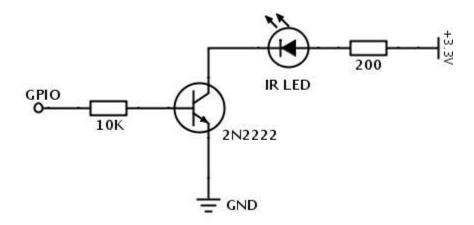
Lirc Setup

This setup was performed on a Raspberry PI 3 running the 11 / 25 / 2016 Jessie Lite version of Raspbian.

Linux xxxxxx 4.4.34-v7+ #930 SMP Wed Nov 23 15:20:41 GMT 2016 armv71 GNU/Linux

lirc was setup for sending ir commands to a JVC receiver. Receiving ir commands was not required. The version in the repo was several revisions old and therefore I chose to build lirc from source.

The ir led was setup using a npn 2222 transitory wired to 5v, G and GPIO 22 with a 10K and a 220 ohm ohm resistors to complete the circuit.



 $\label{linear_continuity} \textbf{Circuit diagram by Dmitri Popov:} \ \underline{\text{http://www.raspberry-pi-geek.com/Archive/2015/10/Raspberry-Pi-IR-remote} \\$

Install lircd using apt-get install or if a newer version is desired build from source.

sudo apt-get install lirc

To build from source:

Download the source. As of 12 / 23 / 2016 the source is found on Sourceforge under files in the lirc project area. The source file is lirc-0.9.4c.tar.gz.

Install dependancies:

sudo apt-get install autoconf automake autopoint autotools-dev bsd-mailx dctrl-tools debhelper debian-keyring debootstrap devscripts dh-autoreconf dh-python dh-strip-nondeterminism diffstat distro-info-data dput equivs exim4-base exim4-config exim4-daemon-light gettext gettext-base hardening-includes intltool-debian libapt-pkg-perl libarchive-zip-perl libasprintf-dev libasprintf0c2 libclass-accessor-perl libclass-inspector-perl libclone-perl libcommon-sense-perl libconvert-binhex-perl libcroco3 libcrypt-ssleay-perl libdigest-hmac-perl libdistro-info-perl libemail-valid-perl liberror-perl libexporter-lite-perl libfile-stripnondeterminism-perl libgettextpo-dev libgettextpo0 libio-pty-perl libio-sessiondata-perl libio-socket-inet6-perl libio-string-perl libio-stringy-perl libipc-run-perl libjson-perl libjson-xs-perl liblist-moreutils-perl liblockfile-bin liblockfile1 libltdl-dev libltdl7 libmail-sendmail-perl libmime-tools-perl libmpdec2 libnet-dns-perl libnet-

domain-tld-perl libnet-ip-perl libossp-uuid-perl libossp-uuid16 libparse-debcontrol-perl libparse-debianchangelog-perl libperlio-gzip-perl libpython3-stdlib libpython3.4-minimal libpython3.4-stdlib libsigsegv2 libsoap-lite-perl libsocket6-perl libsub-name-perl libsys-hostname-long-perl libtask-weaken-perl libtext-levenshtein-perl libtool libunistring0 libxmlrpc-lite-perl lintian m4 patchutils pbuilder po-debconf python3 python3-apt python3-chardet python3-debian python3-magic python3-minimal python3-pkg-resources python3-six python3.4 python3.4-minimal tlutils wdiff

Run ./configure as shown below. This will configure the install the same way the armhf Debian package is.

```
./configure --build=arm-linux-gnueabihf --prefix=/usr --
includedir=\${prefix}/include --mandir=\${prefix}/share/man --
infodir=\${prefix}/share/info --sysconfdir=/etc --localstatedir=/var --
disable-silent-rules --libdir=\${prefix}/lib/arm-linux-gnueabihf --
libexecdir=\${prefix}/lib/arm-linux-gnueabihf --disable-maintainer-mode --
disable-dependency-tracking HAVE_UINPUT=1
```

Run make and sudo make install.

```
make
sudo make install.
```

The lirc build is complete.

lirc Setup:

Ensure that the following lines are in your /boot/config.txt and not commented out. The debug=on is optional but helps with debugging.

```
# Uncomment this to enable the lirc-rpi module
dtoverlay=lirc-rpi,gpio out pin=22,gpio in pin=23,debug=on
```

Add lirc rpi.conf to /etc/modprobe.d:

```
options lirc rpi gpio in pin=23 gpio out pin=22
```

Add lirc.conf to /etc/modules-load.d:

```
lirc_dev
lirc rpi
```

Update the configuration files in /etc/lirc and add jbc_rm-sr309u.conf to /etc/lirc/lircd.conf.d.

Remove lirc from /etc/init.d and enable system scripts:

```
sudo systemctl enable lircd.services
sudo systemctl enable lircd.socket
```

For a more secure setup lirch should run under a user other than root. Setup lircd user

```
sudo useradd -M --shell /bin/false lircd
sudo usermod -L lircd
sudo adduser lircd video
```

Ensure that in the lircd_options.conf file the effective_user is set to the user created above.

If you wish to provide tcp/ip access to lirc you will need to make sure that the listen option is set in the lircd_options.conf file.

Reboot and check the following for errors:

```
dmesg
/var/log/syslog
sudo systemctl status lirc-setup
sudo systemctl status lirc.service
sudo systemctl status lirc.socket
```

Testing

Test JCV remote with the command below. The <u>-count=2 is critical</u> for JVC as if you just send the command once it will be ignored.

```
irsend --count=2 SEND ONCE RM-SR3 09U power audio
```

Troubleshooting

To run lircd from the command line use the command below:

```
sudo lircd --nodaemon --driver=de fault --device=/dev/lirc0 --uinput
```

If you run into problems with your driver not being loadable check that your plugins directory is set right. This is done on the command line using the –plugindir option or can be set in the lirc_options.conf file. Using the ./configure command string above will put the plugins in /usr/lib/arm-linux-gnueabihf/lirc/plugins.

Sources

Raspberry Pi IR remote by Dmitri Popov: http://www.raspberry-pi-geek.com/Archive/2015/10/Raspberry-Pi-IR-remote

Setting Up LIRC on the RaspberryPi by Alex Bain: http://alexba.in/blog/2013/01/06/setting-up-lirc-on-the-raspberrypi/

Lirc.org website: http://www.lirc.org/

Appendix Files

cat hardware.conf

```
# /etc/lirc/hardware.conf
# Arguments which will be used when launching lircd
LIRCD ARGS="--uinput"
# Don't start lircmd even if there seems to be a good config file
# START LIRCMD=false
# Don't start irexec, even if a good config file seems to exist.
# START IREXEC=false
# Try to load appropriate kernel modules
LOAD MODULES=true
# Run "lircd --driver=help" for a list of supported drivers.
DRIVER="default"
# usually /dev/lirc0 is the correct setting for systems using udev
DEVICE="/dev/lirc0"
MODULES="lirc rpi"
# Default configuration files for your hardware if any
LIRCD CONF=""
LIRCMD CONF=""
cat lircd.conf
# Populated config files can be found at http://sf.net/p/lirc-remotes. The
# irdb-get(1) and lirc-setup(1) tools can be used to search and download
# config files.
# From 0.9.2 config files could just be dropped as-is in the lircd.conf.d
# directory and be included by this file.
include "lircd.conf.d/*.conf"
cat lircmd.conf
# Populated config files can be http://sf.net/p/lirc-remotes. The
# irdb-get(1) and lirc-setup(1) tools can be used to search and download
# config files.
cat lirc options.conf
# These are the default options to lircd, if installed as
# /etc/lirc/lirc options.conf. See the lircd(8) and lircmd(8)
# manpages for info on the different options.
[lircd]
```

```
driver
           = /dev/lirc0
device
allow-simulate = No
repeat-max = 600
effective-user = lircd
listen = 8765

#connect = host[:port]

#debug
#uinput
            = ...
#release
            = ...
#logfile
            = ...
[lircmd]
[modprobe]
            = [lircd dev, lirc sir...]
#modules
cat jvc rm-sr309u.conf
# Please make this file available to others
# by sending it to <lirc@bartelmus.de>
# this config file was automatically generated
# using lirc-0.9.0-pre1(default) on Thu Dec 24 21:34:43 2015
# contributed by
# brand:
                          jvc.codes
# model no. of remote control:
# devices being controlled by this remote:
begin remote
 name RM-SR309U
 bits 16
  flags SPACE ENC
  eps
  aeps
            100
            582 1524
  one
  zero
            582 470
             582
  ptrail
            20485
  toggle bit mask 0x0
```

begi	in codes	
	power_audio	0xC5E8
	power vcr	0xC2D0
	power tv	0xC0E8
	source phono	0xC53C
	source cd	0xC5BC
	source tape1	0xC5FC
	source tape2	0xC5E0
	source fm	0xC510
	source am	0xC590
	vcr_play	0xC230
	vcr stop	0xC2C0
	vcr_pause	0xC2B0
	vcr_rewind	0xC2E0
	vcr forward	0xC260
	tape play	0xC130
	tape prev	0xC118
	tape next	0xC198
	tape stop	0xC1C0
	tape_pause	0xC1B0
	tape_rewind	0xC1E0
	tape_forward	0xC160
	cd_play	0xCD9E
	cd prev	0xCD5E
	cd_next	0xCDDE
	cd_stop	0xCD3E
	cd pause	0xCDBE
	cd_rewind	0xCD7E
	cd_forward	0xCD1E
	preset_minus	0xC518
	preset plus	0xC598
	fade	0xC538
	volume_down	0xC5F8
	volume_up	0xC578
end	codes	

end remote