

Topics:

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Necessary condition of optimality

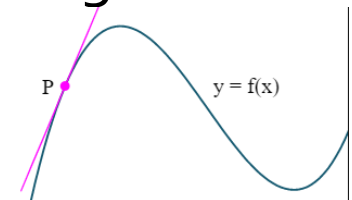
$f: \mathbb{R} \rightarrow \mathbb{R}$ is some function like $y = x^2$

If function has derivative everywhere then we can compute derivative everywhere

$f': \mathbb{R} \rightarrow \mathbb{R}$ for example above it's $y = 2x$

Value $f'(x)$ means in point "x" different things:

1. Speed with which your function moves along y
2. Tangent of angle for local approximation with tangent.



Necessary condition of optimality

Function $f: \mathbb{R} \rightarrow \mathbb{R}$ **decreases then increases**.
 $f'(x)$ should in some point x^* have value
 $f'(x) = 0$

Function $f: \mathbb{R} \rightarrow \mathbb{R}$ **increases then decreases** .
 $f'(x)$ should in some point x^* have value
 $f'(x) = 0$

We assume that f' has derivative everywhere

Necessary condition of optimality

For $f: \mathbb{R}^n \rightarrow \mathbb{R}$ the necessary condition is that $\nabla f = 0$

Consider constraint problem:

$$\min f(x)$$

$$h(x) = 0$$

It's another situation $h(x) = 0$ and directly it's not so clear how handle it. To do it we introduce

Lagrange Function:

$$L(x, \lambda) = f(x) + \lambda \cdot h(x)$$

Equality constraint optimization

Simple description why

$$\min_{x, \lambda} L(x, \lambda)$$

$$L(x, \lambda) = f(x) + \lambda \cdot h(x)$$

Lead to the same solution as

$$\min_x f(x)$$

$$h(x) = 0$$

Proves that we do not loose anything

$$\min_{x,\lambda} f(x) + \lambda \cdot h(x)$$

1. If “f” and “h” are differentiable then necessary condition for optimality is

- $\frac{\partial(f(x)+\lambda \cdot h(x))}{\partial x} = 0$
- $\frac{\partial(f(x)+\lambda \cdot h(x))}{\partial \lambda} = h(x) = 0$

2. Lagrange function achieves minimum in a point (x, λ) where both condition holds.
Particulary $h(x^*) = 0$

3. And we have $f(x^*) + \lambda^* \cdot h(x^*) = f(x^*) + \lambda^* \cdot 0 = f(x^*)$

4. To make $f(x^*) + \lambda^* \cdot 0$ as small as possible we need to make $f(x^*)$ as small as possible.

5. So

$\min_{x,\lambda} f(x) + \lambda \cdot h(x)$ **solves** same optimization problem as

$$\begin{aligned} \min f(x) \\ h(x) = 0 \end{aligned}$$

Summary so far about necessary condition for optimality

If there are several equality constraints.
The Lagrange function has the following form:

$$L(x, \lambda) = f(x) + \sum_{i=1}^n \lambda_i \cdot h_i(x)$$

We know currently that necessary optimality condition is the following

$$\nabla_{x,\lambda} L(x^*, \lambda^*) = \mathbf{0}$$