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Project Report:

**Pathfinding Prowess: Solving Mazes with Shortest
Paths Using DFS and BFS**

Subject Name – Design and Analysis of Algorithms

Subject Code – 23CSH-301

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1. Aim

To solve Mazes with Shortest Paths Using Depth-First Search and Breadth-First Search

2. Objective

Create an algorithm to solve mazes by finding the shortest path from the start to the exit, using either Depth-First Search or Breadth-First Search.

3. Apparatus Used

- Programming Language: C++
- IDE Used: Code:: VS Code / Visual Studio

4. Procedure / Algorithm

A) Algorithm: Maze Solver Using BFS (Shortest Path)

Input:

- A 2D maze represented as a grid (0 = open path, 1 = wall).
- Start coordinates (Sx, Sy) and Exit coordinates (Ex, Ey).

Output:

- Shortest path from start to exit (if exists).

Stepwise Algorithm



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1. Initialize structures

- Create a queue **Q** to hold positions to explore.
- Create a 2D **visited** array to mark visited cells.
- Create a **parent** dictionary to trace the path.

2. Add starting point

- Enqueue the start cell (**Sx**, **Sy**) into **Q**.
- Mark the start cell as visited.

3. Define movement

- Possible movements: **up**, **down**, **left**, **right**.

4. Start BFS loop

- While the queue **Q** is not empty:
 - Dequeue the current cell (**x**, **y**).
 - If (**x**, **y**) is the exit (**Ex**, **Ey**), stop BFS (exit found).
 - For each valid neighboring cell (**nx**, **ny**):
 - Check if (**nx**, **ny**) is inside maze boundaries.
 - Check if (**nx**, **ny**) is open (**0**) and not visited.
 - Enqueue (**nx**, **ny**) into **Q**.
 - Mark (**nx**, **ny**) as visited.



- Store (x, y) as the parent of (nx, ny) .

5. Trace back the path

- If the exit is reached:
 - Initialize an empty list **path**.
 - Start from exit cell (Ex, Ey) .
 - Move backward using the **parent** dictionary until reaching the start.
 - Reverse the **path** to get the correct order from start to exit.

6. Output the result

- If **path** exists, print the shortest path coordinates.
- Else, print "No path exists."

CODE:

```
#include <bits/stdc++.h>
```

```
using namespace std;
```

```
struct Point {
```

```
    int x, y;
```

```
};
```

```
// Directions: up, down, left, right
```

```
int dx[] = {-1, 1, 0, 0};
```

```
int dy[] = {0, 0, -1, 1};
```



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```
bool isValid(int x, int y, int rows, int cols, vector<vector<int>> &maze,
vector<vector<bool>> &visited) {

    return (x >= 0 && x < rows && y >= 0 && y < cols && maze[x][y] == 0 &&
!visited[x][y]);

}

vector<Point> bfsMazeSolver(vector<vector<int>> &maze, Point start, Point end) {

    int rows = maze.size();

    int cols = maze[0].size();

    vector<vector<bool>> visited(rows, vector<bool>(cols, false));

    map<pair<int,int>, pair<int,int>> parent;

    queue<Point> q;

    q.push(start);

    visited[start.x][start.y] = true;

    while (!q.empty()) {

        Point curr = q.front(); q.pop();

        if (curr.x == end.x && curr.y == end.y) {

            // Trace back path

            vector<Point> path;

            pair<int,int> p = {end.x, end.y};

            while (!(p.first == start.x && p.second == start.y)) {

                path.push_back({p.first, p.second});
```



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```
        p = parent[p];
    }
    path.push_back(start);
    reverse(path.begin(), path.end());
    return path;
}

for (int i = 0; i < 4; i++) {
    int nx = curr.x + dx[i];
    int ny = curr.y + dy[i];
    if (isValid(nx, ny, rows, cols, maze, visited)) {
        visited[nx][ny] = true;
        q.push({nx, ny});
        parent[{nx, ny}] = {curr.x, curr.y};
    }
}

return {}; // No path found
}
```

B) Algorithm: Maze Solver Using DFS (Pathfinding)

Input:



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- 2D maze (0 = open, 1 = wall)
- Start (S_x , S_y) and Exit (E_x , E_y)

Output:

- A path from start to exit (may not be shortest).
-

Stepwise Algorithm

1. Initialize structures

- Create a 2D **visited** array to mark cells as visited.
- Create a **path** list to store the current path.

2. Define movement

- Possible directions: up, down, left, right.

3. Recursive DFS function

- Function **dfs(x, y)**:
 1. If (x , y) is outside maze or is a wall or visited, return **False**.
 2. Add (x , y) to **path** and mark visited.
 3. If (x , y) is the exit, return **True**.
 4. For each neighbor (nx , ny):



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- Recursively call **dfs(nx, ny)**.
 - If recursive call returns **True**, propagate **True**.
5. If no path found, backtrack: remove **(x, y)** from **path** and return **False**.
4. Call DFS
- Start DFS from **(Sx, Sy)**.
5. Output
- If DFS succeeds, **path** contains the route from start to exit.
 - Else, print "No path exists."

CODE:

```
#include <bits/stdc++.h>
```

```
using namespace std;
```

```
struct Point {
```

```
    int x, y;
```

```
};
```

```
int dx[] = {-1, 1, 0, 0};
```

```
int dy[] = {0, 0, -1, 1};
```




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```
bool isValid(int x, int y, int rows, int cols, vector<vector<int>> &maze,
vector<vector<bool>> &visited) {

    return (x >= 0 && x < rows && y >= 0 && y < cols && maze[x][y] == 0 &&
!visited[x][y]);

}

bool dfsMazeSolver(vector<vector<int>> &maze, Point curr, Point end,
vector<vector<bool>> &visited, vector<Point> &path) {

    int rows = maze.size();

    int cols = maze[0].size();

    if (!isValid(curr.x, curr.y, rows, cols, maze, visited)) return false;

    path.push_back(curr);

    visited[curr.x][curr.y] = true;

    if (curr.x == end.x && curr.y == end.y) return true;

    for (int i = 0; i < 4; i++) {

        Point next = {curr.x + dx[i], curr.y + dy[i]};

        if (dfsMazeSolver(maze, next, end, visited, path)) return true;

    }

    path.pop_back(); // backtrack

    return false;

}
```

6. Complexity Analysis

Algo	Best Case	Worst / Average Case
BFS	$O(1)$ – exit found immediately	$O(R \times C)$ – explores all cells in the maze
DFS	$O(1)$ – exit found immediately	$O(R \times C)$ – may traverse all cells before finding exit

7. Result

- BFS successfully finds the shortest path from start to exit.
- DFS finds a path (may not be shortest), demonstrating recursive backtracking.

8. Conclusion

- BFS is ideal when the shortest path is required.
- DFS is simpler but may not yield the shortest path, useful for exploring all possible routes.