CS585 Image and Video Computing Spring 2025



Instructor: Mahir Patel

Course Website

Deep Dream

Example Piazza question/responses

Q: Is this right?

A: Well, let's think about the expected results if it was right... (i.e., we won't answer this question directly)

Q: What is *some concept*?

A: This is discussed in the book in section X and/or lecture Y.

Better question: Think about what part is confusing you. Be as specific as possible. Ask follow-up questions if necessary.

Q: Some logistics related question that has been asked before A: *point you to the previously asked question*

You will get your questions answered sooner if you search for if anyone has already asked it

slido

Please download and install the Slido app on all computers you use



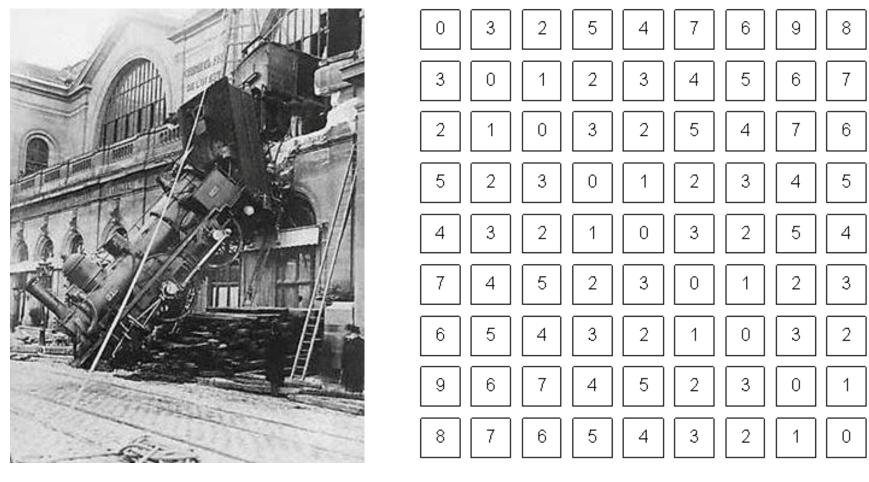


What do you think of when you hear the words "Computer Vision"?

Outline

- Logistics, requirements
- Goal of computer vision and why it is hard
- History of computer vision
- Recent work in vision
- Topics covered in class

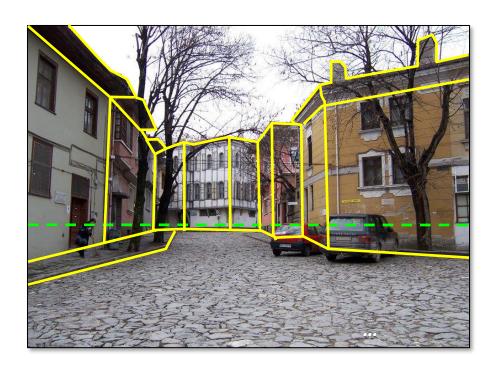
Goal: To extract meaning from pixels



What we see

What a computer sees





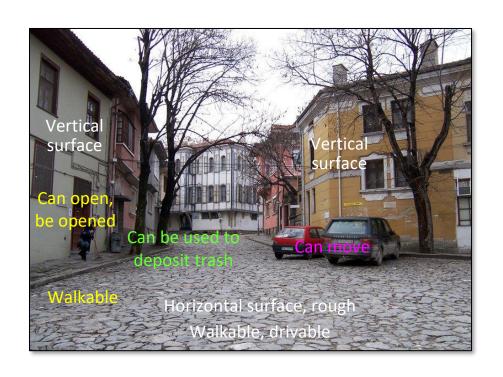
Difficulty

Geometric information



Difficulty

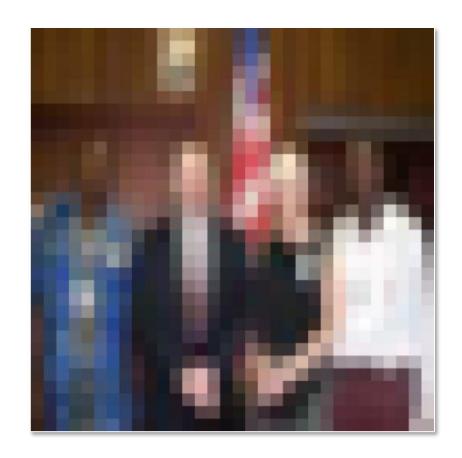




Difficulty



Humans are remarkably good at vision...



...still, vision is hard even for humans



Images are fundamentally ambiguous!





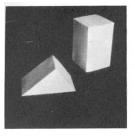


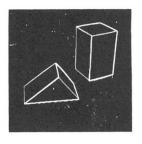


Outline

- Logistics, requirements
- Goal of computer vision and why it is hard
- History of computer vision

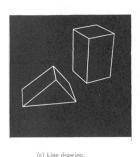
How it started

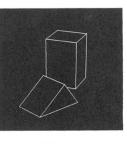




(a) Original picture.

(b) Differentiated picture.





(d) Rotated view

L. G. Roberts, 1963

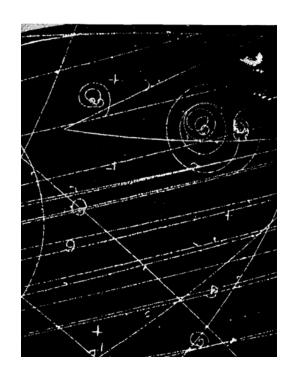
How it's going

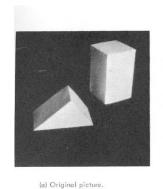
Prompt: a painting of a fox sitting in a field at sunrise in the style of Claude Monet

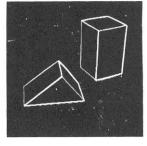


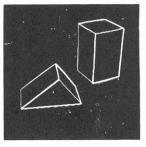
OpenAl DALL-E-2, 2022

Origins



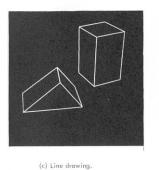




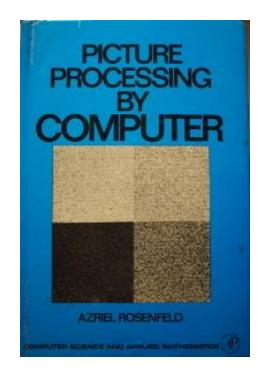


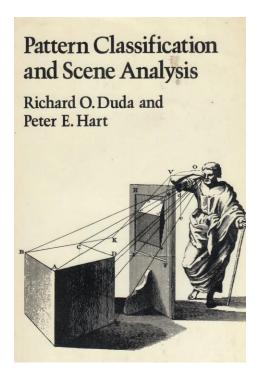
-23-4445(a·d)









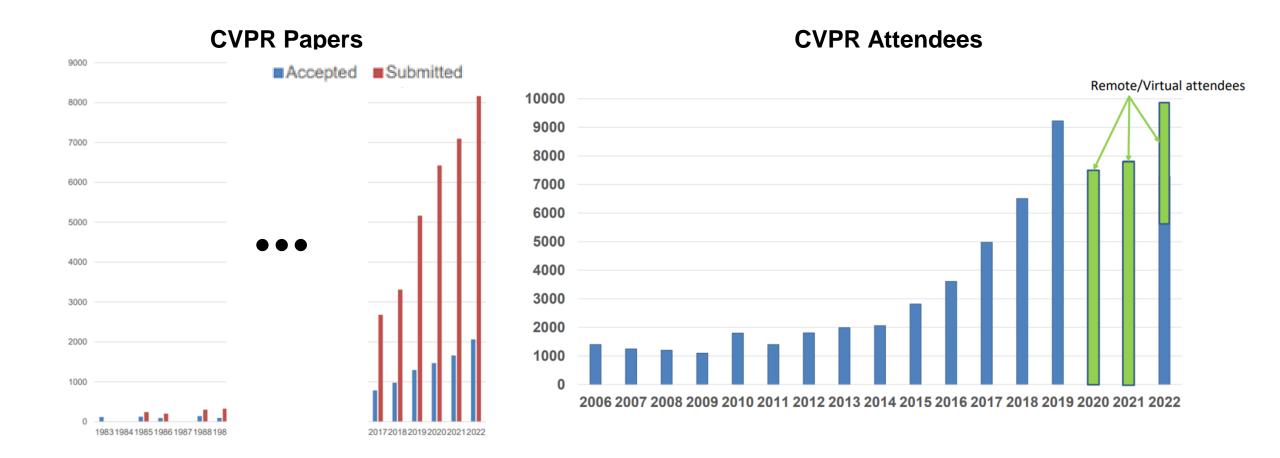


Duda & Hart, 1972 Hough, 1959 Rosenfeld, 1969 Roberts, 1963

Decade by decade

- 1960s: Blocks world, image processing and pattern recognition
- **1970s**: Key recovery problems defined: structure from motion, stereo, shape from shading, color constancy. Attempts at knowledge-based recognition
- **1980s**: Fundamental and essential matrix, multi-scale analysis, corner and edge detection, optical flow, geometric recognition as alignment
- 1990s: Multi-view geometry, statistical and appearance-based models for recognition, first approaches for (class-specific) object detection
- 2000s: Local features, generic object recognition and detection
- 2010s: Deep learning, big data

Growth of the field



Outline

- Logistics, requirements
- Goal of computer vision and why it is hard
- History of computer vision
- Recent work in vision

What can computer vision do today?



In the 60s, Marvin Minsky assigned a couple of undergrads to spend the summer programming a computer to use a camera to identify objects in a scene. He figured they'd have the problem solved by the end of the summer. Half a century later, we're still working on it.

https://xkcd.com/1425/ (September 24, 2014)

What can computer vision do today?

• It's 2025 now...









https://merlin.allaboutbirds.org/

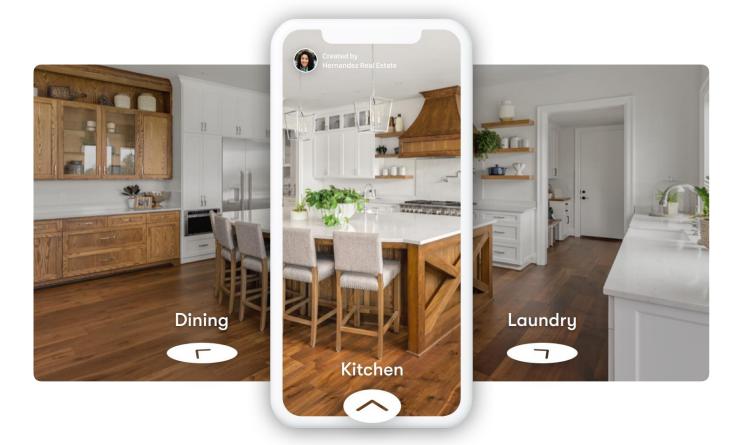
Reconstruction: 3D from photo collections



Q. Shan, R. Adams, B. Curless, Y. Furukawa, and S. Seitz, <u>The Visual</u> <u>Turing Test for Scene Reconstruction</u>, 3DV 2013

Reconstruction: Commercial applications

Make your listing pop with Zillow 3D Home® tours



Reconstruction: Commercial applications

RECONSTRUCT INTEGRATES REALITY AND PLAN







Visual Asset Management

Reconstruct 4D point clouds and organize images and videos from smartphones, time-lapse cameras, and drones around the project schedule. View, annotate, and share anywhere with a web interface.

4D Visual Production Models

Integrate 4D point clouds with 4D BIM, review "who does what work at what location" on a daily basis and improve coordination and communication among project teams.

Predictive Visual Data Analytics

Analyze actual progress deviations by comparing Reality and Plan and predict risk with respect to the execution of the look-ahead schedule for each project location, to offer your project team with an opportunity to tap off potential delays before they surface on your jobsite.

reconstructinc.com

Recognition: "Simple" patterns





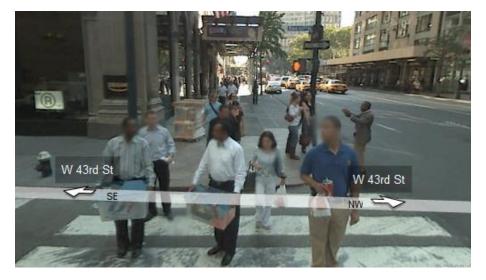




Recognition: Faces







Recognition: Faces



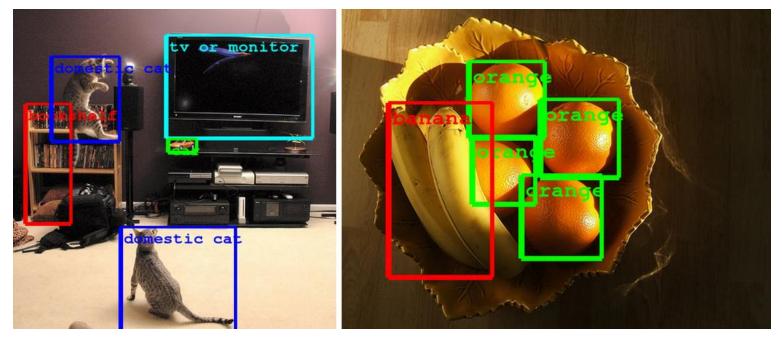


<u>How China Uses High-Tech Surveillance to Subdue Minorities</u> – New York Times, 5/22/2019

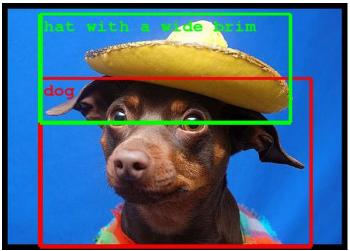
<u>The Secretive Company That Might End Privacy As We Know It</u> – New York Times, 1/18/2020

<u>Wrongfully Accused by an Algorithm</u> – New York Times, 6/24/2020

Recognition: General categories



- Computer Eyesight Gets a Lot More Accurate, NY Times Bits blog, August 18, 2014
- Building A Deeper Understanding of Images,
 Google Research Blog, September 5, 2014



Object detection, instance segmentation



K. He, G. Gkioxari, P. Dollar, and R. Girshick, Mask R-CNN, ICCV 2017 (Best Paper Award)

DeepFakes

Harrison Ford Is Young Han In Solo Deepfake Video

Thanks to deepfake technology, the maligned Solo: A Star Wars Story now stars Harrison Ford instead of Alden Ehrenreich as the young Han.

BY DAN ZINSKI 2 DAYS AGO











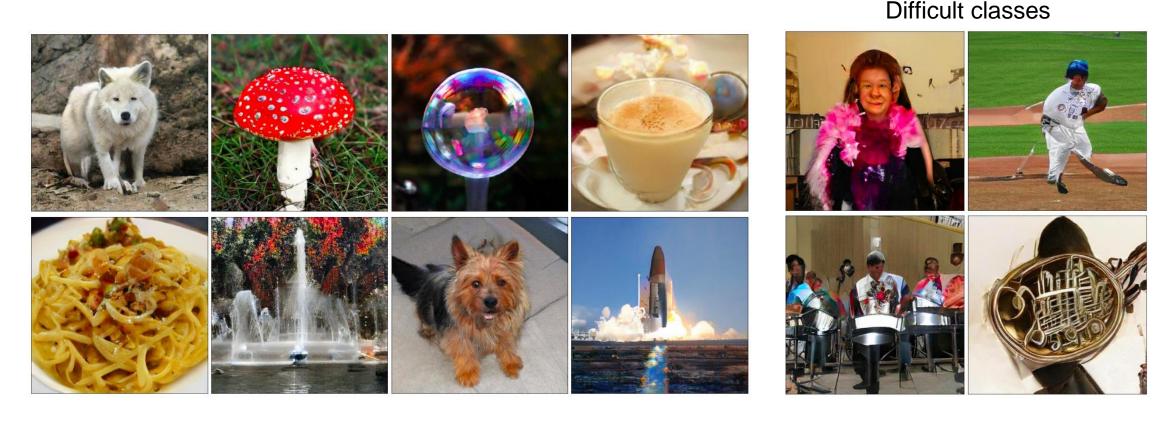
Just a random example...

https://screenrant.com/star-wars-han-solo-movie-harrison-ford-video-deepfake/ https://www.youtube.com/watch?v=bC3uH4Xw4Xo

https://en.wikipedia.org/wiki/Deepfake

Image generation: General categories

 BigGAN: Synthesize ImageNet images, conditioned on class label, up to 512 x 512 resolution



A. Brock, J. Donahue, K. Simonyan, Large scale GAN training for high fidelity natural image synthesis, ICLR 2019

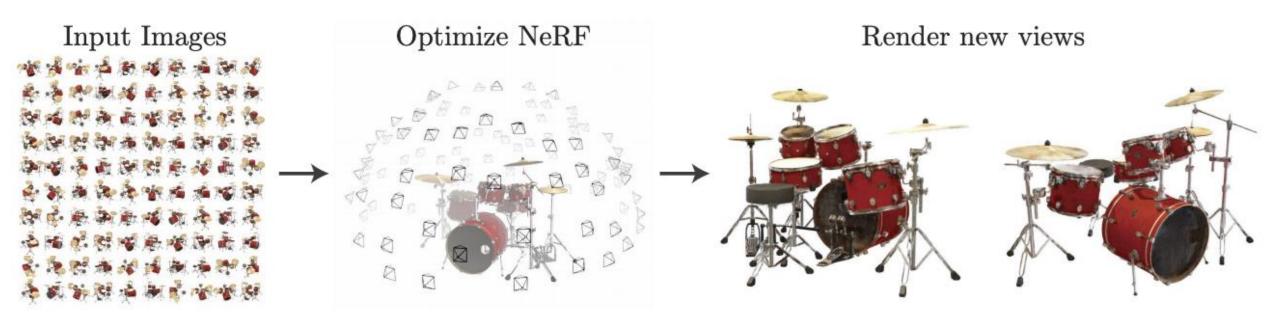
Text-to-image generation: OpenAl DALL-E

Learn a joint sequential transformer model that can be used to generate image based on text prompt



- a tapir with the texture of an hedgehog in a christmas "backprop". a neon sign that accordion.
- sweater walking a dog
- (a) a tapir made of accordion. (b) an illustration of a baby (c) a neon sign that reads reads "backprop". backprop neon sign

3D scene understanding: NERFs



B. Mildenhall et al., Representing Scenes as Neural Radiance Fields for View Synthesis, ECCV 2020

Physical scene understanding: Learning skills from video



Fig. 1. Simulated characters performing highly dynamic skills learned by imitating video clips of human demonstrations. Left: Humanoid performing cartwheel B on irregular terrain. Right: Backflip A retargeted to a simulated Atlas robot.

Video

Outline

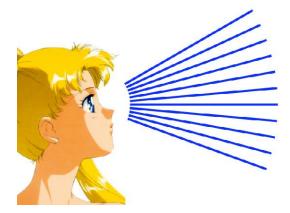
- Logistics, requirements
- Goal of computer vision and why it is hard
- History of computer vision
- Recent work in vision
- Topics covered in class

Topics covered in class

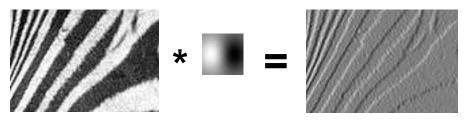
- I. Early vision: Image formation and processing
- II. Recognition
- III. Mid-level vision: Grouping and fitting
- IV. Multi-view geometry

I. Early vision

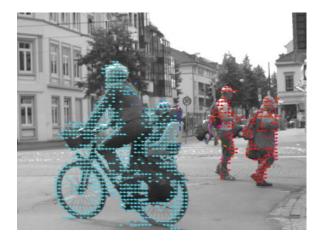
Basic image formation and processing



Cameras and sensors Light and color

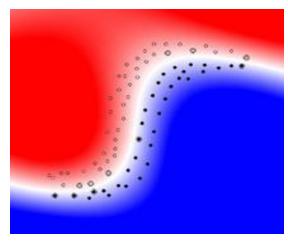


Linear filtering Edge detection

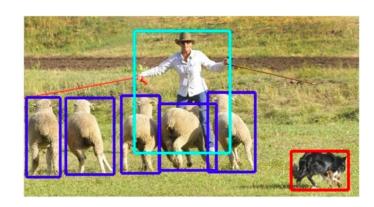


Optical flow

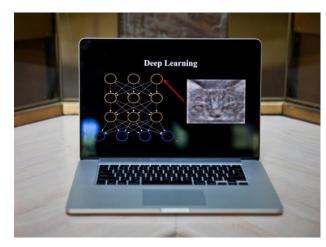
II. Recognition



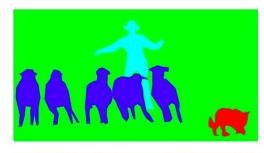
Basic classification



Object detection



Deep learning

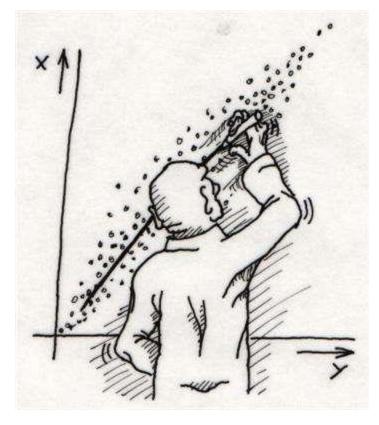




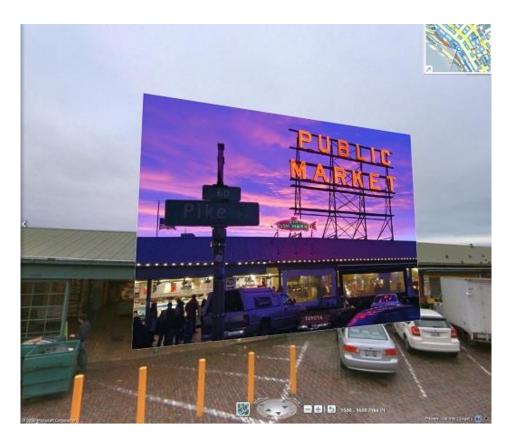
Segmentation

III. "Mid-level vision"

Fitting and grouping



Fitting: Least squares Voting methods



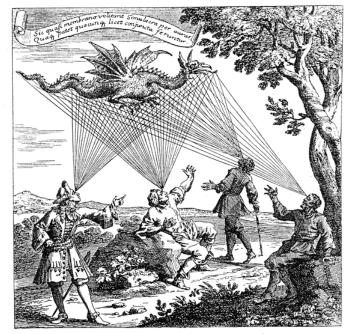
Alignment

IV. Multi-view geometry





Epipolar geometry

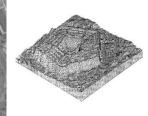


Драконь, видимый подъ различными углами зрънія По гравюрь на мьля изъ "Oculus artificialis telediopricus" Цана. 1702 года.

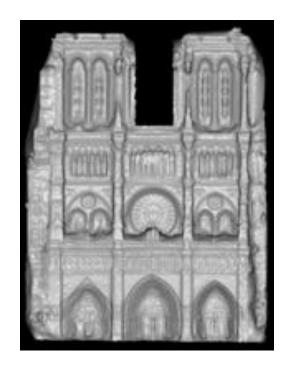
Structure from motion







Two-view stereo



Multi-view stereo

Next Class

Image formation: geometric primitives and transformations, photometric image formation, digital camera

Reading: SZ Ch 2