

## Calibration results

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### Camera-system parameters:

cam0 (/HIKcam/image\_raw):

type: <class 'aslam\_cv.libaslam\_cv\_python.DistortedOmniCameraGeometry'>

distortion: [ 0.100791 0.26262282 -0.00083984 0.00065279] +- [ 0.00848962 0.04838246 0.00031833 0.00028144]

projection: [ 1.93123253 1503.98896073 1504.46247226 1238.905167 1011.09513363] +- [ 0.02299878

12.47629811 12.51612788 0.53580944 0.56884465]

reprojection error: [-0.000007, -0.000002] +- [0.348405, 0.349481]

## Target configuration

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Type: aprilgrid

Tags:

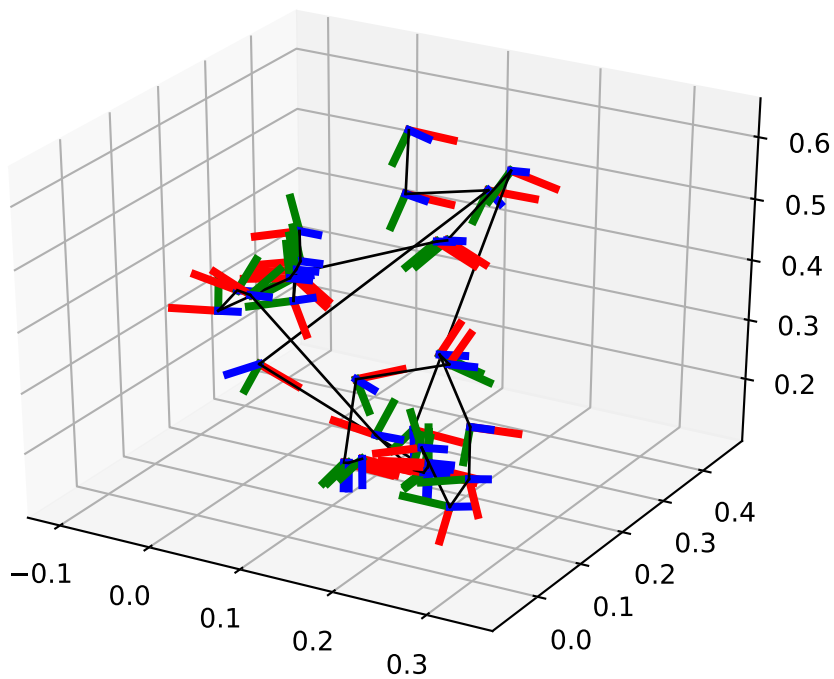
Rows: 6

Cols: 6

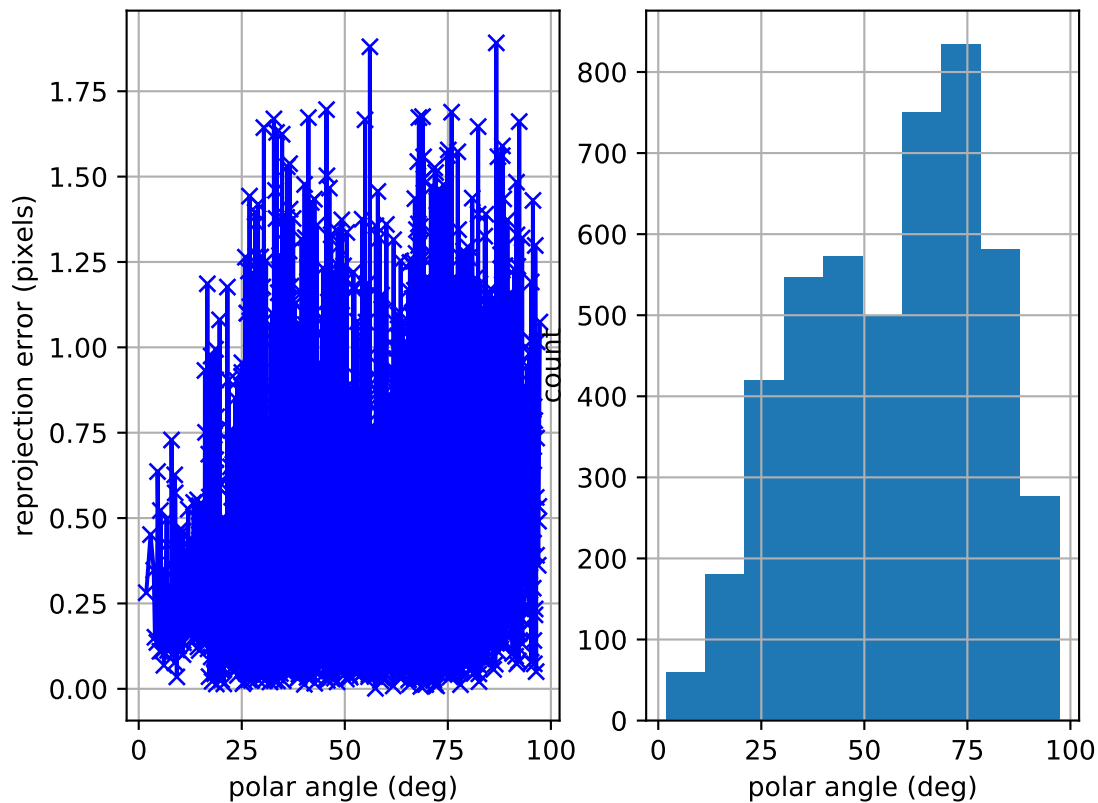
Size: 0.0352 [m]

Spacing 0.01056 [m]

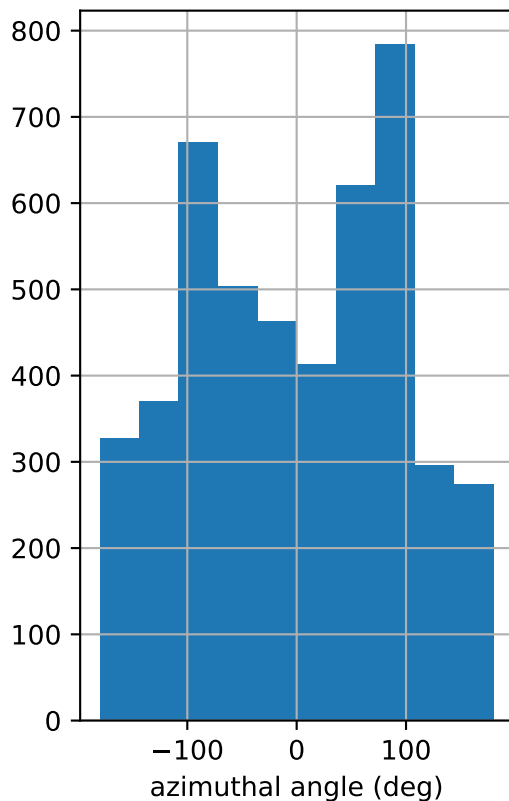
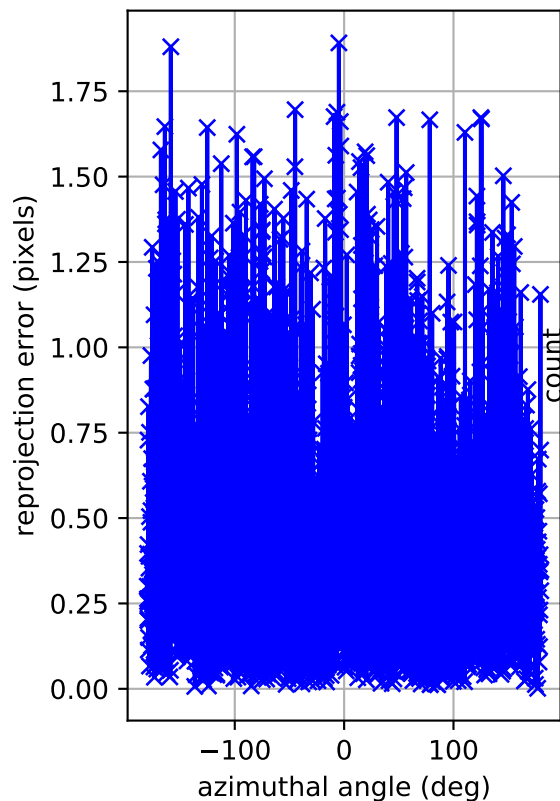
cam0: estimated poses



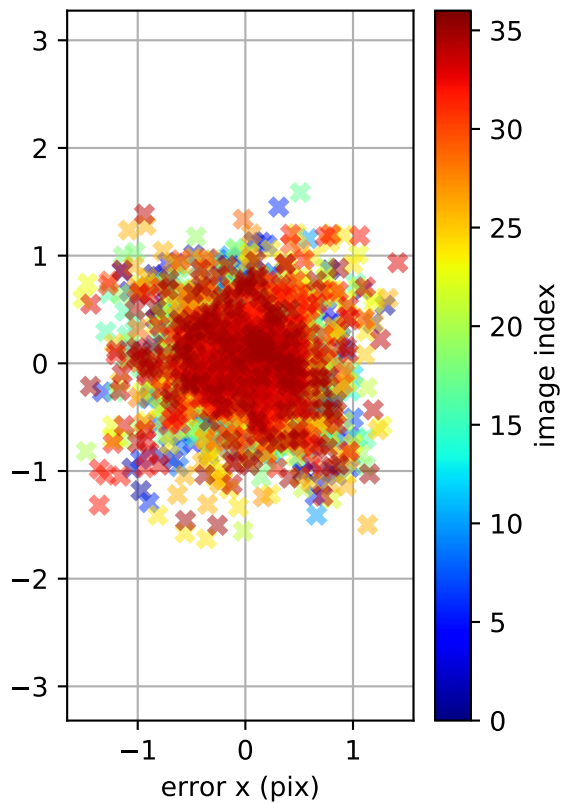
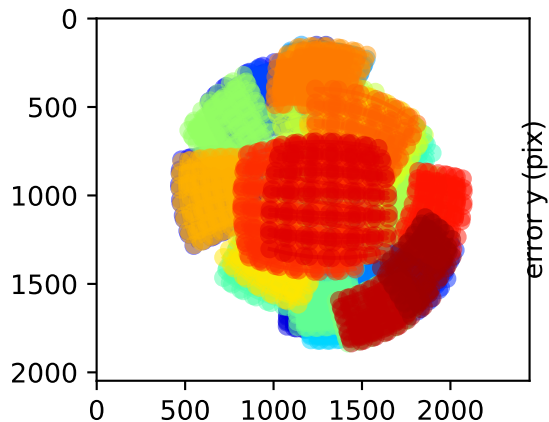
cam0: polar error



cam0: azimuthal error



cam0: reprojection errors



Location of removed outlier corners

