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6. WRITE A PROGRAM TO DISPLAY THE USE OF DIJKSTRA ALGORITHM.

```
#include <limits.h>

#include <stdio.h>

#define V 9

int minDistance(int dist[], bool sptSet[])
{
    // Initialize min value
    int min = INT_MAX, min_index;

    for (int v = 0; v < V; v++)
        if (sptSet[v] == false && dist[v] <= min)
            min = dist[v], min_index = v;

    return min_index;
}

void printSolution(int dist[], int n)
{
    printf("Vertex Distance from Source\n");
    for (int i = 0; i < V; i++)
        printf("\t%d \t\t\t\t %d\n", i, dist[i]);
}

void dijkstra(int graph[V][V], int src)
{
    int dist[V]; // The output array. dist[i] will hold the
                // shortest
                // distance from src to i

    bool sptSet[V]; // sptSet[i] will be true if vertex i is
                // included in shortest

    // Initialize all distances as INFINITE and stpSet[] as
```

```

for (int i = 0; i < V; i++)
    dist[i] = INT_MAX, sptSet[i] = false;

// Distance of source vertex from itself is always 0
dist[src] = 0;

// Find shortest path for all vertices
for (int count = 0; count < V - 1; count++) {
    int u = minDistance(dist, sptSet);

    // Mark the picked vertex as processed
    sptSet[u] = true;

    for (int v = 0; v < V; v++)

        // Update dist[v] only if is not in sptSet,
        // there is an edge from u to v, and total
        // weight of path from src to v through u is
        // smaller than current value of dist[v]
        if (!sptSet[v] && graph[u][v]
            && dist[u] != INT_MAX
            && dist[u] + graph[u][v] < dist[v])
            dist[v] = dist[u] + graph[u][v];
    }
    printSolution(dist, V);
}

int main()
{
    /* Let us create the example graph discussed above */
    int graph[V][V] = { { 0, 4, 0, 0, 0, 0, 0, 8, 0 },

```

```
{ 4, 0, 8, 0, 0, 0, 0, 11, 0 },
{ 0, 8, 0, 7, 0, 4, 0, 0, 2 },
{ 0, 0, 7, 0, 9, 14, 0, 0, 0 },
{ 0, 0, 0, 9, 0, 10, 0, 0, 0 },
{ 0, 0, 4, 14, 10, 0, 2, 0, 0 },
{ 0, 0, 0, 0, 0, 2, 0, 1, 6 },
{ 8, 11, 0, 0, 0, 0, 1, 0, 7 },
{ 0, 0, 2, 0, 0, 0, 6, 7, 0 } };
```

```
    dijkstra(graph, 0);
    return 0;
}
```

OUTPUT:

Vertex	Distance from Source
0	0
1	4
2	12
3	19
4	21
5	11
6	9
7	8
8	14

7. OBTAIN THE TOPOLOGICAL ORDERING OF VERTICES IN A GIVEN DIGRAPH.

```
#include <iostream>

#include <list>

#include <stack>

using namespace std;

class Graph {
    int V; // No. of vertices'
    list<int>* adj;
    void topologicalSortUtil(int v, bool visited[], stack<int>& Stack);

public:
    Graph(int V); // Constructor
    void addEdge(int v, int w);
    void topologicalSort();
};

Graph::Graph(int V)
{
    this->V = V;
    adj = new list<int>[V];
}

void Graph::addEdge(int v, int w)
{
    adj[v].push_back(w); // Add w to v's list.
}

void Graph::topologicalSortUtil(int v, bool visited[],
                                stack<int>& Stack)
{

```

```
visited[v] = true;
list<int>::iterator i;
for (i = adj[v].begin(); i != adj[v].end(); ++i)
    if (!visited[*i])
        topologicalSortUtil(*i, visited, Stack);
Stack.push(v);
}
void Graph::topologicalSort()
{
    stack<int> Stack;
    bool* visited = new bool[V];
    for (int i = 0; i < V; i++)
        visited[i] = false;

    for (int i = 0; i < V; i++)
        if (visited[i] == false)
            topologicalSortUtil(i, visited, Stack);

    while (Stack.empty() == false) {
        cout << Stack.top() << " ";
        Stack.pop();
    }
}
int main()
{
    Graph g(6);
    g.addEdge(5, 2);
    g.addEdge(5, 0);
    g.addEdge(4, 0);
    g.addEdge(4, 1);
```

```
g.addEdge(2, 3);  
g.addEdge(3, 1);  
cout << "Topological Sort of the given graph: ";  
g.topologicalSort  
return 0;  
}
```

OUTPUT:

```
Topological Sort of the given graph: 5 4 2 3 1 0
```


8. PRINT ALL THE NODES REACHABLE FROM A GIVEN STARTING NODE IN A DIGRAPH USING BFS METHOD.

```
#include <bits/stdc++.h>

using namespace std;

class Graph
{
public:
    int V;
    list<int> *adj;

    Graph(int ); // Constructor
    void addEdge(int, int);
    vector<int> BFS(int, int, int []);
};

Graph::Graph(int V)
{
    this->V = V;
    adj = new list<int>[V+1];
}

void Graph::addEdge(int u, int v)
{
    adj[u].push_back(v); // Add w to v's list.
    adj[v].push_back(u); // Add v to w's list.
}

vector<int> Graph::BFS(int componentNum, int src,
                        int visited[])
{
    queue<int> queue;
    queue.push(src);
```

```

visited[src] = componentNum;

// Vector to store all the reachable nodes from 'src'
vector<int> reachableNodes;

while(!queue.empty())
{
    int u = queue.front();
    queue.pop();
    reachableNodes.push_back(u);

    for (auto itr = adj[u].begin();
         itr != adj[u].end(); itr++)
    {
        if (!visited[*itr])
        {
            visited[*itr] = componentNum;
            queue.push(*itr);
        }
    }
}

return reachableNodes;
}

void displayReachableNodes(int n,
                           unordered_map<int, vector<int> > m)
{
    vector<int> temp = m[n];
    for (int i=0; i<temp.size(); i++)
        cout << temp[i] << " ";

    cout << endl;
}

```

```
}  
  
void findReachableNodes(Graph g, int arr[], int n)  
{  
    int V = g.V;  
    int visited[V+1];  
    memset(visited, 0, sizeof(visited));  
    unordered_map <int, vector<int> > m;  
    int componentNum = 0;  
    for (int i = 0 ; i < n ; i++)  
    {  
        int u = arr[i];  
        if (!visited[u])  
        {  
            componentNum++;  
            m[visited[u]] = g.BFS(componentNum, u, visited);  
        }  
        cout << "Reachable Nodes from " << u << " are\n";  
        displayReachableNodes(visited[u], m);  
    }  
}  
  
int main()  
{  
    int V = 7;  
    Graph g(V);  
    g.addEdge(1, 2);  
    g.addEdge(2, 3);  
    g.addEdge(3, 4);  
    g.addEdge(3, 1);  
    g.addEdge(5, 6);  
    g.addEdge(5, 7);
```

```
int arr[] = {2, 4, 5};  
int n = sizeof(arr)/sizeof(int);  
findReachableNodes(g, arr, n);  
  
return 0;  
}
```

OUTPUT:

```
Reachable Nodes from 2 are  
2 1 3 4  
Reachable Nodes from 4 are  
2 1 3 4  
Reachable Nodes from 5 are  
5 6 7
```

9.CHECK WHETHER A GIVEN GRAPH IS CONNECTED OR NOT USING DFS METHOD.

```
#include<iostream>

#define NODE 5

using namespace std;

int graph[NODE][NODE] = {{0, 1, 0, 0, 0},
    {0, 0, 1, 0, 0},
    {0, 0, 0, 1, 1},
    {1, 0, 0, 0, 0},
    {0, 1, 0, 0, 0}};

void traverse(int u, bool visited[]) {
    visited[u] = true;    //mark v as visited
    for(int v = 0; v<NODE; v++) {
        if(graph[u][v]) {
            if(!visited[v])
                traverse(v, visited);
        }
    }
}

bool isConnected() {
    bool *vis = new bool[NODE];

    //for all vertex u as start point, check whether all nodes are visible or not
    for(int u; u < NODE; u++) {
        for(int i = 0; i<NODE; i++)
            vis[i] = false;    //initialize as no node is visited
        traverse(u, vis);
        for(int i = 0; i<NODE; i++) {
            if(!vis[i])    //if there is a node, not visited by traversal, graph is not connected
                return false;
        }
    }
}
```

```
    return true;
}

int main() {
    if(isConnected())
        cout << "The Graph is connected.";
    else
        cout << "The Graph is not connected.";
}
```

OUTPUT:

```
The Graph is connected.
```

10. IMPLEMENT 0/1 KNAPSACK PROBLEM USING DYNAMIC PROGRAMMING.

```
#include <iostream>

using namespace std;

int max(int x, int y) {
    return (x > y) ? x : y;
}

int knapSack(int W, int w[], int v[], int n) {
    int i, wt;
    int K[n + 1][W + 1];
    for (i = 0; i <= n; i++) {
        for (wt = 0; wt <= W; wt++) {
            if (i == 0 || wt == 0)
                K[i][wt] = 0;
            else if (w[i - 1] <= wt)
                K[i][wt] = max(v[i - 1] + K[i - 1][wt - w[i - 1]], K[i - 1][wt]);
            else
                K[i][wt] = K[i - 1][wt];
        }
    }
    return K[n][W];
}

int main() {
    cout << "Enter the number of items in a Knapsack:";
    int n, W;
    cin >> n;
    int v[n], w[n];
    for (int i = 0; i < n; i++) {
        cout << "Enter value and weight for item " << i << ":";
        cin >> v[i];
        cin >> w[i];
    }
}
```

```
}  
cout << "Enter the capacity of knapsack";  
cin >> W;  
cout << knapSack(W, w, v, n);  
return 0;  
}
```

OUTPUT:

```
Enter the number of items in a Knapsack:4  
Enter value and weight for item 0:10  
50  
Enter value and weight for item 1:20  
60  
Enter value and weight for item 2:30  
70  
Enter value and weight for item 3:40  
90  
Enter the capacity of knapsack100  
40
```


11. FIND A SUBSET OF A GIVEN SET $S = \{S_1, S_2, S_N\}$ OF N POSITIVE INTEGERS WHOSE SUM IS EQUAL TO A GIVEN POSITIVE INTEGER D.

```
#include<stdio.h>

int d;

void sum(int,int,int[]);

int main()
{
    int n,w[100],i;
    printf("Enter the no of objects\n");
    scanf("%d",&n);

    printf("Enter the elements in increasing order\n");
    for(i=1;i<=n;i++)
        scanf("%d",&w[i]);
    printf("Enter the maximum capacity\n");
    scanf("%d",&d);
    sum(n,d,w);
}

void sum(int n,int d,int w[])
{
    int x[100],s,k,i,found=0;
    for(i=1;i<=n;i++)
        x[i]=0;
    s=0;
    k=1;
    x[k]=1;
    while(1)
    {
        if(k <= n && x[k]==1)
        {
```

```
if(s+w[k] == d)
{
    found=1;

    printf("The solution is\n");
    for(i=1;i<=n;i++)
    {
        if(x[i]==1)
            printf("%d\t",w[i]);
    }
    printf("\n");
    x[k]=0;
}

else if(s+w[k] < d)
    s+=w[k];

else
{
    x[k]=0;
}
}

else
{
    k--;
    while(k>0 && x[k]==0)
        k--;

    if(k<=0)
    {

        break;
    }
}
```

```
        }  
        x[k]=0;  
        s=s-w[k];  
    }  
    k=k+1;  
    x[k]=1;  
}  
if(!found)  
    printf("no solution\n");  
}
```

OUTPUT:

```
Enter the no of objects  
5  
Enter the elements in increasing order  
1 2 3 4 5  
Enter the maximum capacity  
5  
The solution is  
1 4  
The solution is  
2 3  
The solution is  
5
```

12. COMPUTE THE TRANSITIVE CLOSURE OF A GIVEN DIRECTED GRAPH USING WARSHALL'S ALGORITHM.

```
#include<stdio.h>

const int MAX = 100;

void WarshallTransitiveClosure(int graph[MAX][MAX], int numVert);

int main(void)
{
    int i, j, numVert;
    int graph[MAX][MAX];

    printf("Warshall's Transitive Closure\n");
    printf("Enter the number of vertices : ");
    scanf("%d",&numVert);

    printf("Enter the adjacency matrix :-\n");
    for (i=0; i<numVert; i++)
        for (j=0; j<numVert; j++)
            scanf("%d",&graph[i][j]);

    WarshallTransitiveClosure(graph, numVert);

    printf("\nThe transitive closure for the given graph is :-\n");
    for (i=0; i<numVert; i++)
    {
        for (j=0; j<numVert; j++)
        {
            printf("%d\t",graph[i][j]);
        }
        printf("\n");
    }
    return 0;
}
```

```

void WarshallTransitiveClosure(int graph[MAX][MAX], int numVert)
{
    int i,j,k;

    for (k=0; k<numVert; k++)
    {
        for (i=0; i<numVert; i++)
        {
            for (j=0; j<numVert; j++)
            {
                if (graph[i][j] || (graph[i][k] && graph[k][j]))
                    graph[i][j] = 1;
            }
        }
    }
}

```

OUTPUT:

```

Warshall's Transitive Closure
Enter the number of vertices : 4
Enter the adjacency matrix :-
0 0 1 0 0 0 0 1 1 0 0 0 0 1 0 0

The transitive closure for the given graph is :-
1  0  1  0
0  1  0  1
1  0  1  0
0  1  0  1

```

13. IMPLEMENT ALL-PAIRS SHORTEST PATH PROBLEMS USING FLOYD'S ALGORITHM.

```

#include<iostream>
#include<iomanip>
#define NODE 7
#define INF 999
using namespace std;
int costMat[NODE][NODE] = {
    {0, 3, 6, INF, INF, INF, INF},
    {3, 0, 2, 1, INF, INF, INF},
    {6, 2, 0, 1, 4, 2, INF},
    {INF, 1, 1, 0, 2, INF, 4},
    {INF, INF, 4, 2, 0, 2, 1},
    {INF, INF, 2, INF, 2, 0, 1},
    {INF, INF, INF, 4, 1, 1, 0}
};

void floydWarshal(){
    int cost[NODE][NODE]; //define to store shortest distance from any node to any node
    for(int i = 0; i<NODE; i++)
        for(int j = 0; j<NODE; j++)
            cost[i][j] = costMat[i][j]; //copy costMatrix to new matrix
    for(int k = 0; k<NODE; k++){
        for(int i = 0; i<NODE; i++)
            for(int j = 0; j<NODE; j++)
                if(cost[i][k]+cost[k][j] < cost[i][j])
                    cost[i][j] = cost[i][k]+cost[k][j];
    }
    cout << "The matrix:" << endl;
    for(int i = 0; i<NODE; i++){
        for(int j = 0; j<NODE; j++)
            cout << setw(3) << cost[i][j];
        cout << endl;
    }
}

```

```
}  
}  
int main(){  
    floydWarshal();  
}
```

OUTPUT:

The matrix:

0	3	5	4	6	7	7
3	0	2	1	3	4	4
5	2	0	1	3	2	3
4	1	1	0	2	3	3
6	3	3	2	0	2	1
7	4	2	3	2	0	1
7	4	3	3	1	1	0

14. IMPLEMENT N QUEEN'S PROBLEM USING BACK TRACKING.

```
#include<iostream>

using namespace std;

int grid[10][10];

void print(int n) {
    for (int i = 0; i <= n-1; i++) {
        for (int j = 0; j <= n-1; j++) {
            cout << grid[i][j] << " ";
        }
        cout << endl;
    }
    cout << endl;
    cout << endl;
}

bool isSafe(int col, int row, int n) {
    for (int i = 0; i < row; i++) {
        if (grid[i][col]) {
            return false;
        }
    }
    for (int i = row, j = col; i >= 0 && j >= 0; i--, j--) {
        if (grid[i][j]) {
            return false;
        }
    }
    for (int i = row, j = col; i >= 0 && j < n; j++, i--) {
        if (grid[i][j]) {
            return false;
        }
    }
}
```



```
        return true;
    }
    bool solve (int n, int row) {
        if (n == row) {
            print(n);
            return true;
        }
        bool res = false;
        for (int i = 0; i <= n-1; i++) {
            if (isSafe(i, row, n)) {
                grid[row][i] = 1;
                res = solve(n, row+1) || res; //if res ==false then backtracking will occur
                grid[row][i] = 0;
            }
        }
        return res;
    }
    int main()
    {
        ios_base::sync_with_stdio(false);
        cin.tie(NULL);

        int n;
        cout<<"Enter the number of queen"<<endl;
        cin >> n;
        for (int i = 0; i < n; i++) {
            for (int j = 0; j < n; j++) {
                grid[i][j] = 0;
            }
        }
        bool res = solve(n, 0);
```

```
if(res == false) {  
    cout << -1 << endl; //if there is no possible solution  
} else {  
    cout << endl;  
}  
return 0;  
}
```

OUTPUT:

```
Enter the number of queen  
4  
0 1 0 0  
0 0 0 1  
1 0 0 0  
0 0 1 0  
  
0 0 1 0  
1 0 0 0  
0 0 0 1  
0 1 0 0
```