### Jacobs University Bremen



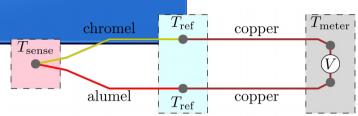
#### Sensors 3

Thermocouple
Capacitive sensing
Accelerometer

Automation CO23-320203



## Thermocouple (and thermopile)



- Another sensor and an actuator in on (=transducer)! This time: from temperature to voltage
- Again, physical chemistry of the metals is responsible for the effect, or actually three effects:

**Seebeck effect**: generation of electrical potential by temperature difference

$$\mathbf{E}_{\mathrm{emf}} = -S\nabla T$$
,

where: E<sub>emf</sub> – local electromotive force (think of it as a voltage!) [V], S – Seebeck coef., T – temperature [K]

Peltier effect: heating/cooling by current flowing between dissimilar metals

$$\dot{Q} = (\Pi_{\rm A} - \Pi_{\rm B})I,$$

where:  $Q_f$  – heat [J],  $\prod$  – Peltier coeficients for both metals, I – current [A]

Thomson effect: combination of the two above in some special conditions

$$\dot{q} = -\mathcal{K}\mathbf{J} \cdot \nabla T$$

where: q - heat [J] per unit volume, K - Thomson coeficient, J - current density [A/mm<sup>2</sup>]

# Thermocouple (and thermopile)

Not really a part of the thermocouple effect, but cannot be excluded of the picture: **Joule heating**, i.e. heating of the conductor due to the flowing electricity:

$$P \propto I^2 R$$

(it affects all wires, not only junctions)

#### **Total:**

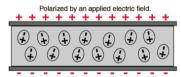
$$-\dot{q}_{
m ext} = 
abla \cdot (\kappa 
abla T) + \mathbf{J} \cdot (\sigma^{-1} \mathbf{J}) - T \mathbf{J} \cdot 
abla S.$$

Bonus: The coefficients are interconnected!

$$\mathcal{K} = T rac{dS}{dT} \qquad \Pi = TS.$$

- A capacitor can be a sensor, and not an actuator. It can be very useful nevertheless.
- The capacitor: two conductors separated by a non-conductive space (void or isolator)





 Mobile charges carriers (here: electrons) move to find an equilibrium of attraction and repulsion due to Coulomb force:

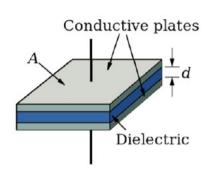
$$F=k_erac{q_1q_2}{r^2}$$

• where  $k_e$  - Coulomb's constant [ $k_e \approx 9 \times 109 \text{ Nm}^2/\text{C}^2$ ],  $q_1$  and  $q_2$  - signed magnitudes of the charges [C] and r - distance between the charges [m]

(visual recap how a capacitor works: https://www.youtube.com/watch?v=f\_MZNsEqyQw)

Capacitance of a capacitor:

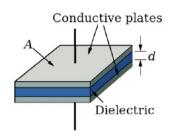
$$C = \epsilon \frac{A}{d}$$
$$= \frac{Q}{V}$$



where: C - capacitance [F],  $\epsilon$  – permittivity of the dielectric, A – area of the plates [m2], d – distance between them [m], Q – electrical charge [C], V – applied voltage [V]

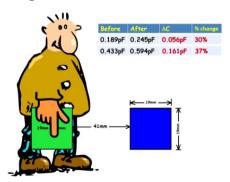
$$\varepsilon = \kappa \ \varepsilon_0$$

where:  $\kappa$  – medium's relative permittivity,  $\epsilon_0$  – permittivity of vacuum [8.85×10<sup>-12</sup> F/m]



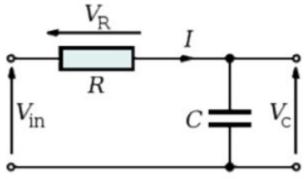
- The capacitance  $C = \epsilon \frac{A}{d}$  depends on several factors
  - we can potentially measure all of them if we can estimate the capacitance at instant t!
- Here is the basic intuition, which works well for turning our capactor into a presence sensor (or even... a button): https://www.youtube.com/watch?v=Qltuf6lNvml

 But how can we really quantify capacitance?



- · We need to employ some dynamics!
- A practical circuit to charge a capacitor:

$$\frac{V_c(s)}{V_{in}(s)} = \frac{1}{1 + RCs}$$
$$V_c(t) = V_{in}(t)(1 - e^{-t/\tau})$$
$$\tau = RC$$



 A good practical summary in a practical circuit: https://www.youtube.com/watch?v=bhspPkxOMxs

# Example: capacitive digitiser

Would you say you have it at your arm's

length?



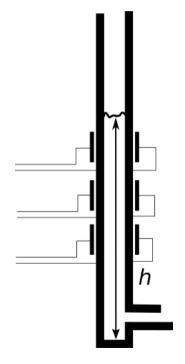
## Capacitive sensing – ε modification

Liquid level detection example revisited



## Capacitive sensing – ε modification

Liquid level detection example revisited



- Accelerometer measures acceleration any acceleration, to be precise:
  - Acceleration due to accelerated motion
  - Acceleration due to gravity
     (and there is no way to distinguish the two!)
- Why? Because of how we measure acceleration: measure the (resultant) force acting on a body.
- Specifically, we use Newton's laws. Here is the second law:

$$F = m a$$

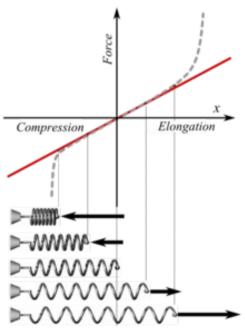
where: F – force applied to body [N], m – body mass [kg] and a – acceleration [ $m/s^2$ ]

 One way to measure force is indirectly, through Hooke's law governing springs:

$$F_s = -k x$$

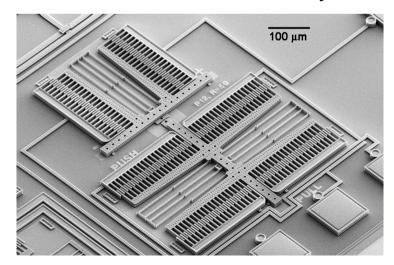
where:  $F_s$  – restoring force acting on the spring [N], k – spring constant [N/m] and x – position [m]

It's an approximate law
 it covers the zone where
 the material stays within its
 elastic limit (not even fully)



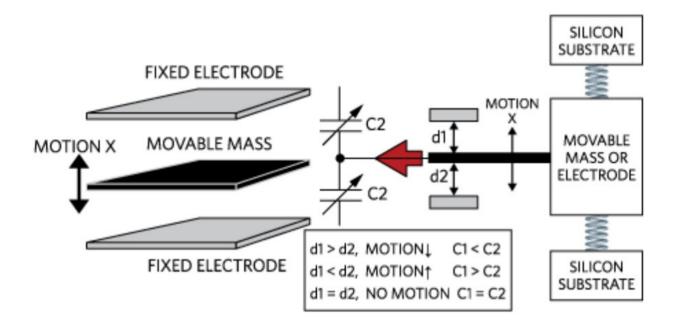
The simplest idea? (blackboard sketch)

- From a naïve device to a serious technology, let's just change the scale!
- MEMS (= Microelectromechanical systems) are made up of components between 1 and 100 micrometers in size
- We are used to manufacture circuits using silicon chip production methods – and that is exactly how MEMS came to life:





Let's put everything together:



How to improve the sensitivity and produce the signal?

