

# Lecture 4: Linking the observed data to the SCM, The statistical model

# A roadmap for causal inference

1. Specify **Causal Model** representing real background knowledge
2. Specify **Causal Question**
3. Specify **Observed Data** and link to causal model
4. **Identify** : Knowledge + data sufficient?
5. Commit to an **estimand** as close to question as possible, and a **statistical model** representing real knowledge.
6. **Estimate**
7. **Interpret** Results

# Outline

1. The observed data and their link to the SCM
2. From the SCM to a Statistical Model
  - What causal structures result in statistical independence
    - The d-separation criteria
  - How to tell what restrictions, if any, the SMC places on the allowed distributions for the observed data

# References

- TLB. Chapter 2
- Pearl. “An Introduction to Causal Inference” *Int J Biostat*, 6(2): Article 7, 2010.
- Greenland and Pearl. “Causal Diagrams” in S. Boslaugh, editor, Encyclopedia of Epidemiology. Sage Publications, Thousand Oaks, CA, 2007
- Greenland, Pearl and Robins. “Causal Diagrams for Epidemiologic Research” *Epidemiology*, 10(1): 37-48, 1999.

# Specify the Observed Data

- Of course, you can do this without the benefit of a causal model
- Example: Observed data are
  - Baseline covariates  $W = (\text{age, sex, SES})$
  - Exposure  $A = \text{Vitamin Use}$
  - Outcome  $Y = \text{Breast cancer status at 5 years}$
  - $O = (W, A, Y) \sim P_0$
- Note: the observed data are a (multidimensional) random variable and have a distribution

# Linking the observed data to the SCM

- We assume that the observed data were generated by a data generating system compatible with our SCM
  - $O$  is a subset of  $X$
- The distribution of  $U$  and the structural equations  $F$  identify the distribution of  $X$ , and thus the distribution of  $O$ 
  - For example: For  $O=X$

$$P_0(O = o) = \sum_u P_f(X = x|U = u)P(U = u) = \sum_u I(X(u) = x)P(U = u)$$

# Linking the observed data to the SCM

- We observe a sample of size  $n$  of the random variable  $O$ 
  - For now we will work with independent samples
  - The framework is not restricted to this
- This gives us  $n$  i.i.d. copies  $O_1, O_2, \dots, O_n$  drawn from probability distribution  $P_0$
- In other words, we assume our observed data were generated by sampling  $n$  times from the data generating system specified in our causal model

# What restrictions, if any, does the SCM put on the observed data distribution?

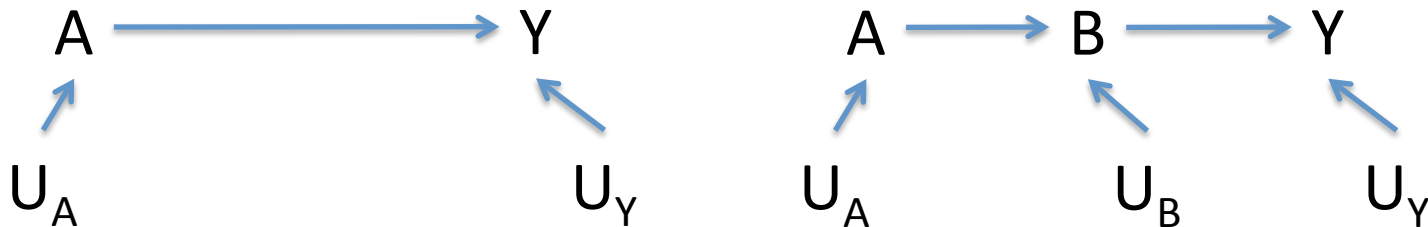
- How to tell what these are?
  - You can work it out based on functions  $F$  and allowed distributions for  $P_U$
  - You can evaluate the causal graph using the d-separation criteria
- Why is this helpful? Any such restrictions
  1. Give us our statistical model
    - Set of allowed distributions for  $P_0$
  2. Give us the testable implications (if any) of our SCM



# What causal structures can lead to dependence between two observed variables?

## 1. Direct and Indirect Effects

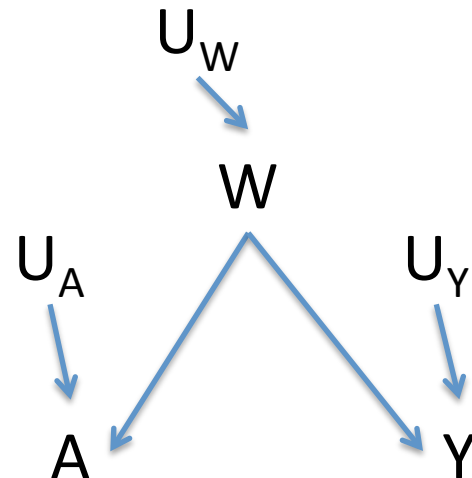
- An effect of A on Y can result in an association



# What causal structures can lead to dependence between two observed variables?

## 2. Shared common cause

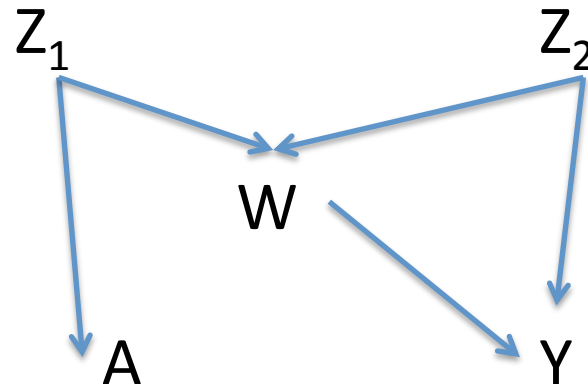
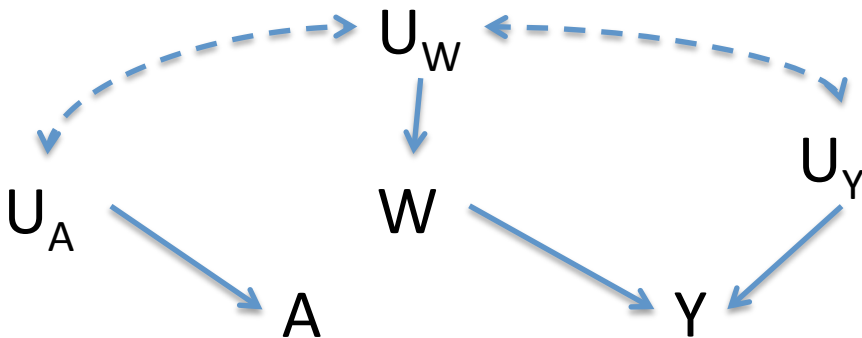
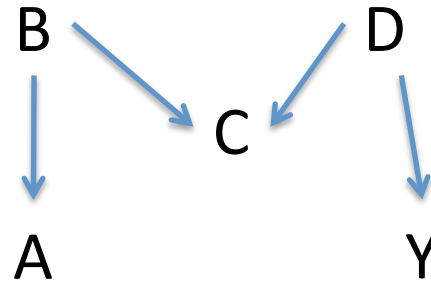
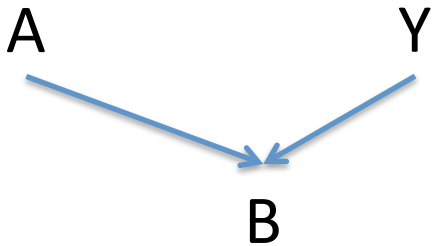
- Common cause (measured or unmeasured) of  $A$  and  $Y$  can result in an association
- When the common cause is not included in  $X$ , it is represented through the dependence it induces between errors  $U$



If neither of these sources of dependence are present, A and Y will be independent in every probability distribution  $P_0$  compatible with the SCM

- In other words, any data generating experiment that is compatible with the SCM will give rise to an observed data distribution in which A and Y are independent
  - Regardless of functional form, strength of associations, etc...
  - See also Pearl Causality Chapter 1

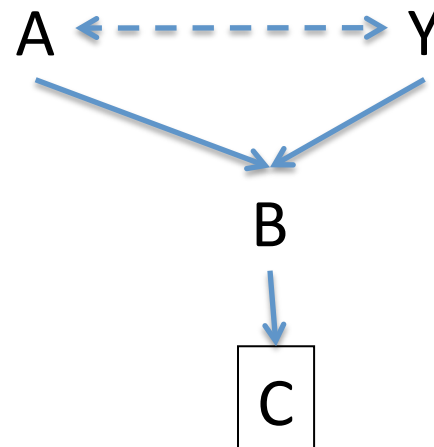
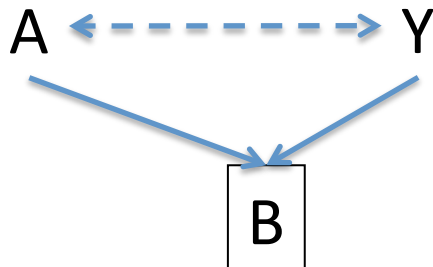
# Examples: A and Y independent?



# What causal structures can lead to dependence between two observed variables?

## 3. Conditioning on a Collider

- Collider= “inverted fork”  $a \rightarrow b \leftarrow c$
- Conditioning on a common effect (descendent) of A and Y can result in an association between A and Y
  - Berkson’s bias/ selection bias

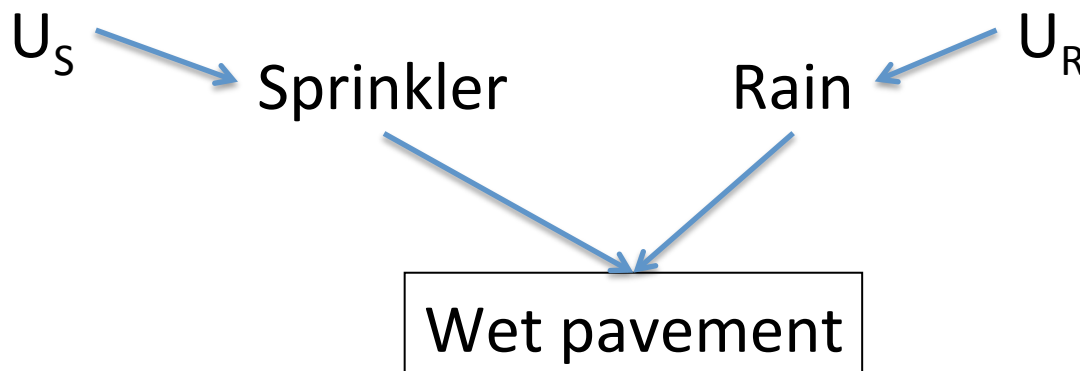


## Example: Sprinkler, rain and wet pavement

- Say the sprinkler is on a timer (unknown to us)
- What would an SCM look like for these three variables?
- Does the Graph imply that the sprinkler going off and it raining are independent?
  - If we learn that the sprinkler went off, does it give us any additional information about whether it rained?
  - If we learn that it rained, does it give us any additional information about whether the sprinkler went off?

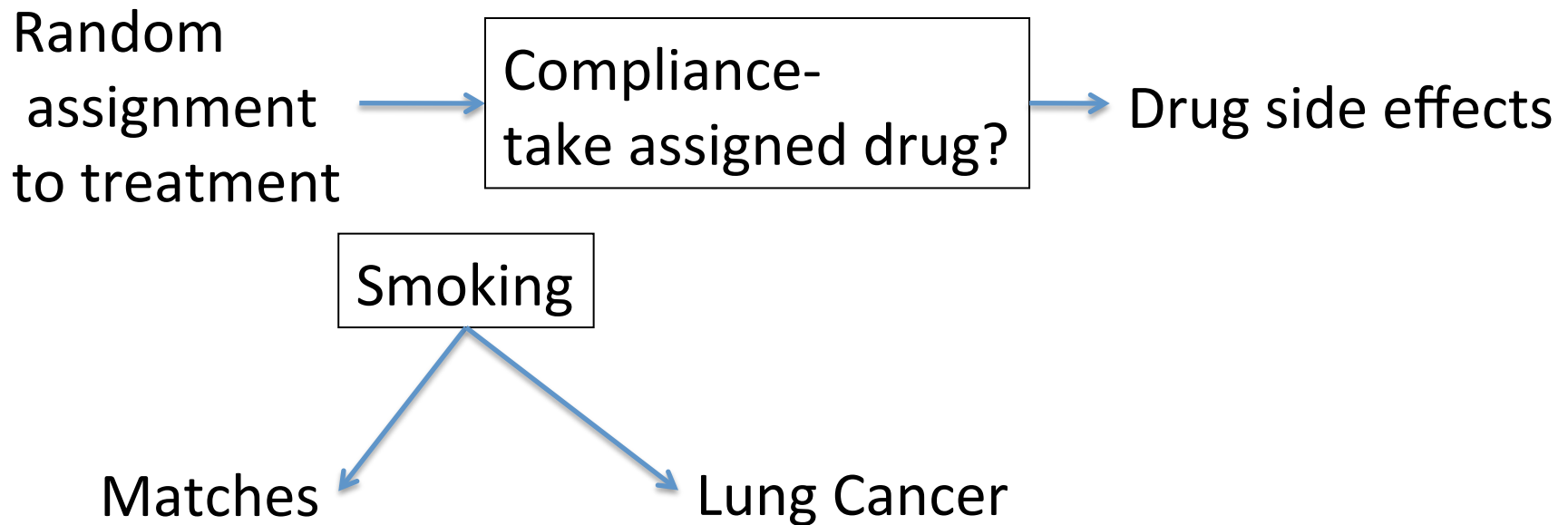
# Example: Sprinkler, rain and wet pavement

- Both cause the pavement to be wet
- Are sprinkler and rain independent conditional on whether the pavement is wet?
  - If we see the pavement is wet and learn that the sprinkler went off, does it give us any additional information about whether it rained?



# What can remove a source of dependence between variables?

- Conditioning on a causal intermediate or shared common cause between A and Y will remove that source of dependence





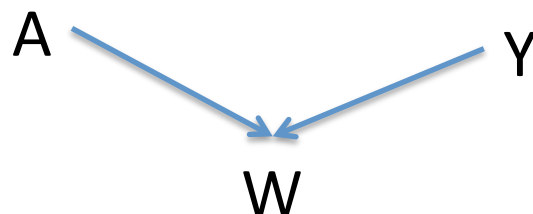
Summing Up: When does a graph/SCM imply that variables/nodes are independent?

- Path= set of connected edges (any directionality)
- A is (unconditionally) independent of Y if

1. There is no path between A and Y

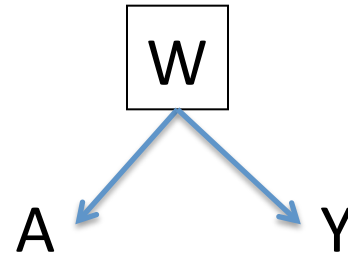
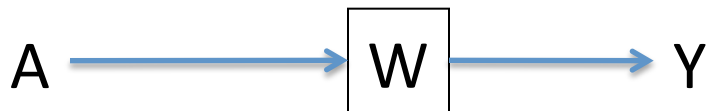
Or,  A  $\longrightarrow$  W                      Y

2. All paths between A and Y are “blocked” by a collider

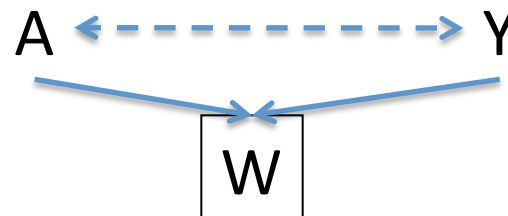


Summing Up: When does a graph imply that variables/nodes are independent?

- A is independent of Y given W if W blocks all unblocked paths and doesn't create any new unblocked paths
  - Conditioning on a non-collider blocks a path



- Conditioning on a collider (or a descendent of a collider) opens a path



# So when is a path blocked?

- If it has a non-collider that has been conditioned on

or

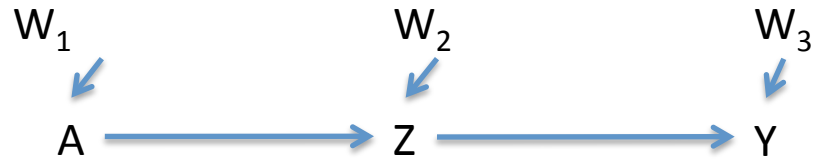
- If it has a collider *and* neither the collider nor a descendent of the collider has been conditioned on
- Absence of unblocked paths implies (conditional) independence

# Definition: D-separation

- A set of nodes  $S$  blocks a path if either
    - 1) The path has at least one arrow emitting node in  $S$ 
      - The path is open, but  $S$  blocks it
    - 2) The path has at least one collider that is outside of  $S$  and has no descendent in  $S$ 
      - The path is already blocked and  $S$  doesn't open it
- If  $S$  blocks all paths from  $X$  to  $Y$  then  $S$  d-separates  $X$  and  $Y$ , and  $X$  is independent of  $Y$  given  $S$*

# Examples of d-separation

- Path  $W_1$  to  $Y$ 
  - Blocked by  $\{\}$ ?
  - Blocked by  $W_2$ ?
  - Blocked by  $Z$ ?
- Path  $W_1$  to  $W_2$ 
  - Blocked by  $\{\}$ ?
  - Blocked by  $Z$ ?
  - Blocked by  $Y$ ?



# Why is *d-separation* helpful?

- Tells us what restrictions (if any) our causal model puts on the allowed distributions for the observed data
  - *d-separation* between two variables  $X$  and  $Y$  conditional on some subset of additional variables  $S$  implies  $X$  independent of  $Y$  given  $S$  in every probability distribution compatible with the SCM
- This is testable
- This gives us our statistical model

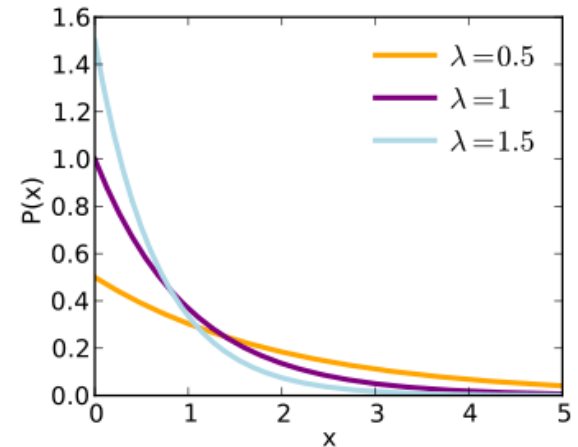
# Statistical Models

- The statistical model  $\mathcal{M}$  is the set of possible distributions for the observed data:  $P_0 \in \mathcal{M}$
- Non-parametric Model: No restrictions on the set of possible distributions  $P_0$
- Semi-parametric Model: Puts some restrictions on the set of possible distributions for  $P_0$
- Parametric Model: Assumes that we know  $P_0$  up to a finite number of unknown parameters

# Example: Parametric Model

- $O = X \sim P_0$ ;  $X$  continuous
- We know that  $X$  has exponential distribution

$$f(x; \lambda) = \begin{cases} \lambda e^{-\lambda x}, & x \geq 0, \\ 0, & x < 0. \end{cases}$$



- $\mathcal{M}$  is the set of all exponential distributions
  - Completely described by a single parameter  $\lambda$
- We know the distribution of  $X$  up to a finite number (in this case one) of unknown parameters



# Non-Parametric Model

- All we know is that we have  $n$  i.i.d. copies of  $O$ 
  - We may have some additional knowledge about how  $O$  was generated (represented in our SCM),
  - This knowledge does not imply any restrictions on the set of possible distributions for  $P_0$
- Example: Non-parametric Model
  - $O = X \sim P_0$ ;  $X$  continuous
  - $\mathcal{M}$  is the set of all possible distributions for  $X$
  - We do not know the distribution of  $X$  up to a finite number of unknown parameters

# Parametric vs. Non-Parametric Models

- Parametric and Non-parametric models are not mutually exclusive categories
- If  $O$  is discrete with finite number of outcomes or possible values then we always know its distribution up to a finite number of unknown parameters
- So a non-parametric model for discrete  $O$  (ie a model that does not restrict the set of allowed distributions for  $O$ ) is also technically parametric (has a finite number of unknown parameters).

# Parametric vs. Non-Parametric Models

- Parametric and Non-parametric models are not mutually exclusive categories
- Example:  $O=(A,W)$ ,  $A$  and  $W$  both binary
  - 4 possible outcomes for  $O$ :  
 $(A=1,W=1)$ ;  $(A=1,W=0)$ ;  $(A=0,W=1)$ ;  $(A=0,W=0)$
  - Probabilities of these mutually exclusive events have to sum to 1
  - > Knowing the probability of 3 of these events gives us the whole probability distribution for  $O$

# Parametric vs. Non-Parametric Models

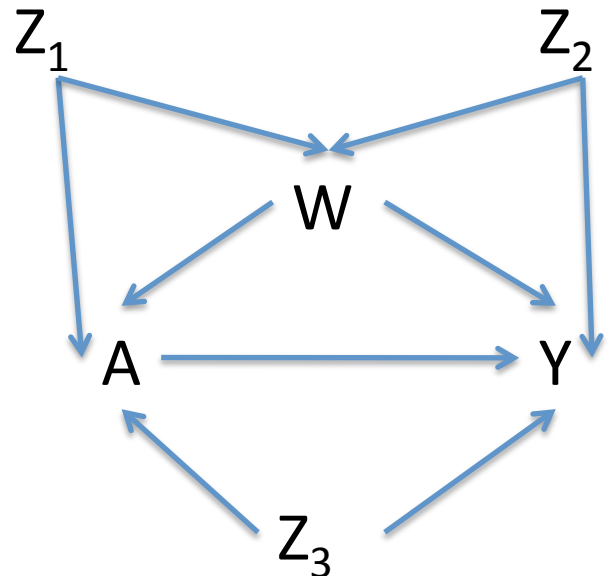
- A non-parametric model for discrete  $O$  (ie a model that does not restrict the set of allowed distributions for  $O$ ) is also parametric (has a finite number of unknown parameters).
  - However, may be many possible parametric models for  $O$  that do restrict its set of allowed distributions.
- The point is not that parametric (or semi-parametric) models are bad
- The point is that our model should accurately reflect our knowledge
  - It should contain the true distribution of  $O$

## Recap: Why is *d-separation* helpful?

- Tells us what restrictions (if any) our causal model puts on the allowed distributions for the observed data
  - *d-separation* between two variables  $X$  and  $Y$  conditional on some subset of additional variables  $S$  implies  $X$  independent of  $Y$  given  $S$  in every probability distribution compatible with the SCM
- This is testable
- This gives us our statistical model

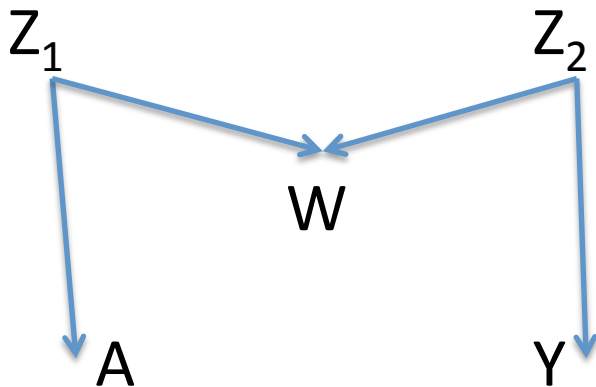
# Examples

- $O=(W,A,Y)$ 
  - No exclusion restrictions or independence assumptions
- What is the graph?
- What are the testable implications?
- What is the statistical model?



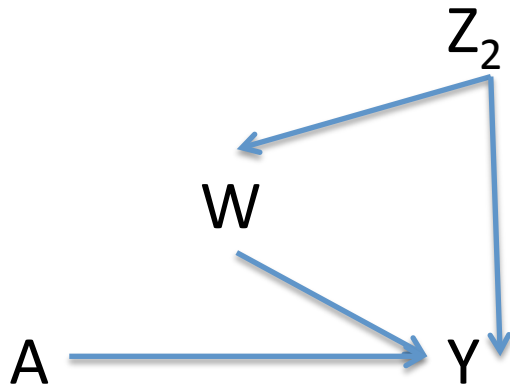
# Examples

- $O=(W,A,Y)$ 
  - $W$  does not affect  $A$  or  $Y$ ;  $A$  does not affect  $Y$
  - $U_A$  and  $U_Y$  independent
- What is the graph?
- What are the testable implications?
- What is the statistical model?



# Examples

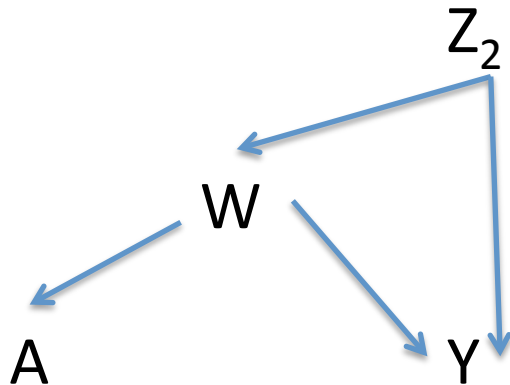
- $O=(W,A,Y)$ 
  - $W$  does not affect  $A$
  - $U_A$  independent of  $U_Y$  and  $U_W$
- What is the graph?
- What are the testable implications?
- What is the statistical model?





# Examples

- $O=(W,A,Y)$ 
  - $A$  does not affect  $Y$
  - $U_A$  independent of  $U_Y$  and  $U_W$
- What is the graph?
- What are the testable implications?
- What is the statistical model?



D-separation implies conditional independence:

If A and Y are d-separated by W, then A and Y are independent given W in every distribution compatible with the SCM

But...

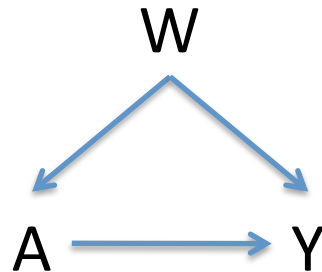
Lack of d-separation does not imply conditional dependence ...

If A and Y are not d-separated by W, then A and Y dependent given W in at least one distribution compatible with the SCM

# Note: Lack of d-separation does not imply dependence...

- Various sources of dependence can cancel each other...

- Example:



- A causes Y
- W is a negative confounder of the effect of A on Y (eg W causes A and prevents Y)
- If these two opposing sources of dependence have the same magnitude, A and Y may still be independent in a distribution compatible with this graph

# Implications...Learning graphs from data

- Why not look at independence in observed data distribution and use them to learn about the true causal model?
- In order to make progress, you end up needing a new assumption: “stability” or “faithfulness”
  - Basically- assumes that all the independencies we see in our observed data are structural (rather than reflecting various sources of dependence cancelling each other out)
- This is a large area of active research
  - We will not cover it in this class

# What have done so far?

- We specified a structural causal model:  $\mathcal{M}^F$ 
  - Consisted of specifying
    - X variables and U variables
    - Structural equations F (one for each X node)
      - Exclusion restrictions on the set of preceding nodes included in each parent set
    - Set of allowed distributions for  $P_U$ 
      - Assumptions on the independence of any two or more U variables
  - This gave the allowed distributions for  $(U,X) \sim P_{U,X}$

# What have we done so far?

- We specified a target causal parameter using counterfactuals
  - Counterfactuals were derived by evaluating the system of structural equations under a specific intervention
  - **The resulting counterfactual parameters are thus parameters of the distribution of (U,X):  $\Psi^F(P_{U,X})$** 
    - Example

$$\Psi^F(P_{U,X}) = E_{U,X}(Y_1 - Y_0)$$

# What have we done so far?

- We linked the observed data to the SCM
  - We assumed that the observed data were drawn from the system we specified using a SCM
  - $O$  is a subset of  $X$
  - $O \sim P_0$
- The model  $\mathcal{M}^{\mathcal{F}}$  (which gives us the allowed distributions for  $P_{U,X}$ ) implied a statistical model  $\mathcal{M}$  (which gives us the allowed distributions for  $P_0$ )

# What have we done so far?

- The *d-separation* criteria provided a straightforward way to indentify what restrictions, if any, the SCM places on the allowed distributions for  $P_0$ 
  - Functional or inequality constraints may also restrict the statistical model
- Often, no restrictions: Non-parametric statistical model
- Sometimes, some restrictions: Semi-parametric statistical model
  - Randomization is a classic example



# The Roadmap....

## 1. Causal Model

Representing background knowledge and uncertainty

## 3. Observed Data

Process that generated the data described by the causal model

## 2. Question

Translate the scientific question into a formal causal quantity (using counterfactuals)

## Statistical Model

Possible distributions for the Observed data



# Key Points

- We assume that the system that generated our observed data is described by our SCM
- Observed data:  $O \sim P_0$
- The SCM, which is a model on  $P_{U,X}$ , implies a model  $\mathcal{M}$  on  $P_0$ 
  - We refer to this as our statistical model
  - d-separation can be used to derive (many of) the testable implications of a SCM
- A non-parametric statistical model places no restrictions on the set of possible distributions for  $O$