





# What is missing



# Questions

