Network 1: Starting command untuk sequence gerak. Dimulai dengan command Go!

Comment
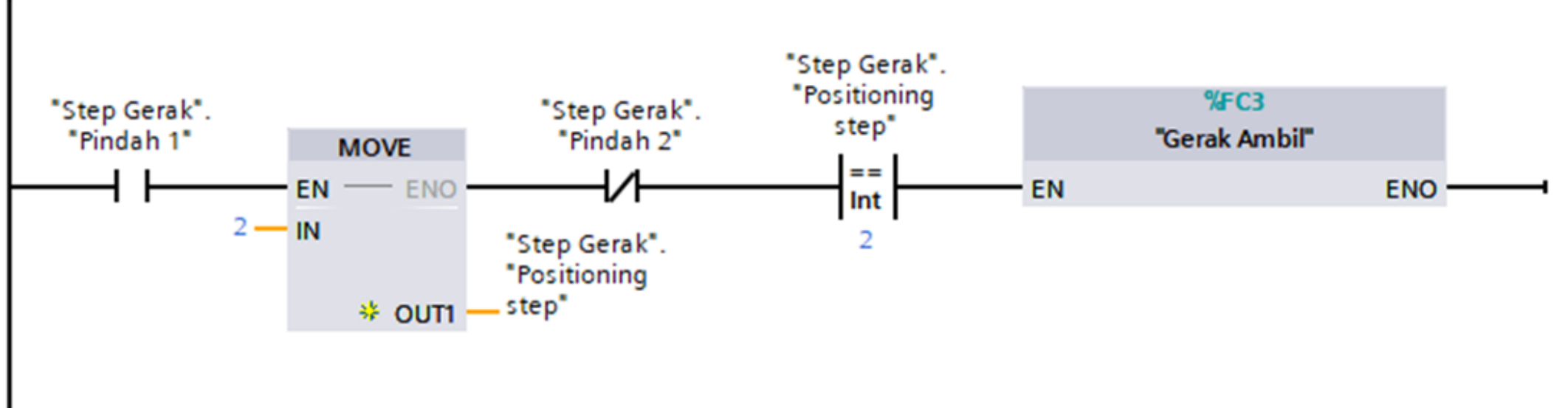
```
"Step Gerak".Go    "Step Gerak".
   | |               "Pindah 1"           MOVE
   | |                   |/|          EN ─── ENO
                                   1 ─ IN
                                                    "Step Gerak".
                                                    "Positioning
                                      * OUT1 ─────   step"
```
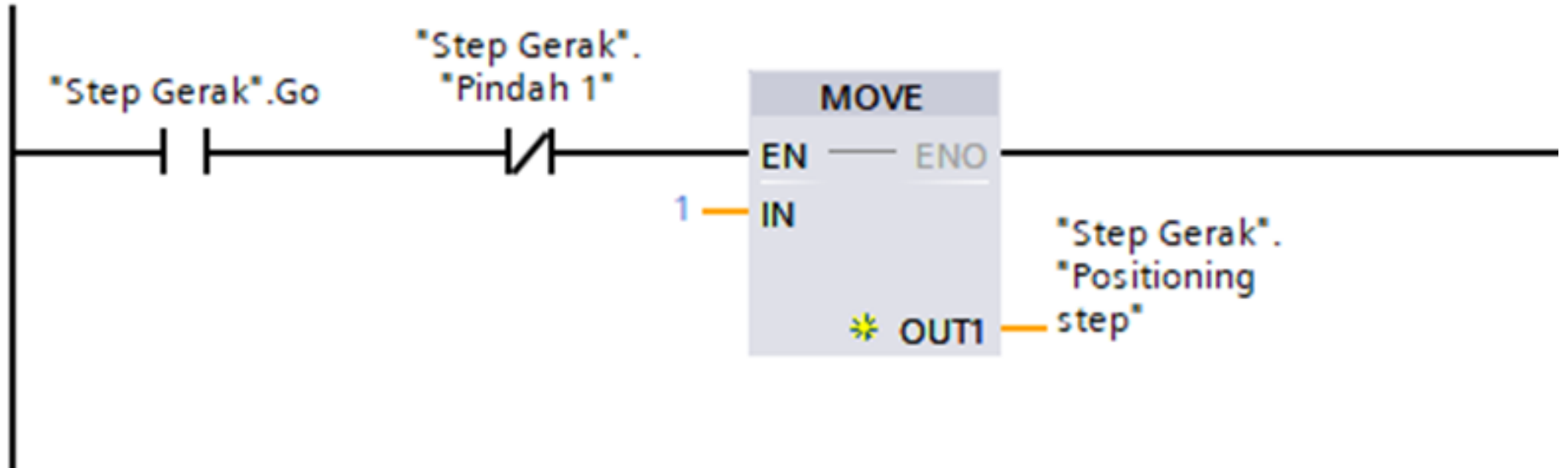
Network 2: Positioning 1 dan 3: Pindah ke posisi horizontal yang sesuai

Comment

```
"Step Gerak".
 "Positioning                                    %FC7
    step"                                     "Gerak Geser"
    ==                                   EN              ENO
    | Int |                                                     "Step Gerak".
      1              "Positioning_                  finished ─┤ "Pindah 1"
                      DB"."current
                         pos" ─── current pos
                     #from ─── equalizer
```

Network 3: Ambil

Comment

```
"Step Gerak".                        "Step Gerak".   "Step Gerak".
 "Pindah 1"          MOVE             "Pindah 2"     "Positioning        %FC3
    | |          EN ─── ENO               |/|           step"        "Gerak Ambil"
    | |       2 ─ IN                                     ==        EN            ENO
                              "Step Gerak".              | Int |
                              "Positioning                 2
                   * OUT1 ───  step"
```
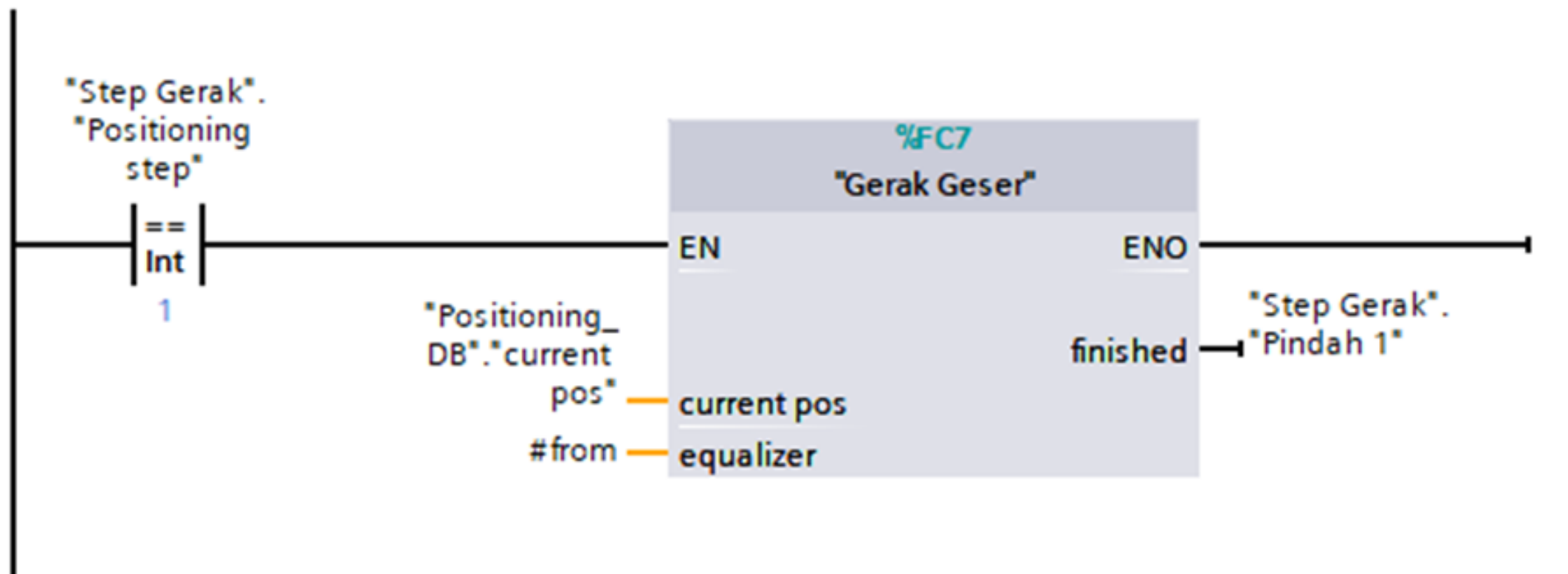
Network 4: Positioning 1 dan 3: Pindah ke posisi horizontal yang sesuai

Comment

```
"Step Gerak".
 "Positioning                                    %FC7
    step"                                     "Gerak Geser"
    ==                                   EN              ENO
    | Int |                                                     "Step Gerak".
      3              "Positioning_                  finished ─┤ "Pindah 2"
                      DB"."current
                         pos" ─── current pos
                     #destination ─── equalizer
```
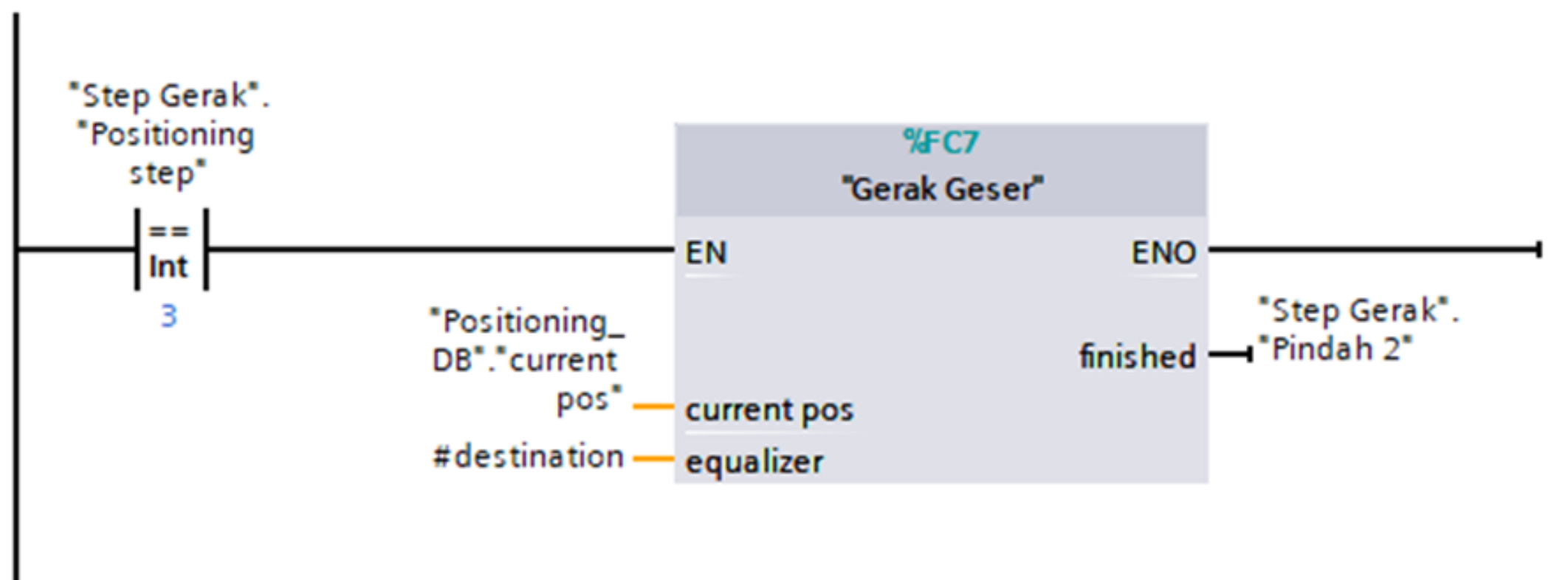
Network 5: Positioning 4: Gerakan melepas, didahului step pindah 2

Comment

```
"Step Gerak".                        "Step Gerak".
 "Pindah 2"          MOVE             "Positioning            %FC5
    | |          EN ─── ENO              step"            "Gerak Lepas"
    | |       4 ─ IN                      ==          EN            ENO
                              "Step Gerak".           | Int |
                              "Positioning               4
                   * OUT1 ───  step"
```
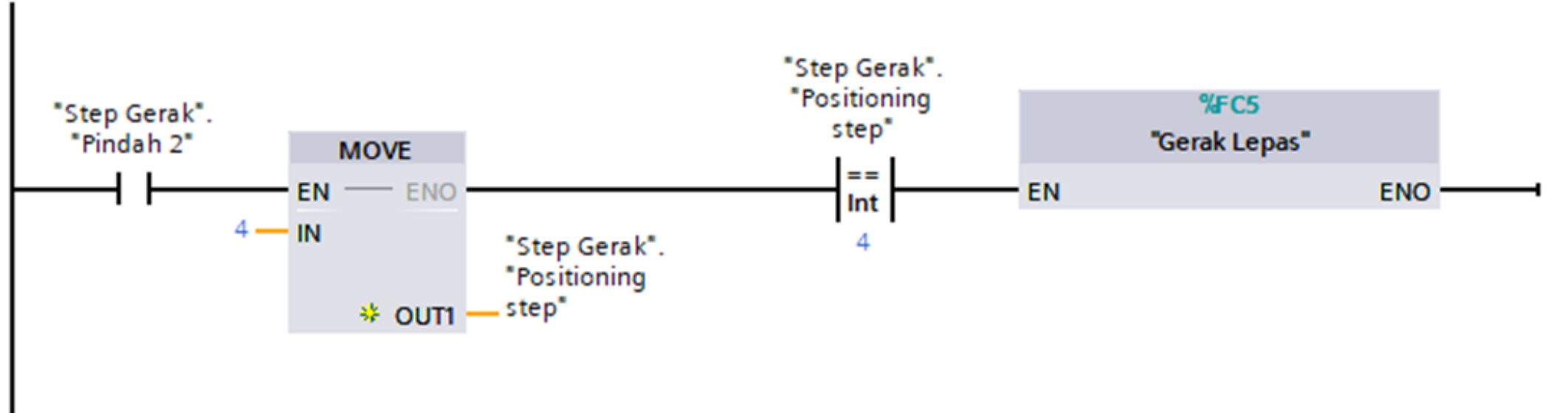
Network 6: Reset all, asalkan seluruh proses selesai

Comment

```
"Step Gerak".   "Step Gerak".   "Step Gerak".   "Step Gerak".
 "Pindah 1"       Ambil          "Pindah 2"       Lepas                        MOVE
    | |            | |              | |            | |                     EN ─── ENC
                                                                        0 ─ IN
                                                                                  "Step Gerak".
                                                                                  "Positioning
                                                                           * OUT1 ─  step"
 %M10.0
"Hard Reset DB
   Hanger"                                              "Step Gerak".
    | |                                                  "Pindah 1"
                                                           ─( R )
                                                        "Step Gerak".
                                                          Ambil
                                                           ─( R )
                                                        "Step Gerak".
                                                         "Pindah 2"
                                                           ─( R )
                                                        "Step Gerak".
                                                          Lepas
                                                           ─( R )
                                                        "Step Gerak".Take
                                                           ─( R )
                                                        "Step Gerak".
                                                          Release
                                                           ─( R )
                                                        "Step Gerak".Go
                                                           ─( R )
```